

GEOMETRIC CONTROL IN THE PRESENCE OF A BLACK BOX

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1. INTRODUCTION

The purpose of this paper is to show how ideas coming from scattering theory (resolvent estimates) lead to results in control theory and to some closely related eigenfunction estimates.

The black box approach in scattering theory developed by Sjöstrand and the second author [37] puts scattering problems with different structures in one framework and allows abstract applications of spectral results known for confined systems. One striking example is a reduction of scattering on finite volume surfaces to one dimensional black box scattering. In this paper we take the opposite point of view: a black box in a confined system is replaced by a scattering problem. That permits having isolated dynamical phenomena (such as only one closed orbit) impossible in confined systems. It also permits using some finer results of scattering theory directly.

We stress that this follows the well-established trend (see Bardos-Lebeau-Rauch [2]) of using propagation of singularities results developed for scattering theory in geometric control theory. We also mention that the term “black box” is commonly used, in a similar context, in applied control theory [39].

Since the proofs are simple and since it is profitable to state the results in an abstract setting which requires a certain amount of preparation, in this section we will present some typical applications.

In geometric control theory for the Schrödinger equation (see Lebeau [29], and also [30], [44] for earlier work and background) we are concerned with the following mixed problem:

$$(1.1) \quad \begin{aligned} (i\partial_t + \Delta)u &= 0 \quad \text{in } \Omega, \\ u|_{[0,T] \times \Omega} &= g \mathbb{1}_{[0,T] \times \Gamma}, \\ u|_{t=0} &= u_0, \end{aligned}$$

where Ω is an open subset of \mathbb{R}^d , $\partial\Omega$ is its boundary and Γ is an open subset of $\partial\Omega$. The question is to determine a (large) class of functions u_0 for which there exists a control g such that $u|_{t=T} = 0$. In a geometric setting in which full geometric control fails, the following result was established by the first author in [5]:

Theorem 1. *Consider $\Theta = \bigcup_{j=1}^N \Theta_j \subset \mathbb{R}^d$, a union of mutually disjoint closed sets with strictly convex smooth boundaries and satisfying the assumptions in subsection*

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6.2 below. Let $\tilde{\Omega}$ be a bounded domain with a smooth boundary and containing $\text{convhull}(\Theta)$. Denote by $\Omega = \tilde{\Omega} \setminus \Theta$ and $\Gamma = \partial\tilde{\Omega}$. Then for any $T, \varepsilon > 0$ and any $u_0 \in H_0^{1+\varepsilon}(\Omega)$ there exists $g \in L^2([0, T] \times \Gamma)$ such that in (1.1) we have $u|_{t>T} \equiv 0$.

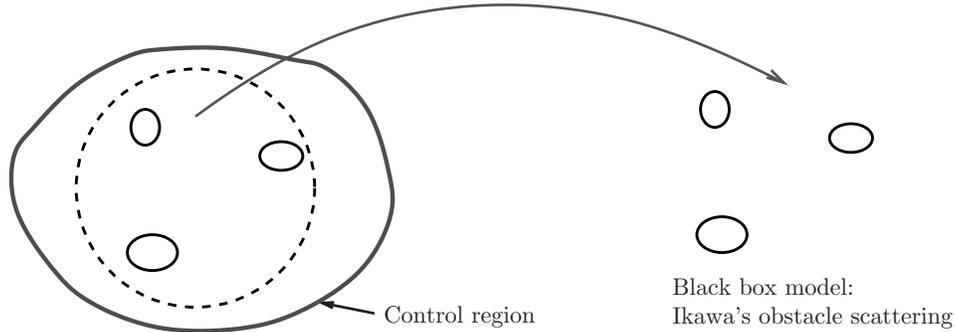


FIGURE 1. Control in the exterior of several convex bodies.

In Figure 1 on the left we have three convex obstacles inside of the boundary of $\tilde{\Omega}$. Inside of the black box bounded by the dotted line the local geometry is the same as in the scattering problem on the right.

We are going to show how Theorem 1 can be obtained directly from estimates on the resolvent of the Laplace operator, which in turn can be deduced from semi-classical microlocal analysis or from known results in scattering theory. In the case quoted above, these come from the work of Ikawa [26] and in particular we can now avoid most of the delicate analysis of [5].

The next application generalizes a result of Colin de Verdière and Parisse [13] who considered a special case of an isolated trajectory lying on a segment of a constant negative curvature cylinder in dimension two:

Theorem 2. *Suppose that (X, g) is a compact Riemannian manifold with a (possibly empty) boundary and $\gamma \subset X$ is a closed real hyperbolic geodesic not intersecting the boundary. If $\chi \in C^\infty(X, [0, 1])$ is supported in a sufficiently small neighbourhood of γ , then there exists a constant $C = C(\gamma)$ such that for any eigenfunction, u , of the Laplacian, Δ_g with Dirichlet or Neumann boundary conditions, we have*

$$(1.2) \quad C \int_X |u(x)|^2 (1 - \chi)(x) d\text{vol}_g \geq \frac{1}{\log \lambda} \int_X |u(x)|^2 d\text{vol}_g, \quad -\Delta_g u = \lambda u.$$

An example [13] of a cylinder segment with Dirichlet boundary conditions shows that the result is optimal. The theorem remains true if we allow broken geodesic flow as long as the reflections are all transversal. To make the exposition self-contained (in particular, the derivation of the needed estimates in the Appendix), we present the result in the simpler case.

The proof of Theorem 2 (see also Theorem 2') is based on putting the closed hyperbolic orbit into a *microlocal black box*, where that orbit becomes the only trapped orbit in a scattering problem. We can then use scattering estimates based on the work of Gérard [17] and Gérard-Sjöstrand [18] to obtain estimates leading to (1.2). When the geodesic does not hit the boundary, we present a self-contained argument where in place of a scattering black box we use a complex absorbing potential.

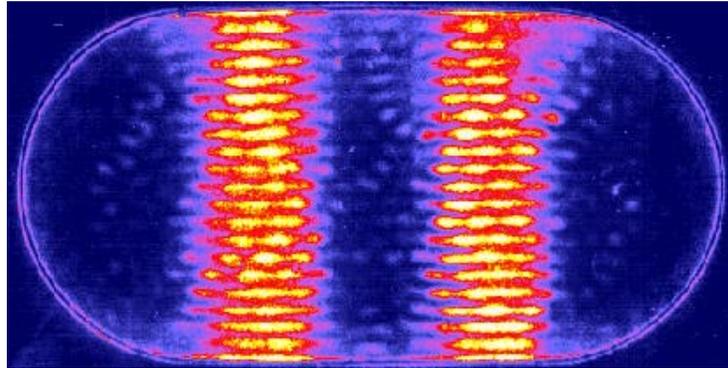


FIGURE 2. An experimental image of the wave in the “black box” in Figure 5; see [11] and <http://www.bath.ac.uk/~pyscmd/acoustics>.

We conclude with a brief discussion of another example related to *eigenvalue scarring* (see Theorem 9 below for a full discussion). While in Theorem 2 we eliminated the need for separation of variables, its use is essential in this case. For the Bunimovich cavity shown in Figure 2 the natural black box for constructing bouncing ball modes (two are shown in the same figure) is a rectangle constituting the central part of the cavity – see the recent discussion of this in [16] and [42]. On one hand, our result shows that the crude error estimate

$$(1.3) \quad (-\Delta_D - \lambda)u_\lambda = \mathcal{O}(1), \quad \|u_\lambda\| = 1,$$

for the quasimodes obtained by truncating the rectangle modes is in fact the best possible and on the other hand that the eigenfunctions *cannot* accumulate at high frequency only in the central part. This agrees with the experimental results [11] where it was stressed that phenomena shown in Figure 2 can occur only at low frequencies (see also [1] for a different discussion and references to the physics literature). For an exact eigenstate we have the following

Theorem 3. *Let u be a Dirichlet eigenfunction of the Laplacian on the Bunimovich stadium M :*

$$-\Delta u = \lambda u, \quad u|_{\partial M} = 0$$

Let $a(x)$ be any continuous function identically 1 on the nonrectangular part of M . Then there exists $C > 0$ such that

$$(1.4) \quad C \int_M |a(x)u(x)|^2 dx \geq \int_M |u(x)|^2 dx.$$

Stronger results (implying (1.4)) are presented in Theorems 3' and 9 in subsection 6.3. A self-contained proof of Theorem 3 and a discussion of related mathematical and physical literature has been presented in [10]. We stress that only the properties of the rectangular part used as a “black box” are needed for this result.

2. PRELIMINARIES

In this section we review some basic aspects of semi-classical microlocal analysis, following [38, Section 3]. Thus, let X be a compact C^∞ manifold. We consider pseudodifferential operators as acting on half-densities, $u(x)|dx|^{\frac{1}{2}} \in C^\infty(X, \Omega_X^{\frac{1}{2}})$,

where we use the informal notation indicating how the half-densities change under changes of variables:

$$u(x)|dx|^{\frac{1}{2}} = v(y)|dy|^{\frac{1}{2}}, \quad y = \kappa(x) \iff v(\kappa(x))|\kappa'(x)|^{\frac{1}{2}} = u(x),$$

Consequently the symbols will also be considered as half-densities; see [24, Section 18.1] for a general introduction and [38, Appendix] for a discussion of the semi-classical case. This way our results are more general and do not depend on the choice of a metric on X . If X is a Riemannian manifold and the operator we consider is its Laplace-Bertrami operator, then the natural Riemannian density is all we need.

By symbols on X we mean the following class:

$$S^{k,m}(T^*X, \Omega_{T^*X}^{\frac{1}{2}}) = \{a \in C^\infty(T^*X \times (0, 1], \Omega_{T^*X}^{\frac{1}{2}}) : |\partial_x^\alpha \partial_\xi^\beta a(x, \xi, h)| \leq C_{\alpha,\beta} h^{-m} \langle \xi \rangle^{k-|\beta|}\},$$

and the class of corresponding pseudodifferential operators, $\Psi_h^{m,k}(X, \Omega_X^{\frac{1}{2}})$, obtained from a local formula in \mathbb{R}^n :

$$(2.1) \quad \text{Op}_h^w(a)u(x) = \frac{1}{(2\pi h)^n} \int \int a\left(\frac{x+y}{2}, \xi, h\right) e^{i(x-y, \xi)/h} u(y) dy d\xi.$$

The principal symbol map,

$$\sigma_h : \Psi_h^{m,k}(X, \Omega_X^{\frac{1}{2}}) \longrightarrow S^{k,m}/S^{k-1,m-1}(T^*X, \Omega_{T^*X}^{\frac{1}{2}}),$$

gives the left inverse of Op_h^w in the sense that $\sigma_h \circ \text{Op}_h^w : S^{m,k} \rightarrow S^{m,k}/S^{m-1,k-1}$ is the natural projection. We refer to [15] for a detailed discussion of the Weyl quantization and to [41] for a discussion in the case of manifolds.

When acting on half-densities, the principal symbol is in fact well defined in $S^{k,m}/S^{k-2,m-2}$, that is, up to $\mathcal{O}(h^2)$ as far as the order in h is concerned; see [38, Appendix]. When $P(h)$ is polyhomogeneous, that is, $P(h) = \text{Op}(P(\bullet, h))$, and $P(x, \xi, h) \sim p_0(x, \xi) + hp_1(x, \xi) + \dots$, $p_j \in S^{k-j,m}$, the subprincipal symbol,

$$(2.2) \quad p_1^s(x, \xi) = p_1(x, \xi),$$

is well defined. In general, we will say that the subprincipal symbol of $P(h) \in \Psi_h^{m,k}(X, \Omega_X^{\frac{1}{2}})$ vanishes if the principal symbol of $P(h)$ in $S^{k,m}/S^{k-2,m-2}$ is independent of h .

