A FINITE ELEMENT MODEL FOR THE
TIME-DEPENDENT JOULE HEATING PROBLEM

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Abstract. We study a spatially semidiscrete and a completely discrete finite element model for a nonlinear system consisting of an elliptic and a parabolic partial differential equation describing the electric heating of a conducting body. We prove error bounds of optimal order under minimal regularity assumptions when the number of spatial variables \( d \leq 3 \). We establish the existence of solutions with the required regularity over arbitrarily long intervals of time when \( d \leq 2 \).

1. Introduction

In this note we consider the numerical approximation by the finite element method of the following nonlinear elliptic-parabolic system

\[
\begin{align*}
    u_t - \Delta u &= \sigma(u)|\nabla \phi|^2, & x \in \Omega, & t \in [0, T], \\
    - \nabla \cdot (\sigma(u)\nabla \phi) &= 0, & x \in \Omega, & t \in [0, T],
\end{align*}
\]

where \( u = u(x, t) \), \( \phi = \phi(x, t) \), \( u_t = \partial u/\partial t \), \( \nabla \) denotes the gradient with respect to the \( x \)-variables and \( \Delta = \nabla \cdot \nabla \) is the Laplacian. These differential equations are studied for \( t \) in a finite interval \([0, T]\) and for \( x \) in a bounded convex polygonal domain \( \Omega \) in \( \mathbb{R}^d \), \( d = 1, 2 \) or \( 3 \), together with initial and boundary conditions

\[
\begin{align*}
    u(x, t) &= 0, & \phi(x, t) &= g(x, t), & x \in \partial \Omega, & t \in [0, T], \\
    u(x, 0) &= u_0(x), & \phi(x, 0) &= 0, & x \in \Omega.
\end{align*}
\]

We make the assumption that the function \( \sigma \in C^2(\mathbb{R}) \) and that, for some \( \kappa, K > 0 \) and all \( s \in \mathbb{R} \),

\[
0 < \kappa \leq \sigma(s) \leq K, \quad |\sigma'(s)| + |\sigma''(s)| \leq K.
\]

This system models the electric heating of a conducting body [5] with \( u \) being the temperature, \( \phi \) the electric potential, and \( \sigma \) the temperature-dependent electric conductivity.

Let \( (\cdot, \cdot) \) and \( \| \cdot \| \) denote the inner product and norm in \( L_2 = L_2(\Omega) \), and \( H^1 = H^1(\Omega) = \{ u \in L^2 : |\nabla u| \in L_2 \} \), \( H^1_0 = \{ u \in H^1 : u|_{\partial \Omega} = 0 \} \)

Received by the editor February 7, 1994 and, in revised form, September 20, 1994.
1991 Mathematics Subject Classification. Primary 65N30, 65N15, 35K60.
Key words and phrases. Joule heating, nonlinear, elliptic, parabolic, finite element, backward Euler, existence, regularity.
This research was partially supported by the SERC grant number GR/F85659.

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be the standard Sobolev spaces. The finite element method is based on the weak formulation of the above initial boundary value problem, where we seek \( u(t) \in H^1_0 \), \( \phi(t) \in H^1 \) with \( \phi(t) - g(t) \in H^1_0 \) such that

\[
(u_t, \chi) + (\nabla u, \nabla \chi) = (\sigma(u)|\nabla \phi|^2, \chi), \quad \forall \chi \in H^1_0, \ t \in [0, T],
\]

\[
u(0) = u_0,
\]

and

\[
(\sigma(u)\nabla \phi, \nabla \chi) = 0, \quad \forall \chi \in H^1_0, \ t \in [0, T].
\]

Let \( \{S_h\}_{h>0} \) be a family of approximating subspaces of \( H^1 \), where each space \( S_h \) consists of continuous piecewise linear polynomials with respect to a triangulation of \( \Omega \) with maximum meshwidth \( h \). With each \( S_h \) we associate the subspace \( S_h = \{u_h \in S_h : u_h|_{\partial \Omega} = 0\} \). We assume that the family of triangulations is such that the standard interpolation error estimates [4, Theorem 3.2.1] and inverse estimates [4, Theorem 3.2.6] hold.

We first consider a semidiscrete approximation: find \( u_h(t) \in S_h, \phi_h(t) \in S_h \) with \( \phi_h(t) - \pi_h g(t) \in S_h \) such that

\[
(u_{ht}, \chi) + (\nabla u_h, \nabla \chi) = (\sigma(u_h)|\nabla \phi_h|^2, \chi), \quad \forall \chi \in S_h, \ t \in [0, T],
\]

\[
u_h(0) = u_{h0},
\]

and

\[
(\sigma(u_h)\nabla \phi_h, \nabla \chi) = 0, \quad \forall \chi \in S_h, \ t \in [0, T],
\]

where \( \pi_h : C(\hat{\Omega}) \to S_h \) denotes the standard Lagrangian interpolation operator and \( u_{h0} \in S_h \) is an appropriate approximation of \( u_0 \). For this method we prove an error estimate of the form

\[
\|u_h(t) - u(t)\| + \|\phi_h(t) - \phi(t)\| \leq C(u, \phi, T)h^2, \quad t \in [0, T],
\]

(see Theorem 3.1 below) under a certain assumption about the regularity of the exact solutions \( u \) and \( \phi \). This assumption is essentially the same as in the standard error analysis for the corresponding linear elliptic and parabolic problems. The main difficulty here concerns the treatment of the gradient-dependent nonlinearity: one has to deal with the expression

\[
\sigma(u_h)|\nabla \phi_h|^2 - \sigma(u)|\nabla \phi|^2 = \sigma(u_h)\nabla (\phi_h + \phi) \cdot \nabla (\phi_h - \phi) + (\sigma(u_h) - \sigma(u))|\nabla \phi|^2,
\]

where \( \nabla (\phi_h - \phi) \) is formally only \( O(h) \), and where \( \nabla \phi \) and \( \nabla \phi_h \) enter in a nonlinear way. These difficulties are handled by means of a duality argument and by taking advantage of parabolic smoothing. In particular, we avoid using a maximum norm bound for \( \nabla \phi_h \), which would be difficult to obtain.

We also consider a completely discrete scheme based on the backward Euler method with semi-implicit linearization: find \( U_n \in S_h, \Phi_n \in S_h \) with \( \Phi_n - \pi_h g(t_n) \in S_h \) such that

\[
(\partial_t U_n, \chi) + (\nabla U_n, \nabla \chi) = (\sigma(U_{n-1})|\nabla \Phi_{n-1}|^2, \chi), \quad \forall \chi \in S_h, \ t_n \in (0, T],
\]

\[
u_0 = u_{h0},
\]

and

\[
(\sigma(U_n)\nabla \Phi_n, \nabla \chi) = 0, \quad \forall \chi \in S_h, \ t_n \in [0, T).
\]
Here \( \partial_t U_n = (U_n - U_{n-1})/k \), \( t_n = nk \), \( n = 0, 1, 2, \ldots \), and \( k \) is the timestep. For this scheme we show in Theorem 3.3 that
\[
\|U_n - u(t_n)\| + \|\Phi_n - \phi(t_n)\| \leq C(u, \phi, T)(h^2 + k), \quad t_n \in [0, T],
\]
again under the same regularity requirement as for linear problems.

We begin the error analysis in §2 by recalling some results about linear elliptic and parabolic finite element problems. The nonlinear error analysis is carried out in §3, where it is assumed that the number of spatial variables \( d \leq 3 \), and that the exact solutions have minimal regularity. Finally, in §4 we prove the global existence of solutions with the required regularity when \( d \leq 2 \). Our argument here builds upon the techniques of Cimatti [5], who showed the existence of weak solutions. We are not aware of any existence and regularity result in the three-dimensional case.

There is a vast literature on finite element methods for nonlinear elliptic and parabolic problems. For example, we mention the work [6, 7] on the porous media equations, which are similar to the Joule heating problem. Roughly speaking, the porous media equations are (1.1) with the term \( \sigma(u)|\nabla \phi|^2 \) replaced by \( \nabla \phi \cdot \nabla u \), where \( u \) is a concentration, \( \phi \) is the pressure, and \( \nabla \phi \) is the velocity. In [6, 7] the equation for \( \phi \) is solved by a mixed method where both \( \phi \) and \( \nabla \phi \) are approximated to order \( O(h^2) \), so that some difficulties that we address here are partly avoided there.

After the present work was finished we became aware of the paper [18], which addresses the same problem as we do, but obtains nonoptimal results.

Throughout this work we use the notation \( \|u\|_{m, p} = (\sum_{|\alpha| \leq m} \|D^\alpha u\|_{L^p})^{1/p} \) for the norm in the standard Sobolev space \( W_p^m = W_p^m(\Omega) \) with the usual modification for \( p = \infty \), and with the exception that \( \| \cdot \| \) and \( (\cdot, \cdot) \) denote the norm and inner product in \( L^2 \). We also write \( H^m = W^m_2 \) when \( p = 2 \).

