## NOTE ON THE PROJECTIVE GEOMETRY OF PATHS

BY T. Y. THOMAS*

1. Projective Geometry of Paths. It was first shown by Weyl $\dagger$ that the functions $\Gamma_{\alpha \beta}^{i}$ and the functions

$$
\begin{equation*}
\boldsymbol{A}_{\alpha \beta}^{i}=\Gamma_{\alpha \beta}^{i}+\delta_{\alpha}^{i} \psi_{\beta}+\delta_{\beta}^{i} \psi_{\alpha} \tag{1}
\end{equation*}
$$

where $\psi_{\alpha}$ is an arbitrary covariant vector, and

$$
\boldsymbol{\delta}_{\alpha}^{i}=0, \quad \text { for } i \neq \alpha ; \quad=1, \quad \text { for } i=\alpha
$$

define the same geometry of paths. This leads to the consideration of properties of the paths which are independent of the particular set of functions $\Gamma_{\alpha \beta}^{i}$ by means of which the paths are defined. Theorems expressing such properties constitute the projective geometry of paths. In the following note we give a few theorems belonging to the projective geometry of paths.
2. Projective Tensors. Theorems of the projective geometry of paths appear to have their statement in terms of what may be called projective tensors, i. e. tensors which are independent of the particular set of functions $\Gamma_{\alpha \beta}^{i}$ defining the paths. We shall show how a set of projective tensors may be derived by covariant differentiation from an $n$-uple of mutually independent vectors.

Let $h_{(\alpha) i}$ denote an $n$-uple of independent covariant vectors. Then the determinant

$$
\begin{equation*}
h=\left|h_{(\alpha) i}\right| \tag{2}
\end{equation*}
$$

does not vanish identically. We may therefore define an $n$-uple of contravariant vectors $h^{(\alpha) i}$ as the cofactors of the

[^0]corresponding $h_{(\alpha) i}$ in the determinant $h$ divided by $h$. Hence
\[

$$
\begin{equation*}
h_{(\alpha) i} l_{l}^{(\alpha) j}=\delta_{i}^{j} \tag{3}
\end{equation*}
$$

\]

and

$$
\begin{equation*}
h_{(i) \alpha} h_{i}^{(j) \alpha}=\delta_{i}^{j} \tag{4}
\end{equation*}
$$

where the left members represent a summation in $\alpha$ from $a=1$ to $a=n$. It will be understood in the following that each index which appears twice in a term, once as a subscript and once as a superscript, is to be summed over the values 1 to $n$.

The change $\left[h_{(\alpha) i, j}\right]$ in the covariant derivative $h_{(\alpha) i, j}$ of the $n$-uple $h_{(\alpha) i}$, based on the functions $I_{\alpha \beta}^{i}$, when the $\Gamma$ 's are replaced by the above functions $\Lambda$, is

$$
\begin{equation*}
\left[h_{(\kappa) i, j}\right]=-h_{(\alpha) i} \psi_{j}^{\prime}-h_{(\omega) j} \psi_{i} . \tag{5}
\end{equation*}
$$

Hence

$$
\begin{equation*}
(n+1) \psi_{i}=-h^{(\alpha) \beta}\left[h_{(c) \beta, i}\right] \tag{6}
\end{equation*}
$$

The vector $\gamma_{i}$ defined by

$$
\begin{equation*}
(n+1) \gamma_{i}=-h^{(\alpha) \beta} h_{(\alpha) \beta, i} \tag{7}
\end{equation*}
$$

will therefore change by $\psi_{i}^{\prime}$ when $\Gamma_{\alpha \beta}^{i}$ is replaced by $\boldsymbol{\Lambda}_{\alpha \beta}^{i}$, i.e.

$$
\begin{equation*}
\left[\gamma_{i}\right]=\psi^{\prime} i \tag{8}
\end{equation*}
$$

Hence

$$
\begin{equation*}
h_{(\alpha) i j}=h_{(\alpha i, i, j}+h_{(\alpha) i} \gamma_{j}+h_{(\alpha) j} \gamma_{i} \tag{9}
\end{equation*}
$$

represents a set of $n$ projective covariant tensors of the second order.