For $a \in S^{m,k}(T^*X, \Omega_{T^*X}^{\frac{1}{2}})$ we follow [38] in defining

$$\text{ess-sup}_h a \subset T^*X \sqcup S^*X, \quad S^*X \stackrel{\text{def}}{=} (T^*X \setminus 0)/\mathbb{R}_+,$$

where the usual \mathbb{R}_+ action is given by multiplication on the fibers: $(x, \xi) \mapsto (x, t\xi)$, as

$$\begin{aligned} \text{ess-sup}_h a = & \mathcal{C}\{(x, \xi) \in T^*X : \exists \epsilon > 0 \partial_x^\alpha \partial_\xi^\beta a(x', \xi') = \mathcal{O}(h^\infty), d(x, x') + |\xi - \xi'| < \epsilon\} \\ & \cup \mathcal{C}\{(x, \xi) \in T^*X \setminus 0 : \exists \epsilon > 0 \partial_x^\alpha \partial_\xi^\beta a(x', \xi') = \mathcal{O}(h^\infty \langle \xi' \rangle^{-\infty}), \\ & d(x, x') + 1/|\xi'| + |\xi/|\xi| - \xi'/|\xi'|| < \epsilon\}/\mathbb{R}_+. \end{aligned}$$

For $A \in \Psi_h^{m,k}(X, \Omega_X^{\frac{1}{2}})$, put

$$WF_h(A) = \text{ess-sup}_h a, \quad A = \text{Op}_h^w(a),$$

and this definition does not depend on the choice of Op_h^w . For

$$u \in \mathcal{C}^\infty((0, 1]_h, \mathcal{D}'(X, \Omega_X^{\frac{1}{2}})), \quad \exists N_0, \quad h^{N_0}u \text{ is bounded in } \mathcal{D}'(X, \Omega_X^{\frac{1}{2}}),$$

we define the *semi-classical wave front set* as

$$\begin{aligned} WF_h(u) = \mathbb{C}\{(x, \xi) : \exists A \in \Psi_h^{0,0}(X, \Omega_X^{\frac{1}{2}}) \sigma_h(A)(x, \xi) \neq 0, \\ Au \in h^\infty \mathcal{C}^\infty((0, 1]_h, \mathcal{C}^\infty(X, \Omega_X^{\frac{1}{2}}))\}. \end{aligned}$$

When u is not necessarily smooth, we can give a definition analogous to that of $\text{ess-sup}_h a$. In this paper we will work in a pure semi-classical setting and consequently only *compact* subsets of T^*X will be important. Consequently, this definition is sufficient for our purposes.

We also need to review the notion of microlocal equivalence of operators and other objects. Suppose that

$$T : \mathcal{C}^\infty(X, \Omega_X^{\frac{1}{2}}) \rightarrow \mathcal{C}^\infty(X, \Omega_X^{\frac{1}{2}})$$

and that for any semi-norm $\|\bullet\|_1$ on $\mathcal{C}^\infty(X, \Omega_X^{\frac{1}{2}})$ there exists a semi-norm $\|\bullet\|_2$ and M_0 such that

$$\|Tu\|_1 = \mathcal{O}(h^{-M_0})\|u\|_2.$$

This condition makes T *semi-classically tempered*. In the sequel all operators considered will be assumed to satisfy this temperance condition. For open precompact sets, $V \subset T^*X$, $U \subset T^*X$, the operators *defined microlocally* near $V \times U$ are given by equivalence classes of tempered operators given by the relation

$$T \sim T' \iff A(T - T')B = \mathcal{O}(h^\infty) : \mathcal{D}'(X, \Omega_X^{\frac{1}{2}}) \longrightarrow \mathcal{C}^\infty(X, \Omega_X^{\frac{1}{2}}),$$

for any $A, B \in \Psi_h^{0,0}(X, \Omega_X^{\frac{1}{2}})$ such that

$$(2.3) \quad \begin{aligned} WF(A) \subset \tilde{V}, \quad WF(B) \subset \tilde{U}, \\ \bar{V} \Subset \tilde{V} \Subset T^*X, \quad \bar{U} \Subset \tilde{U} \Subset T^*X, \quad \tilde{U}, \tilde{V} \text{ open.} \end{aligned}$$

We say that $P = Q$ *microlocally* near $U \times V$ if $APB - AQB = \mathcal{O}_{L^2 \rightarrow L^2}(h^\infty)$, where because of the assumed precompactness of U and V the L^2 norms can be replaced by any other norms. For operator identities this will be the meaning of equality of operators in this paper, with U, V specified (or clear from the context). Similarly, we say that $B = T^{-1}$ *microlocally* near $V \times V$ if $BT = I$ *microlocally* near $U \times U$ and $TB = I$ *microlocally* near $V \times U$. More generally, we could say that $P = Q$ *microlocally* on $W \subset T^*X \times T^*X$ (or, say, P is *microlocally defined* there) if for any $U, V, U \times V \subset W$, $P = Q$ *microlocally* in $U \times V$. We should stress that “*microlocally*” is always meant in this semi-classical sense in our paper.

Rather than review the definition of h -Fourier integral operators, we will recall a characterization which is essentially a converse of Egorov’s theorem:

Proposition 2.1. *Suppose that $U = \mathcal{O}(1) : L^2(X) \rightarrow L^2(X)$ and that for every $A \in \Psi_h^{0,0}(X)$ we have*

$$AU = UB, \quad B \in \Psi_h^{0,0}(X), \quad \sigma(B) = \kappa^* \sigma(A),$$

*microlocally near (m_0, m_0) where $\kappa : T^*X \rightarrow T^*X$ is a symplectomorphism, defined locally near m_0 , $\kappa(m_0) = m_0$. Then U is, microlocally, near (m_0, m_0) , an h -Fourier integral operator of order zero, quantizing κ , that is associated to the graph of κ .*

For the proof and further details we refer the reader to [38, Lemma 3.4]. We will use the following well-known fact (see [38, Proposition 3.5] for the proof):

Proposition 2.2. *Suppose that $P \in \Psi_h^{0,k}(X)$ has a real principal symbol which satisfies the condition*

$$p = 0 \implies dp \neq 0.$$

For any $m_0 \in p^{-1}(0)$ there exists an h -Fourier integral operator, F ,

$$FP = hD_{x_1}F, \quad \text{microlocally near } ((0,0), m_0),$$

$$F^{-1} \text{ exists microlocally near } (m_0, (0,0)).$$

3. FROM RESOLVENT ESTIMATES TO TIME DEPENDENT CONTROL

In this section we will present a simple abstract argument showing how semi-classical resolvent estimates give a control result for the semi-classical Schrödinger operator. An adaptation of this argument to the classical control setting will be presented in Section 5. That section will also provide a motivation for this type of estimates.

Theorem 4. *Let $P(h)$ be a family of self-adjoint operators on a Hilbert space \mathcal{H} , with a fixed domain \mathcal{D} . Let \mathcal{H}_1 be another Hilbert space, and suppose that for a bounded family of operators, $A(h) : \mathcal{D} \rightarrow \mathcal{H}_1$, we have*

$$(3.1) \quad \|u\|_{\mathcal{H}} \leq \frac{G(h)}{h} \|(P(h) + \tau)u\|_{\mathcal{H}} + g(h) \|A(h)u\|_{\mathcal{H}_1},$$

for all $\tau \in I = (-b, -a) \Subset \mathbb{R}$, $1 \leq G(h) = \mathcal{O}(h^{-N_0})$, for some N_0 . Fix $\chi \in \mathcal{C}_c^\infty((a, b))$. There exist constants c_0, C_0 and $h_0 > 0$ such that for any $T(h)$ satisfying

$$(3.2) \quad \frac{G(h)}{T(h)} < c_0$$

we have for $0 < h < h_0$,

$$(3.3) \quad \|\chi(P(h))u\|_{\mathcal{H}}^2 \leq C_0 \frac{g(h)^2}{T(h)} \int_0^{T(h)} \|A(h)e^{-itP(h)/h}\chi(P(h))u\|_{\mathcal{H}_1}^2 dt.$$

To motivate the abstract presentation, we relate the notation of Theorem 4 to a concrete situation. Thus let $P(h) = -h^2\Delta$ be the Dirichlet Laplacian on a compact manifold Ω , with boundary $\partial\Omega$. Then

$$\mathcal{H} = L^2(\Omega), \quad \mathcal{D} = H^2(\Omega) \cap H_0^1(\Omega).$$

Let $\Gamma \subset \partial\Omega$. We then define

$$\mathcal{H}_1 = L^2(\Gamma), \quad \mathcal{D} \ni u \longmapsto A(h)u = h\partial_\nu u|_\Gamma \in \mathcal{H}_1,$$

where ∂_ν denotes the inward pointing normal to $\partial\Omega$. The estimate (3.3) is a typical *observability estimate* equivalent by duality to an *exact control* statement (see subsection 6.1). An abstract method for obtaining semi-classical estimates (3.1) will be presented in Section 4.

Proof. Let us put $v(t) = \exp(-itP(h)/h)\chi(P(h))u$. We introduce a function $\psi \in \mathcal{C}_c^\infty(\mathbb{R}, [0, 1])$ and put

$$w(t) = \psi\left(\frac{t}{T(h)}\right)v(t).$$

Clearly,

$$(ih\partial_t - P)w(t) = \frac{ih}{T(h)}\psi'\left(\frac{t}{T(h)}\right)v(t).$$

Because of the compact support, we can take the (semi-classical) Fourier transform in t which gives

$$(\tau + P)\widehat{w}(\tau) = -\frac{ih}{T(h)}\mathcal{F}_{t \rightarrow \tau}(\psi'(\bullet/T(h))v)(\tau).$$

For $\tau \in I$ we can use (3.1) which gives

$$\|\widehat{w}(\tau)\|_{\mathcal{H}} \leq \frac{G(h)}{T(h)}\|\mathcal{F}_{t \rightarrow \tau}(\psi'(\bullet/T(h))v)(\tau)\|_{\mathcal{H}} + g(h)\|A(h)\widehat{w}(\tau)\|_{\mathcal{H}_1}.$$

Using the generalized Plancherel theorem, we obtain

$$\int_I \|\widehat{w}(\tau)\|_{\mathcal{H}}^2 d\tau \leq 2\frac{G(h)^2}{T(h)^2}\|\psi'(\bullet/T(h))v\|_{L^2(\mathbb{R}_t, \mathcal{H})}^2 + 2g(h)^2\|A(h)w\|_{L^2(\mathbb{R}_t, \mathcal{H}_1)}^2.$$

We now want to show that we can integrate over \mathbb{R} in place of I in the left-hand side. That follows from

$$(3.4) \quad \|\widehat{w}(\tau)\mathbb{1}_{\mathbb{R} \setminus I}(\tau)\|_{\mathcal{H}} = \mathcal{O}\left(\left(\frac{h}{1+|\tau|}\right)^\infty\right)\|\chi(P)u\|_{\mathcal{H}},$$

which in turn follows from integration by parts in

$$\begin{aligned} \widehat{w}(\tau) &= \int_{\mathbb{R}} e^{-it(P+\tau)/h} \psi\left(\frac{t}{T}\right) \chi(P)u dt \\ &= \int_{\mathbb{R}} (-(P+\tau)^{-1} h D_t e^{-it(P+\tau)/h}) \psi\left(\frac{t}{T}\right) \chi(P)u dt, \end{aligned}$$

using

$$\forall \tau \in \mathbb{R} \setminus I \quad \|(P+\tau)\chi(P)u\|_{\mathcal{H}} \geq \frac{1}{C}\|\chi(P)u\|_{\mathcal{H}}.$$

Thus we obtained

$$\begin{aligned} \|w\|_{L^2(\mathbb{R}_t, \mathcal{H})}^2 &\leq 2\frac{G(h)^2}{T(h)^2}\|\psi'(\bullet/T(h))v\|_{L^2(\mathbb{R}_t, \mathcal{H})}^2 \\ &\quad + 2g(h)^2\|A(h)w\|_{L^2(\mathbb{R}_t, \mathcal{H}_1)}^2 + \mathcal{O}(h^\infty)\|\chi(P)u\|^2, \end{aligned}$$

and the first term on the right can be absorbed on the left using (3.2). In fact, since

$$(3.5) \quad \sup_{\phi \in \mathcal{C}_c^\infty((0,1))} \frac{\int_0^1 \phi(s)^2 ds}{\int_0^1 \phi'(s)^2 ds} = \pi^{-2},$$

we have from the definition of w , and for any $\epsilon > 0$,

$$\begin{aligned} \|\chi(P)u\|_{\mathcal{H}}^2 &\leq 2(\pi^2 + \epsilon)\frac{G(h)^2}{T(h)^2}\|\chi(P)u\|_{\mathcal{H}}^2 \\ &\quad + 2\frac{g(h)^2}{T(h)}\|A(h)w\|_{L^2(\mathbb{R}_t, \mathcal{H}_1)}^2 + \mathcal{O}(h^\infty)\|\chi(P)u\|_{\mathcal{H}}^2. \end{aligned}$$

This completes the proof once we take h small enough. \square

It is a little surprising that *any* nonvanishing function ψ with properties required in the proof will give an estimate with some constant, and consequently (3.5) is irrelevant.

