SHEFFER'S SET OF FIVE POSTULATES FOR BOOLEAN ALGEBRAS IN TERMS OF THE **OPERATION "REJECTION" MADE COM-**PLETELY INDEPENDENT.

BY DR. J. S. TAYLOR.

(Read before the American Mathematical Society December 31, 1919.)

Some time ago Professor L. L. Dines* demonstrated the fact that while Sheffer's† five postulates for Boolean algebras in terms of "rejection" are independent in the ordinary sense that no one of the postulates is implied by the other four, they are not completely independent in the sense defined by Professor E. H. Moore[‡] inasmuch as the negative of the first postulate implies the third, fourth, and fifth postulates of the set. It is the purpose of this paper to demonstrate that if the first postulate is replaced by one postulating a minimum of four instead of two distinct elements the resulting set of postulates is a completely independent set.§

Sheffer's five postulates concerning a system $\Sigma(K, |)$ are:

1. There are at least two elements in K.

2. Whenever a and b are elements of K, $a \mid b$ is an element of K. Definition: $a' = a \mid a$.

3. Whenever a and the indicated combinations of a are elements of K, (a')' = a.

4. Whenever a, b, and the indicated combinations of a and b are elements of K,

$$a \mid (b \mid b') = a'.$$

^{*} L. L. Dines. "Complete existential theory of Sheffer's postulates for Boolean algebras," this BULLETIN, vol. 21 (Jan., 1915), pp. 183–188. † H. M. Sheffer, "A set of five postulates for Boolean algebras with applications to logical constants," *Transactions Amer. Math. Society*, vol. 14

^{(1913),} pp. 481–488.
‡ E. H. Moore, "Introduction to a form of general analysis," New Haven Mathematical Colloquium, Yale University Press, page 82.
§ A set of m postulates is said to be ordinarily independent if no one of the set of the

A set of m postulates is said to be ordinarily independent if no one of the m postulates is implied by the others. A set of m postulates is said to be completely independent if, and only if, there are no implicational relations existing among the properties defined either by the postulates as they stand or by the negatives of the postulates. For, if the truth or falsity of one postulate implies either that another postulate is true or that it is false, it would seem either that the two postulates are concerned with two aspects of the same fundamental property on that there are two fundamental of the same fundamental property, or that there are two fundamental properties involved in such a manner that one of the postulates, at least, deals with both properties.

5. Whenever a, b, c, and the indicated combinations of a, b and c are elements of K,

$$[a | (b | c)]' = (b' | a) | (c' | a).$$

As stated above, the negative of the first postulate implies the third, fourth, and fifth postulates. For, if K contains less than two distinct elements, these three postulates are satisfied either evidently or vacuously according as the second postulate does or does not hold. This difficulty is no longer encountered, however, if, instead of assuming postulate 1, we assume the following.

1'. There are at least four distinct elements in K.

The truth of this statement is demonstrated by the exhibition of thirty-two systems having the $2^5 = 32$ possible characters (+++++), (++++-),..., (----), the *i*th sign being plus or minus according as the *i*th postulate is or is not satisfied.

There are two systems with K^{singular} , eight with K^{dual} , six with K^{triple} , and sixteen with $K^{\text{quadruple}}$. In each case the systems have been chosen with as few elements as possible.

In accordance with custom the result of combining elements is given by means of tables. For example, if K contains two elements l_1 and l_2 and if $l_1 | l_1 = l_1$, $l_1 | l_2 = l_1$, $l_2 | l_1 = l_2$, and $l_2 | l_2 = l_2$, this will be stated in the form

$$\frac{1}{l_1} \frac{l_1}{l_1} \frac{l_2}{l_1} \frac{l_1}{l_2} \frac{l_2}{l_2} \frac{l_2}{l_2} \frac{l_2}{l_2}$$

If $l_i | l_j$ does not give an element in K, this will be indicated by saying that $l_i | l_j = x$. The extension of this sort of table to systems containing more than two elements is obvious.