2. Linear error analysis

In this section we collect some facts about linear elliptic and parabolic finite element problems that we will need in the sequel. Since \( \partial \Omega \) is a convex polygon, it is well known [9] that the Laplacian \( \Delta \) is an isomorphism from \( H^2 \cap H_0^1 \) onto \( L^2 \), and we let \( \Delta^{-1} \) denote its inverse. Let \( R_h : H_0^1 \to \hat{S}_h \) be defined by the equation
\[
(\nabla R_h u, \nabla \chi) = (\nabla u, \nabla \chi), \quad \forall u \in H_0^1, \, \chi \in \hat{S}_h.
\]

From the standard error analysis [4, Theorems 3.2.2, 3.2.5] for linear elliptic finite element problems we quote the error estimates
\[
\|(R_h - I)u\| + h\|(R_h - I)u\|_{1, 2} \leq C h^2 \|u\|_{1, 2}, \quad \forall u \in H^2 \cap H_0^1.
\]

We denote by \( \Delta_h : \hat{S}_h \to \hat{S}_h \) the discrete Laplacian defined by
\[
(-\Delta_h \chi, \eta) = (\nabla \chi, \nabla \eta), \quad \forall \chi, \eta \in \hat{S}_h,
\]
and we let \( E_h(t) = \exp(t\Delta_h) \) be the analytic semigroup generated by \( \Delta_h \), and \( P_h : L^2 \to \hat{S}_h \) the orthogonal projector. It is well known that \( E_h(t)P_h \) satisfies the following bounds:
\[
\|E_h(t)P_h \psi\| + t^{1/2} \|E_h(t)P_h \psi\|_{1, 2} + t \|\Delta_h E_h(t)P_h \psi\| \leq C \|\psi\|, \quad t > 0,
\]
for \( \psi \in L_2 \), where \( C \) is independent of \( h \) and \( t \), reflecting the uniform analyticity of the evolution operator. In a similar way, for the discrete evolution operator \( E_{kh}^n = (I - k\Delta h)^{-n} \) associated with the backward Euler method, we have

\[
\|E_{kh}^nP_h\psi\| + t_n^{1/2}\|E_{kh}^nP_h\psi\|_{1,2} + t_n\|\Delta h E_{kh}^nP_h\psi\| \leq C\|\psi\|, \quad t_n > 0.
\]

We may now state and prove error bounds for linear parabolic finite element problems. Such results are common in the literature, but a particular feature of the error bounds presented here is that the regularity requirement is optimal and expressed in a form that is suitable for our regularity analysis in \$4\$. Similar results are proved in Chapter 2 of [17] for spatially semidiscrete approximations of the linear homogeneous problem, but are not readily available for the non-homogeneous problem and completely discrete schemes. Moreover, our proof technique is different from that of [17]; being based on (2.3) and (2.4), this technique will also be used in our nonlinear error analysis below.

**Theorem 2.1.** (a) Suppose that \( u(t) \in H_0^1 \) is the solution of the linear heat equation

\[
(ut, \chi) + (\nabla u, \nabla \chi) = (f(t), \chi), \quad \forall \chi \in H_0^1, \quad t > 0,
\]

\[
u(0) = u_0,
\]

and that \( u_h(t) \in \mathcal{S}_h \) satisfies

\[
(ut, \chi) + (\nabla u_h, \nabla \chi) = (f(t), \chi), \quad \forall \chi \in \mathcal{S}_h, \quad t > 0,
\]

\[
u(0) = u_{h0}.
\]

Then, for \( t > 0 \), we have

\[
\|u(t) - u(t)\| \leq C\|u_{h0} - u_0\| + C h^2 \sup_{0 < s \leq t} \left( \|u(s)\|_{1,2} + s\|u_t(s)\|_{2,2} \right),
\]

provided that the solution \( u \) has the regularity implied by the norms on the right-hand side. (b) If \( U_n \in \mathcal{S}_h \) satisfies

\[
(\partial_t U_n, \chi) + (\nabla U_n, \nabla \chi) = (f(t_n), \chi), \quad \forall \chi \in \mathcal{S}_h, \quad t_n > 0,
\]

\[
U_0 = u_{h0},
\]

then, for \( t_n > 0 \), we have

\[
\|U_n - u(t_n)\| \leq C\|u_{h0} - u_0\|
\]

\[
+ C h^2 \sup_{0 < s \leq t_n} \left( \|u(s)\|_{1,2} + \|u_t(s)\|_{2,2} \right)
\]

\[
+ C k \sup_{0 < s \leq t_n} \left( \|\Delta^{-1}u_{tt}(s)\| + s\|u_{tt}(s)\| \right).
\]

**Proof.** We prove (2.8) only; (2.6) can be proved in a similar way; indeed, it essentially follows from (2.8) as \( k \to 0 \). See also [17, Lemma 4 of Chapter 2] for a different proof of (2.6). Let for simplicity

\[
F(u) = \sup_{0 < s \leq t_n} \left( \|u(s)\|_{1,2} + \|u_t(s)\|_{2,2} + s\|u_{tt}(s)\|_{1,2} \right),
\]

\[
G(u) = \sup_{0 < s \leq t_n} \left( \|\Delta^{-1}u_{tt}(s)\| + s\|u_{tt}(s)\| \right).
\]
We write
\[ e_n \equiv U_n - u(t_n) = (U_n - R_h u(t_n)) + (R_h u(t_n) - u(t_n)) \equiv \theta_n + \rho_n, \]
and the required estimate for \( \rho_n \) follows from (2.2):
\[ \| \rho_n \| \leq C h^2 \| u(t_n) \|_{2,2} \leq C h^2 F(u). \]
Moreover, we have
\[ \| \partial_t \rho_n \| \leq C h^2 t_n^{-1} F(u), \quad t_n > 0, \]
because
\[ \| \partial_t \rho_n \| \leq C h^2 t_n^{-1} \max_{0 \leq t \leq t_n} (t \| u(t) \|_{2,2}) \leq C h^2 t_n^{-1} F(u), \]
for \( t_n \geq t_2 \), and
\[ \| \partial_t \rho_1 \| \leq C h^2 k^{-1} \max_{0 \leq t \leq k} \| u(t) \|_{2,2} \leq C h^2 t_1^{-1} F(u). \]

The remaining term \( \theta_n \) belongs to \( S_h \), and using (2.7), (2.5) and (2.1), we find that it satisfies the equation
\[ \partial_t \theta_n - \Delta_h \theta_n = P_h \left( -\partial_t \rho_n + \omega_n \right), \]
where \( \omega_n = u_i(t_n) - \partial_t u(t_n) \). Hence, by Duhamel's principle,
\[ \theta_n = E^n_k \theta_0 + k \sum_{j=1}^{n} E^{n-j+1}_k P_h \left( -\partial_j \rho_j + \omega_j \right). \]

Let \( [n/2] \) be the integer part of \( n/2 \). Summation by parts gives
\[ -k \sum_{j=1}^{[n/2]} E^{n-j+1}_k P_h \partial_j \rho_j = E^n_k P_h \rho_0 - E^{n-[n/2]}_k P_h \rho_{[n/2]} + k \sum_{j=1}^{[n/2]} \left( \partial_j E^{n-j}_k \right) P_h \rho_j, \]
where \( \partial_j E^{n-j}_k = -\Delta_h E^{n-j+1}_k \), so that
\[ \theta_n = E^n_k P_h \rho_0 - E^{n-[n/2]}_k P_h \rho_{[n/2]} - k \sum_{j=1}^{[n/2]} \Delta_h E^{n-j+1}_k P_h \rho_j \]
\[ -k \sum_{j=[n/2]+1}^{n} E^{n-j+1}_k P_h \partial_j \rho_j + k \sum_{j=1}^{[n/2]} \Delta_h E^{n-j+1}_k \left( \Delta_h^{-1} P_h - P_h \Delta_h^{-1} \right) \omega_j \]
\[ + k \sum_{j=1}^{[n/2]} \Delta_h E^{n-j+1}_k P_h \Delta_h^{-1} \omega_j + k \sum_{j=[n/2]+1}^{n} E^{n-j+1}_k P_h \omega_j \equiv \sum_{i=1}^{7} R_i. \]

We proceed to estimate the seven terms on the right-hand side. Using the smoothing property (2.4), the error bounds (2.9) and (2.10), we have
\[ \sum_{i=1}^{4} \| R_i \| \leq C \left( \| e_0 \| + \| \rho_{[n/2]} \| \right) + C k \sum_{j=1}^{[n/2]} t_{n-j+1}^{-1} \| \rho_j \| + C k \sum_{j=[n/2]+1}^{n} \| \partial_j \rho_j \| \]
\[ \leq C \| e_0 \| + C h^2 F(u) \left( 1 + k \sum_{j=1}^{[n/2]} t_{n-j+1}^{-1} + k \sum_{j=[n/2]+1}^{n} t_{j}^{-1} \right) \]
\[ \leq C \| e_0 \| + C h^2 F(u). \]
For the fifth term we use the fact that \( \Delta_h^{-1} P_h - \Delta^{-1} = (R_h - I) \Delta^{-1} \), so that by (2.2) and elliptic regularity

\[
\| (\Delta_h^{-1} P_h - \Delta^{-1}) \omega_j \| = \| (R_h - I) \Delta^{-1} \omega_j \| \leq C h^2 \| \Delta^{-1} \omega_j \|_{2,2} \leq C h^2 \| \omega_j \|
\]

\[
\leq C h^2 \max_{t_{j-1} \leq t \leq t_j} \| u(t) \| \leq C h^2 F(u).
\]