4. SEMICLASSICAL BLACK BOX RESOLVENT ESTIMATES

In this section we will make assumptions under which resolvent estimates can be obtained in the semi-classical setting. For simplicity no boundary will be allowed here.

Let X be a compact C^∞ manifold. Let $P(h) \in \Psi_h^{2,0}(X, \Omega_X^{\frac{1}{2}})$ be formally self-adjoint on $L^2(X, \Omega_X^{\frac{1}{2}})$. We assume that, if p is the principal symbol of $P(h)$, then

$$(4.1) \quad p = 0 \implies dp \neq 0, \quad p \geq \langle \xi \rangle^2 / C \text{ for } |\xi| \geq C,$$

and that for some $\delta > 0$

$$(4.2) \quad p^{-1}([-\delta, \delta]) \Subset T^*X.$$

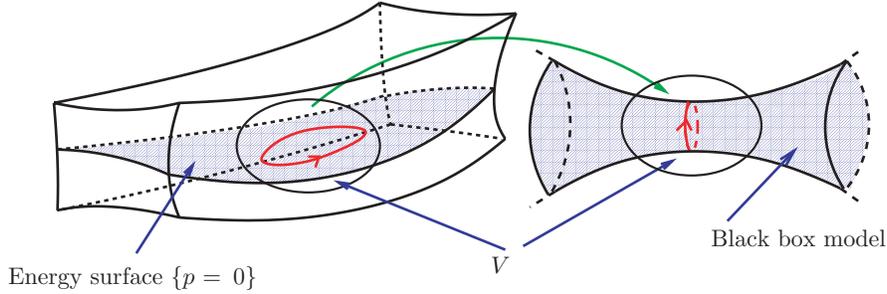


FIGURE 3. A semi-classical black box with an hyperbolic trapped trajectory.

Suppose that $Q(h)$ is a family of bounded invertible operators on a Hilbert space \mathcal{H} . Suppose that there exist bounded operators

$$\begin{aligned} U_1(h) &: L^2(X, \Omega_X^{\frac{1}{2}}) \longrightarrow \mathcal{H}, \\ U_2(h) &: \mathcal{H} \longrightarrow L^2(X, \Omega_X^{\frac{1}{2}}), \\ \chi^\sharp(h) &: \mathcal{H} \longrightarrow \mathcal{H}, \end{aligned}$$

such that, microlocally near V , an open subset of $p^{-1}([-\delta, \delta])$, we have

$$(4.3) \quad \begin{aligned} U_2(h) \circ U_1(h) &= Id, \\ U_1(h) \circ U_2(h) &= \chi^\sharp(h), \\ U_1(h) \circ P(h) \circ U_2(h) &= Q(h) \circ \chi^\sharp(h). \end{aligned}$$

In practice, the operators $U_j(h)$ are h -Fourier integral operators (see Proposition 2.1) but we do not need to make this assumption in the abstract presentation. Figure 3 shows our setup schematically in the case relevant for the proof of Theorem 2.

Theorem 5. *Let $P(h)$ and $Q(h)$ satisfy the assumptions above and let V_0 be an open relatively compact subset of T^*X . Suppose that $A \in \Psi_h^{0,0}(X, \Omega_X^{\frac{1}{2}})$ is microlocally elliptic in V_0 and that there exists $T > 0$ such that*

$$(4.4) \quad \begin{aligned} \forall \rho \in p^{-1}(0) \setminus V \exists 0 < t < T, \epsilon \in \{\pm 1\} \\ \exp(\epsilon s H_p)(\rho) \subset p^{-1}(0) \setminus V, \quad 0 < s < t, \quad \exp(\epsilon t H_p)(\rho) \in V_0. \end{aligned}$$

Suppose also that

$$(4.5) \quad \|\chi^\sharp(h)Q(h)^{-1}\| \leq \frac{G(h)}{h}, \quad G(h) \geq 1.$$

Then for $u \in \mathcal{C}^\infty(X, \Omega_X^{\frac{1}{2}})$ we have

$$(4.6) \quad \|u\| \leq C \frac{G(h)}{h} \|Pu\| + G(h) \|Au\|.$$

We start with the following standard:

Lemma 4.1. *Suppose that p, A , and V satisfy (4.4). If $B \in \Psi^{0,0}(X, \Omega_X^{\frac{1}{2}})$ and $WF(B) \subset T^*X \setminus V$, then*

$$(4.7) \quad \|Bu\| \leq Ch^{-1} \|Pu\| + \|Au\| + \mathcal{O}(h^\infty) \|u\|.$$

Proof. In view of the compactness of $p^{-1}(0)$ we can replace V_0 by a precompact neighbourhood of $V_0 \cap p^{-1}(0)$. The assumption (4.4) then shows that it is enough to prove a local version of the estimate. We can suppose that $WF(A) \subset U$ where U is a small neighbourhood of $m_0 \in V_0$ and

$$WF(B) \subset \bigcup_{0 \leq t \leq t_0} \exp(etH_p)(U_1) \subset T^*X \setminus V, \quad U_1 \Subset U.$$

If t_0 is small enough, we can apply Proposition 2.2, as the estimate is clear in the case of $P = hD_{x_1}$. In general, we can then split the interval $[0, t_0]$ into subintervals in which the t_0 -small argument can be applied. \square

Proof of Theorem 5. Suppose that B_1 satisfies

$$WF(B_1) \subset V_1, \quad V \Subset V_1, \quad WF(I - B_1) \subset T^*X \setminus V.$$

Then if V_1 is sufficiently close to V , using the second part of (4.3), we have

$$(4.8) \quad \begin{aligned} \|B_1u\| &= \|U_2(\chi^\sharp)^2 U_1 B_1u\| + \mathcal{O}(h^\infty) \|u\| \\ &= \|U_2 \chi^\sharp Q^{-1} Q \chi^\sharp U_1 B_1u\| + \mathcal{O}(h^\infty) \|u\|. \end{aligned}$$

If we now apply (4.5) and then (4.3) again, we obtain

$$(4.9) \quad \begin{aligned} \|B_1u\| &\leq C \frac{G(h)}{h} \|Q \chi^\sharp U_1 B_1u\|_{\mathcal{H}} + \mathcal{O}(h^\infty) \|u\| \\ &\leq C \frac{G(h)}{h} (\|Pu\| + \|[P, B_1]u\|) + \mathcal{O}(h^\infty) \|u\| \\ &\leq C \frac{G(h)}{h} \|Pu\| + G(h) \|B_2u\| + \mathcal{O}(h^\infty) \|u\|, \end{aligned}$$

where $B_2 \in \Psi^{0,0}(X, \Omega_X^{\frac{1}{2}})$ satisfies

$$WF(B_2) \subset V_1 \setminus V, \quad WF((I - B_2)[P, B_1]) = \emptyset.$$

Lemma 4.1 now shows that

$$\|B_1u\| \leq C \frac{G(h)}{h} \|Pu\| + G(h) \|Au\| + \mathcal{O}(h^\infty) \|u\|.$$

We now choose $B_3 \in \Psi_h^{0,0}(X, \Omega_X^{\frac{1}{2}})$ such that

$$WF(B_3) \subset T^*X \setminus V \quad \text{and} \quad WF(I - B_3) \subset V_1.$$

We can apply Lemma 4.1 with $B = B_3$ and that gives (4.6) as $\|u\| \simeq \|B_1u\| + \|B_3u\|$. \square

In some situations we can obtain improved estimates under a modified assumption on Q^{-1} . This modification will be crucial in Section 6 where we will prove (1.2). We present it separately not to obscure the simplicity of Theorem 5:

Theorem 5'. *Suppose that the assumptions of Theorem 5 hold and that in addition*

$$(4.10) \quad \|\chi^\sharp(h)Q^{-1}U_1\phi(h)\| \leq \frac{g(h)}{h},$$

where $\phi(h)$ is a microlocal cut-off to a neighbourhood of $V_1 \setminus V$, where $V_1 \ni V$ is a small neighbourhood of V . Then we have,

$$(4.11) \quad \|u\| \leq C \frac{G(h)}{h} \|Pu\| + g(h) \|Au\|.$$

Proof. We revisit the proof of Theorem 5. Instead of moving instantly to (4.9) from (4.8) using (4.6), we apply the identities (4.3) and write

$$\begin{aligned} \|B_1u\| &\leq C \|\chi^\sharp Q^{-1}Q\chi^\sharp U_1 B_1u\|_{\mathcal{H}} + \mathcal{O}(h^\infty) \|u\| \\ &= \|\chi^\sharp Q^{-1}U_1(B_1Pu + [P, B_1]u)\|_{\mathcal{H}} + \mathcal{O}(h^\infty) \|u\| \\ &\leq \|\chi^\sharp Q^{-1}U_1 B_1Pu\|_{\mathcal{H}} + \|\chi^\sharp Q^{-1}U_1\phi(h)[P, B_1]u\|_{\mathcal{H}} + \mathcal{O}(h^\infty) \|u\|, \end{aligned}$$

where we could insert the cut-off $\phi(h)$ due to the microsupport properties of B_1 .

If we apply (4.6) and (4.10), we obtain a local version of (4.11):

$$\|B_1u\| \leq C \frac{G(h)}{h} \|Pu\| + \frac{g(h)}{h} \|[P, B_1]u\| + \mathcal{O}(h^\infty) \|u\|.$$

The proof is then completed as in the case of Theorem 5. \square

5. ESTIMATES IN THE HOMOGENEOUS CASE: CLASSICAL CONTROL

In this section we will adapt the semi-classical arguments of Section 4 to obtain a classical version of estimate (4.6). We start by modifying the black box assumptions where we essentially follow [37], [36] but change the ambient space from \mathbb{R}^n to an arbitrary manifold.

Thus let X be a compact \mathcal{C}^∞ manifold with a (possibly empty) boundary ∂X . We consider an elliptic differential operator of order two,

$$P_0 \in \text{Diff}^2(X, \Omega_{\frac{1}{2}}^{\frac{1}{2}}),$$

with a domain $\mathcal{D}_0 \subset L^2(X, \Omega_{\frac{1}{2}}^{\frac{1}{2}})$. The choice of the domain includes the possible boundary conditions.

Let $Y \subset X$ be an open set. We also consider an auxiliary manifold \tilde{X} , which coincides with X on a neighbourhood \tilde{Y} of Y ; see Figure 4 for a visualization.

We then consider complex Hilbert spaces \mathcal{H} , \mathcal{H}_{bb} with orthogonal decompositions

$$\begin{aligned} \mathcal{H} &= \mathcal{H}_Y \oplus L^2(X \setminus Y, \Omega_{\frac{1}{2}}^{\frac{1}{2}}), \\ \mathcal{H}_{\text{bb}} &= \mathcal{H}_Y \oplus L^2(\tilde{X} \setminus Y, \Omega_{\frac{1}{2}}^{\frac{1}{2}}). \end{aligned}$$

For \mathcal{H} the orthogonal projections on the two factors are denoted by $\mathbb{1}_Y$ and $\mathbb{1}_{X \setminus Y}$, respectively. If $\chi_j \in \mathcal{C}^\infty(X)$ satisfy

$$(5.1) \quad \text{supp } \chi_0 \subset \mathbb{C} \text{supp}(1 - \chi_1) \subset \text{supp } \chi_1 \subset \tilde{Y}, \quad \text{supp}(1 - \chi_0) \subset X \setminus \tilde{Y},$$

then multiplication by χ_j is well defined on \mathcal{H} and \mathcal{H}_{bb} .

Proof. We first prove the following estimate:

$$(5.4) \quad \langle \lambda \rangle^{-1/2} \|[P_0, \chi_0]u\|_{\mathcal{H}} \leq C \left(\langle \lambda \rangle^{-1/2} \|(P - \lambda)u\|_{\mathcal{H}} + \|u\|_{X \setminus Y} \right).$$

Indeed, the ellipticity of P_0 gives

$$(5.5) \quad \begin{aligned} \|u\|_{H^2(\text{supp}(\nabla \chi_0))} &\leq C (\|P_0 u\|_{L^2(X \setminus Y)} + \|u\|_{L^2(X \setminus Y)}) \\ &\leq C (\|(P - \lambda)u\|_{L^2(X \setminus Y)} + \langle \lambda \rangle \|u\|_{L^2(X \setminus Y)}). \end{aligned}$$

Using the inequality $\|u\|_{H^1} \leq C \sqrt{\|u\|_{H^2} \|u\|_{L^2}}$, we get (5.4).

