## APPROXIMATE SOLUTIONS OF A SYSTEM OF DIFFERENTIAL EQUATIONS OF MATHEMATICAL PHYSICS BY LEAST SQUARES*

BY N. KRYLOFF

1. Systems of First Order. In many problems of mathematical physics and particularly in electrical circuit theory, it is of importance to find approximate solutions of a system of differential equations of the form

$$
\begin{equation*}
\frac{d x_{i}}{d t}=f_{i}\left(t, x_{1}, x_{2}, \cdots, x_{p}\right), \quad(i=1,2, \cdots, p) \tag{1}
\end{equation*}
$$

Sometimes it may be shown by physical considerations that a system of type (1) which corresponds to some definite experimental fact, really possesses a periodic solution with a period equal to $T$. By a suitable change of variables, we may suppose that
(2) $\quad x_{i}=0, \quad(i=1, \cdots, p) \quad$ for $\quad t=0, \quad t=T$;
and it then remains only to find the numerical solution of (1) and (2) with a given degree of approximation. We shall suppose first that the system (1) is linear with variable coefficients, that is to say, that
(3) $\frac{d x_{i}}{d t}-A_{i 1} x_{1}-A_{i 2} x_{2}-\cdots-A_{i p} x_{p}=F_{i},(i=1,2, \cdots, p)$,
where $A_{i 1}, A_{i 2}, \cdots, A_{i \mu}, F_{i}$ are functions of $t$. As in the method of least squares, we shall try to render stationary the integral

$$
\begin{array}{r}
\int_{0}^{T} \sum_{i=1}^{p}\left[\frac{d x_{i}}{d t}-\sum_{k=1}^{p} A_{i k} x_{k}-F_{i}\right]^{2} d t  \tag{4}\\
=\int_{0}^{T} \sum_{i=1}^{p}\left[L_{i}\left(x_{i}\right)-F_{i}\right]^{2} d t
\end{array}
$$

[^0]by the means of a sequence of the type
\[

$$
\begin{equation*}
x_{i}^{(n)}=\sum_{k=1}^{n} a_{i k}^{(n)} \varphi_{k}(t) \tag{5}
\end{equation*}
$$

\]

where the functions $\varphi_{k}(t)$ satisfy* the boundary conditions (2). For what follows, we must suppose also that the results of the modern theory of summation (for example, that of $L$. Féjer, or that of D. Jackson) are applicable to the system $\left[\varphi_{k}(t)\right]$. If this be true, it is possible to indicate the degree of approximation not only of

$$
\begin{equation*}
\left|x_{i}-X_{i}^{(n)}\right| \tag{6}
\end{equation*}
$$

but also of

$$
\begin{equation*}
\left|\frac{d x_{i}}{d t}-\frac{d X_{i}^{(n)}}{d t}\right| \tag{7}
\end{equation*}
$$

where $X_{i}^{(n)}=\sum_{k=1}^{n} b_{i k}^{(n)} \varphi_{k}(t)$ is a partial sum of order $n$ formed by means of Féjer's or Jackson's process, if $A_{i k}, F_{i}$ are to be supposed to satisfy the well known Lipschitz condition.

If we suppose that the coefficients $A_{i k}, F_{i}$ can be differentiated, the degrees of approximation of (6) and (7) are given by the recent investigations in the domain of the theory of functions of a real variable. $\dagger$ If we substitute (5) in (4) instead of $x_{i}$, and differentiate with respect to $a_{i k}$, it is easy to see that the conditions for a minimum take the form

$$
\begin{align*}
& \int_{0}^{T}\left\{\left[L_{i}\left(x_{i}^{(n)}\right)-F_{i}\right]\left[\frac{d \varphi_{k}}{d t}-A_{i i} \varphi_{k}\right]\right.  \tag{8}\\
& \left.\quad+\sum_{r=1}^{r=p}(i)\left[L_{r}\left(x_{i}^{(n)}\right)-F_{r}\right] A_{r i} \varphi_{k}\right\} d t=0
\end{align*}
$$