The thirty-two systems with their indicated charactersfollow:

$$K Singular.$$
System I₁. $(-++++)$ $l_1 | l_1 = l_1.$
System I₂. $(--+++)$ $l_1 | l_1 \neq l_1.$
K Dual.
System II₁.
System II₂.
 $(-+++-) \frac{1}{l_1} \frac{l_1 \ l_2}{l_1 \ l_1}$ $(-++-+) \frac{1}{l_1} \frac{l_1 \ l_2}{l_1 \ l_2}$
 $(-++-+) \frac{1}{l_2} \frac{l_1 \ l_2}{l_2 \ l_2}$

Syste	em	II	3•
	1	l_1	l_2
(-+-++)	l_1	l_1	l_1
	l_2	l_1	l_1

 $(-+--+) \frac{1}{l_1} \frac{l_1}{l_1} \frac{l_2}{l_1} \frac{l_1}{l_2} \frac{l_2}{l_2} \frac{l_1}{l_1}$

System II₇.

 $(---++) \begin{array}{c|c} \frac{1}{l_1} & \frac{l_1}{l_1} & \frac{l_2}{l_1} \\ \frac{l_1}{l_2} & \frac{l_1}{x} & \frac{l_1}{l_1} \end{array}$

System II₅.

System II₄.
(-++--)
$$\frac{1}{l_1} \frac{l_1 \quad l_2}{l_1 \quad l_1 \quad l_2}$$

 $l_2 \mid l_1 \quad l_2$

System II₆.
(--+-+)
$$\frac{1}{l_1} \frac{l_1}{l_1} \frac{l_2}{l_1} \frac{l_2}{l_2} \frac{l_2}{x} \frac{l_2}{z}$$

System II₈.
(---+)
$$\frac{1}{l_1} \frac{l_1 \quad l_2}{l_2 \quad l_1}$$

 $l_2 \mid x \quad l_2$

K Triple.

System III₁.

$$(-+-+-) \frac{\frac{1}{l_1} \begin{vmatrix} l_1 & l_2 & l_3 \\ l_1 & l_1 & l_2 & l_3 \\ l_2 & l_1 & l_1 & l_1 \\ l_3 & l_2 & l_1 & l_2 \end{vmatrix}}$$

$$(-+--) \frac{\frac{1}{l_1}}{l_2} \frac{l_1 \quad l_2 \quad l_3}{l_1 \quad l_2 \quad l_3}}{l_3 \quad l_1 \quad l_3} \frac{l_2 \quad l_3 \quad l_1 \quad l_3}{l_2 \quad l_3 \quad l_2}$$

System III₅.

$$(---+-) \frac{\frac{1}{l_1} \begin{vmatrix} l_1 & l_2 & l_3 \\ l_1 & l_2 & x \\ l_2 & l_1 & l_1 & l_1 \\ l_3 & l_2 & l_1 & l_2 \end{vmatrix}}{}$$

System III₂.

$$(--++-) \frac{1}{l_1} \begin{vmatrix} l_1 & l_2 & l_3 \\ l_1 & l_2 & l_3 \\ l_3 & l_3 & l_1 \\ l_3 & l_2 & x & x \end{vmatrix}$$

System III₄.

$$(--+--) \frac{\frac{1}{l_1}}{\begin{array}{c}l_1 & l_2 & l_3\\ l_1 & l_2 & l_3\\ l_3 & l_1 & x & l_3\end{array}} \frac{1}{l_1} \frac{l_1 & l_2 & l_3}{l_1 & l_2 & l_3}$$

System III₆.

$$(----) \frac{\frac{1}{l_1}}{\frac{l_1}{l_2}} \frac{l_1}{l_1} \frac{l_2}{l_2} \frac{l_3}{l_1} \frac{l_2}{l_2} \frac{l_3}{l_1} \frac{l_2}{l_2}}{\frac{l_3}{l_1}} \frac{l_2}{l_2} \frac{l_3}{l_1} \frac{l_2}{l_2} \frac{l_3}{l_2} \frac{l_3}{l_1} \frac{l_2}{l_2} \frac{l_3}{l_2} \frac{l_3}{l_1} \frac{l_2}{l_2} \frac{l_3}{l_2} \frac{l_3}{l_1} \frac{l_2}{l_2} \frac{l_3}{l_2} \frac{l_3}{l_1} \frac{l_2}{l_2} \frac{l_3}{l_2} \frac{l_3$$