We now turn to the proof of (5.3). The black box assumptions give

$$(P_{\text{bb}} - \lambda)\chi_0 u = (P - \lambda)\chi_0 u = [P_0, \chi_0]u + \chi_0(P - \lambda)u.$$

Using (5.2), we obtain

$$\begin{aligned} \|\chi_0 u\|_{\mathcal{H}} &= \|\chi_0 u\|_{\mathcal{H}_{\text{bb}}} \\ &\leq G(\lambda) \left(\langle \lambda \rangle^{-1/2} (\|\chi_0(P - \lambda)u\|_{\mathcal{H}_{\text{bb}}} + \|[P_0, \chi_0]u\|_{\mathcal{H}_{\text{bb}}}) + \|A_{\text{bb}}\chi_0 u\|_{\mathcal{H}_1} \right). \end{aligned}$$

Above, we can replace the norms in \mathcal{H}_{bb} by norms in \mathcal{H} and, using (5.2) and (5.4), this implies

$$\|\chi_0 u\|_{\mathcal{H}} \leq CG(\lambda) \left(\langle \lambda \rangle^{-1/2} \|(P - \lambda)u\|_{\mathcal{H}} + \|Au\|_{\mathcal{H}_1} + \mathcal{O}(\langle \lambda \rangle^{-\infty}) \|u\|_{\mathcal{H}} + \|u\|_{\mathcal{D}^{-k}} \right).$$

To conclude the proof, we use the first inequality in (5.2) and the fact that

$$\|u\|_{\mathcal{D}^{-k}} = \|(P + i)^{-k}u\|_{\mathcal{H}} \leq C_k \langle \lambda \rangle^{-k} \|u\|_{\mathcal{H}} + \|(P - \lambda)u\|_{\mathcal{H}}.$$

□

Remark 1. In the proof above, the operators A and A_{bb} could depend on λ as long as the assumptions are uniform in λ .

The difference between the semi-classical and classical control estimates, (3.3) and (5.9) below, is more serious. In the classical case the low energy contribution does not allow an explicit time dependent constant as we have in (3.3) (compare (5.9) and (5.26) below). As investigated recently in [33], violent behaviour is expected when fast control is a goal.

Theorem 7. *Suppose that $A : \mathcal{D}(A) \rightarrow \mathcal{H}_1$, where \mathcal{H}_1 is a Hilbert space, $\mathcal{D}(A) \supset \mathcal{D}^\infty$, satisfies the following condition: for all N there exists C_N such that for all $k \in \mathbb{N}$ and $u \in \mathcal{D}^\infty$,*

$$(5.6) \quad \begin{aligned} \|A\psi(2^{-k}P)u\|_{\mathcal{H}_1} + \|A(1 - \psi)(2^{-k}P)u\|_{\mathcal{H}_1} \\ \leq C_N (\|Au\|_{\mathcal{H}_1} + 2^{-kN} \|u\|_{\mathcal{D}^{-N}}), \end{aligned}$$

$\psi \in C_0^\infty((1/2, 2))$.

Suppose also that for all $\lambda \in \mathbb{R}$ and $u \in \mathcal{D}^\infty$ we have

$$(5.7) \quad \|u\|_{\mathcal{H}} \leq G(\lambda) \|(P - \lambda)u\|_{\mathcal{H}} + g(\lambda) \|Au\|_{\mathcal{H}_1},$$

where G and g satisfy

$$(5.8) \quad \langle \lambda \rangle^{-1} \leq G(\lambda) \leq \langle \lambda \rangle^{N_0}, \quad C \langle \lambda \rangle^{-N_0} \leq g(\lambda) \leq C' \langle \lambda \rangle^{N_0}, \quad g(\lambda/2) \leq Cg(\lambda) \leq C'g(2\lambda).$$

We also assume the following weak continuity property (see Remark 2 for a discussion). There exist $N_1 \in \mathbb{N}$ and a Hilbert space \mathcal{H}^\sharp such that $\mathcal{H}_1 \subset \mathcal{H}^\sharp$ continuously, and the operator Ae^{itP} is continuous from \mathcal{D}^{-N_0} to $H_{\text{loc}}^{-N_1}(\mathbb{R}_t, \mathcal{H}^\sharp)$.

Then there exist constants C_0 and $C_1 = C_1(T)$ such that for any

$$T > C_1 \limsup_{|\lambda| \rightarrow \infty} G(\lambda)$$

we have for $u \in \mathcal{D}^\infty$,

$$(5.9) \quad \|\langle g(P) \rangle^{-1} u\|_{\mathcal{H}}^2 \leq C_1(T) \int_0^T \|e^{itP} Au\|_{\mathcal{H}_1}^2 dt.$$

Remark 2. In the case where the operator P is the Laplace operator with Dirichlet boundary conditions, the weak continuity is satisfied in the two following typical situations:

- (1) If A is a pseudodifferential operator supported in the interior of X , then $\mathcal{H}_1 = L^2(X)$ and we can take \mathcal{H}^\sharp to be another Sobolev space $H^{-s}(X)$.
- (2) If $Au = \partial_\nu|_\Gamma$ where $\Gamma \subset \partial\Omega$ and ∂_ν is the normal derivative to the boundary, then we can take $\mathcal{H}^\sharp = \mathcal{H}_1 = L^2(\partial X)$ as standard trace regularity results for solutions of Schrödinger equations show that the assumptions hold with N_0 sufficiently large.

Proof of Theorem 7. We follow closely the proof of Theorem 4 observing first that, with $\Psi \in C_0^\infty(]1/2, 2[)$ equal to 1 close to 1, (5.7) and (5.6) imply

$$(5.10) \quad \begin{aligned} & \langle g(\lambda) \rangle^{-1} \|\Psi(P/\langle \lambda \rangle)u\|_{\mathcal{H}} \\ & \leq G(\lambda) \langle g(\lambda) \rangle^{-1} \|\Psi(P/\langle \lambda \rangle)(P - \lambda)u\|_{\mathcal{H}} + C_N \|Au\|_{\mathcal{H}_1} + C \langle \lambda \rangle^{-N} \|u\|_{\mathcal{D}^{-N}} \end{aligned}$$

which in turn implies

$$(5.11) \quad \begin{aligned} & \|\langle g(P) \rangle^{-1} \Psi(P/\langle \lambda \rangle)u\|_{\mathcal{H}} \\ & \leq G(\lambda) \|\langle g(P) \rangle^{-1} (P - \lambda)u\|_{\mathcal{H}} + C_N \|Au\|_{\mathcal{H}_1} + C \langle \lambda \rangle^{-N} \|u\|_{\mathcal{D}^{-N}}. \end{aligned}$$

The functional calculus of self adjoint operators gives

$$\begin{aligned} \|(1 - \Psi)(P/\langle \lambda \rangle) \langle g(P) \rangle^{-1} u\|_{\mathcal{H}} & \leq \sup_{\xi} \left| \frac{(1 - \Psi)(\xi/\langle \lambda \rangle)}{\xi - \lambda} \right| \|\langle g(P) \rangle^{-1} u\|_{\mathcal{H}} \\ & \leq \frac{C}{1 + |\lambda|} \|\langle g(P) \rangle^{-1} u\|_{\mathcal{H}}, \end{aligned}$$

which, using (5.6) again, and (5.8) implies (taking N large enough) that for $|\lambda|$ large enough,

$$(5.12) \quad \|\langle g(P) \rangle^{-1} u\|_{\mathcal{H}} \leq CG(\lambda) \|\langle g(P) \rangle^{-1} (P - \lambda)u\|_{\mathcal{H}} + C \|Au\|_{\mathcal{H}_1}.$$

Proceeding as in the proof of Theorem 4, we define $v(t) = \exp(itP)u$. We introduce a function $\psi \in C_0^\infty(]0, 1[)$ and put

$$w(t) = \psi\left(\frac{t}{T}\right) v(t),$$

so that

$$(i\partial_t - P)w(t) = \frac{i}{T} \psi'\left(\frac{t}{T}\right) v(t).$$

Because of the compact support we can take the Fourier transform in t which gives

$$(\tau - P)\widehat{w}(\tau) = \frac{i}{T} \mathcal{F}_{t \rightarrow \tau}(\psi'(\bullet/T)v)(\tau).$$

Let ϱ be a large constant to be fixed later. For $\langle \tau \rangle \geq \varrho/2$ we estimate $\widehat{w}(\tau)$ using (5.12) which gives

$$(5.13) \quad \|\langle g(P) \rangle^{-1} \widehat{w}(\tau)\|_{\mathcal{H}} \leq C \frac{G(\tau)}{T} \|\langle g(P) \rangle^{-1} \mathcal{F}_{t \rightarrow \tau}(\psi'(\bullet/T)v)(\tau)\|_{\mathcal{H}} + C \|A\widehat{w}(\tau)\|_{\mathcal{H}_1}.$$

For $\langle \tau \rangle \leq \varrho/2$ we simply write, with $\chi \in C_0^\infty(-1, 1]$ equal to 1 on $[-1/2, 1/2]$,

$$(5.14) \quad \widehat{w}(\tau) = \int_{t \in \mathbb{R}} e^{it(P-\tau)} \psi\left(\frac{t}{T}\right) (\chi(P/\varrho)u + (1 - \chi(P/\varrho))u) dt.$$

The contribution of the first term is bounded (in \mathcal{H}) by $\|\chi(P/\varrho)u\|_{\mathcal{H}}$ and by integrations by parts with the operator $\frac{i\partial_t}{P-\tau}$ we can bound the contribution of the second term by

$$(5.15) \quad C_N \left\| \frac{1}{(1 + |T| + |\varrho| + \langle P \rangle)^N} u \right\|_{\mathcal{H}}.$$

From (5.13), (5.14), (5.15) and the bounds on the weight g , we get

$$(5.16) \quad \begin{aligned} & \|\langle g(P) \rangle^{-1} \widehat{w}(\tau)\|_{L^2(\mathbb{R}_\tau, \mathcal{H})}^2 \\ & \leq C \left(\frac{\sup_{|\tau| \geq \varrho/2} G(\tau)}{T} \right)^2 \|\langle g(P) \rangle^{-1} \mathcal{F}_{t \rightarrow \tau}(\psi'(\bullet/T)v)\|_{L^2(\mathbb{R}_\tau, \mathcal{H})}^2 \\ & \quad + C \int_0^T \|Ae^{itP}u\|_{\mathcal{H}_1}^2 dt + C_\varrho \|\mathbb{1}_{\langle P \rangle \leq \rho} u\|_{\mathcal{H}}^2 + C \langle \varrho \rangle^{-N_0} \|u\|_{\mathcal{D}^{-N_0}}^2. \end{aligned}$$

Note that

$$(5.17) \quad \|\langle g(P) \rangle^{-1} \widehat{w}(\tau)\|_{L^2(\mathbb{R}_\tau, \mathcal{H})} = T^{1/2} \|\Psi\|_{L^2} \|\langle g(P) \rangle^{-1} u\|_{\mathcal{H}}$$

and

$$(5.18) \quad \|\langle g(P) \rangle^{-1} \mathcal{F}_{t \rightarrow \tau}(\psi'(\bullet/T)v)\|_{L^2(\mathbb{R}_\tau, \mathcal{H})} = T^{1/2} \|\Psi'\|_{L^2} \|\langle g(P) \rangle^{-1} u\|_{\mathcal{H}}.$$

Consequently, taking ρ large enough, the assumption $T > C_1 \limsup_{|\lambda| \rightarrow \infty} G(\lambda)$ ensures that we can eliminate the first and the last terms in the right-hand side and get

$$(5.19) \quad \|\langle g(P) \rangle^{-1} u\|_{\mathcal{H}} \leq C \int_0^T \|Ae^{itP}u\|_{\mathcal{H}_1}^2 dt + C_\varrho \|\mathbb{1}_{\langle P \rangle \leq \rho} u\|_{\mathcal{H}}^2.$$

To eliminate the last term, we use the compactness-uniqueness argument from [2] which we now recall. Proceeding by contradiction, we obtain a sequence (u_n) such that

$$(5.20) \quad C \|\mathbb{1}_{\langle P \rangle \leq \rho} u_n\|_{\mathcal{H}}^2 \geq 1 = \|\langle g(P) \rangle^{-1} u_n\|_{\mathcal{H}}^2 \geq n \int_0^T \|Ae^{itP}u_n\|_{\mathcal{H}_1}^2 dt.$$

Define

$$(5.21) \quad H_T = \{u \in \mathcal{D}^{-N_0} : \|\langle g(P) \rangle^{-1} u\|_{\mathcal{H}}^2 + \int_0^T \|Ae^{itP}u\|_{\mathcal{H}_1}^2 dt < +\infty\}$$

with its natural norm (the definition makes sense because of the weak continuity property of Ae^{itP}). Due to the assumption (5.8) and the weak continuity property of Ae^{itP} , H_T is a Hilbert space which is continuously embedded in \mathcal{D}^{-N_0} . The sequence (u_n) is bounded in H and we can extract a subsequence converging weakly

in H to a limit u . Using the compactness of $(P + i)^{-1}$, the operator $\mathbb{1}_{\langle P \rangle \leq \rho}$ is also compact on \mathcal{D}^{-N_0} . By passing to the limit, we see that u satisfies

$$(5.22) \quad C \|\mathbb{1}_{\langle P \rangle \leq \rho} u\|_{\mathcal{H}}^2 \geq 1$$

and

$$(5.23) \quad 0 = \int_0^T \|Ae^{itP} u\|_{\mathcal{H}_1}^2 dt.$$

The contradiction comes from the following:

Lemma 5.1. *Let*

$$(5.24) \quad N = \left\{ u \in H_T : 0 = \int_0^T \|Ae^{itP} u\|_{\mathcal{H}_1}^2 dt \right\}.$$

Then $N = \{0\}$.