Hence,

\[
\| R_5 \| \leq C h^2 F(u) k \sum_{j=1}^{[n/2]} t_{n-j+1}^{-1} \leq C h^2 F(u).
\]

For the sixth term we note that

\[
\| \Delta^{-1} \omega_j \| = \left\| k^{-1} \int_{t_{j-1}}^{t_j} (t - t_{j-1}) \Delta^{-1} u_{tt}(t) \, dt \right\| \leq k \max_{t_{j-1} \leq t \leq t_j} \| \Delta^{-1} u_{tt}(t) \| \leq k G(u),
\]

so that

\[
\| R_6 \| \leq C k G(u) k \sum_{j=1}^{[n/2]} t_{n-j+1}^{-1} \leq C k G(u).
\]

Finally, we have

\[
\| \omega_j \| \leq C k t_j^{-1} G(u), \quad t_j > 0,
\]

because

\[
\| \omega_j \| = \left\| k^{-1} \int_{t_{j-1}}^{t_j} (t - t_{j-1}) u_{tt}(t) \, dt \right\| \leq k t_j^{-1} \max_{t_{j-1} \leq t \leq t_j} \left( t \| u_{tt}(t) \| \right) \leq C k t_j^{-1} G(u),
\]

for \( t_j \geq t_2 \), and

\[
\| \omega_1 \| = \left\| k^{-1} \int_0^k t u_{tt}(t) \, dt \right\| \leq \max_{0 < r \leq k} \left( t \| u_{tt}(t) \| \right) \leq G(u) = k t_1^{-1} G(u).
\]

Hence,

\[
\| R_7 \| \leq C k \sum_{j=[n/2]+1}^{n} \| \omega_j \| \leq C k G(u) k \sum_{j=[n/2]+1}^{n} t_j^{-1} \leq C k G(u).
\]

Taken together, these estimates prove (2.8). \( \square \)

3. Nonlinear error analysis

3.1. The semidiscrete case. Let \( u_h, \phi_h \) be the semidiscrete finite element approximations of the solutions \( u, \phi \) of the nonlinear problem (1.1). In this section we estimate the errors \( u(t) - u_h(t) \) and \( \phi(t) - \phi_h(t) \) uniformly over a finite time interval \( 0 \leq t \leq T \) under minimal assumptions about the regularity of \( u \) and \( \phi \). The error analysis is carried out under the assumption that the number of spatial variables \( d \leq 3 \); the regularity assumptions, however, have only been verified for \( d \leq 2 \), see §4 below. The result is presented in the following theorem.
Theorem 3.1. Let \( u, \phi \) and \( u_h, \phi_h \) be solutions of (1.4)-(1.5) and (1.6)-(1.7), respectively, with \( u_{h0} \) chosen so that

\[
\|u_0 - u_{h0}\| \leq M_1 h^2.
\]

Assume further that \( d \leq 3 \) and that

\[
(3.1) \sup_0 \leq t \leq T \left( \|u(t)\|_{2,2} + t\|u_t(t)\|_{2,2} \right) \leq M_2,
\]

\[
(3.2) \sup_0 \leq t \leq T \left( \|g(t)\|_{H^2(\partial \Omega)} + \|\phi(t)\|_{2,2} + \|\phi(t)\|_{1,\infty} \right) \leq M_3,
\]

for some positive numbers \( T \) and \( M_i, \ i = 1, \ldots, 3 \). Then there is a constant \( C = C(\kappa, K, M_1, M_2, M_3, T) \) such that

\[
(3.4) \|u(t) - u_h(t)\| + \|\phi(t) - \phi_h(t)\| \leq C h^2, \quad t \in [0, T].
\]

Here, \( \| \cdot \|_{H^2(\partial \Omega)} \) is defined by summation over the flat parts of the polygon \( \partial \Omega \). In the remainder of this section we let \( C \) denote various quantities that may depend on the data of our problem as in the statement of Theorem 3.1. All estimates that are derived hold uniformly with respect to \( t \in [0, T] \). We prepare for the proof of Theorem 3.1 by proving some preliminary bounds for \( \phi(t) - \phi_h(t) \).

Lemma 3.2. Under the assumptions of Theorem 3.1 we have

\[
(3.5) \|\nabla(\phi(t) - \phi_h(t))\| \leq C \left( h + \|u(t) - u_h(t)\| \right),
\]

\[
(3.6) \|\phi(t) - \phi_h(t)\| \leq C \left( h^2 + \|u(t) - u_h(t)\| + h^{-d/6}\|u(t) - u_h(t)\|^2 \right).
\]

Proof. Since all results below are uniform in \( t \), we do not make the \( t \)-dependence explicit. Let \( e_\phi = \phi - \phi_h \). It follows from (1.5) and (1.7) that

\[
(3.7) (\sigma(u_h)\nabla e_\phi, \nabla \chi) = ([\sigma(u_h) - \sigma(u)]\nabla \phi, \nabla \chi), \quad \forall \chi \in \mathcal{H}_h,
\]

and

\[
(3.8) (\sigma(u)\nabla e_\phi, \nabla \chi) = ([\sigma(u_h) - \sigma(u)]\nabla \phi_h, \nabla \chi), \quad \forall \chi \in \mathcal{H}_h.
\]

Since \( \pi_h \phi - \phi_h \in \mathcal{H}_h \), we have from (3.7) that

\[
(\sigma(u_h)\nabla e_\phi, \nabla e_\phi) = (\sigma(u_h)\nabla e_\phi, \nabla(\phi - \pi_h \phi)) + (\sigma(u_h)\nabla e_\phi, \nabla(\pi_h \phi - \phi_h))
\]

\[
= (\sigma(u_h)\nabla e_\phi, \nabla(\phi - \pi_h \phi))
\]

\[
+ ([\sigma(u_h) - \sigma(u)]\nabla \phi, \nabla(\pi_h \phi - \phi_h)).
\]

It now follows from (1.3) and (3.3) that

\[
\|\nabla e_\phi\|^2 \leq C \left( \|\nabla e_\phi\| \|\nabla(\phi - \pi_h \phi)\| + \|u_h - u\| \|\phi\|_{1,\infty} \|\nabla(\phi - \pi_h \phi)\| \right)
\]

\[
\leq C \left( \|\nabla e_\phi\| \|\nabla(\phi - \pi_h \phi)\| + \|u_h - u\| \left( \|\nabla(\phi - \pi_h \phi)\| + \|\nabla e_\phi\| \right) \right)
\]

\[
\leq C \left( \|\nabla(\phi - \pi_h \phi)\|^2 + \|u_h - u\|^2 \right) + \frac{1}{2} \|\nabla e_\phi\|^2.
\]

Hence,

\[
\|\nabla e_\phi\| \leq C \left( \|\nabla(\phi - \pi_h \phi)\| + \|u_h - u\| \right),
\]

which immediately yields (3.5) in view of an interpolation error estimate and (3.3).

The $L_2$ estimate of $e_\phi$ is obtained by the standard duality argument. Let $\psi$ be the unique solution of the Dirichlet problem

\begin{equation}
-\nabla \cdot (\sigma(u) \nabla \psi) = e_\phi \text{ in } \Omega; \quad \psi = 0 \text{ on } \partial \Omega.
\end{equation}

Then the standard regularity estimate yields (recall that $\Omega$ is a convex polygon)

$$
\|\psi\|_{2,2} \leq C \|\Delta \psi\| = C \left( \frac{\sigma'(u) \nabla u \cdot \nabla \psi + e_\phi}{\sigma(u)} \right).
$$

Using (1.3), Hölder's inequality, an interpolation inequality (see (4.2) below), the trivial estimate $\|\psi\|_{1,2} \leq C \|e_\phi\|$, and $\|u\|_{2,2} \leq M_2$ from (3.2), we obtain

$$
\|\psi\|_{2,2} \leq C \left( \|\nabla u\|_{0,6} \|\nabla \psi\|_{0,3} + \|e_\phi\| \right)
\leq C \left( \|u\|_{2,2} \|\psi\|_{1,2}^{1-d/6} \|\psi\|_{2,2}^{d/6} + \|e_\phi\| \right)
\leq C \left( \|u\|_{2,2} \|\psi\|_{1,2} + \|e_\phi\| \right) + \frac{1}{2} \|\psi\|_{2,2}
\leq C \|e_\phi\| + \frac{1}{2} \|\psi\|_{2,2}.
$$

Hence,

$$
\|\psi\|_{2,2} \leq C \|e_\phi\|.
$$

From (3.9) and Green’s formula it follows that

$$
\|e_\phi\|^2 = -\left( \nabla \cdot (\sigma(u) \nabla \psi), e_\phi \right)
= \left( \sigma(u) \nabla \psi, \nabla e_\phi \right) - \left( \sigma(u) \nabla \psi \cdot \nu, e_\phi \right)
= \left( \sigma(u) \nabla (\psi - \psi_h), \nabla e_\phi \right) + \left( \sigma(u) \nabla \psi_h, \nabla e_\phi \right)
- \left( \sigma(u) \nabla \psi \cdot \nu, \gamma - \gamma_h \gamma \right)
\equiv T_1 + T_2 + T_3,
$$

where $\psi_h = \pi_h \psi \in \hat{S}_h$, and where we have used $\langle \cdot, \cdot \rangle$ to denote the inner product in $L_2(\partial \Omega)$, and $\nu$ is the unit outward normal vector on $\partial \Omega$.

