A SYMMETRIC COEFFICIENT OF CORRELATION FOR SEVERAL VARIABLES*

BY DUNHAM JACKSON

Let \((x_1, x_2, \ldots, x_n)\) and \((y_1, y_2, \ldots, y_n)\) be two sets of \(n\) real numbers each, neither set consisting entirely of zeros. In order that the ensuing use of technical terms may be in accordance with established practice, let it be supposed that

\[
\sum x_k = \sum y_k = 0,
\]

though the mathematical relations to be considered are in themselves not dependent on this hypothesis. The coefficient of correlation between the \(x\)'s and the \(y\)'s, defined by the formula

\[
r = \frac{\sum x_k y_k}{\sqrt{\sum x_k^2 \sum y_k^2}},
\]

may be regarded as a measure of the degree of resemblance of the two given sets of numbers, and may be interpreted as the cosine of the angle \(POQ = \theta\), if \(O, P, Q\) represent respectively the origin, the point with coordinates \((x_1, x_2, \ldots, x_n)\), and the point \((y_1, y_2, \ldots, y_n)\), in space of \(n\) dimensions.†

Let a third set of real numbers \((z_1, z_2, \ldots, z_n)\) be given, not all zero (and subject, let us say, to the condition \(\sum z_k = 0\)). There may sometimes be occasion to consider a measure of the degree of resemblance of the three sets \((x_k), (y_k), \text{and} (z_k)\), not an asymmetric measure of the dependence of a specified set on the other two, as in the case of a coefficient of double correlation, but a formula

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† For an elementary exposition of this idea, and for bibliographical references, see a paper by the author entitled *The trigonometry of correlation*, American Mathematical Monthly, vol. 31 (1924), pp. 275–280.
treating all three sets alike.* Such a formula will be dis-
cussed in the following pages. Some theoretical advantages
belonging to it will appear in the course of the discussion;
its practical utility must naturally await the test of ex-
perience. If it has already been treated elsewhere, as is
not unlikely, the writer hopes that the present exposition
may nevertheless serve a useful purpose in giving it wider
publicity.

Without loss of generality, it may be assumed that the
given sets of numbers are normalized, so that

$$\sum x_k^2 = \sum y_k^2 = \sum z_k^2 = 1.$$ 

Then the points $P$ and $Q$, and the point $R$ with coordinates
$(x_1, x_2, \ldots, x_n)$, are on the surface of a sphere of unit radius
about the origin. The discussion is concerned with the
degree of propinquity of these three points. As the corre-
lation of the first two sets of numbers is measured by
means of the angle $POQ$, there would be a certain analogy
in making use, at the next stage, of the solid angle $O-PQR$,
or, in other words, of passing from the length of the arc
$PQ$ to the area of the spherical triangle $PQR$ as a
quantitative indication. But the area of the triangle is
zero whenever the three points lie on the same great
circle, whether the points themselves are close together
or widely separated, so that it seems necessary to look
further for a satisfactory definition.

Let $S$ be the middle point of the chord $PQ$. The value
of the coefficient of correlation $r$ can of course be expressed
in terms of the angle $\Phi = \frac{1}{2} \theta = POS$, the relation being

$$r = \cos \theta = \cos 2\Phi = 2 \cos^2 \Phi - 1.$$ 

The extreme limiting values of $\cos \Phi$, for all possible
positions of $P$ and $Q$, are not $-1$ and $1$, as in the case
of $\cos \theta$, but $0$ and $1$. As $\cos \Phi = OS$ is the perpendi-

* This problem was suggested to the writer by a study of the
distribution of freshman grades, in which Professor W. H. Bussey was
engaged.
cular distance of the chord $PQ$ from $O$, an analogous quantity in some respects would be the distance from $O$ to the plane of $P$, $Q$, and $R$. But a knowledge of this quantity would scarcely give the kind of information that is desired, since the distance is zero whenever the three points are on the same great circle, and may be either zero or arbitrarily near unity for three points arbitrarily close to each other, becoming wholly indeterminate between these limits in the one case for which an unmistakable characterization is most essential, the case of actual coincidence of $P$, $Q$, and $R$.