Proof. We first show that N is invariant under the action of the operator P . Using that $Pe^{itP}u = i\partial_t e^{itP}u$, the only thing to show is that if $u \in N$, then $\|\langle g(P) \rangle^{-1} Pu\|_{\mathcal{H}}$ is bounded.

We put $v(t) = e^{itP}u$ and apply (5.19) with T replaced by $T - \varepsilon_0$ to the sequence of functions

$$(5.25) \quad v_\varepsilon = i \frac{v(t + \varepsilon) - v(t)}{\varepsilon}.$$

We get for $0 < \varepsilon < \varepsilon_0$

$$(5.26) \quad \|\langle g(P) \rangle^{-1} v_\varepsilon|_{t=0}\|_{\mathcal{H}} \leq C \|\mathbb{1}_{\langle P \rangle \leq \rho} v_\varepsilon|_{t=0}\|_{\mathcal{H}_1}^2$$

and using that $v_\varepsilon|_{t=0}$ converges to $i\partial_t u|_{t=0} = Pu|_{t=0}$ in \mathcal{D}^{-N_0-1} , we obtain that the right-hand side is bounded as ε tends to 0. Consequently, we can extract a subsequence v_ε converging in $H_{T-\varepsilon_0}$. The limit is necessarily (due to the weak continuity property) Pu which implies that $Pu \in N$. To conclude, remark that $\|\mathbb{1}_{\langle P \rangle \leq \rho} u_n\|_{\mathcal{H}_1}^2$ is a norm on N equivalent to the natural norm. Consequently N is finite dimensional. The space N is invariant by the operator P which consequently has an eigenvector. But any eigenvector of P in N satisfies $Au = 0$ and is equal to 0 due to (5.7). Consequently $N = \{0\}$. \square

6. EXAMPLES AND APPLICATIONS

In this section we present several applications of our method, giving, in particular, the proof of Theorems 1, 2 and 3 stated in the introduction.

6.1. Geometric control. As in the introduction we consider Ω , a smooth domain in \mathbb{R}^d , $\Gamma \subset \partial\Omega$, and we fix $T > 0$. For any $g \in L^2([0, T] \times \Gamma)$, we consider u the solution of the mixed problem (1.1). The goal is to find conditions on Γ so that there exists a large class of functions u_0 which can be “controlled” by g , in the sense that

$$(6.1) \quad u|_{t=T} = 0.$$

When one deals with such *control* problems, the usual first step (called the H.U.M. method) is a dual approach: For any $g \in L^2([0, T] \times \Gamma)$, consider v , the

solution of the mixed problem

$$(6.2) \quad \begin{aligned} (i\partial_t - \Delta)v &= 0, \\ v|_{\partial\Omega} &= g\mathbb{1}_{[0,T]\times\Gamma}, \\ v|_{t=T} &= 0, \end{aligned}$$

and define $S(g) = v|_{t=0}$. In this setting the control problem is to determine the range of the operator S . For that consider $u = e^{it\Delta_D}u_0$, the solution of

$$(6.3) \quad \begin{aligned} (i\partial_t - \Delta)u &= 0, \\ u|_{\partial\Omega} &= 0, \\ u|_{t=0} &= u_0. \end{aligned}$$

We then define a new operator

$$T(u_0) \stackrel{\text{def}}{=} \partial_\nu u|_{[0,T]\times\Gamma}.$$

Lemma 6.1 (H.U.M. method, [30]). *The operators S and T have the continuity properties*

$$\begin{aligned} S &: L^2([0, T] \times \Gamma) \longrightarrow H^{-1}(\Omega), \\ T &: H_0^1(\Omega) \longrightarrow L^2([0, T] \times \Gamma), \end{aligned}$$

and the adjoint of T is equal to iS .

Proof. Let us define $X(t, x) = \phi(t)Y(x)$, where $Y(x)$ is a smooth vector field on $\bar{\Omega}$ equal to ∂_n close to $\partial\Omega$ and $\phi \in C_c^\infty(\mathbb{R})$. With $u(t, x)$ as in (6.2), an application of Stokes's formula gives

$$(6.4) \quad \int_{\mathbb{R}_t \times \Omega} [(i\partial_t - \Delta), X]u\bar{u}dxdt = - \int_{\mathbb{R}_t \times \partial\Omega} (Xu)|_{\partial\Omega} \overline{\partial_\nu u}d\sigma dt.$$

Since the operator $[(i\partial_t - \Delta), X]$ is a second order differential operator *in the x variable only*, the left-hand side in (6.4) is bounded by $C\|u\|_{L^\infty(\mathbb{R}_t, H_0^1(\Omega))}^2 \sim \|u_0\|_{H_0^1(\Omega)}^2$. The right-hand side is equal to

$$\|\phi(t)\partial_\nu u\|_{L^2(\mathbb{R}_t \times \partial\Omega)}^2$$

and that implies the continuity of the operator T .

To see the duality of T and iS , we multiply (1.1) by \bar{u} and integrate over $[0, T] \times \Omega$. Using the boundary conditions satisfied by u and v , we obtain

$$(6.5) \quad \begin{aligned} 0 &= \int_0^T \int_\Omega (i\partial_t - \Delta)v\bar{u}dxdt \\ &= i \left[\int_\Omega v\bar{u} \right]_0^T + \int_0^T \int_{\partial\Omega} (-\partial_\nu v\bar{u} + v\overline{\partial_\nu u}) d\sigma dt \\ &= -i \int_\Omega S(g)\bar{u}_0 + \int_0^T \int_\Gamma g\overline{T(u_0)}d\sigma dt, \end{aligned}$$

which proves the claim $T^* = iS$. The continuity of the operator S follows. □

As an application of Lemma 6.1, we see that the range of the operator S is dense (approximate controllability) if and only if the operator T is injective. Also, the range of S is equal to $H^{-1}(\Omega)$ (exact controllability) if and only if

$$\exists C > 0 \quad \|T(u_0)\|_{L^2([0,T]\times\Gamma)} \geq C\|u_0\|_{H_0^1(\Omega)}.$$

Finally, any reasonable estimate implying the injectivity of the operator T will give information on the range of S . For example

$$\|T(u_0)\|_{L^2([0,T]\times\Gamma)} \geq C\|u_0\|_{H^{-s}(\Omega)} \implies H^s(\Omega) \cap H_0^1(\Omega) \subset \text{Range}(S).$$

In the context of exact geometric control, the basic result was obtained by Lebeau [29] (see also [30] and [44]). It involves the natural concepts of the broken geodesic flow and of nondiffractive points (see [32] and also [6]):

Theorem 8. *Suppose that Γ controls Ω geometrically, that is,*

(6.6) $\exists L_0$ such that every trajectory of length L_0 meets Γ at a nondiffractive point, where trajectories are with respect to the broken geodesic flow. Then for any $T > 0$ and any $u_1 \in H^{-1}(\Omega)$ there exists $g \in L^2([0, T] \times \Gamma)$ such that $S(g)|_{t>T} \equiv 0$.

Proof. We first recall that as an application of Lions’s H.U.M. method (Lemma 6.1), we see that Theorem 8 is equivalent to

$$(6.7) \quad \exists C > 0; \quad \|u_0\|_{H_0^1(\Omega)} \leq C\|\partial_\nu(e^{it\Delta_D}u_0)|_{[0,T]\times\Gamma}\|_{L^2([0,T]\times\Gamma)}.$$

Estimate (6.7) follows from Theorem 7 and the following resolvent estimate:

$$(6.8) \quad \begin{aligned} \exists C > 0 \forall z \in \mathbb{C} \setminus \mathbb{R}, \|R(z)f\|_{H^1(\Omega)} + \sqrt{|z|}\|R(z)f\|_{L^2(\Omega)} \\ \leq C\|\partial_\nu R(z)f\|_{L^2(\Gamma)} + C\|f\|_{L^2(\Omega)}, \end{aligned}$$

where $R(z) = (-\Delta_D - z)^{-1}$, with Δ_D the Dirichlet Laplacian on Ω . In fact, we can simply put $Au = \partial_\nu u|_\Gamma$ and $\mathcal{H}_1 = L^2(\Gamma)$. To establish (6.8), we remark first that due to standard elliptic estimates, the only problem is when z is close to the spectrum of $-\Delta$, \mathbb{R}^+ . We can use the microlocal defect measures arguments as in [6]: we first prove (6.8) for large z and argue by contradiction. We obtain sequences z_n such that $\text{Re } z_n \rightarrow +\infty$ and $\text{Im } z_n \rightarrow 0$ and with u_n a solution of

$$(6.9) \quad (-\Delta - z_n)u_n = f_n, \quad \|u_n\|_{L^2(\Omega)} + \frac{1}{\sqrt{z_n}}\|\nabla_x u_n\|_{L^2(\Omega)} = 1,$$

$$(6.10) \quad \|f_n\|_{L^2(\Omega)} = o\left(\sqrt{\text{Re } z_n}\right),$$

$$(6.11) \quad \|\partial_n u_n\|_{L^2(\Gamma)} = o\left(\sqrt{\text{Re } z_n}\right).$$

Denote $h_n = (\text{Re}(z_n))^{-1/2}$. Then, modulo the extraction of a subsequence (see [19, 6]), there exists a positive Radon measure (a semi-classical defect measure on $T^*\mathbb{R}^d$) such that, if \underline{u}_n is the extension of u_n by 0 outside of $\overline{\Omega}$, we have

- (1) For any h -pseudodifferential operator, A , on \mathbb{R}^d ,

$$\langle \mu, \sigma_0(A) \rangle = \lim_{n \rightarrow +\infty} (A(x, h_n D_x) \underline{u}_n, \underline{u}_n)_{L^2(\mathbb{R}^d)}.$$

- (2) The measure μ is supported in the semi-classical characteristic variety:

$$(6.12) \quad \text{supp}(\mu) \subset T^*\mathbb{R}^d \cap \{(x, \xi); x \in \overline{M}, |\xi|^2 = 1\}.$$

Furthermore (see [6, 9]), using (6.10), we obtain that this measure is invariant along the generalized bicharacteristic flow. In the interior, this property is straightforward, whereas, near the boundary, it is more involved. In particular, we can show that the measure of the hyperbolic set (corresponding to transversal reflections) is equal to 0. This allows a definition of a bicharacteristic flow on the set (6.12), μ almost everywhere. Due to (6.11) the measure is equal to 0 near any nondiffractive

point in Γ (see [8]), which, by (6.6), implies that the measure is identically null. Finally the contradiction arises from the fact that according to (6.9) the measure has total mass 1.