The first term on the right of (3.11) is easily estimated by means of an interpolation error bound, (3.5) and (3.10):

$$
|T_1| \leq C \|\nabla (\psi - \psi_h)\| \|\nabla e_\phi\| \leq Ch \|\psi\|_{2,2} \left( h + \|u - u_h\| \right)
\leq C \left( h^2 + \|u - u_h\| \right) \|e_\phi\|.
$$

Using (3.8), we have

$$
T_2 = \left( \sigma(u) \nabla e_\phi, \nabla \psi_h \right) = \left( [\sigma(u_h) - \sigma(u)] \nabla \phi_h, \nabla \psi_h \right)
= \left( [\sigma(u_h) - \sigma(u)] \nabla \phi, \nabla \psi_h \right) + \left( [\sigma(u_h) - \sigma(u)] \nabla (\phi_h - \phi), \nabla \psi \right)
+ \left( [\sigma(u_h) - \sigma(u)] \nabla (\phi_h - \phi), \nabla (\psi_h - \psi) \right).
$$

Hence,

$$
|T_2| \leq C \|u - u_h\| \left( \|\phi\|_{1,\infty} \|\psi_h\|_{1,2} + \|\nabla e_\phi\|_{0,3} \|\psi\|_{1,6} \right) + C \|\nabla e_\phi\| \|\nabla (\psi_h - \psi)\|.
$$
Using the facts that $\|\phi\|_{1,\infty} \leq M_3$, $\|\psi_h\|_{1,2} + \|\psi\|_{1,6} \leq C\|\psi\|_{2,2} \leq C\|e_\phi\|$ and $\|\nabla(\psi_h - \psi)\| \leq C h\|\psi\|_{2,2} \leq C h\|e_\phi\|$, we obtain

$$|T_2| \leq C \left(\|u - u_h\|(1 + \|\nabla e_\phi\|_{0,3} + h\|\nabla e_\phi\|)\|e_\phi\|.$$

By interpolation error estimates, an inverse estimate, (3.3) and (3.5) we have

$$\|\nabla e_\phi\|_{0,3} \leq \|\nabla(\phi - \pi_h\phi)\|_{0,3} + \|\nabla(\pi_h\phi - \phi_h)\|_{0,3}$$

$$\leq C h^{1-\delta/6} \|\phi\|_{2,2} + C h^{-d/6}\|\nabla(\pi_h\phi - \phi_h)\|$$

$$\leq C h^{1-\delta/6} \|\phi\|_{2,2} + C h^{-d/6} \left(C h\|\phi\|_{2,2} + \|\nabla e_\phi\|\right)$$

$$\leq C \left(1 + h^{-d/6}\|u - u_h\|\right),$$

so that

$$|T_2| \leq C \left(h^2 + \|u - u_h\| + h^{-d/6}\|u - u_h\|^2\right)\|e_\phi\|.$$

Finally, we have

$$|T_3| \leq C\|g - \pi_h g\|_{L^2(\partial\Omega)}\|\psi\|_{2,2} \leq C h^2\|g\|_{H^2(\partial\Omega)}\|e_\phi\| \leq C h^2\|e_\phi\|,$$

where a trace inequality, an interpolation error estimate and (3.10) have been used. Together, the above estimates prove (3.6).

Proof of Theorem 3.1. It is convenient to split the error into two parts: $u_h - u = (u_h - \tilde{u}_h) + (\tilde{u}_h - u)$, where $\tilde{u}_h : [0, T] \to \hat{S}_h$ is uniquely defined by

$$\langle \tilde{u}_h(t), \chi \rangle + \langle \nabla \tilde{u}_h, \nabla \chi \rangle = (F(u, \phi), \chi), \quad \forall \chi \in \hat{S}_h, \ t \in [0, T],$$

$$\tilde{u}_h(0) = u_0,$$

with $F(u, \phi) = \sigma(u)|\nabla \phi|^2$. Applying the known error analysis for linear parabolic equations, we obtain

$$\|\tilde{u}_h(t) - u(t)\| \leq C h^2,$$

where $C$ depends on $M_1$ and $M_2$, see Theorem 2.1.

Forming the difference between (1.6) and (3.12), we have for $\zeta = u_h - \tilde{u}_h$ that

$$\zeta_t - \Delta_h \zeta = P_h\left(F(u_h, \phi_h) - F(u, \phi)\right), \quad t \in [0, T]; \quad \zeta(0) = 0.$$

Hence, the variation of constants formula implies that

$$\|\zeta(t)\| \leq \int_0^t \|E_h(t - s)P_h\left(F(u_h(s), \phi_h(s)) - F(u(s), \phi(s))\right)\| ds.$$

We proceed to estimate $\|\zeta(t)\|$ by bounding the right side in various ways. In doing so, we shall need several bounds for the operator $E_h(t)P_h$. In addition to (2.3) we quote from [11, Lemma 5.2] a bound of the norm of $E_h(t)P_h$ considered as an operator from $L_2$ into $L_\infty$, namely, for any $\epsilon > 0$ there is $C_\epsilon > 0$ such that

$$\|E_h(t)P_h\|_{0,\infty} \leq C_\epsilon t^{-d/4-\epsilon}\|\psi\|, \quad t > 0.$$
By duality we also have the same bound for the norm of $E_h(t)P_h : L_1 \to L_2$, that is,
\begin{equation}
\|E_h(t)P_h\| \leq C \epsilon^{-d/4-\epsilon} \|\psi\|_{0,1}, \quad t > 0, \quad \epsilon > 0.
\end{equation}
In fact,
\begin{equation}
\|E_h(t)P_h\psi\| = \sup_{x \in L_2} \frac{|(E_h(t)P_h\psi, x)|}{\|x\|} = \sup_{x \in L_2} \frac{|(\psi, E_h(t)P_hx)|}{\|x\|},
\end{equation}
since $E_h(t)P_h$ is selfadjoint, so that (3.16) follows from (3.15).

We begin by deriving a preliminary low-order estimate of $\|\zeta(t)\|$. We have
\begin{equation}
WF(u_h, <\phi_h> - E(u_h, \phi)) \
< |\phi(u_h)V\phi - \phi| ||\phi|| + |(\phi(u_h) - \phi)||W_0,1 + ||(\phi(u_h) - \phi)||W_0,1
\end{equation}
\begin{equation}
\leq C(||V_{\phi}|| + ||\phi||) ||\phi|| + C ||u_h - u|| ||\phi||_{1,\infty}
\end{equation}
\begin{equation}
\leq C(h + ||u_h - u||),
\end{equation}
where we have used the easily proved fact that $||\nabla_\phi(t)|| + ||\nabla_\phi(t)|| \leq C$, the assumption $||\phi||_{1,\infty} \leq M_3$, and the error bound (3.5). Hence, by (3.14), (3.16) and (3.13) we have
\begin{equation}
||u_h(t) - u(t)|| \leq ||\tilde{u}_h(t) - u(t)|| + ||\zeta(t)||
\end{equation}
\begin{equation}
\leq Ch^2 + C \int_0^t (t-s)^{-\alpha} ||F(u_h(s), \phi_h(s)) - F(u(s), \phi(s))||_{0,1} ds
\end{equation}
\begin{equation}
\leq Ch^2 + C \int_0^t (t-s)^{-\alpha} (h + ||u_h(s) - u(s)||) ds
\end{equation}
\begin{equation}
\leq Ch + C \int_0^t (t-s)^{-\alpha} ||u_h(s) - u(s)|| ds,
\end{equation}
where it is possible to choose $\alpha \in (3/4, 1)$, since $d \leq 3$. Hence, a variant of Gronwall's lemma (see, e.g., [14, Lemma 5.6.7], [10, Lemma 7.1.1] or Lemma 3.4 below) yields the preliminary bound
\begin{equation}
||u_h(t) - u(t)|| \leq Ch.
\end{equation}
Inserted into (3.5) and (3.6), this gives
\begin{equation}
||\phi_h(t) - \phi(t)||_{1,2} \leq Ch,
\end{equation}
\begin{equation}
||\phi_h(t) - \phi(t)|| \leq C(h^2 + ||u_h(t) - u(t)||).
\end{equation}

The reason for the suboptimality of the preliminary bound is that we estimated $F(u_h, \phi_h) - F(u, \phi)$ in terms of $\nabla(\phi_h - \phi)$, which is only $O(h)$. In order to obtain an estimate of second order, we shall use a duality argument to remove the gradient from the latter term. This argument requires a more accurate expansion of $F(u_h, \phi_h) - F(u, \phi)$, namely
\begin{equation}
F(u_h, \phi_h) - F(u, \phi) = [\sigma(u_h) - \sigma(u)]||\nabla \phi||^2
+ 2\sigma(u)\nabla \phi \cdot \nabla(\phi_h - \phi)
+ 2[\sigma(u_h) - \sigma(u)]\nabla \phi \cdot \nabla(\phi_h - \phi)
+ \sigma(u_h)||\nabla(\phi_h - \phi)||^2
\equiv R_1 + R_2 + R_3 + R_4.
\end{equation}
Using (2.3) and (3.16), we shall estimate each of the terms $\|E_h(t - s)P_hR_i(s)\|$ and substitute the result into the right-hand side of (3.14).