				K	C Qu	adruple.
Syste	em	IV	1•			
	1	l_1	l_2	l_3	l_4	
	$\overline{l_1}$	l_2	l_1	l_4	$\overline{l_3}$	
(+++++)	l_2	l_1	l_1	l_1	l_1	(+++
	l_3	l_4	l_1	l_4	l_1	
	l_4	l_3	l_1	l_1	l_3	
Syste	em	IV	3.			
	1	l_1	l_2	l_3	l_4	
	$\overline{l_1}$	l_1	l_1	l_1	$\overline{l_1}$	
(+++-+)	l_2	l_1	l_2	l_1	l_1	(++-
	l_3	l_1	l_1	l_3	l_1	
	l_4	l_1	l_1	l_1	l_4	
Syste	em	IV	5.			
	1	l_1	l_2	l_3	l_4	
	$\overline{l_1}$	\overline{x}	x	x	x	
(+-+++)	l_2	\mathbf{x}	\boldsymbol{x}	x	x	(+++
	l_3	x	x	\boldsymbol{x}	\boldsymbol{x}	
	l_4	x	x	x	x	
\mathbf{Syst}	em	IV	7.			
	1	$ l_1 $	l_2	l_3	l_4	
	$\overline{l_1}$	l_2	l_2	l_1	l_1	
(++-+-)	$\overline{l_2}$	l_1	$\bar{l_1}$	l_1	l_1	(+-+
•••••	l_3	l_1	l_1	l_1	l_1	·
	l_4	l_1	l_1	l_1	l_1	
\mathbf{Syst}	\mathbf{em}	ı IV	· 9.			
	1	$ l_1 $	l_2	l_3	l_4	
	$\overline{l_{i}}$	1	la	h		
(+++)	し	L	1	h	h	(++
XII I)	l	li	h	h	h	<u> </u>
	l_4	l_1	l_1	l_1	l_1	

System IV₂. $\frac{1}{l_1} \frac{l_1}{l_1} \frac{l_2}{l_1} \frac{l_3}{l_1} \frac{l_4}{l_1}$ $(-+-) l_2 l_2 l_2 l_2 l_2 l_2$ System IV₄. $-++) \frac{1}{l_1} \begin{vmatrix} l_1 & l_2 & l_3 & l_4 \\ \hline l_1 & l_1 & l_1 & l_1 \\ \hline l_2 & l_1 & l_1 & l_1 & l_1 \\ \hline l_3 & l_1 & l_1 & l_1 & l_1 \end{vmatrix}$ 14 h h h h System IV₆. $\frac{1}{l_1} \begin{vmatrix} l_1 & l_2 & l_3 & l_4 \\ \hline l_1 & l_2 & l_3 & l_4 \end{vmatrix}$ $(---) l_2 l_1 l_2 l_3 l_4$ System IV₈. $l_4 x$ \boldsymbol{x} xx

System IV₁₀.

$$(+-+-+) \begin{array}{c|c} \frac{1}{l_1} & \frac{l_1}{l_1} & \frac{l_2}{l_1} & \frac{l_3}{l_4} \\ \hline l_1 & \frac{l_2}{l_2} & x & x \\ \frac{l_3}{x} & x & x & x \\ \frac{l_3}{x} & x & x & x \\ \hline l_4 & x & x & x & x \end{array}$$