The proof of (6.8) for $z \leq C$ is obtained by a contradiction argument (and compactness) and the classical uniqueness theorem for second order elliptic operators (for this point we simply use that $\overset{\circ}{\Gamma} \neq \emptyset$). □

6.2. Ikawa’s black box. In the proof of Lebeau’s theorem we did not use any “black-box” technology. As illustrated by Figure 1, we can employ it in

Proof of Theorem 1. As in the proof of Theorem 8 we use the H.U.M. method and Theorem 7 to reduce the argument to the estimate

$$\|R(z)f\|_{H^1(\Omega)} + \sqrt{|z|}\|R(z)f\|_{L^2(\Omega)} \leq C \log(|z|) (\|\partial_n R(z)f\|_{L^2(\Gamma)} + \|f\|_{L^2(\Omega)}) ,$$

for $\text{Im } z \neq 0$. This estimate follows from Theorem 6 and the following consequence of the work of Ikawa [26, Theorem 2.1]. Suppose that $R_{\text{bb}}(k)$ is the *outgoing*¹ resolvent for the Dirichlet problem in the exterior of the union of convex obstacles satisfying

- (convhull $\Theta_j \cup \Theta_k$) $\cap \Theta_l = \emptyset$, $j \neq l \neq k$.
- Denote by κ the infimum of the principal curvatures of the boundaries of the obstacles Θ_i and by L the infimum of the distances between two obstacles. Then if $N > 2$, we assume that $\kappa L > N$ (no assumption if $N = 2$).

Then there exist $\alpha > 0$, C_0 , and N_0 such that for $\text{Im } k > -\alpha$ we have

$$\|\chi R_{\text{bb}}(k)\chi\|_{L^2 \rightarrow L^2} \leq C_0 \langle k \rangle^{N_0}, \quad \chi \in \mathcal{C}_c^\infty(\mathbb{R}^n).$$

An application of the maximum principle as in [40, Lemma 2] and [7, Lemma 4.10] (see also Lemma A.2 below) gives a bound for $k \in \mathbb{R}$

$$(6.13) \quad \|\chi R_{\text{bb}}(k)\chi\|_{L^2 \rightarrow L^2} \leq C_1 \frac{\log \langle k \rangle}{\langle k \rangle},$$

and that gives the “black-box” assumption (5.2) with $G(\lambda) = \log \langle \lambda \rangle$ and $A_{\text{bb}} \equiv 0$. □

6.3. Bunimovich stadium with the flat part as the black box. Our next control theoretical application is a new result about high frequency scarring in the case of the Bunimovich stadium². The same argument applies also in recent examples related to *quantum unique ergodicity* [16], [42] where the flat part “black box” needs to be replaced by a flat torus. The result which we use in the black box (see Proposition 6.1 below) applies to that case as well.

Theorem 3’. *Consider Ω the Bunimovich stadium associated to a rectangle R and $\omega \subset \Omega$ which controls a neighbourhood of $\Omega \setminus R$ geometrically. For any solution of the equation $(\Delta - z)v = f$, $u|_{\partial\Omega} = 0$, we then have*

$$(6.14) \quad \|v\|_{L^2(\Omega)} \leq C (\|f\|_{L^2(\Omega)} + \|\mathbb{1}_\omega v\|_{L^2(\omega)}) .$$

¹The outgoing resolvent is the meromorphic continuation of $(-\Delta - k^2)^{-1}$ from $\text{Im } k > 0$.

²Which is perhaps the most celebrated example of a convex chaotic billiard.

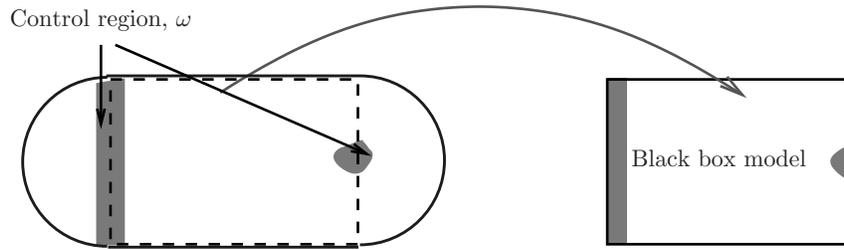


FIGURE 5. Control on the Bunimovich stadium.

Theorem 3 follows by considering the case of $f \equiv 0$. We also have the following immediate consequence of Theorem 7:

Theorem 9. *Consider Ω the Bunimovich stadium associated to a rectangle R and $\omega \subset \Omega$ which controls $\Omega \setminus R$ geometrically. Then there exist $T > 0$ and $C > 0$ such that*

$$(6.15) \quad \|u_0\|_{L^2(\Omega)}^2 \leq C \int_0^T \|\mathbb{1}_\omega e^{it\Delta} u_0\|_{L^2(\Omega)}^2.$$

In fact, by using a *temporal* black box, we could prove Theorem 9 for any $T > 0$.

Before presenting the proof (see also [10] for a self-contained and elementary proof of a slightly weaker result), we briefly discuss the significance of the result. The Schnirelman theorem for the case of bounded planar domains (proved in [19] and [43]) implies that

$$\begin{aligned} \exists \{n_k\}_{k=1}^\infty \subset \mathbb{N} \quad \lim_{N \rightarrow \infty} \frac{1}{N} |\{n_k : k \leq N\}| = 1, \quad \int_V |u_{n_k}(x)|^2 dx \longrightarrow \text{Area}(V), \\ V \subset \Omega, \quad -\Delta u_\ell = \lambda_\ell u_\ell, \quad \int_\Omega |u_\ell(x)|^2 dx = 0, \end{aligned}$$

and $\lambda_1 < \lambda_2 \leq \dots \lambda_\ell \leq \dots$ is the sequence of all eigenvalues. That means that a concentration on a subset of Ω can occur only for an eigenvalue subsequence of density 0. A finer version can be stated in the language of semi-classical defect measures reviewed in the proof of Theorem 8: for a subsequence of density one the only limiting measure is the Liouville measure on the cosphere bundle.

Theorem 3 states that there cannot exist any sequence of eigenfunctions which concentrates away from a region geometrically controlling $\Omega \setminus R$, in particular, away from any neighbourhood of the vertical boundaries of the rectangular part. This is in agreement with the numerical (see for instance [1] and references given there) and experimental (for instance [11] and Figure 2) results indicating that there exist *bouncing ball modes* which on a sequence of density zero concentrate inside of the rectangle, stretching all the way to the boundary of the rectangle. Other applications, for instance to the case of the Sinai billiard, are presented in [10]. The fact that the semi-classical measure of any sequence of eigenfunctions (with increasing eigenvalues) is invariant by the action of the Hamiltonian flow is a consequence of the propagation results (Lemma 4.1). Apart from the beautiful, more precise but particular results on arithmetic surfaces [34], [31], this result seems to be the first one showing that there exist some invariant measures which are *not* the semi-classical measures of any sequence of eigenfunctions.

We are going to deduce Theorem 3' from the following result [4] which is related to some earlier control results of Haraux [22] and Jaffard [27].

Proposition 6.1. *Let Δ be the Dirichlet Laplace operator on the rectangle $R = [0, 1]_x \times [0, a]_y$. Then for any open nonempty $\omega \subset R$ of the form $\omega = \omega_x \times [0, a]_y$, there exists C such that for any solutions of*

$$(6.16) \quad (\Delta - z)u = f \quad \text{on } R, \quad u|_{\partial R} = 0, \quad z \in \mathbb{R},$$

we have

$$(6.17) \quad \|u\|_{L^2(R)}^2 \leq C \left(\|f\|_{H^{-1}([0,1]_x, L^2([0,a]_y))}^2 + \|u|_{\omega}\|_{L^2(\omega)}^2 \right).$$

Proof. We decompose u, f in terms of the basis of $L^2([0, a])$ formed by the Dirichlet eigenfunctions $e_k(y) = \sqrt{2/a} \sin(2k\pi y/a)$,

$$(6.18) \quad u(x, y) = \sum_k e_k(y)u_k(x), \quad f(x, y) = \sum_k e_k(y)f_k(x),$$

and we get for u_k, f_k the equation

$$(6.19) \quad \left(\Delta_x - \left(z + (2k\pi/a)^2 \right) \right) u_k = f_k, \quad u_k(0) = u_k(1) = 0.$$

Since ω_x controls geometrically $[0, 1]$, a slight variant of (6.8) (or, in this simple case, a direct calculation) gives

$$(6.20) \quad \|u_k\|_{L^2([0,1]_x)}^2 \leq C \left(\|f_k\|_{H^{-1}([0,1]_x)}^2 + \|u_k|_{\omega_x}\|_{L^2(\omega)}^2 \right),$$

and summing the squares on k , we get (6.17).³ □

Proof of Theorem 3'. Let us take x, y as the coordinates on the stadium, so that x is the longitudinal direction, y the transversal direction, and the internal rectangle is $[0, 1]_x \times [0, a]_y$. Let us then consider u, f satisfying $(\Delta - z)u = f$, $u = 0$ on the boundary of the stadium, and $\chi(x) \in C_0^\infty(0, 1)$ equal to 1 on $[\varepsilon, 1 - \varepsilon]$. Then $\chi(x)u(x, y)$ is a solution of

$$(6.21) \quad (\Delta - z)\chi u = \chi f + [\Delta, \chi]u \quad \text{in } R$$

with Dirichlet boundary conditions on ∂R . Applying Proposition 6.1, we get

$$(6.22) \quad \|\chi u\|_{L^2(R)} \leq C \left(\|\chi f\|_{H_x^{-1}, L_y^2} + \|u|_{\omega_\varepsilon}\|_{L^2(\omega_\varepsilon)} \right)$$

where ω_ε is a neighbourhood of the support of $\nabla \chi$. Consequently we get for V a neighbourhood of $\Omega \setminus R$,

$$(6.23) \quad \|u\|_{L^2(R)} \leq C \left(\|f\|_{L^2(R)} + \|u|_V\|_{L^2(V)} \right).$$

Finally, by standard propagation of semi-classical singularities as in subsection 6.1, we can replace V by ω in (6.23). □

³We remark that as noted in [4] the proof applies to any product manifold $M = M_x \times M_y$, and consequently Theorem 3' holds also for that geometry as a black box.

6.4. Semi-classical control with a prescribed loss. For completeness we propose a natural class of examples in which we expect $G(h)$ in Theorems 4 and 5 to be essentially any power of h :

$$G(h) = h^{-\alpha} \log(1/h), \quad \alpha = \frac{m-1}{m+1}, \quad m = 1, 2, \dots$$

For that, consider the following set of Schrödinger operators on \mathbb{R}^2 :

$$P_m(h) = -h^2 \Delta + x_1^2 - x_2^{2m}, \quad m \in \mathbb{N}.$$

The Helffer-Sjöstrand theory of resonances [23] applies to this case (see also [35, Section 1] where a discussion of a general polynomial is given). In particular, for the meromorphically continued resolvent, $R_m(z, h) = (P_m(h) - z)^{-1}$, we have the following bound for the cut-off resolvent:

$$(6.24) \quad \|\chi R_m(z, h) \chi\| \leq Ch^{-\frac{2m}{m+1}} \log(1/h).$$

A separation of variables argument and the rescaling $x = h^{\frac{1}{m+1}} y$ suggest that the resonances are at the distance $h^{\frac{2m}{m+1}}$ from the real axis. The same method shows that the resolvent is polynomially bounded in h^{-1} and hence the interpolation argument we used before (see Lemma A.2 below) gives (6.24).

From $P_m(h)$ we can construct a “black box” for an operator $P(h)$ to which Theorems 4 and 5 will be applicable with $G(h) = h^{-\frac{m-1}{m+1}} \log(1/h)$.

6.5. Closed hyperbolic orbits on manifolds. We will now discuss in more detail the case occurring when the black box contains a hyperbolic orbit, leading to the proof of Theorem 2.

Thus suppose that the hypotheses of that theorem are satisfied. It is well known that we can find a coordinate system in a neighbourhood of γ , $U \simeq \mathbb{S}^1 \times V$, V a neighbourhood of 0 in \mathbb{R}^{n-1} , in which γ is identified with \mathbb{S}^1 and the metric is given by

$$g = d\theta^2 + \sum_{1 \leq i, j \leq n-1} h_{ij}(x, \theta) dx_i dx_j, \quad \theta \in \mathbb{S}^1, \quad x \in V.$$

Since γ is hyperbolic, we can assume that \mathbb{S}^1 is the only closed geodesic in U .

From this local construction we now build a global scattering problem by extending g to a metric, g_{bb} , defined on $\mathbb{S}^1 \times \mathbb{R}^{n-1} \simeq \mathbb{S}_\theta^1 \times \mathbb{S}_\omega^{n-1} \times [0, \infty)$. We choose g to be asymptotically Euclidean:

$$g_{\text{bb}} \sim dr^2 + r^2 d\theta^2 + r^2 g_{\mathbb{S}^{n-1}}(d\omega), \quad r \rightarrow \infty,$$

and so that γ is the only closed geodesic of g_{bb} .

