The inertia of a zero-nonzero pattern or sign pattern $\mathcal{A}$ is the collection of 3-tuples $i(\mathcal{A}) = \{(n_+, n_-, n_0)\}$, where $A$ runs over all matrix realizations of $\mathcal{A}$ and $n_+, n_-, n_0$ give the number of eigenvalues of $A$ with positive, negative, and zero real part (respectively). This talk focuses on $n \times n$ patterns whose inertia contains $S_n = \{(0, n, 0), (0, n-1, 1), (1, n-1, 0)\}$, and we discuss some results pertaining to both zero-nonzero patterns and sign patterns. We also give a construction for an infinite family of patterns whose refined inertia contains $S_n$. (Received January 09, 2019)