A Construction of Nonnegative Approximate Quadratures*

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1. Introduction. In a paper which appeared in 1957, V. Tchakaloff [1] proved the following theorem. Let \( B \) be a closed bounded set in the plane with positive area. Let \( \phi_1, \phi_2, \ldots, \phi_N \) be \( N \) linearly independent and continuous functions of \( x, y \) in \( B \), of which one does not vanish in \( B \). Then we can find \( N \) points \( P_i: (x_i, y_i) \) lying in \( B \) and \( N \) weights \( w_i \geq 0 \) such that

\[
\iint_B \phi_j dx dy = \sum_{i=1}^{N} w_i \phi_j(P_i), \quad j = 1, 2, \ldots, N.
\]

Tchakaloff's demonstration is a very beautiful one, involving the theory of convex bodies. A separating hyperplane is employed and a nonconstructive proof is obtained. The theorem is valid for weighted integrals of dimension \( d \geq 1 \).

Equivalent results on finite moment spaces were obtained earlier by various authors. See, e.g., Karlin and Studden [2, Chapter II]. Tchakaloff's independent work appears to be the first to formulate the result explicitly as in (1.1), thereby stressing its numerical analysis aspect.

This result is interesting for numerical analysis because: (1) Quadrature rules with nonnegative weights are more favorable than rules with mixed weights in that they lead to more stable computations; (2) Interpolating quadrature formulas determined by brute force methods do not often yield weights that are of one sign.

The purpose of the present paper is to give an alternative proof of Tchakaloff's theorem which is constructive in its nature. The present proof is also a more "elementary" one than Tchakaloff's in that it makes use only of the familiar raw materials of elementary numerical analysis.

Extensions and numerical applications will be published subsequently by the author and by M. W. Wilson.

2. An Alternate Proof of Tchakaloff's Theorem. In this proof we limit ourselves to integrals of dimension \( d = 2 \) and to functions \( \phi_1, \phi_2, \ldots, \phi_N \) that are monomials (i.e., powers) in \( x, y \). This limitation will still enable us to exhibit the essential features of the method.

We begin with a number of very simple lemmas.

Lemma 1. Let \( \phi_1(x, y) = 1, \phi_2(x, y) = x, \phi_3(x, y) = y, \phi_4(x, y) = x^2, \phi_5(x, y) = xy, \phi_6(x, y) = y^2, \ldots \) be an arrangement of the powers \( x^i y^j, 0 \leq i, j < \infty \). For any integer \( N \geq 1 \), the functions \( \phi_1, \ldots, \phi_N \) are linearly independent. That is, if \( f(x, y) = \sum_{i=1}^{N} a_i \phi_i(x, y) = 0 \) in a region \( R \), then \( a_i = 0 \), \( i = 1, 2, \ldots, N \).

Proof. Call \( m+n \) the degree of the monomial \( x^m y^n \). We have \( \partial^{m+n} x^m y^n / \partial x^m \partial y^n = m! n! \), and \( \partial^{m+n} x^m y^n / \partial x^m \partial y^n = 0 \) if \( m' + n' = m + n \) but \( (m', n') \neq (m, n) \), or if

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m' + n' < m + n. Assume that \( f \equiv 0 \) in \( R \). Now let \( a_j x^m y^n \) be a monomial of highest degree in \( f \). Then, \( \partial^{m'+f}/\partial x^m \partial y^n \equiv 0 = a_j m' n' \). Hence \( a_j = 0 \). Now iterate this process and conclude that all the coefficients vanish.

**Corollary.** If \( \sigma_N \) designates the linear space of functions \( \sum_{i=1}^{N} a_i \phi_i \), then \( \sigma_N \) is of dimension \( N \).

**Lemma 2.** Let \( B \) be a region in the \( x, y \) plane. Then, we can find points \( P_1 = (x_1, y_1), \ldots, P_N = (x_N, y_N) \) in \( B \) such that

\[
\begin{vmatrix}
\phi_1(P_1) & \phi_2(P_1) & \cdots & \phi_N(P_1) \\
\vdots & & & \vdots \\
\phi_1(P_N) & \phi_2(P_N) & \cdots & \phi_N(P_N)
\end{vmatrix} \neq 0.
\]

**Proof.** Select any point in \( B \) as \( P_1 \). Then \( \phi_1(P_1) \neq 0 \). Consider the function

\[
\begin{vmatrix}
\phi_1(P_1) & \phi_2(P_1) \\
\phi_1(P) & \phi_2(P)
\end{vmatrix} = g(P).
\]