1920.7

System IV ₁₁ .						System IV_{12} .						
	1	l_1	l_2	l_3	l_4		1	$ l_1 $	l_2	l_3	l_4	
	$\overline{l_1}$	l_1	x	x	x		$\overline{l_1}$	l_2	l_1	l_1	l_1	
(+++)	l_2	\boldsymbol{x}	l_1	\boldsymbol{x}	x	(++)	l_2	l_1	l_3	l_1	l_1	
	l_3	\boldsymbol{x}	x	x	\boldsymbol{x}		l_3	l_3	l_3	l_3	l_3	
	l_4	x	x	x	x		l_4	l_4	l_4	l_4	l_4	

\mathbf{Syst}	em IV	7 ₁₃ .		System IV_{14} .					
	$1 \mid l_1$	l_2	l_3	l_4		$1 \mid l_1$	l_2	l_3	
	$\overline{l_1}$ $\overline{l_1}$	l_2	x	x		l_1 l_1	l_2	l_3	
(+-+)	$l_2 \mid l_1$	l_2	x	\boldsymbol{x}	(++-)	$l_2 \mid l_1$	l_1	l_1	
	$l_3 \mid x$	x	x	\boldsymbol{x}		$l_3 \mid l_2$	l_1	l_2	
	$l_4 \mid x$	x	x	x		$l_4 \mid x$	x	x	
\mathbf{Syst}	em IV	7 ₁₅ .			\mathbf{Sys}	tem I	V16.		
	$1 l_1$	l_2	l_3	l_4		$1 \mid l_1$	l_2	l_3	

It may be of interest to note that a similar change in the first postulate of Bernstein's* set of four postulates in terms of the operator "rejection" also makes that set completely independent, as I have shown in an earlier paper, † and that furthermore this same change makes my own set of five postulates in terms of "exception"[‡] completely independent (together with a change in the fifth postulate at a sacrifice of simplicity). It would be interesting to ascertain whether this postulation of a minimum of four distinct elements is sufficient to being about the complete independence of any

 l_4 \boldsymbol{x} \boldsymbol{x} x x

l4

^{*}B. A. Bernstein, "A set of four independent postulates for Boolean algebras," Transactions Amer. Math. Society, vol. 17 (1916), pp. 50-52. † J. S. Taylor, "Complete existential theory of Bernstein's set of four postulates for Boolean algebras," Annals of Mathematics, second series, vol. 19, no. 1 (Sept., 1917), pp. 64-69. ‡ J. S. Taylor, "A set of five postulates for Boolean algebras in terms of the operation 'exception," University of California Publications in Mathe-matics, vol. 1 (April 12, 1920), pp. 241-248.

454 ROTATION SURFACES OF CONSTANT CURVATURE. [July,

set of postulates for Boolean algebras where the remaining postulates of the set are already free from all implicational relationships among themselves.

MASSACHUSETTS INSTITUTE OF TECHNOLOGY.

ROTATION SURFACES OF CONSTANT CURVATURE IN SPACE OF FOUR DIMENSIONS.

BY PROFESSOR C. L. E. MOORE.

(Read before the American Mathematical Society April 24, 1920.)

1. In space of four dimensions there are two special rotations each of which has circles for path curves. In this note I shall discuss the surfaces generated by these special rotations which have constant curvature. The first type is given by the equations

(1)
$$X = x \cos t - y \sin t, \quad Y = x \sin t + y \cos t, \\ Z = z, \quad W = w.$$

This rotation leaves each point of the zw-plane invariant and any plane completely perpendicular to it is left invariant as a plane but not point for point. The rotation then is simply isomorphic with a rotation in the xy-plane.*

If the curve

(c)
$$x = x(s), y = y(s), z = z(s), w = w(s),$$

where s denotes arc length measured from a fixed point, is rotated, equations (1) are the parametric equations of the surface generated. The parameter curves s = const., t = const.will be orthogonal if

(2)
$$xy' - x'y = 0$$
 or $y = kx$,

where primes denote derivatives with respect to s. Hence the meridian curves (orthogonal trajectories of the path curves) on a surface generated by rotation (1), lie in a 3-space which contains the absolutely invariant plane. If the meridian curve

^{*} Phillips and Moore, "Rotations in space of even dimensions," Proceedings Amer. Academy, vol. 55.