Omitting the dependence on $t - s$ and $s$ in intermediate steps, we obtain for the first term
\[\|E_h(t - s)P_hR_1(s)\| = \|E_hP_h[(\sigma(u_h) - \sigma(u))\nabla\phi|^2]\| \leq C\|u_h - u\| \|\phi\|_2,\infty^2 \leq C\|u_h(s) - u(s)\|,\]

For the second term we use a duality argument (cf. (3.17)): for $\chi \in L_2$ we have
\[(E_h(t - s)P_hR_2(s), \chi) = -2(\phi - \phi, \nabla \cdot (\sigma(u)\nabla \phi P_h\chi)) \leq -2(\phi - \phi, \nabla \cdot (\sigma(u)\nabla \phi P_h\chi)),\]

since $\nabla \cdot (\sigma(u)\nabla \phi) = 0$. Hence, by (2.3),
\[\|E_h(t - s)P_hR_2(s)\| \leq C(t - s)^{-1/2}\|u_h(s) - u(s)\|\chi\|,\]

so that, in view of the second estimate in (3.19),
\[\|E_h(t - s)P_hR_2(s)\| \leq C(t - s)^{-1/2}\left(h^2 + \|u_h(s) - u(s)\|C(t - s)^{-1/2}\right).\]

By (3.16) there is $\alpha \in (3/4, 1)$ such that
\[\|E_h(t - s)P_hR_3(s)\| \leq C(t - s)^{-\alpha}\|u_h(s) - u(s)\|\chi\|,\]

Similarly, by the first estimate in (3.19),
\[\|E_h(t - s)P_hR_4(s)\| \leq C(t - s)^{-\alpha}\|u_h(s) - u(s)\|\chi\|,\]

Combining these bounds with (3.14) and (3.13), we obtain
\[\|u_h(t) - u(t)\| \leq C h^2 + C \int_0^t (t - s)^{-\alpha}\left(h^2 + \|u_h(s) - u(s)\|\right) ds.\]

Gronwall’s lemma now yields the desired bound for $\|u_h(t) - u(t)\|$ in (3.4), and hence, in view of (3.19), also the bound for $\|\phi_h(t) - \phi(t)\|.\]

3.2. The completely discrete case. We now turn to the completely discrete scheme. Our result is the following.

Theorem 3.3. Let $u$, $\phi$ and $U_n, \Phi_n$ be solutions of (1.4)-(1.5) and (1.8)-(1.9), respectively, with $u_{h0}$ chosen so that
\[\|u_0 - u_{h0}\| \leq M_1 h^2.\]

Assume further that $d \leq 3$ and that
\[\sup_{0 < t \leq T}\left(\|u(t)\|_{2,2} + \|u_1(t)\| + \|\Delta^{-1}u_{tt}(t)\| + t\|u_{tt}(t)\|_{2,2} + t\|u_{tt}(t)\|\right) \leq M_2,\]

\[\sup_{0 < t \leq T}\left(\|g(t)\|_{H^2(\partial\Omega)} + \|\phi(t)\|_{2,2} + \|\phi(t)\|_{1,\infty} + \|\phi(t)\|_{1,2}\right) \leq M_3,\]
and that $k \leq M_4 h^{d/6}$ for some positive numbers $T$ and $M_i$, $i = 1, \ldots, 4$. Then there is $C = C(\kappa, K, M_1, M_2, M_3, M_4, T)$ such that

$$
\|u(t_n) - U_n\| + \|\phi(t_n) - \Phi_n\| \leq C(h^2 + k), \quad t_n \in [0, T].
$$

We will need a discrete version of the generalized Gronwall lemma that we referred to in the previous proof. We formulate this in the following lemma, where we use the convention that a sum is considered to be empty if its upper limit is smaller than its lower limit, that is, $\sum_{l=n}^{m} a_l = 0$ if $m < n$.

**Lemma 3.4.** Assume that the sequence $\varphi_n$ satisfies

$$
0 \leq \varphi_n \leq A + B k \sum_{l=0}^{n-1} t_{n-l-1}^{1+\beta} \varphi_l \quad \text{for} \quad t_n \in [0, T],
$$

where $A, B, T$ are positive numbers and $0 < \beta < 1$. Then there is a constant $C = C(\beta, B, T)$ such that $\varphi_n \leq CA$ for $t_n \in [0, T]$.

**Proof.** Iterating the given inequality once, using the inequalities

$$
k \sum_{l=0}^{n-1} t_{n-l-1}^{1+\beta} \leq \int_0^{t_n} (t_n - s)^{-1+\beta} ds = C \beta t_n^\beta,
$$

valid for $0 < \beta, \gamma < 1$, we obtain

$$
\varphi_n \leq A + AB k \sum_{l=0}^{n-1} t_{n-l-1}^{1+\beta} + B^2 \sum_{j=0}^{n-2} \left( k \sum_{l=j+1}^{n-1} t_{n-l-1}^{1+\beta} t_{l-j}^{1+\beta} \right) \varphi_j
$$

$$
\leq C_1(\beta, B, T) A + C_2(\beta, B) k \sum_{l=0}^{n-2} t_{n-l-1}^{1+2\beta} \varphi_l.
$$

After $N-1$ iterations, where $N$ is the smallest integer such that $-1 + N\beta \geq 0$, we have

$$
\varphi_n \leq C_1(\beta, B, T) A + C_2(\beta, B) k \sum_{l=0}^{n-N} t_{n-l-1}^{1+N\beta} \varphi_l
$$

$$
\leq C_1(\beta, B, T) A + C_2(\beta, B, T) k \sum_{l=0}^{n-N} \varphi_l,
$$

and the desired conclusion follows by the standard Gronwall lemma. □

**Proof of Theorem 3.3.** The proof is a generalization of the proof of Theorem 3.1. We begin by splitting the error into two parts: $U_n - u_n = (U_n - \tilde{U}_n) + (\tilde{U}_n - u_n)$, where $\tilde{U}_n \in \mathcal{S}_h$ is uniquely defined by

$$
(\partial_t \tilde{U}_n, \chi) + (\nabla \tilde{U}_n, \nabla \chi) = (F(u_n, \phi_n), \chi), \quad \forall \chi \in \mathcal{S}_h, \quad t_n \in [0, T],
$$

$$
\tilde{U}_0 = u_{h_0}.
$$

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with \( u_n = u(t_n) \), \( \phi_n = \phi(t_n) \) and \( F(u_n, \phi_n) = \sigma(u_n)|\nabla \phi_n|^2 \). Applying the known error analysis for linear parabolic equations, we obtain

\[
\| \tilde{U}_n - u_n \| \leq C(h^2 + k),
\]

where \( C \) depends on \( M_1 \) and \( M_2 \), see Theorem 2.1.

Forming the difference between (1.8) and (3.22) and applying the variation of constants formula, we have for \( \zeta_n = U_n - \tilde{U}_n \) that

\[
\| \zeta_n \| \leq k \sum_{l=0}^{n-1} \| E_{kh}^{n-l} P_h \left( (F(U_l, \Phi_l) - F(u_{l+1}, \phi_{l+1})) \right) \|.
\]

In addition to (2.4), the discrete evolution operator \( E_{kh}^n P_h \) satisfies the bound

\[
\| E_{kh}^n P_h \psi \| \leq C \epsilon t_n^{d/4 - \epsilon} \| \psi \|_{0,1}, \quad t_n > 0, \quad \epsilon > 0.
\]

The proof of this is analogous to that of (3.16). Indeed, by inspection of the proof of [11, Lemma 5.2] it is clear that a completely discrete analog of (3.15) holds and hence (3.25) follows by duality.

