

## ASSOCIATED ALGEBRAIC AND PARTIAL DIFFERENTIAL EQUATIONS

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1. *Introduction.* Between an algebraic equation and an ordinary linear homogeneous differential equation with constant coefficients, in a single unknown, there is a familiar and useful association, illustrated by the equations

$$x^2 + 3x - 4 = 0, \quad u'' + 3u' - 4u = 0.$$

Riquier\* has shown that a similar association exists between finite systems consisting of  $m$  algebraic equations in  $n$  unknowns and  $m$  linear homogeneous partial differential equations in a single unknown and  $n$  independent variables as follows. Let

$$(1) \quad \sum_0^p a_{i_1 \dots i_n}^\alpha (i_1 \dots i_n) = 0, \quad (\alpha = 1, \dots, m),$$

be any system of algebraic equations, where the  $a$ 's are constants and  $(i_1 \dots i_n)$  is to be interpreted as the monomial  $x_1^{i_1} \dots x_n^{i_n}$ . Let the associated system of partial differential equations be

$$(2) \quad \sum_0^p a_{i_1 \dots i_n}^\alpha (i_1 \dots i_n) u = 0, \quad (\alpha = 1, \dots, m),$$

where  $(i_1 \dots i_n)$  is to be interpreted as the differential operator  $\partial^{i_1 + \dots + i_n} / \partial x_1^{i_1} \dots \partial x_n^{i_n}$ .

We shall prove in this paper the two following theorems.

**THEOREM 1.** *System (1) is inconsistent if and only if the general solution of (2) is  $u = 0$ .*

**THEOREM 2.** *The general solution of (2) is a non-zero polynomial if and only if  $x_1 = \dots = x_n = 0$  is the solution of (1).*

2. *Corresponding Operations on the Two Systems.* We shall mul-

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\* *Sur la résolution numérique du système d'équations algébriques entières à un nombre quelconque d'inconnues*, Annales Scientifiques de l'École Normale Supérieure, vol. 63 (1928), pp. 145-188.

multiply the equations by  $(j_1 \cdots j_\nu)$  and then form linear combinations of them with constant coefficients. The interpretation of the  $(j_1 \cdots j_\nu)$  is to be that of the system into which it is multiplied. This gives rise to new associated systems of equations.

3. *System (1) Inconsistent.* Let us assume (1) is inconsistent. Then according to a known theorem\* there exist for system (1)  $C$ 's satisfying the relation

$$(3) \quad 1 \equiv \sum_{\alpha}^{1, \dots, m} C^{\alpha} \left( \sum_0^p a_{i_1 \dots i_n}^{\alpha} (i_1 \cdots i_n) \right),$$

where

$$(4) \quad C^{\alpha} = \sum_0^r k_{i_1 \dots i_n}^{\alpha} (i_1 \cdots i_n).$$

The corresponding result on (2) would of course be obtained by multiplying both sides of the equations (3) on the right by  $u$ . Then (2) implies  $u = 0$  and from the form of (2) it is seen to be an actual solution.

If (1) has a solution  $(\bar{x}_1, \dots, \bar{x}_n)$ , then (2) has the obvious *immediate*† solution  $c \exp(\bar{x}_1 x_1 + \dots + \bar{x}_n x_n)$ , where  $c$  is an arbitrary constant. On the assumption that  $u = 0$  is the general solution of (2), it follows immediately from this that (1) must be inconsistent. Thus Theorem 1 is established.

4. *System (1) Consistent with only the Trivial Solution.* Now consider the case where  $x_1 = \dots = x_n = 0$  is the solution of (1). According to Hilbert's zero theorem there exist  $C$ 's similar to (4) and positive integers  $\rho_j$  such that

$$(5) \quad x_j^{\rho_j} \equiv \sum_{\alpha} C^{\alpha_j} \left( \sum_0^p a_{i_1 \dots i_n}^{\alpha} (i_1 \cdots i_n) \right),$$

( $\alpha = 1, \dots, m; j = 1, \dots, n$ ).

Again, multiplying both sides of (5) on the right by  $u$  and interpreting  $x_j^{\rho_j}$  as in (2), we see that the left member becomes  $\partial^{\rho_j} u / \partial x_j^{\rho_j}$ . System (2) implies that these derivatives vanish

\* B. L. Van der Waerden, *Moderne Algebra*, vol. 1, 1930, p. 10.

† Riquier, loc. cit.

identically. Observe that there must be a non-zero solution of (2) else we have a contradiction with Theorem 1.

Consider any derivative  $(i_1 \cdots i_n)$  whose order equals or exceeds  $\rho_1 + \cdots + \rho_n$ , that is,

$$(i_1 - \rho_1) + \cdots + (i_n - \rho_n) \geq 0.$$

Then  $i_j \geq \rho_j$  for at least one  $j$ . Hence every derivative of the order considered is zero. Since there are but a finite number of derivatives below a given order taken with respect to a finite number of variables, it is clear that the series expansion solution for  $u$  reduces to a non-zero polynomial. If we assume that a non-zero polynomial is the general solution of (2), then (1) cannot have more than the trivial solution. For if it did, (2) would have a non-constant exponential solution. But if (1) has no solution our present hypothesis contradicts Theorem 1. Therefore (1) has the trivial solution and that alone, and Theorem 2 is proved.

We give an example illustrating the second result. Let (1) be

$$x_1^3 + x_2^3 = 0, \quad x_1^3 - x_2^3 = 0,$$

and its associated system of partial differential equations (2) be

$$\frac{\partial^3 u}{\partial x_1^3} + \frac{\partial^3 u}{\partial x_2^3} = 0, \quad \frac{\partial^3 u}{\partial x_1^3} - \frac{\partial^3 u}{\partial x_2^3} = 0.$$

Clearly  $\rho_1 = \rho_2 = 3$ . Thus the series expansion for  $u$  reduces to

$$u = \sum_0^2 a_{i_1 i_2} x_1^{i_1} x_2^{i_2},$$

where the coefficients are arbitrary constants.

An interesting application of the results obtained in this paper is that the conditions given by Riquier\* for the existence of a solution of a system of algebraic equations (1) can now be extended to read: *The system (1) is consistent if and only if there exists a non-zero solution of (2).* In other words, *if (2) has any non-zero solution, it also has a non-zero immediate solution.*

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\* Riquier, loc. cit.