A Quadratic Formula for Finding the Root of an Equation

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Abstract. An extension is made to Reguli Falsi involving a parabolic approximation. Formulae are derived which have convergence exponents 2, 2.414, 2.732, respectively.

1. Introduction. Let \((a, A), (b, B), (c, C)\) be three points on the curve \(y = f(x)\). The parabola passing through these three points whose axis is parallel to the \(x\)-axis is given by

\[
\frac{y}{(v - B)(v - C)} = \frac{(v - A)(v - C)}{(A - B)(A - C)} + \frac{(v - A)(v - B)}{(B - C)(B - A)} + \frac{(v - A)(v - B)}{(C - A)(C - B)}.
\]

The value of \(x\), denoted by \(d\), at which \(y\) vanishes is given by

\[
d = \frac{aBC}{(A - B)(A - C)} + \frac{bCA}{(B - C)(B - A)} + \frac{cAB}{(C - A)(C - B)}.
\]

Suppose that \(\xi\) is a root of the equation \(f(x) = 0\) and suppose that \(a = \xi + \alpha, b = \xi + \beta, c = \xi + \gamma\) are approximations to the root. Then, if \(d = \xi + \delta\), it can easily be seen that

\[
\delta = \frac{\alpha BC}{(A - B)(A - C)} + \frac{\beta CA}{(B - C)(B - A)} + \frac{\gamma AB}{(C - A)(C - B)}
\]

\[
= \alpha \delta \gamma (P - Q + P^3)\{1 + \text{terms of higher order}\},
\]

where \(P = f''(\xi)/2f'(\xi), Q = f'''(\xi)/6f'(\xi)\). Thus

\[
\delta = K \alpha \delta \gamma, \text{ where } K \text{ is a constant.}
\]

Many iterative formulae have been obtained for the solution of the equation \(f(x) = 0\), and these are readily available [2], [3]. It is the purpose of this note to indicate certain new iterative formulae which can be derived using Eq. (1.2). The associated order of convergence will be given by Eq. (1.4). Obviously the method will not be applicable for a double root, as in this case, the associated curve touches the \(x\)-axis and lies only on one side of it and cannot be approximated by a representation of \(x\) as a polynomial in \(y\). For the same reason, it is clear that it is necessary for the root to be isolated.

2. Iterative Formulae.
(a) Third Order Iteration. The obvious iterative sequence to consider in connec-

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tion with formula (1.2) is the third-order iteration defined by \( a = x_{n-2}, b = x_{n-1}, c = x_n, d = x_{n+1} \):

\[
x_{n+1} = \frac{x_{n-2}y_{n-1}y_n}{(y_{n-2} - y_{n-1})(y_{n-2} - y_n)} + \frac{x_{n-1}y_{n-2}y_n}{(y_{n-1} - y_n)(y_{n-1} - y_{n-2})} + \frac{x_ny_{n-2}y_{n-1}}{(y_n - y_{n-1})(y_n - y_{n-2})}
\]  

(2.1)

If \( x_n = \xi + \epsilon_n \), then from Eq. (1.4) the convergence is determined by

\[
\epsilon_{n+1} = K\epsilon_n\epsilon_{n-1}\epsilon_{n-2}
\]

(2.2)

This is the same relation as that of Muller's method [1] and so

\[
\epsilon_{n+1} = L\epsilon_n^{1.84}
\]

(2.3)

where \( L \) is a constant.

(b) Improved Second Order Iterations. It does not seem to have been noticed previously that it is possible to use modifications of second-order iterations which in fact have a better convergence exponent than the third-order iteration discussed already. In these, one of the interpolation points is a function of the other two. That is: \( a = x_{n-1}, b = x_n, d = x_{n+1} \) and \( c = x^*_n \), where \( x^*_n \) is some function of \( x_{n-1} \) and \( x_n \).

The iterative sequence becomes

\[
x_{n+1} = \frac{x^*_n y_{n-1} y_n}{(y^*_n - y_n)(y^*_n - y_{n-1})} + \frac{x_{n-1} y^*_n y_n}{(y_{n-1} - y_n)(y_{n-1} - y^*_n)} + \frac{x_n y^*_n y_{n-1}}{(y_n - y_{n-1})(y_n - y^*_n)}
\]

(2.4)

and the convergence is given by

\[
\epsilon_{n+1} = K\epsilon_n\epsilon_{n-1}\epsilon^*_n
\]

(2.5)

with an obvious notation.

Only a few out of the many possible definitions for \( x^*_n \) will be discussed here. First, the "mean" iteration will be considered. In this

\[
x^*_n = \frac{1}{2}(x_n + x_{n-1})
\]

(2.6)

giving

\[
\epsilon_{n+1} = K\epsilon_n\epsilon_{n-1}\cdot\frac{1}{2}(\epsilon_n + \epsilon_{n-1}) = L\epsilon_n^{1.5}
\]

(2.7)

as \( \epsilon_n \) is negligible compared with \( \epsilon_{n-1} \). The convergence exponent may easily be determined. Let

\[
\epsilon_{n+1} = M\epsilon_n^p.
\]

(2.8)

It follows that

\[
\mu = 1 + \frac{2}{\mu},
\]

the appropriate root of which is \( \mu = 2 \). Thus

\[
\epsilon_{n+1} = M\epsilon_n^2
\]

(2.9)
and the convergence is quadratic. It is fairly easy to see that the same would be true for any linear iteration of the Wegstein type $x^*_n = gx_n + (1 - g)x_{n-1}$, $g \neq 1$. If $g = 1$, $x^*_n = x_n$ and the formula (2.4) becomes

$$x_{n+1} = \frac{x_{n-1}y_n^2}{(y_{n-1} - y_n)^2} + \left(\frac{y_n}{y_{n-1} - y_n}\right)_{x^*_n = x_n} \left(\frac{x^*_ny_{n-1}y_n}{y_n^2 - y_{n-1}} - \frac{x_ny_{n-1}y^*_n}{y_n - y_{n-1}}\right).$$

(2.10)

This, in effect, is equivalent to taking a parabola passing through $(x_{n-1}, y_{n-1})$ and touching the curve $y = f(x)$ at $(x_n, y_n)$. The convergence exponent is given by

$$\epsilon_{n+1} = K\epsilon_n\epsilon_{n-1},$$

(2.11)

because $\epsilon^*_n = \epsilon_n$ and if $\epsilon_{n+1} = L\epsilon_n$, then $\mu = 2 + 1/\mu$, and $\mu = 1 + \sqrt{2}$ and so,

$$\epsilon_{n+1} = K\epsilon_n^{2.414}.$$  

(2.12)

This procedure has the same order of convergence as a similar one discussed by Ostrowski [2].

Finally, suppose that $x^*_n$ is determined by Reguli Falsi [1] as applied to $x_{n-1}, x_n$; that is

$$x^*_n = \frac{x_{n-1}y_n - x_ny_{n-1}}{y_n - y_{n-1}}.$$  

(2.13)

$\epsilon^*_n$ is defined by an expression of the form

$$\epsilon^*_n = L\epsilon_n\epsilon_{n-1},$$  

and so

$$\epsilon_{n+1} = K\epsilon_n\epsilon_{n-1}L\epsilon_n\epsilon_{n-1} = M\epsilon_n^{2.732}.$$  

(2.14)

Following the usual procedure $\epsilon^*_n = N\epsilon_n$, $\mu = 2 + 2/\mu$ and $\mu = 1 + \sqrt{3},$

(2.15)

It is interesting to note that these improved second-order iterations all give higher convergence exponents than does the third-order iteration.

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