[^1]Multiplying the equations (8) respectively by $a_{i k}^{(n)}-b_{i k}^{(n)}$, adding them together, and assuming that the determinant of $A_{i k}$ is symmetric, we obtain

$$
\int_{0}^{T} \sum_{i=1}^{p}\left[L_{i}\left(x_{i}^{(n)}\right)-F_{i}\right]\left[L_{i}\left(x_{i}^{(n)}-X_{i}^{(n)}\right)\right] d t=0
$$

Evidently we have also

$$
\int_{0}^{T} \sum_{i=1}^{p}\left[L_{i}\left(x_{i}\right)-F_{i}\right]\left[L_{i}\left(x_{i}^{(n)}-X_{i}^{(n)}\right)\right] d t=0
$$

because $x_{i}$ are the solutions of (2); therefore

$$
\int_{0}^{T} \sum_{i=1}^{p} L_{i}\left(x_{i}-x_{i}^{(n)}\right) L_{i}\left(x_{i}^{(n)}-X_{i}^{(n)}\right) d t=0
$$

But we have

$$
x_{i}^{(n)}-X_{i}^{(n)}=x_{i}^{(n)}-x_{i}+x_{i}-X_{i}^{(n)} ;
$$

hence

$$
\begin{align*}
& \int_{0}^{T} \sum_{i=1}^{p}\left[L_{i}\left(x_{i}-x_{i}^{(n)}\right)\right]^{2} d t  \tag{9}\\
& \quad=\int_{0}^{T}\left\{\sum_{i=1}^{p} L_{i}\left(x_{i}-x_{i}^{(n)}\right) L_{i}\left(x_{i}-X_{i}^{(n)}\right)\right\} d t
\end{align*}
$$

If we utilise now the well known Bouniakowsky-Schwartz inequality, we find, from (9),

$$
\begin{aligned}
\int_{0}^{T} \sum_{i=1}^{p}\left[L_{i}\left(x_{i}-x_{i}^{(n)}\right)\right]^{2} d t & \leqq \sum_{i=1}^{p} \sqrt{\int_{0}^{T}\left[L_{i}\left(x_{i}-x_{i}^{(n)}\right)\right]^{2}} d t \\
& \times \sqrt{\int_{0}^{T}\left[L_{i}\left(x_{i}-X_{i}^{(n)}\right)\right]^{2} d t}
\end{aligned}
$$

Remembering what was said above about the approximation of $x_{i}$ and $d x_{i} / d t$, respectively, by $X_{i}^{(n)}$ and $d X_{i}^{(n)} / d t$, we obtain from (9)

$$
\begin{equation*}
\int_{0}^{T}\left[L_{i}\left(x_{i}-x_{i}^{(n)}\right)\right]^{2} d t<\epsilon_{i n}, \quad(i=1,2, \cdots, p) \tag{10}
\end{equation*}
$$

where the order of magnitude of $\epsilon_{i n}$ can be determined according to the restrictive conditions imposed on $A_{i k}$ and $F_{i}$. From (10), by the means of the same Schwartz inequality, we find immediately

$$
\left|\int_{0}^{x} L_{i}\left(x_{i}-x_{i}^{(n)}\right) d t\right|<\eta_{i n}, \quad(i=1,2, \cdots, p)
$$

where

$$
\eta_{i n}<\sqrt{\epsilon_{i n}} .
$$

Using the boundary conditions for $\varphi_{k}(t)$, we get the system of inequalities

$$
\left|x_{i}-x_{i}^{(n)}+\int_{0}^{x} A_{i k}\left(x_{k}-x_{k}^{(n)}\right) d t\right|<\eta_{i n} .
$$

The formulas for solving the system of integral equations of the second kind of the Volterra type enable us to state that

$$
\left|x_{i}-x_{i}^{(n)}\right|<A \epsilon_{i n}, \quad(i=1,2,3, \cdots, p)
$$

where the order of magnitude of $\boldsymbol{\epsilon}_{i n}$ can be indicated and $A$ is a constant. Thus the following theorem is demonstrated.