Lemma 3.2 is directly applicable to the equation for \( \Phi_n \) and gives

\[
\| \nabla (\Phi_n - \phi_n) \| \leq C \left( h + \| U_n - u_n \| \right),
\]

\[
\| \Phi_n - \phi_n \| \leq C \left( h^2 + \| U_n - u_n \| + h^{-d/6} \| U_n - u_n \|^2 \right).
\]

Hence,

\[
\| F(U_{n-1}, \Phi_{n-1}) - F(u_{n-1}, \phi_{n-1}) \|_{0,1} \leq C \left( h + \| U_{n-1} - u_{n-1} \| \right),
\]

cf. (3.18). In a similar way we have

\[
\| F(u_{n-1}, \phi_{n-1}) - F(u_n, \phi_n) \|_{0,1}
\leq \| \sigma(u_{n-1}) \nabla (\phi_{n-1} + \phi_n) \cdot \nabla (\phi_{n-1} - \phi_n) \|_{0,1}
+ \| (\sigma(u_{n-1}) - \sigma(u_n)) |\nabla \phi_n|^2 \|_{0,1}
\leq C \left( \| \nabla \phi_{n-1} \| + \| \nabla \phi_n \| \right) \| \phi_{n-1} - \phi_n \|_{1,2}
+ C \| u_{n-1} - u_n \| \| \phi_n \|_{1, \infty}^2
\leq C \left( \| \phi_{n-1} - \phi_n \|_{1,2} + \| u_{n-1} - u_n \| \right)
\leq C k \sup_{0 \leq t \leq T} \left( \| \phi(t) \|_{1,2} + \| u(t) \| \right) \leq C k.
\]

Therefore,

\[
\| F(U_{n-1}, \Phi_{n-1}) - F(u_n, \phi_n) \|_{0,1} \leq C \left( h + k + \| U_{n-1} - u_{n-1} \| \right),
\]
so that, by (3.24), (3.23) and (3.25),

\[ \|U_n - u_n\| \leq \|\tilde{U}_n - u_n\| + \|\zeta_n\| \]

\[ \leq C(h^2 + k) + Ck \sum_{l=0}^{n-1} t_{n-l}^{-\alpha/2} \|F(U_l, \Phi_l) - F(u_{l+1}, \phi_{l+1})\|_{0,1} \]

\[ \leq C(h^2 + k) + Ck \sum_{l=0}^{n-1} \left( h + k + \|U_l - u_l\| \right) \]

\[ \leq C(h + k) + Ck \sum_{l=0}^{n-1} t_{n-l}^{-\alpha/2} \|U_l - u_l\|, \]

where we have chosen \( \alpha \in (3/4, 1) \). Hence, Lemma 3.4 yields the preliminary bound

\[ \|U_n - u_n\| \leq C(h + k), \]

which, in view of (3.26), leads to

\[ \|\Phi_n - \phi_n\|_{1,2} \leq C(h + k), \]

\[ \|\Phi_n - \phi_n\| \leq C(h + k + \|U_n - u_n\|), \]

where we have also used the assumption that \( kh^{-d/6} \leq M_4 \). In order to complete the proof, we repeat the steps leading to (3.21) using (3.28) and replacing (3.27) by a more accurate expansion as in (3.20). This gives

\[ \|U_n - u_n\| \leq C(h^2 + k) + Ck \sum_{l=0}^{n-1} t_{n-l}^{-\alpha/2} \|U_l - u_l\|, \]

so that \( \|U_n - u_n\| \leq C(h^2 + k) \) follows by the Gronwall argument of Lemma 3.4, and hence, in view of (3.29), we also obtain \( \|\Phi_n - \phi_n\| \leq C(h^2 + k) \).

4. Existence and regularity

In this section we study the solvability of the system (1.1)–(1.2). The existence of global weak solutions in two space dimensions (\( \Omega \subset \mathbb{R}^2 \)) was shown by Cimatti [5], see also Rodrigues [15] and Allegretto and Xie [2] for existence results for related problems. The regularity of these solutions, however, is insufficient for the purpose of proving error bounds of optimal order, cf. Theorems 3.1 and 3.3. Building upon the techniques of [5], we obtain global strong solutions with the required regularity in one and two space dimensions. The three-dimensional case remains an open problem.

**Theorem 4.1.** Assume that \( \Omega \subset \mathbb{R}^d, \ d \leq 2, \) is a bounded domain whose boundary is either smooth or a convex polygon. Let \( T > 0, \ r > 2 \) and assume that \( u_0 \in H^2 \cap H^1_0, \ g \in L_{\infty}([0, T], W^2_r), \ g_t \in L_{\infty}([0, T], H^2) \) and \( g_{tt} \in L_{\infty}([0, T], H^1) \). Then (1.1)–(1.2) has a unique solution \( u \in C^1([0, T], L_2) \cap C([0, T], H^2), \ \phi \in L_{\infty}([0, T], H^2) \). Moreover, there is a constant \( C, \) depending on \( T, r, u_0, g, \Omega \) and on \( \sigma \) through the constants \( \kappa, K \) in (1.3), such that for \( t \in [0, T] \) we have

\[ \|u(t)\|_{2,2} + \|u_t(t)\| + \|\Delta^{-1} u_{tt}(t)\| + \|u_t(t)\|_{2,2} + \|u_{tt}(t)\| + \|\phi(t)\|_{2,2} + \|\phi(t)\|_{1,\infty} + \|\phi_t(t)\|_{1,2} \leq C. \]
In order to prepare the way for the proof, we recall some facts that we shall need. The assumption about \( \Omega \) guarantees that for any \( p \in [2, \infty) \) there is \( C \) such that

\[
\|u\|_{2,p} \leq C\|\Delta u\|_{0,p} , \quad \forall u \in W_p^2 \cap H_0^1 ,
\]

see [9]. Under even weaker assumptions about \( \Omega \subset \mathbb{R}^d \) we have the following interpolation result [1]: let \( 1 \leq p \leq \infty \), \( m \geq 1 \) and assume that \( u \in W_p^m \). Then there is a constant \( C = C(m, p, q, d, \Omega) \) such that the inequality

\[
\|u\|_{0,q} \leq C\|u\|_{0,p}^{1-\theta} \|u\|_{m,p}^{\theta} , \quad \text{where} \quad \theta = \frac{d}{m} \left( \frac{1}{p} - \frac{1}{q} \right),
\]

holds for \( q \in [p, \infty) \) if \( m - d/p > 0 \), for \( q \in [p, \infty) \) if \( m - d/p = 0 \), and for \( q \in [p, -d/(m - d/p)] \) if \( m - d/p < 0 \). Note that \( 0 \leq \theta \leq 1 \). We shall also use a theorem of Meyers [13], which we quote here in a special case suitable for our purpose. We use the standard notation \( W_p^1 = \{u \in W_p^1 : u|_{\partial \Omega} = 0\} \) and \( W_q^{-1} \) is the dual space of \( W_q^1 \), where \( q \) and \( q' \) are conjugate exponents.

**Theorem 4.2 (Meyers [13]).** Assume that \( \Omega \subset \mathbb{R}^d \) has the property that, for some \( q \in (2, \infty) \) and \( L \geq 1 \), the Laplacian \( \Delta \) is an isomorphism from \( W_q^1 \) onto \( W_q^{-1} \) with \( \|\Delta^{-1}\| \leq L \), and let the function \( a \) satisfy the inequalities \( 0 < \kappa \leq a(x) \leq K \) for all \( x \in \Omega \). Then there are \( p \in (2, q) \) and \( C > 0 \) depending only on \( q, \kappa, K, L \) such that the following holds true: Let \( f \in (L_p)^d \) be a vector field and let \( u \in H_0^1 \) be the unique solution of

\[
(a\nabla u, \nabla \chi) = (f, \nabla \chi) , \quad \forall \chi \in H_0^1 .
\]

Then \( u \in W_p^1 \) and \( \|\nabla u\|_{0,p} \leq C\|f\|_{0,p} \).

The assumption in Meyers' theorem is satisfied, for example, if \( \Omega \subset \mathbb{R}^2 \) is bounded and \( \partial \Omega \) is either smooth [12] or a polygon [8]. See also [3] for a modern presentation of Meyers' theorem, and [16] for a finite element version.

**Proof of Theorem 4.1.** Let \( V_m \) be the eigenspace corresponding to the \( m \) smallest eigenvalues of the operator \( -\Delta \) with domain of definition \( H^2 \cap H_0^1 \). We consider the initial value problem

\[
(U(t) \in V_m , \quad (U_t, \chi) + (\nabla U, \nabla \chi) = (\sigma(U)|\nabla \Phi|^2, \chi) , \quad \forall \chi \in V_m , \quad t > 0 , \quad (U(0), \chi) = (u_0, \chi) , \quad \forall \chi \in V_m ,
\]

where \( \Phi(t) \) is determined by the linear elliptic boundary value problem

\[
\Phi(t) \in H^1 , \quad \Phi(t) - g(t) \in H_0^1 , \quad \sigma(U)\nabla \Phi, \nabla \chi = 0 , \quad \forall \chi \in H_0^1 , \quad t > 0 .
\]

Clearly, given \( U(t) \) and \( g(t) \), there is a unique solution \( \Phi(t) \) of (4.4). It follows that (4.3) is an initial value problem for a finite-dimensional system of ordinary differential equations for the Fourier coefficients of \( U \). Hence, there exists a unique solution to (4.3) on a time interval \([0, T_m]\), where \( T_m \) depends on \( u_0 \) and \( m \). We proceed to derive a priori bounds, which show that (4.3) has a solution on the prescribed time interval \([0, T]\). These estimates will also allow the passage to the limit in \( U \) and \( \Phi \) as \( m \to \infty \), yielding the existence
of a solution \( u, \phi \) to (1.1)–(1.2) with the desired regularity. This passage to the limit is rather standard and we omit the details (cf. [5]).