This is a linear combination of \( \phi_1(P) \) and \( \phi_2(P) \). If \( g(P) \equiv 0 \) in \( B \), it would follow from Lemma 1 that \( \phi_1(P_1) = 0 \) and \( \phi_2(P_1) = 0 \). This is impossible. Hence there is a \( P_2 \) such that \( g(P_2) \neq 0 \). Consider next the function

\[
\begin{vmatrix}
\phi_1(P_1) & \phi_2(P_1) & \phi_3(P_1) \\
\phi_1(P_2) & \phi_2(P_2) & \phi_3(P_2) \\
\phi_1(P) & \phi_2(P) & \phi_3(P)
\end{vmatrix} = h(P).
\]

This is a linear combination of \( \phi_1(P) \), \( \phi_2(P) \), \( \phi_3(P) \). If \( h(P) \equiv 0 \), all coefficients would be zero. But the coefficient of \( \phi_3(P) \) is \( g(P_2) \neq 0 \). In this way we may proceed step by step.

It should be observed that if \( Q_1, \ldots, Q_N \) are \( N \) distinct points in \( B \), it does not necessarily follow (as in the case of polynomials of one variable) that \( |\phi_i(Q_j)| \neq 0 \). However, the following may be asserted.

**Corollary.** Given \( N \) points \( Q_1, Q_2, \ldots, Q_N \) in \( B \), and given \( \epsilon > 0 \). Then we can find \( N \) points \( P_1, P_2, \ldots, P_N \) such that \( |Q_i - P_i| \leq \epsilon, i = 1, 2, \ldots, N \) and \( |\phi_i(Q_j)| \neq 0 \).

**Proof.** Select \( P_1 = Q_1 \). The above argument for \( g(P) \) yields a point \( P_2 \) in any neighborhood of \( Q_2 \) such that \( g(P_2) \neq 0 \). We may now proceed step by step.

**Lemma 3.** Given a rectangle \( R: x_1 \leq x \leq x_2, y_1 \leq y \leq y_2 \) and a fixed integer \( N \geq 1 \). We can find an integer \( k(N) \) and \( k(N) \) points \( P_1, P_2, \ldots, P_{k(N)} \), and \( k(N) \) weights \( w_1 > 0, w_2 > 0, \ldots, w_{k(N)} > 0 \) such that

\[
\int_R f(x,y) \; dx \; dy = \sum_{i=1}^{k(N)} w_i \phi_j(P_i), \quad j = 1, 2, \ldots, N.
\]

**Proof.** This can be accomplished in many ways. For example, one can use a product rule of Gauss rules of sufficiently high order. To be more specific, let the highest power of \( x \) and \( y \) in \( \phi_1, \phi_2, \ldots, \phi_N \) be respectively \( p(N) \) and \( q(N) \). Determine \( p^*(N) \) and \( q^*(N) \) such that \( 2p^*(N) - 1 \geq p(N) \) and \( 2q^*(N) - 1 \geq q(N) \). Set \( k(N) = p^*(N)q^*(N) \) and form the product rule of Gauss rules of order \( p^*(N) \) in \( x \) and \( q^*(N) \) in \( y \). This product rule will integrate over \( R \) exactly all monomials \( x^i y^j, 0 \leq i \leq 2p^* - 1, 0 \leq j \leq 2q^* - 1 \), and a fortiori \( \phi_1, \phi_2, \ldots, \phi_N \). The points
\[ P_1, P_2, \ldots \] are \((x_\alpha, y_\beta)\) where \(\{x_\alpha\}\) and \(\{y_\beta\}\) are the Gaussian abscissas along the \(x\) and \(y\) axes respectively. The weights are products of Gaussian weights and hence are positive.

**Corollary.** By taking Gauss rules of odd order, one of the points \(P_i\) will be the center of the rectangle.

**Lemma 4.** Given a region \(B\) and \(N\) distinct points \(P_1, P_2, \ldots, P_N\) lying in the interior of \(B\). Then we can find \(N\) squares \(S_i; x_{1i} \leq x \leq x_{2i}, y_{1i} \leq y \leq y_{2i}, i = 1, 2, \ldots, N_\), sufficiently small and placed in such a manner that
\[
\begin{align*}
(a) \quad & S_i \subset B, \\
(b) \quad & S_i \cap S_j = 0 \text{ if } i \neq j.
\end{align*}
\]
**Proof.** Take, e.g., \(P_i\) as the center of the squares and take the diameter of the squares less than \(\frac{1}{2} \min_{1 \leq i, j \leq N} |P_i - P_j|\).