It seems more instructive to regard $OS$ as the distance from $O$ to the center of gravity of the points $P$ and $Q$, regarded as material particles of equal weight. Let $T$ be defined as the center of gravity of $P$, $Q$, and $R$, and let $\bar{r}_1 = OT$. This $\bar{r}_1$ is 1 if and only if the three points are coincident; it is 0 if and only if they are situated on a great circle at angular distances of 120° from each other; and it has a value intermediate between 0 and 1 in all other cases. A formal expression for it is readily calculated. The coordinates $(w_1, w_2, \cdots, w_n)$ of $T$ are given by

$$w_k = \frac{1}{3}(x_k + y_k + z_k),$$

so that $\bar{r}_1 = \sqrt{w_1^2 + w_2^2 + \cdots + w_n^2}$

$$= \frac{1}{3}\sqrt{\sum x_k^2 + \sum y_k^2 + \sum z_k^2 + 2\sum x_k y_k + 2\sum x_k z_k + 2\sum y_k z_k}.$$ 

In consequence of the hypothesis that the $x$'s, $y$'s, and $z$'s are normalized, the sums of squares under the last radical are each equal to 1, and the product sums are the respective coefficients of correlation $r_{12}$, $r_{13}$, $r_{23}$ of the given sets of numbers, taken two sets at a time. That is,

$$\bar{r}_1 = \frac{1}{3}\sqrt{3 + 2r_{12} + 2r_{13} + 2r_{23}}.$$ 

Taken on its own merits, independently of any geometric interpretation, this formula defines a number which is mani-
festly subject to the inequalities \(0 \leq r_1 \leq 1\), since the radical is of course to be taken as positive or zero, and none of the numbers \(r_{12}, r_{13}, r_{23}\) can exceed 1; the quantity under the radical sign is equal to 9 if \(r_{12} = r_{13} = r_{23} = 1\), is 0 if* \(r_{12} = r_{13} = r_{23} = -\frac{1}{2}\), and can never be negative,† since it is equal to \(9 \sum w_k^2\).

A measure somewhat more closely analogous to the ordinary coefficient of correlation, and slightly easier to compute, the measure which it is the main purpose of this paper to suggest, is related to \(\tilde{r}_1\) as \(\cos \theta\) is related to \(\cos \phi\), and is defined by the formula

\[
\tilde{r} = 2r_1^2 - 1 = \frac{4}{9} (r_{12} + r_{13} + r_{23}) - \frac{1}{3}.
\]

From its dependence on \(\tilde{r}_1\), it ranges between the extreme values \(-1\) and \(+1\), the latter value signifying perfect correlation of all three of the given sets of quantities. It is simply a linear function of the "average coefficient of correlation" of the given sets, adjusted so as to have \(-1\) and \(+1\) for its extremes; this adjustment, however, appears from the above treatment not as a mere piece of algebraic formalism, but as a natural corollary of simple geometric relations.

When there are \(m\) variables instead of three, that is, \(m\) given (normalized) sets of \(n\) quantities each, the notation is to be changed by letting \((w_1, \cdots, w_m)\) stand for the co-

* These relations, together with the conditions \(\Sigma x_i - \Sigma y_i = \Sigma z_i = 0\), are satisfied if, for example, the \(x\)'s, \(y\)'s and \(z\)'s are respectively

\[
\left(\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}, 0, \cdots, 0\right), \quad \left(-\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}, \cdots, 0\right),
\]

\[
\left(0, \frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}, \cdots, 0\right),
\]

all the entries after the first three being zero in each parenthesis.

† In particular, such a combination as \(r_{12} = r_{13} = r_{23} = -1\) is impossible; it is readily seen that if \(r_{12} = r_{13} = -1\), the third coefficient \(r_{23}\) must necessarily be \(+1\).
ordinates of the center of gravity of the $m$ corresponding points of the unit sphere, so that

$$w_k = \frac{1}{m}(x_k + y_k + z_k + \cdots), \quad (k = 1, 2, \cdots, n);$$

$$\bar{r}_1 = \sqrt{\sum w_k^2} = \frac{1}{m}\sqrt{m + 2\sum r_{ij}},$$

$$\bar{r} = 2\bar{r}_1^2 - 1 = \frac{4}{m^2}\sum r_{ij} - \frac{m - 2}{m}.$$

The quantities $r_{ij}$ are once more the coefficients of correlation of two sets at a time of the given $m$ sets of numbers, supposed subject to the conditions

$$\sum x_k = \sum y_k = \sum z_k = \cdots = 0.$$

It is readily seen, both algebraically and quasi-geometrically, that $\bar{r}$ varies from the value $-1$ at one extreme to the value $+1$, denoting perfect correlation, at the other.

It is well known that the center of gravity of a system of particles corresponds to the solution of a simple problem in least squares. If the particles are of equal weight, as is assumed to be the case here, the center of gravity is the point so situated that the sum of the squares of the distances of the various particles from it is a minimum. Something analogous to the idea of least squares can be made apparent in the present connection under a slightly different form.