Throughout this proof we let \( C \) denote various quantities that may depend on the data \( T, r, u_0, g, \Omega \) and on \( \sigma \) through the constants \( \kappa, K \) in (1.3), but not on \( m \) and \( t \). All estimates that we derive below hold uniformly with respect to \( t \in [0, T] \).

**Step 1.** We begin by showing some preliminary estimates of \( \Phi \). The starting point is the maximum principle, which yields

\[
\|\Phi(t)\|_{0, \infty} \leq \|g(t)\|_{0, \infty} \leq C.
\]

Next we apply Meyers' Theorem 4.2 to equation (4.4), which implies that there is \( p > 2 \) such that \( \|\nabla \Phi\|_{0, p} \leq C \|\nabla g\|_{0, p} \). The constant \( C \) depends only on \( \Omega \) and \( \sigma \) through the bounds in (1.3). The optimal value of \( p \) is unknown; for simplicity we assume that \( 2 < p \leq r \). Together with (4.5), this shows that

\[
\|\Phi(t)\|_{1, p} \leq C.
\]

Further estimates of \( \Phi \) depend on derivatives of \( \sigma(U) \), and we shall take this carefully into account.

First we note that equation (4.4) implies \( -\sigma(U)\Delta \Phi - \nabla \sigma(U) \cdot \nabla \Phi = 0 \), so that, by Hölder's inequality,

\[
\|\Delta \Phi\|_{0, p} = \left\| \frac{\sigma'(U)}{\sigma(U)} U \cdot \nabla \Phi \right\|_{0, p} \leq C \|\nabla U\|_{0, q'} \|\nabla \Phi\|_{0, q},
\]

for any \( q, q' \) satisfying \( 1/q + 1/q' = 1/p \). Applying the regularity estimate (4.1) to the function \( \Phi - g \in H^1_0 \), we thus obtain

\[
\|\Phi\|_{2, p} \leq C \left( \|\Delta \Phi\|_{0, p} + \|g\|_{2, p} \right) \leq C \left( 1 + \|\nabla U\|_{0, q'} \|\nabla \Phi\|_{0, q} \right).
\]

Hence, using also the interpolation inequality (4.2) and (4.6), we have

\[
\|\Phi\|_{2, p} \leq C \left( 1 + \|U\|_{2, 2} \|\Phi\|_{0, p}^{1-\alpha} \right)
\leq C \left( 1 + \|U\|_{2, 2} \|\Phi\|_{0, p}^{1-\alpha} \right)
\leq C \left( 1 + \|U\|_{2, 2}^{1/\alpha} \right) + \frac{1}{2} \|\Phi\|_{2, p},
\]

where \( \alpha = 1 - d/p + d/q = 1 - d/q' \). In the last step we also used Young's inequality

\[
ab \leq \epsilon^{1-\theta} a^{1/\theta} + \epsilon b^{1/(1-\theta)}, \quad \epsilon > 0, \ 0 < \theta < 1, \ a, b \geq 0.
\]

For the above estimate of \( \|\nabla U\|_{0, q'} \) to hold, it is required that \( q' < \infty \), which in its turn is equivalent to \( \alpha < 1 \). We have thus proved the preliminary estimate

\[
\|\Phi(t)\|_{2, p} \leq C \left( 1 + \|U(t)\|_{2, 2}^{1/\alpha} \right), \quad \text{for} \ \alpha \in [1 - d/p, 1),
\]

where \( C \) is independent of \( \alpha \). We next proceed to show that there are \( \beta < 1 \) and \( C > 0 \) such that

\[
\|\Phi(t)\|_{1, \infty} + \|\Phi(t)\|_{1, 4}^2 \leq C \left( 1 + \|U(t)\|_{2, 2}^{\beta} \right).
\]
In fact, arguing as above using (4.6) and (4.8), we have
\[ \| \nabla \Phi \|_{0, \infty} \leq C \| \Phi \|_{1, p}^{-\gamma} \| \Phi \|_{2, p}^2 \leq C \left( 1 + \| U \|_{2, 2}^{2\alpha/\gamma} \right) , \]
where \( \gamma = d/p < 1 \). By taking \( \alpha \) sufficiently near 1, and in view of the maximum norm estimate in (4.5), we obtain the desired sublinear estimate of \( \| \Phi \|_{1, \infty} \) in (4.9). Similarly,
\[ \| \nabla \Phi \|_{0, 4} \leq C \left( \| \Phi \|_{1, 4}^{-\gamma} \| \Phi \|_{2, 4}^2 \right) \leq C \left( 1 + \| U \|_{2, 2}^{2\alpha/\gamma} \right) , \]
where now \( \gamma = d/p - d/4 \). Since \( 2\gamma = (4/p - 1)d/2 < 1 \), the bound for \( \| \Phi \|_{1, 4} \) in (4.9) follows by taking \( \alpha \) sufficiently near 1.

Remark. This is where the restriction to two space variables occurs: if \( d = 3 \), then we must have \( q' \leq 6 \) and \( \alpha \leq 1/2 \), so that we can only guarantee that \( \beta < 3 \) in (4.9).

Step 2. We now estimate \( \| U \|_{2, 2} \) and \( \| U_t \| \). We begin by noting that it suffices to estimate \( \| U_t \| \). Indeed, equation (4.3) implies that \( U_t - \Delta U = P_m (\sigma(U) \nabla \Phi) \), where \( P_m \) denotes the orthogonal projection onto \( V_m \). Hence, using the regularity estimate (4.1), (4.9) and (4.7), we obtain
\[ \| U_t \|_{2, 2} \leq C \left( \| \Delta U \| + \| \sigma(U) \nabla \Phi \| \right) \leq C \left( \| U_t \| + \| \Phi \|_{1, 4}^2 \right) \leq C \left( 1 + \| U_t \| + \| U \|_{2, 2}^\beta \right) \]
where \( \beta < 1 \). This shows that
\[ (4.10) \quad \| U(t) \|_{2, 2} \leq C \left( 1 + \| U_t(t) \| \right) . \]
Taking \( \chi = U_t \) in (4.3), we obtain
\[ \| U_t \|_{2, 2} + \frac{1}{2} \frac{d}{dt} \| \nabla U \|^2 = (\sigma(U) \nabla \Phi, U_t) \leq C \| \Phi \|_{1, 4}^2 \| U_t \| \leq C \left( 1 + \| U_t \|^{\beta} \right) \| U_t \| \leq C + \frac{1}{2} \| U_t \|_{2, 2} , \]
since \( \beta < 1 \), where we have employed (4.9), (4.10) and (4.7). Integration with respect to \( t \) then yields
\[ (4.11) \quad \int_0^1 \| U_t \|_{2, 2} ds + \| \nabla U(t) \|_{1, \infty} \| U_t \|_{2, 2} \leq C \| \nabla (P_m u_0) \|_{1, \infty} + Ct \leq C , \]
since \( U(0) = P_m u_0 \), where \( P_m \) is bounded independently of \( m \) with respect to the norm \( \| \nabla \cdot \| \) .

In order to obtain further estimates of \( U_t \), we differentiate equations (4.3) and (4.4) with respect to \( t \). Beginning with (4.4), we have
\[ (4.12) \quad (\sigma(U) \nabla \Phi_t, \nabla \chi) = -(\sigma(U)_t \nabla \Phi, \nabla \chi) , \quad \forall \chi \in H_0 . \]
Straightforward estimates based on taking \( \chi = \Phi_t - g_t \) give
\[ \| \Phi_t \|_{1, 2} \leq C \left( \| g_t \|_{1, 2} + \| \sigma(U) U_t \nabla \Phi \| \right) \leq C \left( 1 + \| U_t \| \| \Phi \|_{1, \infty} \right) , \]
so that in view of (4.9) and (4.10)

\[(4.13) \quad \|\Phi(t)\|_{1,2} \leq C \left(1 + \|U(t)\|^2\right).\]

Next we note that the source term in (4.3) may be transformed as follows, by Green's formula and equation (4.4):

\[(\sigma(U)|\nabla\Phi|^2, \chi) = -(\sigma(U)\Phi, \nabla\chi), \quad \forall \chi \in V_m.\]

Differentiating equation (4.3) with respect to \(t\), we thus have

\[(4.14) \quad (U_t, \chi) + (\nabla U_t, \nabla \chi) = -((\sigma(U)\Phi, \nabla \chi), \chi), \quad \forall \chi \in V_m.\]

With \(\chi = U_t\) this leads to

\[(4.15) \quad \frac{\partial}{\partial t} \|U_t\|^2 + \|\nabla U_t\|^2 \leq \|\sigma(U)\Phi \nabla \Phi_t\|^2.\]