**Lemma 5.** Given a bounded region \(B\) and \(N\) distinct points \(P_1, P_2, \ldots, P_N\) in \(B\). Given a \(\delta > 0\). Then we can find an integer \(s (s = s(B; P_1, \ldots, P_N; \delta))\) and \(s\) rectangles \(R_1, R_2, \ldots, R_s\) with sides parallel to the \(x\) and \(y\) axes such that
\[
\begin{align*}
(a) \quad & \text{The } R_i \text{ include the squares } S_i \text{ already constructed in Lemma 4,} \\
(b) \quad & R_i \subset B, \\
(c) \quad & R_i \cap R_j = 0 \text{ if } i \neq j, \\
(d) \quad & \text{area } B - \sum_{i=1}^{s} \text{area } R_i \leq \delta.
\end{align*}
\]
**Proof.** Take \(R_1 = S_1, \ldots, R_N = S_N\). For the remaining rectangles, pack \(B - \bigcup_{i=1}^{N} S_i\) with nonoverlapping rectangles sufficiently densely so that the area of \(B\) is approximated by \(\sum_{i} \text{area } R_i\) to within \(\delta\). The exact details here do not have to be spelled out.

**Remark.** If \(N\) is held fixed but if \(\delta \rightarrow 0\), note that the first \(N\) rectangles, the first of which contains \(P_1\), the second \(P_2\), etc., may be kept fixed.

**Theorem.** Let \(B\) be a bounded region in the \(x-y\) plane. Let \(N \geq 1\) be fixed. Then we can find points \(T_1, T_2, \ldots, T_N\) in \(B\) and nonnegative weights \(w_1, w_2, \ldots, w_N\) such that
\[
\int_{B} \phi dx dy = \sum_{i=1}^{N} w_i \phi(T_i), \quad j = 1, 2, \ldots, N.
\]
**Proof.** I. Select \(N\) points \(P_1, \ldots, P_N\) in \(B\) such that \(|\phi_i(P_j)| \neq 0\). This is possible by Lemma 2. Pack \(B\) with rectangles \(R_1, R_2, \ldots, R_s\) as in Lemma 5. The relevant \(\delta\) will be specified shortly. The first \(N\) rectangles will be squares \(S_1, \ldots, S_N\). Over each rectangle \(R_i\), define a positive quadrature rule as in Lemma 3. In \(S_1, \ldots, S_N\) make sure that one of the nodal points in the respective squares is the center of the square, i.e., \(P_i\), where \(i = 1, 2, \ldots, N\).

Let \(u_i, U_i (i = 1, 2, \ldots, n)\) designate the weights and respective locations that occur in all the rules defined over all the rectangles. Note that \(u_i > 0\). Note further that we may arrange the order so that \(U_1 = P_1, U_2 = P_2, \ldots, U_N = P_N\).

For any matrix \(A = (a_{ij})\), let \(||A||\) designate the matrix norm \(\max_i \sum_j |a_{ij}|\) and for a vector \(v = (v_1, \ldots)\) let \(||v||\) designate the compatible vector norm \(\max_i |v_i|\). Let \(M = \max_{1 \leq i \leq N} \sup_{P \in B} |\phi_j(P)|\). Now select \(\delta\) such that
\[
0 < \delta < \min_{1 \leq i \leq N} \frac{u_i}{M ||(\phi_j(P_i))||^{-1}}.
\]
Use such a value of $\delta$ in packing $B$ with rectangles. (Note the order of procedure here. $N$ is given. Determine $P_1, \cdots, P_N$. Put squares $S_i$ around $P_i$, $i = 1, 2, \cdots, N$, and in each square define a product Gauss rule of which one node is $P_i$ and the corresponding weight is $u_i$. Next determine $\delta$ from (2.4) and use it to form a packing of $B$ by rectangles into which we also insert a positive quadrature.)