Theorem. If the coefficients $A_{i k}, F_{i}(i, k=1,2, \cdots, p)$ of the system (3) satisfy the Lipschitz conditions, and if the determinant formed from the $A_{i c}$ is symmetric then the effective calculation of the solutions of the system (3) can be derived from the method based upon the minimizing of the integral (4). Such a method, which may be called the method of least squares, gives not only a convergent process, but also the possibility of calculating the solutions of (2) with a given degree of approximation.
2. Systems of Second Order. If instead of the system (3) we have to integrate the system of the differential equations of the second order

$$
\begin{align*}
\frac{d^{2} x_{i}}{d t^{2}} & -A_{i 1} x_{1}-A_{i 2} x_{2}-\cdots-A_{i p} x_{p}  \tag{11}\\
& =L_{i}\left(x_{1} x_{2}, \cdots, x_{p}\right)=F_{i},(i=1,2,3, \cdots, p)
\end{align*}
$$

with the boundary conditions $x_{i}(a)=x_{i}(b)=0$, then applying reasoning similar to that used before,* we can state that

$$
\begin{equation*}
\int_{a}^{b}\left[L_{i}\left(x_{i}-x_{i}^{(n)}\right)\right]^{2} d t<\epsilon_{i n}, \quad(i=1,2, \cdots, p) \tag{12}
\end{equation*}
$$

where the order of smallness of $\epsilon_{i n}$ can be fixed in advance corresponding to the supplementary restrictive conditions imposed on the coefficients $A_{i k}, F_{i}$. Then, if the determinant $A_{i k}$ is symmetric we can start from the obvious identity.

$$
\begin{aligned}
& \int_{a}^{b}\left\{\sum_{i=1}^{p}\left[\frac{d\left(x_{i}-x_{i}^{(m)}\right)}{d t}\right]^{2}+\left[A_{11}\left(x_{1}-x_{1}^{(m)}\right)^{2}\right.\right. \\
& \left.\left.+2 A_{12}\left(x_{1}-x_{1}^{(m)}\right)\left(x_{2}-x_{2}^{(m)}\right)+\cdots\right]\right\} d t \\
& =-\int_{a}^{b} \sum_{i=1}^{p} L_{i}\left(x_{1}-x_{1}^{(m)}, \cdots, x_{p}-x_{p}^{(m)}\right)\left(x_{i}-x_{i}^{(m)}\right) d t .
\end{aligned}
$$

If the quadratic form

$$
A_{11}\left(x_{1}-x_{1}^{(m)}\right)^{2}+2 A_{12}\left(x_{1}-x_{1}^{(m)}\right)\left(x_{2}-{ }_{x_{2}}^{(m)}\right)+\cdots
$$

is definitely positive, we easily obtain, by the use of the Bouniakowsky-Schwartz inequality,

$$
\left|x_{i}-x_{i}^{(m)}\right|<\eta_{m}, \quad(i=1,2,3, \cdots, p)
$$

where the order of magnitude of $\eta_{m}$ can be fixed in advance according to the order of $\boldsymbol{\epsilon}_{i n}$.

In further communications, I shall state other applications of the method of least squares (and more generally of the method of least powers) which presents, it seems to me, a very powerful method for the approximate integration of differential equations of mathematical physics.

The University of Kieff

[^2]
[^0]:    * Presented to the Society, December 29, 1925.

[^1]:    * We may take, for example, $\varphi_{k}(t)=\sin k t$.
    $\dagger$ See, e.g., de la Vallée Poussin, Legons sur l'Approximation des Fonctions d'une Variable Reélle, Paris, Gauthier-Villars, 1919.

[^2]:    * In the case of one equation of the second order it was first stated in my recent communication to the French Academy. See N. Kryloff, Sur une méthode, basée sur le principe du minimum pour l'intégration approchée des équations différentielles, Comptes Rendus, vol. 181 (1925).

