James C Cameron* (j_cameron@utexas.edu), Luis Diego Granera, Peter Jaworski and Loren Santana. Discrete Models with Proportional Harvesting.

Difference equations used to model populations are analyzed, and we show how to control stability and induce chaos using proportional harvesting. In particular, we use the Beverton-Holt and Ricker models with proportional harvesting to demonstrate that a harvested system can be more stable than its unharvested counterpart. We also use digraphs to analyze the periodic structure of continuous functions, and we provide necessary and sufficient conditions for a digraph to support a continuous or piecewise monotone function. (Received July 27, 2011)