Here we have

\[
\|\sigma(U)\Phi \nabla \Phi_t\| \leq \|\sigma'(U)U_t \Phi \nabla \Phi\| + \|\sigma(U)\Phi_t \nabla \Phi\| + \|\sigma(U)\Phi \nabla \Phi_t\|
\leq C \left(\|U_t\|\|\Phi\|_{0,\infty} + \|\Phi_t\|_{0,\infty} + \|\Phi\|_{0,\infty} \Phi_1,1,2\right),
\]

where \(1/q + 1/p = 1/2\). Using Sobolev's inequality \(\|\Phi_1\|_{0,q} \leq C\|\Phi_1\|_{1,2}\) and known bounds for \(\Phi\) and \(\Phi_t\) in (4.5), (4.9), (4.13) and (4.10), we arrive at

\[
\|\sigma(U)\Phi \nabla \Phi_t\| \leq C \left(1 + \|U_t\|^2\right).
\]

Using the fact that \(U(0) = P_m u_0\), so that \(\|U(0)\|_{2,2} \leq C\|\Delta U(0)\| \leq C\|\Delta u_0\| \leq C\), and hence by (4.9),

\[
\|U_t(0)\| \leq \|\Delta U(0)\| + \|P_m(\sigma(U(0))\nabla \Phi(0))^2\|
\leq \|\Delta U(0)\| + C\|\Phi(0)\|^2_{1,4} \leq C \left(1 + \|U(0)\|^2_{2,2}\right) \leq C,
\]

we integrate (4.15) to get

\[
\|U_t(t)\|^2 + \int_0^t \|\nabla U_t\|^2 \, ds \leq C + C \int_0^t \|U_t\|^4 \, ds.
\]

Applying Gronwall's lemma together with (4.11), we obtain

\[(4.16) \quad \|U_t(t)\|^2 + \int_0^t \|\nabla U_t\|^2 \, ds \leq C \exp \left(\int_0^t \|U_t\|^2 \, ds\right) \leq C.\]

Substituting this result into (4.10), (4.9), (4.13) and (4.8), we may conclude

\[(4.17) \quad \|U(t)\|_{2,2} + \|U_t(t)\| + \|\Phi(t)\|_{2,2} + \|\Phi(t)\|_{1,\infty} + \|\Phi_t(t)\|_{1,2} \leq C.\]

**Step 3.** It remains to bound \(\|\Delta^{-1} U_t(t)\|\), \(t\|U_t(t)\|_{2,2}\) and \(t\|U(t)\|\). We begin by noting that \(U_t - \Delta U_t = P_m(\sigma(U)\nabla \Phi)^2_t\), where, in view of (4.17),

\[(4.18) \quad \|\sigma(U)|\nabla \Phi|^2_t\| \leq \|\sigma'(U)U_t |\nabla \Phi|^2\| + \|\sigma(U)\nabla \Phi \cdot \nabla \Phi_t\|
\leq C \left(\|U_t\|\|\Phi\|^2_{1,\infty} + \|\Phi\|^4_{1,\infty}\Phi_1,1,2\right) \leq C,
\]

so that

\[(4.19) \quad \|U_t(t)\|_{2,2} \leq C \left(1 + \|U(t)\|\right),\]
and also

$$\|\Delta^{-1} U_{tt}(t)\| \leq \|U_t\| + \|\Delta^{-1}\left(\sigma(U)|\nabla \Phi|^2\right)\| \leq C.$$  

It now only remains to estimate $t\|U_{tt}(t)\|$. In order to do so, we differentiate equation (4.3) with respect to $t$ and substitute $x = U_{tt}$, which after some simple manipulations gives

$$\|U_{tt}\|^2 + \frac{d}{dt}\|\nabla U_t\|^2 \leq \|(\sigma(U)|\nabla \Phi|^2)_{tt}\|^2 \leq C,$$

where we employed (4.18) in the last step. Multiplication by $t$ and integration now yields

$$\int_0^t s\|U_{tt}\|^2 ds + t\|\nabla U_t(t)\|^2 \leq C + \int_0^t \|
abla U_t\|^2 ds \leq C,$$

in view of (4.16). In the next step we differentiate equation (4.14) with respect to $t$ and substitute $x = U_{tt}$ to obtain

$$\int_0^t s\|U_{tt}\|^2 ds + t\|\nabla U_{tt}\|^2 \leq \|(\sigma(U)|\Phi\nabla \Phi)_{tt}\|^2.$$  

Here we have

$$(\sigma(U)|\Phi\nabla \Phi)_{tt} = \sigma(U)_{tt}\Phi\nabla \Phi + \sigma(U)\Phi_{tt}\nabla \Phi$$  

$$+ \sigma(U)\Phi_{tt}\Phi_t\nabla \Phi + 2\sigma(U)_t\Phi_{tt}\Phi_t\nabla \Phi$$

$$+ 2\sigma(U)_t\Phi_{tt}\Phi_t + 2\sigma(U)\Phi_t\Phi_{tt}\Phi_t.$$  

In order to estimate the terms on the right, we shall repeatedly use bounds from (4.17) together with

$$\|U_t\|_{0,\infty} \leq C\|U_t\|_{2,2} \leq C\left(1 + \|U_{tt}\|\right),$$

which follows from Sobolev's inequality and (4.19). Thus,

$$\|(\sigma(U)_t|\Phi_t\nabla \Phi)\| = \|(\sigma(U)_{tt}\Phi_t\nabla \Phi) + \sigma(U)\Phi_{tt}\Phi_t\nabla \Phi\|$$

$$\leq C\left(\|U_{tt}\| + \|U_t\|\|U_t\|_{0,\infty}\|\Phi_t\|^2_{1,\infty}\right)$$

$$\leq C\left(1 + \|U_{tt}\|\right),$$

and

$$\|(\sigma(U)_t|\Phi_t\nabla \Phi)\| + \|(\sigma(U)_t|\Phi_{tt}\Phi_t)\| \leq C\|U_t\|_{0,\infty}\|\Phi_t\|_{1,2}\|\Phi_t\|_{1,\infty} \leq C\left(1 + \|U_{tt}\|\right).$$

Similarly,

$$\|(\sigma(U)|\Phi_t\nabla \Phi)\| \leq C\|\Phi_t\|_{0,\infty}\|\Phi_t\|_{1,2} \leq C\|\Phi_t\|_{0,\infty}.$$

Application of Meyers' theorem to equation (4.12) shows that

$$\|\nabla \Phi_t\|_{0,p} \leq C\left(\|\sigma'(U)\nabla \Phi\|_{0,p} + \|\sigma(U)\nabla g_t\|_{0,p}\right)$$

$$\leq C\left(1 + \|U_t\|_{0,\infty}\|\Phi_t\|_{1,p}\right) \leq C\left(1 + \|U_{tt}\|\right),$$

where $p \in (2, r]$ is the same as before, and since $\|\Phi_t\|_{0,\infty} \leq C\|\Phi_t\|_{1,p}$ we may conclude that

$$\|(\sigma(U)|\Phi_t\nabla \Phi)\| \leq C\left(1 + \|U_{tt}\|\right).$$

Finally, for the remaining two terms in (4.22) we have

$$\|(\sigma(U)|\Phi_{tt}\nabla \Phi)\| + \|(\sigma(U)|\Phi_t\nabla \Phi_{tt}\| \leq C\|\Phi_t\|_{1,\infty}\|\Phi_{tt}\|_{1,2} \leq C\|\Phi_{tt}\|_{1,2}.$$
In order to bound $\|\Phi_{tt}\|_{1,2}$, we differentiate equation (4.12) with respect to $t$ to get
\[ (\sigma(U)\nabla \Phi_{tt}, \nabla \chi) = - (\sigma(U)_{tt} \nabla \Phi + 2\sigma(U)_t \nabla \Phi_t, \nabla \chi), \quad \forall \chi \in H_0^1. \]
With $\chi = \Phi_{tt} - g_{tt}$ this gives
\[ \|\Phi_{tt}\|_{1,2} \leq C \left( \|g_{tt}\|_{1,2} + (\|U_{tt}\| + \|U_t\|_0,\infty)\|\Phi\|_{1,\infty} + \|U_t\|_0,\infty \|\Phi_t\|_{1,2} \right) \]
\[ \leq C \left( 1 + \|U_{tt}\| \right). \]
Together, these estimates show that
\[ \|(\sigma(U)\Phi \nabla \Phi)_{tt}\| \leq C \left( 1 + \|U_{tt}\| \right). \]
If we substitute this into (4.21), multiply by $t^2$ and integrate, then we get
\[ t^2 \|U_{tt}(t)\|^2 + \int_0^t s^2 \|\nabla U_{tt}\|^2 ds \leq C \left( 1 + \int_0^t s \|U_{tt}\|^2 ds \right) \leq C, \]
in view of (4.20), and the proof of the a priori bounds is complete.

**Step 4.** Finally, in order to prove uniqueness, we let $u_1$, $\phi_1$ and $u_2$, $\phi_2$ be two solutions of (1.1)-(1.2). By means of the a priori bounds $\|\phi_i\|_{1,\infty} \leq C$, $i = 1, 2$, it is straightforward to show that $\|\phi_1 - \phi_2\|_{1,2} \leq C\|u_1 - u_2\|$, and $\frac{d}{dt}\|u_1 - u_2\|^2 \leq C\|u_1 - u_2\|^2$, so that uniqueness follows. \(\square\)

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