If $R = \bigcup_{i=1}^{\infty} R_i$, we have

\[(2.5) \quad \iint_R \phi_j \, dx \, dy = \sum_{i=1}^n u_i \phi_j(U_i), \quad j = 1, 2, \cdots, N.\]

Let

\[(2.6) \quad \epsilon_j = \iint_B \phi_j \, dx \, dy - \iint_R \phi_j \, dx \, dy, \quad j = 1, 2, \cdots, N.\]

Then,

\[(2.7) \quad |\epsilon_j| \leq \iint_{B-R} |\phi_j| \, dx \, dy \leq M \iint_{B-R} dxdy \leq M\delta, \quad j = 1, 2, \cdots, N.\]

Now (2.5) can be rewritten as

\[(2.8) \quad \iint_B \phi_j \, dx \, dy - \epsilon_j = \sum_{i=1}^n u_i \phi_j(P_i) + \sum_{i=N+1}^n u_i \phi_j(U_i).\]

Now consider the $N \times N$ system in variables $t = (t_1, \cdots, t_N)$

\[(2.9) \quad \sum_{i=1}^N t_i \phi_j(P_i) = \epsilon_j, \quad j = 1, 2, \cdots, N.\]

If $\epsilon = (\epsilon_1, \epsilon_2, \cdots, \epsilon_N)'$, (2.9) has the solution

\[(2.10) \quad t = \left[\phi_j(P_i)\right]^{-1} \epsilon\]

and hence by (2.7) and (2.4),

\[(2.11) \quad \|\zeta\| \leq \left\|\left[\phi_j(P_i)\right]^{-1}\right\| \|\epsilon\|\]

\[\leq \left\|\left[\phi_j(P_i)\right]^{-1}\right\| M\delta\]

\[< \min_{1 \leq i \leq N} u_i.\]

Hence,

\[(2.12) \quad \max_{1 \leq i \leq N} |t_i| < \min_{1 < i < N} u_i.\]

Combining (2.9) and (2.8) we obtain

\[(2.13) \quad \iint_B \phi_j \, dx \, dy = \sum_{i=1}^N (u_i + t_i) \phi_j(P_i) + \sum_{i=N+1}^n u_i \phi_j(U_i)\]

\[= \sum_{i=1}^n u_i' \phi_j(U_i), \quad j = 1, 2, \cdots, N,\]

where, in view of (2.12), $u_i' > 0$.

II. The object of part I was to produce a quadrature formula (2.13) with posi-
tive weights. The abscissas or nodes are \( U_1, U_2, \cdots, U_n \), where \( n \) may be very much larger than \( N \). We shall next show that we may reduce \( n \) to \( N \) by using an appropriate subset of \( \{ U_i \} \). This can be done by a method of E. Steinitz [3].

The linear space \( \Phi_N \) of functions \( \sum_{i=1}^N a_i \phi_i \) defined on a region \( R \) is of dimension \( N \). Hence, the algebraic dual space (the space of all linear functionals defined on \( \Phi_N \)) is also of dimension \( N \). Among the \( n \) linear functionals
\[
L_i(f) = f(U_i)
\]
at most \( N \) can be linearly independent. Hence if \( n > N \), we must have
\[
a_1L_1 + \cdots + a_nL_n = 0
\]
where not all the \( a \)'s vanish and, in fact, one of the \( a \)'s may be assumed to be positive. Define
\[
L = u_1'L_1 + u_2'L_2 + \cdots + u_n'L_n , \quad (u_i' > 0)
\]
where the \( u_i' \) are from (2.13), and set
\[
(2.17) \quad \sigma = \max_{1 \leq i \leq n} \frac{a_i}{u_i'} .
\]
Note that \( \sigma > 0 \), \( \sigma u_i' - a_i \geq 0 \), and furthermore, \( \sigma u_i' - a_i = 0 \) for at least one \( i \).

From (2.16) and (2.15) we obtain
\[
(2.18) \quad L = \frac{\sigma u_1' - a_1}{\sigma} L_1 + \frac{\sigma u_2' - a_2}{\sigma} L_2 + \cdots + \frac{\sigma u_n' - a_n}{\sigma} L_n .
\]

Thus, \( L \) has been expressed as a linear combination of at most \( n-1 \) of \( L_1, \cdots, L_n \) with nonnegative coefficients. Iterating this process, we arrive at
\[
(2.19) \quad L = w_1L_1 + w_2L_2 + \cdots + w_NL_N , \quad w_i \geq 0 .
\]
Hence, from (2.13)
\[
(2.20) \quad \int_B \phi_i dx dy = \sum_{i=1}^N w_i \phi_i(U_i') , \quad w_i \geq 0 , \quad j = 1, 2, \cdots, N ,
\]
where the \( U_i' (i = 1, 2, \cdots, N) \) are a subset of \( U_i (i = 1, 2, \cdots, n) \).