In a similar way we may treat the case of an $n$-uple of independent contravariant vectors $h^{(\alpha) i}$. This leads to a set of $n$ projective mixed tensors of the second order given by

$$
\begin{equation*}
h_{j}^{(\alpha) i}=h_{, j}^{(\alpha) i}-h^{(\alpha) i} \lambda_{j}-\delta_{j}^{i} h^{(\alpha) \beta} \lambda_{\beta} \tag{10}
\end{equation*}
$$

where the vector $\lambda_{i}$ is defined as

$$
\begin{equation*}
(n+1) \lambda_{i}=h_{(\alpha) \beta^{\beta^{(\alpha) \beta}}, i} \tag{11}
\end{equation*}
$$

in which the covariant $n$-uple $h_{(\alpha) i}$ is obtained from the
contravariant $n$-uple $h^{(\alpha) i}$ by dividing the cofactors of the elements of the determinant

$$
h=\left|h^{(\alpha) i}\right|
$$

by the determinant $h$. Other projective tensors will appear in the following paragraphs.
3. The $n$-uple of Parallel Vectors.* If $h_{(\alpha) i}$ represents an $n$-uple of independent parallel covariant vectors for some set of functions $\Gamma_{\alpha \beta}^{i}$ defining the paths, then

$$
\begin{equation*}
h_{(\alpha x) j}=0 \tag{12}
\end{equation*}
$$

identically. The condition (12) is also sufficient for the $n$-uple of independent covariant vectors $h_{(\alpha) i}$ to be parallel. Hence we have the following theorem.

Theorem I. A necessary and sufficient condition for the $n$-uple of independent covariant vectors $h_{(\alpha) i}$ to be parallel in the projective geometry of paths is that (12) be satisfied.

Forming the equations

$$
\begin{equation*}
h_{j}^{(\alpha) i}=0, \tag{13}
\end{equation*}
$$

we may state the corresponding theorem for the case of a contravariant $n$-uple.
Theorem II. A necessary and sufficient condition for the $n$-uple of independent contravariant vectors $h^{(\omega) i}$ to be parallel in the projective geometry of paths is that (13) be satisfied.
4. Reduction to the Euclidean Gcometry. The affine geometry of paths becomes a euclidean geometry if there exists an $n$-uple of independent parallel covariant vectors $h_{(\alpha) i}$. This is obviously a necessary condition and it is seen to be sufficient since the existence of an $n$-uple of parallel vectors $h_{(\alpha) i}$ leads to the equations

$$
\begin{equation*}
h_{(i) \sigma} B_{\alpha \beta \gamma}^{\sigma}=0, \tag{14}
\end{equation*}
$$

where $B_{\alpha, \beta \gamma}^{\sigma}$ is the affine (ordinary) curvature tensor, and hence

[^1]\[

$$
\begin{equation*}
B_{\alpha \beta \gamma}^{i}=0 \tag{15}
\end{equation*}
$$

\]

owing to the independence of the vectors $h_{(\alpha) i}$. Hence we have the following theorem.

Theorem III. A necessary and sufficient condition for the projective geometry of paths to be a euclidean geometry is that the I's be such that there exists an n-uple of independent covariant vectors $h_{(\alpha) i}$ satisfying (12).

A similar theorem may be stated for the $n$-uple of contravariant vectors.
5. Reduction to the Riemann Geometry. For the projective geometry of paths to be a Riemann geometry it is necessary and sufficient that the $\Gamma$ 's be such that there exists a symmetric tensor $g_{\alpha \beta}$ whose determinant

$$
\begin{equation*}
g=\left|g_{\alpha \beta}\right| \tag{16}
\end{equation*}
$$

does not vanish identically, and a vector $\psi_{i}$ such that

$$
\begin{equation*}
\tilde{g}_{\alpha \beta, \gamma}=0 \tag{17}
\end{equation*}
$$

where $\tilde{g}_{\alpha \beta, \gamma}$ is the covariant derivative of $g_{\alpha \beta}$ based on the functions $A_{\alpha \beta}^{i}$ given by (1). Writing (17) in the form

$$
\begin{equation*}
g_{\alpha \beta, \gamma}-2 g_{\alpha \beta} \psi_{\gamma}-g_{\gamma \beta} \psi_{\alpha}-g_{\alpha \gamma} \psi_{\beta}=0 \tag{18}
\end{equation*}
$$

where $g_{\alpha \beta, \gamma}$ is the covariant derivative of $g_{\alpha \beta}$ based on the functions $\Gamma_{\alpha \beta}^{i}$, and multiplying by the contravariant tensor $g^{\alpha \beta}$, formed in the ordinary manner from the tensor $g_{\alpha \beta}$, we have

$$
\begin{equation*}
2(n+1) \psi_{\gamma}=g^{\alpha \beta} g_{\alpha \beta, \gamma} \tag{19}
\end{equation*}
$$