Since $\cos \theta$ is approximately equal to $1 - \frac{1}{2} \theta^2$, when $\theta$ is small, the minimizing of a sum of squares may be looked upon as related to the problem of making a sum of cosines a maximum. Let $(\mu_1, \mu_2, \cdots, \mu_n)$ be the direction cosines of an arbitrary line $OM$, that is, an arbitrary set of $n$ numbers subject to the condition $\mu_1^2 + \mu_2^2 + \cdots + \mu_n^2 = 1$. If the point $M$ is taken at unit distance from the origin, the numbers $\mu_k$ will be its coordinates. Let the angles $POM, QOM, \cdots$, be denoted by $\varphi_1, \varphi_2, \cdots$, and let the problem be proposed of determining the $\mu$'s so that

* It is not assumed that $\sum \mu_k = 0$. 
\[ \cos \varphi_1 + \cos \varphi_2 + \cdots + \cos \varphi_m \text{ shall be a maximum. } \]
\[
\cos \varphi_1 = x_1 \mu_1 + x_2 \mu_2 + \cdots + x_n \mu_n,
\]
etc., the quantity \( s \) to be made a maximum is
\[
s = (x_1 + y_1 + \cdots) \mu_1
+ (x_2 + y_2 + \cdots) \mu_2 + \cdots + (x_n + y_n + \cdots) \mu_n
= m(w_1 \mu_1 + w_2 \mu_2 + \cdots + w_n \mu_n),
\]
or, if \( \lambda_k \) denotes the \( k \)th direction cosine of the line from \( O \) to the center of gravity\(^*\) \( T \),
\[
\lambda_k = \frac{w_k}{\sqrt{w_1^2 + w_2^2 + \cdots + w_n^2}} = \frac{w_k}{\nu_1},
\]
then
\[
s = m\nu_1 (\lambda_1 \mu_1 + \lambda_2 \mu_2 + \cdots + \lambda_n \mu_n).
\]
The last parenthesis is the cosine of the angle \( TOM \), and can not exceed 1, being equal to 1 when \( \mu_k = \lambda_k \), that is, when the line \( OM \) is drawn through \( T \). So \( OT \) is determined as the line for which the sum of cosines is greatest. The maximum value of the sum is seen to be \( m\nu_1 \).

As \( \cos \varphi_i \) is equal to
\[
1 - 2 \sin^2 \left( \frac{1}{2} \varphi_i \right),
\]
it can also be said that the sum of the squares of the sines of the half angles has been made a minimum, and hence that there has been literally a solution of a problem in least squares. Let \( L \) denote the point with coordinates \((\lambda_1, \lambda_2, \cdots, \lambda_n)\), where the line \( OT \) pierces the unit sphere, and let \( \varphi_1, \varphi_2, \cdots \), now stand for the angles \( POL, QOL, \cdots \). Then \( 2 \sin \left( \frac{1}{2} \varphi_i \right) \) is the length of the chord \( LP \), etc., and \( L \) is determined on the surface of the sphere as the point for which the sum of the squares of the rectilinear distances from \( P, Q, \cdots \), is a minimum. If these distances from \( P, Q, \cdots \), to \( L \) are denoted by \( d_1, d_2, \cdots \),

\(^*\) The problem becomes indeterminate in the limiting case in which \( T \) falls at the origin.
\[ \sum_{i=1}^{m} q_i^2 = 4 \sum_{i=1}^{m} \sin^2 q_i = 2 \sum_{i=1}^{m} (1 - \cos q_i) = 2(m - m\bar{r}_1), \]

and \( \bar{r}_1 \) has the value

\[ \bar{r}_1 = 1 - \frac{1}{2m} \sum_{i=1}^{m} q_i^2. \]

But this reckoning does not seem to lead to any particularly simple geometric interpretation for \( \bar{r} \). It may turn out, in some circumstances at least, that \( \bar{r}_1 \) is the more significant measure after all.

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METHODS FOR FINDING FACTORS OF LARGE INTEGERS*

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1. Introduction. We shall examine, in this paper, the problem of finding factors of integers beyond the range of Lehmer's factor tables, by methods shorter than that of dividing the integer by all the primes less than its square root.

Three methods will be proposed here. The first two depend on the representation of the integer as a definite quadratic form, and the third on the representation as an indefinite quadratic form. As I hope to devote another paper to the development of the last two methods, only outlines and a few examples will be given in connection with them.

The theory of quadratic forms has been applied in several different ways to the problem.†

In particular, Seelhoff‡ gave an expeditious method with the use of tables, which, however, is limited in application,

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