Because of the work of Ikawa [26], Gérard [17], and of Gérard-Sjöstrand [18], it is expected that the resolvent of the Laplacian of g_{bb} can be controlled using (6.13), as in subsection 6.2. Since the two metrics agree in a neighbourhood of the closed geodesics, we can use the scattering problem as our “black box” and apply Theorem 5 with $A = (1 - \chi)$. That would give Theorem 2 with $(\log \lambda)^2$ in place of $\log \lambda$. To get the improved (and, thanks to an example in [13], optimal) statement, we need an improved estimate for the resolvent so that Theorem 5’ can be applied:

$$\|\chi R_{\text{bb}}(k) \phi\|_{L^2 \rightarrow L^2} \leq C_1 \frac{\sqrt{\log \langle k \rangle}}{\langle k \rangle}, \quad \phi \in C_c^\infty, \quad \text{supp } \phi \cap \gamma = \emptyset.$$

Since the needed results from scattering theory, although expected, are not yet available⁴, we take a simplified route and use a complex absorbing potential to construct a black box operator Q in Theorem 5'⁵. That is done in the Appendix with Theorem A furnishing us with the needed estimates. Since the subprincipal symbol of the Laplace operator $-h^2\Delta$ is equal to 0, Theorem 2 follows from its more general fully semi-classical variant:

Theorem 2'. *Suppose that X is a compact n -manifold or \mathbb{R}^n and that $P(h) \in \Psi_h^{m,0}(X, \Omega_X^{\frac{1}{2}})$ has the real principal symbol, p , satisfying*

$$\begin{aligned} p^{-1}([-\epsilon, \epsilon]) &\Subset T^*X, \text{ for some } \epsilon > 0, \\ p(\rho) = 0 &\implies dp(\rho) \neq 0, \\ \exists C > 0 \quad \langle \xi \rangle \geq C &\implies p \geq \langle \xi \rangle^m / C. \end{aligned}$$

Assume also that the subprincipal symbol of p , (2.2), is equal to zero. Let $\gamma \subset p^{-1}(0)$ be a closed hyperbolic orbit of the Hamilton flow of p , in the sense that all eigenvalues of the linearized Poincaré map are real and different from one.

There exist constants C_0 and h_0 , such that if $u(h) \in L^2(X, \Omega_X^{\frac{1}{2}})$ satisfies

$$P(h)u = f,$$

then for any $A(h) \in \Psi_h^{0,0}(X, \Omega_X^{\frac{1}{2}})$, with its essential support, $WF(A)$, contained in a small neighbourhood of γ , we have

$$C_0 \left(h^{-2}(\log(1/h))^2 \int_X |f|^2 + \log(1/h) \int_X |(I - A(h))u|^2 \right) \geq \int_X |u|^2, \quad h < h_0.$$

APPENDIX

In this appendix we will construct an operator Q appearing in Theorem 5 for a black box containing a hyperbolic orbit on a Riemannian manifold, or more generally for the operator appearing in Theorem 2'. Ideally, we would like Q to be the complex scaled Laplacian, $-h^2\Delta_\theta - z$ on an asymptotically Euclidean manifold having one closed hyperbolic geodesic as its trapped set. The results of [17], [18] indicate that precise estimates of the type needed, and in fact, the full understanding of resonances in logarithmic neighbourhoods of the real axis, should be possible.

In the case of the Laplacian on a compact Riemannian manifold we construct the reference operator as follows. Let $a \in C^\infty(X, [0, 1])$ be equal to 0 in a neighbourhood of γ and to 1 in a neighbourhood of infinity. We then put

$$Q = Q(z) \stackrel{\text{def}}{=} -h^2\Delta_g - z - iha, \quad z \in [1, 2] + i[-\epsilon, \epsilon].$$

When considering a more general operator $P(h)$ given in Theorem 2', we put

$$(A.1) \quad Q = Q(z) \stackrel{\text{def}}{=} P(h) - z - iha, \quad z \in [1, 2] + i[-\epsilon, \epsilon],$$

where a is a pseudodifferential operator with $WF_h(a) \cap \gamma = \emptyset$ and a is elliptic, positive away from γ on T^*X . We recall that $P(h)$ is assumed to be of real principal type and to have a vanishing subprincipal symbol. That means that the Weyl

⁴In [26] only convex obstacles in the Euclidean case are studied, while in [18] an analyticity assumption is made.

⁵We remark however that the results of [20] and [12] would have been sufficient for the case of hyperbolic geodesics on constant negative curvature segments, if one takes the black box approach.

principal symbol of $P(h)$ is independent of h and in any local coordinates $P(h)$ differs from its Weyl quantization by $\mathcal{O}(h^2)$.

The following result will allow applications of Theorem 5:

Theorem A. *If $Q(z)$ is given by (A.1) and $z \in I \Subset (0, \infty)$, then for $h < h_0$, we have*

$$\|Q(z)^{-1}\|_{L^2(X) \rightarrow L^2(X)} \leq C \frac{\log(1/h)}{h}.$$

If $\phi \in \mathcal{C}_b^\infty(X)$ is supported away from γ , then we also have

$$\|Q(z)^{-1}\phi\|_{L^2(X) \rightarrow L^2(X)} \leq C \frac{\sqrt{\log(1/h)}}{h}.$$

To prove this theorem, we will use the strategy of the proof of Theorem 5 which means that it will be reduced to a local estimate near γ .

We first show that we have control away from a small neighbourhood of γ . See Figure 6 for an illustration of the hypotheses of the following

Proposition A.1. *Suppose that $\psi_0 \in S^0(T^*X) \cap \mathcal{C}_c^\infty(T^*X)$ is a microlocal cut-off to a small neighbourhood of $\gamma \subset p^{-1}(0)$. Then, with $Q(z)$ as in (A.1) and $z \in [1, 2] + i(-c_0h, +\infty)$, $c_0 > 0$, we have*

$$(A.2) \quad Q(z)u = f \implies \|(1 - \psi_0)u\| \leq C \frac{1}{h} \|f\| + \mathcal{O}(h^\infty) \|u\|.$$

Proof. We will prove (A.2) using Lemma 4.1. For that we choose $c_0 > 0$ and $\psi_1, \psi_2 \in \mathcal{C}_c^\infty(T^*X)$ with $WF_h(1 - \psi_j) \cap \gamma = \emptyset$, so that, as operators,

$$(a - c_0)(1 - \psi_1) \geq \begin{cases} c_0/2(1 - \psi_1), \\ c_0(1 - \psi_2)^*(1 - \psi_2)/2, \end{cases}$$

and $\psi_1 \equiv 0$ on $\text{supp}(1 - \psi_2)$. We then have

$$\begin{aligned} \frac{1}{2}c_0h \int_X |(1 - \psi_2)u|^2 &\leq h \int_X (a + (\text{Im } z/h)) \overline{(1 - \psi_1)u} \\ &= -\text{Im} \int_X Q(z)u \overline{(1 - \psi_1)u} \\ &= -\text{Im} \int_X f \overline{(1 - \psi_1)u} \\ &\leq \|f\| (\|(1 - \psi_1)u\| + \mathcal{O}(h^\infty) \|u\|) \\ &\leq 2\varepsilon h^{-1} \|f\|^2 + \varepsilon h \|(1 - \psi_1)u\|^2 + \mathcal{O}(h^\infty) \|u\|^2, \end{aligned}$$

where we use the same symbols to denote the operator Weyl quantizing the corresponding functions. Lemma 4.1 can be applied to $Q(z)$ since both the imaginary term $ia(x)h$ and z are lower order terms, and we can choose $Au \stackrel{\text{def}}{=} (1 - \psi_2)u$. Hence

$$\begin{aligned} \|(1 - \psi_1)u\|^2 &\leq C \|f\| \left(\frac{1}{h} \|f\| + \|(1 - \psi_2)u\| + \mathcal{O}(h^\infty) \|u\| \right) \\ &\leq 2 \frac{C}{\varepsilon} h^{-1} \|f\|^2 + C\varepsilon h \|(1 - \psi_2)u\|^2 + \mathcal{O}(h^\infty) \|u\|^2, \end{aligned}$$

which proves (A.2) with ψ_0 replaced by ψ_1 . We can estimate $\|(\psi_0 - \psi_1)u\|$ using Lemma 4.1 which gives (A.2). \square

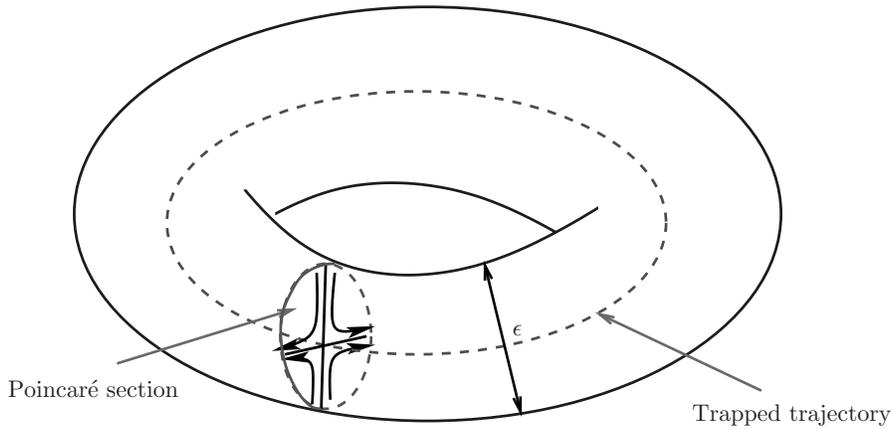


FIGURE 6. A hyperbolic trapped trajectory.

With the help of the above result we have essentially reduced the proof of Theorem A to the proof of the following

Proposition A.2. *With the notation of Proposition A.1 there exist c_0, h_0 , and N_0 such that for u with $WF_h(u)$ in a small neighbourhood of γ , $z \in [1, 2] + i(-c_0h, +\infty)$, and $h < h_0$, we have*

$$\|u\| \leq Ch^{-N_0} \|Q(z)u\|.$$

To prove this, we start with the following essentially well-know geometric lemma (see for instance [21]):

Lemma A.1. *Suppose that $p \in C^\infty(T^*X)$ satisfies $p = 0 \Rightarrow dp \neq 0$ and that $\gamma \subset p^{-1}(0)$ is a closed real hyperbolic orbit of the Hamilton flow of p . There exists a neighbourhood U of γ in T^*X and a symplectomorphism $\kappa : U \rightarrow \kappa(U) \subset T^*\mathbb{S}^1_{(t,\tau)} \times T^*\mathbb{R}^{n-1}_{(x,\xi)}$ such that*

$$(A.3) \quad \begin{aligned} \kappa(\gamma) &= \{(t, 0; 0, 0) : t \in \mathbb{S}^1\}, \quad p = \kappa^*(h + h_3), \\ h(t, \tau; x, \xi) &= \tau + \sum_{j=1}^{n-1} \lambda_j x_j \xi_j, \quad h_3(t, \tau, x, \xi) = \mathcal{O}(|x|^3 + |\xi|^3). \end{aligned}$$

□

The lemma is schematically illustrated in Figure 6 where the axes in the Poincaré section correspond to x and ξ .

Proof of Proposition A.2. In the notation of Lemma A.1 we can assume that $\text{ess-supp } \psi_0 \subset U$ and hence we will work microlocally in that neighbourhood which we identify with the neighbourhood of $\mathbb{S}^1 \times \{(0; 0, 0)\}$ in $T^*\mathbb{S}^1 \times T^*\mathbb{R}^{n-1}$. The principal part of $P(h)$ is then of the form given in (A.3). We will use the same notation for the full symbol of $P(h)$ defined in these coordinates: $P(h) = \text{Op}_h^w(p(\bullet, h))$.

We now follow a method inspired by many previous works on resonances generated by a hyperbolic trajectory; see [3, Section 6.3] for a recent presentation and references (among them [17] and [18], already mentioned above). The aim there was to prove the closely related $\mathcal{O}(h^{-C})$ bounds on resonance projectors. Instead

of using the FBI transform, we follow [14, Section 4.2] and make the presentation essentially self-contained.