Substituting this value of $\psi_{\gamma}$ in the left member of (18) and denoting the resulting expression by $g_{\alpha \beta \gamma}$, we find
(20) $g_{\alpha \beta \gamma}=g_{\alpha \beta, \gamma}-\frac{g^{\mu \nu}}{n+1}\left(g_{\alpha \beta} g_{\mu \nu, \gamma}+\frac{1}{2} g_{\gamma \beta} g_{\mu \nu, \alpha}+\frac{1}{2} g_{\alpha \gamma} g_{\mu \nu, \beta}\right)$.

Hence (18) takes the form

$$
\begin{equation*}
g_{\alpha \beta \gamma}=0 \tag{21}
\end{equation*}
$$

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The tensor $g_{\alpha \beta \gamma}$ defined by (20) may be shown to be projective.

The equations (21) constitute a necessary condition for the projective geometry of paths to be a Riemann geometry based on the tensor $g_{\alpha \beta \beta}$ as the fundamental metric tensor. This condition is easily shown to be sufficient. Hence we have the following theorem.
Theorem IV. A necessary and sufficient condition for the projective geometry of paths to be a Riemann geometry is that the $\Gamma$ 's be such that there exists a tensor $g_{\alpha \beta}$ which satisfies the equations (21).
6. Reduction to the Weyl Geometry.* Let us denote by $g_{\kappa \beta}$ a covariant symmetric tensor whose determinant $g$ does not vanish identically, as in the preceding paragraph, and also by $\varphi_{c}$ a covariant vector. Let us then form the equations

$$
\begin{equation*}
g_{\alpha \beta \gamma}=g_{\alpha \beta} \varphi_{\gamma}, \tag{22}
\end{equation*}
$$

where $g_{\alpha \beta \gamma}$ is now defined by

$$
\begin{gather*}
g_{\alpha \beta \gamma}=g_{\alpha \beta, \gamma}-\frac{g^{\mu \nu}}{n+1}\left(g_{\alpha \beta} g_{\mu \nu, \gamma}+\frac{1}{2} g_{\gamma \beta} g_{\mu \nu, \alpha}+\frac{1}{2} g_{\alpha \gamma} g_{\mu \nu, \beta}\right) \\
+\frac{n}{n+1}\left(g_{\alpha \beta} \varphi_{\gamma}+\frac{1}{2} g_{\gamma \beta} \varphi_{\alpha}+\frac{1}{2} g_{\alpha \gamma} \varphi_{\beta}\right), \tag{23}
\end{gather*}
$$

in which $g_{\alpha \beta, \gamma}$ is the covariant derivative of $y_{\alpha \beta}$ based on the functions $\Gamma_{\alpha \beta}^{i}$. The tensor $g_{\alpha \beta \gamma}$ defined by (23) is a projective tensor. We may prove the following theorem.

Theorem V. A necessary and sufficient condition for the projective geometry of paths to be a Weyl geometry is that the $\Gamma$ 's be such that there exists a tensor $g_{\alpha \beta}$ and vector $\varphi_{c}$ which satisfy the equations (22).

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[^0]:    * National Research Fellow in Mathematical Physics.
    $\dagger$ H. Weyl, Göttinger Nachrichten, 1921, p. 99. See also O. Veblen, Proceedings of the National Academy, vol. 8 (1922), p. 347; and O. Veblen and T. Y. Thomas, Transactions of this Society, vol. 25, p. 557.

[^1]:    * L. P. Eisenhart, Proceedings of the National Academy, vol. 8 (1922), p. 207. See also O. Veblen and T. Y. Thomas, loc. cit., p. 589.

[^2]:    * By the Weyl geometry is meant the geometry used by Weyl as the basis of his combined theory of gravitation and electricity. See H. Weyl, Raum, Zeit, Materie, 4th ed., p. 113.