We start with a rescaling in (x, ξ) coordinates:

$$(A.4) \quad X = (hM)^{-\frac{1}{2}}x, \quad \Xi = (hM)^{-\frac{1}{2}}\xi, \quad |(X, \Xi)| \leq (hM)^{-\frac{1}{2}}\epsilon,$$

where M is a large constant. Unless specifically stated, all estimates below are uniform in M for $0 < h < h_0(M)$. We note that the unitary transformation

$$(A.5) \quad U_{h,M}u(X) = (hM)^{\frac{n-1}{2}}u((hM)^{\frac{1}{2}}X)$$

conjugates operators $a^w(x, hD_x)$ and $a_{h,M}^w(X, M^{-1}D_X)$,

$$a_{h,M}(X, \Xi) = a((hM)^{\frac{1}{2}}X, (hM)^{\frac{1}{2}}\Xi).$$

Hence,

$$\begin{aligned} \tilde{P}(h) &= U_{h,M}^{-1}P(h)U_{h,M} = U_{h,M}^{-1}\text{Op}_h^w(p^w(t, hD_t, \bullet, h))U_{h,M} \\ &= \text{Op}_{M^{-1}}^w(\tilde{p}^w(t, hD_t, \bullet, h)), \end{aligned}$$

where $\text{Op}_{M^{-1}}^w$ denotes the Weyl quantization in (X, Ξ) variables with h replaced by M^{-1} , and, since the subprincipal symbol of $P(h)$ vanishes,

$$(A.6) \quad \begin{aligned} \tilde{p}(t, \tau; X, \Xi, h) &= \tau + \sum_{j=1}^{n-1} Mh\lambda_j X_j \Xi_j + (hM)^{\frac{3}{2}}\mathcal{O}(|X|^3 + |\Xi|^3) + \mathcal{O}(h^2), \\ |\partial_{X, \Xi}^\alpha \tilde{p}| &\leq C_\alpha \left((hM)^{\frac{1}{2}} + \epsilon / \langle (X, \Xi) \rangle \right)^{|\alpha|}. \end{aligned}$$

In particular, the remainder, $\mathcal{O}(h^2)$, satisfies these estimates multiplied by h^2 .

Let $\psi_0 \in \mathcal{C}_c^\infty(T^*\mathbb{R}^{n-1})$ be supported near $(0, 0)$ and equal to 1 in a smaller neighbourhood of that point. In variables X and Ξ we define the escape function

$$(A.7) \quad \begin{aligned} G(X, \Xi) &\stackrel{\text{def}}{=} \frac{1}{2} \sum_{j=1}^{n-1} (\log(1 + X_j^2) - \log(1 + \Xi_j^2)) \psi_0(h^{\frac{1}{2}}(X, \Xi)), \\ |\partial_X^\alpha \partial_\Xi^\beta G(X, \Xi)| &\leq C_{\alpha\beta} \langle X \rangle^{-|\alpha|} \langle \Xi \rangle^{-|\beta|}, \quad (0, 0) \neq (\alpha, \beta) \in \mathbb{N}^{2(n-1)}, \end{aligned}$$

and also

$$G = \mathcal{O}(\log(1/h)).$$

For $|(X, \Xi)| \leq h^{-\frac{1}{2}}\epsilon$ we also have, using (A.6),

$$\begin{aligned} \frac{1}{hM} H_{\tilde{p}} G &= \frac{1}{hM} \sum_{j=1}^{n-1} \left(\frac{X_j \partial_{\Xi_j}}{1 + X_j^2} + \frac{\Xi_j \partial_{X_j}}{1 + \Xi_j^2} \right) \\ &\quad \times \left(\sum_{j=1}^{n-1} Mh\lambda_j X_j \Xi_j + (hM)^{\frac{3}{2}}\mathcal{O}(|X|^3 + |\Xi|^3) + \mathcal{O}(h^2) \right) \\ &= \sum_{j=1}^{n-1} \left(\frac{\lambda_j X_j^2}{1 + X_j^2} + \frac{\lambda_j \Xi_j^2}{1 + \Xi_j^2} \right) (1 + \mathcal{O}(\epsilon)) + \mathcal{O}(h^{\frac{3}{2}}M^{-\frac{1}{2}}). \end{aligned}$$

We now consider $G^w = \text{Op}_{M^{-1}}^w(G)$ and define

$$\tilde{P}_t(h) = e^{tG^w} \tilde{P}(h) \text{Op}_{M^{-1}}^w(\psi_0(h^{\frac{1}{2}}\bullet)) e^{-tG^w} = \exp(\text{tad}_{G^w}) \tilde{P}(h) \text{Op}_{M^{-1}}^w(\psi_0(h^{\frac{1}{2}}\bullet)),$$

with the exponential defined in the sense of bounded self-adjoint operators.

The Weyl calculus, with the effective Planck constant given by M^{-1} , and using the estimates in (A.6) and (A.7), gives

$$(A.8) \quad [\tilde{P}(h), G^w] = \frac{1}{iM} \text{Op}_{M^{-1}}^w(H_{\tilde{P}}G) + \mathcal{O}(M^{-2}h).$$

In fact, the composition formula holds:

$$\begin{aligned} \text{Op}_{M^{-1}}^w(a) \circ \text{Op}_{M^{-1}}^w(b) &= \text{Op}_{M^{-1}}^w(a\sharp b), \\ a\sharp b(x, \xi) &\sim \sum_{k=0}^{\infty} \frac{1}{k!M^k} (\sigma(D_x, D_\xi; D_y, D_\eta))^k a(x, \xi)b(y, \eta)|_{(x, \xi)=(y, \eta)}, \end{aligned}$$

and the estimates of the remainders follow from the estimates on the individual terms; see [15, Chapter 7]. Similarly, for h small enough and M large and fixed,

$$(A.9) \quad \begin{aligned} \tilde{P}_t(h) &= \exp(t\text{ad}_{G^w})\tilde{P}(h) \text{Op}_{M^{-1}}^w(\psi_0(h^{\frac{1}{2}}\bullet)) \sim \sum_{k=0}^{\infty} \frac{t^k}{k!} \text{ad}_{G^w}^k \left(\tilde{P}(h) \text{Op}_{M^{-1}}^w(\psi_0(h^{\frac{1}{2}}\bullet)) \right), \\ \text{ad}_{G^w}^k \left(\tilde{P}(h) \text{Op}_{M^{-1}}^w(\psi_0(h^{\frac{1}{2}}\bullet)) \right) &= \mathcal{O}_{L^2 \rightarrow L^2}(hM^{1-k}). \end{aligned}$$

Hence, using (A.8),

$$\tilde{P}_t(h) = \tilde{P}(h) - it h A^w + th \mathcal{O}(h + M^{-2}) + \mathcal{O}(t^2 h M^{-1}), \quad A^w = \text{Op}_{M^{-1}}^w(A),$$

where \mathcal{O} is meant in the sense of operators on L^2 and

$$A(X, \Xi) = \sum_{j=1}^{n-1} \left(\frac{\lambda_j X_j^2}{1 + X_j^2} + \frac{\lambda_j \Xi_j^2}{1 + \Xi_j^2} \right) (1 + \mathcal{O}(\epsilon)).$$

We will now show that for M sufficiently large,

$$(A.10) \quad \langle A^w U, U \rangle \geq \frac{c_0}{M} \|U\|^2,$$

which essentially is the lower bound for the harmonic oscillator $(D_X/M)^2 + X^2$. In fact, assuming for simplicity $\lambda_j = 1$ and using the M^{-1} -Weyl calculus, we write

$$A_0(X, \Xi) = \frac{X^2}{\langle X \rangle^2} + \frac{\Xi^2}{\langle \Xi \rangle^2} = |B(X, \Xi)|^2, \quad B = \frac{X}{\langle X \rangle} - i \frac{\Xi}{\langle \Xi \rangle},$$

$$\begin{aligned} A_0^w(X, M^{-1}D_X) &= B^w(X, M^{-1}D_X)^* B^w(X, M^{-1}D_X) + C^w(X, M^{-1}D_X, M^{-1}), \\ C(X, \Xi, M^{-1}) &= M^{-1} \langle X \rangle^{-3} \langle \Xi \rangle^{-3} + \mathcal{O}(M^{-2}). \end{aligned}$$

The C^w term provides control for (X, Ξ) small and the $(B^w)^* B^w$ term gives a lower bound (independent of M) in the rest of phase space, giving (A.10) with A replaced by A_0 . Since the operators differ by an elliptic factor, invertible for M large, (A.10) follows.

Hence for U satisfying $\text{Op}_{M^{-1}}^w(\psi_0(h^{\frac{1}{2}}\bullet))U = U + \mathcal{O}(h^\infty)$ we see that

$$-\text{Im} \langle \tilde{P}_t(h)U, U \rangle \geq \frac{h}{C_1 M} \|U\|^2.$$

Translating this to estimates for the original operator shows that for u with $WF_h(u)$ in a small neighbourhood of γ , we have

$$-\text{Im} \langle e^{tB_h}(P(h) - z)e^{-tB_h}u, u \rangle \geq \frac{h}{C_2} \|u\|^2, \quad z \in [1, 2] + i(-c_0 h, +\infty),$$

where $B_h = \mathcal{O}(\log(1/h))$ comes from transplanting G^w to the original coordinates by the unitary transformation described after (A.4). Since $\|\exp(\pm tB_h)\| = \mathcal{O}(h^{-N})$ for some N , the proposition follows. \square

To prove Theorem A, we need the following lemma which, for possible future use, we state in a slightly excessive generality:

Lemma A.2. *Suppose that A and B are bounded self-adjoint operators on a Hilbert space \mathcal{H} ,*

$$A^2 = A, \quad BA = AB = A,$$

and $F(z)$ is a family of bounded operators satisfying

$$(A.11) \quad \begin{aligned} F(z)^* &= F(\bar{z}), \quad \partial_z F|_{\mathbb{R}} \geq cId, \quad c > 0, \\ BF(z)^{-1}B &\text{ is holomorphic in } [-\epsilon, \epsilon] + i[-\delta, \delta], \quad \frac{\delta}{\epsilon} \ll 1/\log M, \\ \|BF(z)^{-1}B\| &\leq M, \quad \|AF(z)^{-1}A\| \leq 1. \end{aligned}$$

Then for $|z| < \epsilon/2, \text{Im } z = 0$ we have

$$(A.12) \quad \|BF(z)^{-1}B\| \leq C \frac{\log M}{\delta}, \quad \|BF(z)^{-1}A\| \leq C \sqrt{\frac{\log M}{\delta}}.$$

Proof. The first part of (A.12) works exactly as in [40, Lemma 2] and [7, Lemma 4.2]. To see the improved version, we start by observing that the conditions on F and A imply that for $\text{Im } z > 0$, small,

$$\text{Im } z \|u\|^2 \leq C \text{Im} \langle F(z)u, u \rangle.$$

If now $F(z)u = Af$, then by the assumptions on F , $\|Au\| \leq \|Af\|$, and consequently,

$$\|Bu\|^2 \leq C \|u\|^2 \leq \frac{1}{\text{Im } z} \langle Af, Au \rangle \leq \frac{1}{\text{Im } z} \|Af\|^2.$$

Here we used the facts that $A^2 = A = A^*$. Since $u = F(z)^{-1}Af$, this and the fact that $BA = A$ give

$$\begin{aligned} \|BF(z)^{-1}A\| &\leq \frac{C}{\sqrt{\text{Im } z}}, \quad \text{Im } z > 0, \\ \|BF(z)^{-1}A\| &\leq C \|BF(z)^{-1}B\| \leq CM. \end{aligned}$$

Interpolating as before gives (A.12). \square

Proof of Theorem A. We first combine Propositions A.1 and A.2 to see that

$$\begin{aligned} \|(1 - \psi_0)u\| &\leq Ch^{-1} \|Qu\| + \mathcal{O}(h^\infty) \|u\|, \\ \|\psi_0 u\| &\leq Ch^{-N} \|\psi_0 Qu\| + Ch^{-N} \|[Q, \psi_0]u\| \leq C'h^{-N} \|Qu\| + \mathcal{O}(h^\infty) \|u\|, \end{aligned}$$

where we used the fact that $\|[Q, \psi_0]u\| = \|[Q, \psi_0](1 - \tilde{\psi}_0)u\| + \mathcal{O}(h^\infty) \|u\|$, for some $\tilde{\psi}_0$ satisfying the assumptions of Proposition A.1.

Finally we combine this latter estimate and (A.2) with Lemma A.2 applied to the family of operators $w \mapsto F(w) = (i/h)Q(z_0 + hw)$ and $A = \mathbb{1}_{\text{supp } \phi}, B = 1$. We can take δ independent of h and $\epsilon = 1/(Ch)$ so that the assumption $\delta/\epsilon \ll 1/\log(1/h^N)$ is satisfied. \square

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