

## MULTIGRID METHODS FOR THE COMPUTATION OF SINGULAR SOLUTIONS AND STRESS INTENSITY FACTORS I: CORNER SINGULARITIES

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ABSTRACT. We consider the Poisson equation  $-\Delta u = f$  with homogeneous Dirichlet boundary condition on a two-dimensional polygonal domain  $\Omega$  with re-entrant angles. A multigrid method for the computation of singular solutions and stress intensity factors using piecewise linear functions is analyzed. When  $f \in L^2(\Omega)$ , the rate of convergence to the singular solution in the energy norm is shown to be  $\mathcal{O}(h)$ , and the rate of convergence to the stress intensity factors is shown to be  $\mathcal{O}(h^{1+(\pi/\omega)-\epsilon})$ , where  $\omega$  is the largest re-entrant angle of the domain and  $\epsilon > 0$  can be arbitrarily small. The cost of the algorithm is  $\mathcal{O}(h^{-2})$ . When  $f \in H^1(\Omega)$ , the algorithm can be modified so that the convergence rate to the stress intensity factors is  $\mathcal{O}(h^{2-\epsilon})$ . In this case the maximum error of the multigrid solution over the vertices of the triangulation is shown to be  $\mathcal{O}(h^{2-\epsilon})$ .

### 1. INTRODUCTION

Let  $\Omega$  be a bounded polygonal domain in  $\mathbb{R}^2$  with at least one re-entrant angle. Consider the Poisson equation with homogeneous Dirichlet boundary condition:

$$(1.1) \quad \begin{aligned} -\Delta u &= f & \text{in } \Omega, \\ u &= 0 & \text{on } \partial\Omega, \end{aligned}$$

where  $f \in L^2(\Omega)$ .

Let  $\omega_1, \dots, \omega_J$  be the internal angles of  $\Omega$  which satisfy  $\pi < \omega_j < 2\pi$  and let  $p_j$  be the corresponding vertices. It is well known (cf. [23], [27], [32], [39]) that the unique solution  $u \in H_0^1(\Omega)$  of (1.1) has the representation

$$(1.2) \quad u = \sum_{j=1}^J \kappa_j s_j + w,$$

where  $w \in H^2(\Omega) \cap H_0^1(\Omega)$  and the singular functions  $s_j$  are defined as follows. Let polar coordinates  $(r_j, \theta_j)$  be chosen at the vertex  $p_j$  so that the internal angle  $\omega_j$  is spanned by the two half lines  $\theta_j = 0$  and  $\theta_j = \omega_j$ . Then we have

$$(1.3) \quad s_j(r_j, \theta_j) = \phi_j(r_j) r_j^{\pi/\omega_j} \sin((\pi/\omega_j)\theta_j),$$

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where  $\phi_j$  ( $j = 1, \dots, J$ ) are smooth cut-off functions which equal 1 identically in a neighborhood of 0, and the supports of the  $\phi_j$ 's are small enough so that the singular functions  $s_j$  vanish identically on  $\partial\Omega$ . Moreover, the following regularity estimate holds:

$$(1.4) \quad \|w\|_{H^2(\Omega)} + \sum_{j=1}^J |\kappa_j| \lesssim \|f\|_{L^2(\Omega)}.$$

(Throughout this paper the statement  $F \lesssim G$  means that  $F$  is bounded by  $G$  multiplied by a constant which is independent of the mesh size and grid level. In the statement  $F \lesssim_\epsilon G$ , the constant can depend on  $\epsilon$ .) The coefficient  $\kappa_j$  can be expressed in terms of  $u$  by the following *extraction formula*:

$$(1.5) \quad \kappa_j = \frac{1}{\pi} \left\{ \int_{\Omega} f s_{-j} dx + \int_{\Omega} u \Delta s_{-j} dx \right\},$$

where the dual singular function  $s_{-j}$  is defined in the polar coordinate system  $(r_j, \theta_j)$  as

$$(1.6) \quad s_{-j}(r_j, \theta_j) = \phi_j(r_j) r_j^{-\pi/\omega_j} \sin((\pi/\omega_j)\theta_j)$$

(cf. [6], [7], [3], [27], [24], [39]).

Formulas similar to (1.2) and (1.5) also hold for the solution of two-dimensional elasticity problems (cf. [49], [28], [29], [30], [33]). In that context, the coefficients  $\kappa_j$  are known as stress intensity factors, and we will adopt that terminology here. These quantities play a particularly important role in linear fracture mechanics.

In view of (1.5), it is natural to compute an approximation  $\kappa_{j,h}$  to  $\kappa_j$  by

$$(1.7) \quad \kappa_{j,h} = \frac{1}{\pi} \left\{ \int_{\Omega} f s_{-j} dx + \int_{\Omega} u_h \Delta s_{-j} dx \right\},$$

where  $u_h$  is a finite element approximation of  $u$ . The accuracy of  $\kappa_{j,h}$  computed by (1.7) depends on the accuracy of  $u_h$ , which ultimately depends on the regularity of  $u$ .

It is known (cf. [27]) that the singular functions  $s_j \in H^r(\Omega)$  for all  $r < 1 + (\pi/\omega_j)$  and  $s_j \notin H^{1+(\pi/\omega_j)}(\Omega)$ . It follows from (1.2) that the best one can say about the regularity of  $u$  is

$$(1.8) \quad u \in H^r(\Omega) \quad \forall r < 1 + \frac{\pi}{\omega},$$

where

$$(1.9) \quad \omega = \max(\omega_1, \omega_2, \dots, \omega_J).$$

Suppose  $V_h \subseteq H_0^1(\Omega)$  is the piecewise linear finite element space associated with a quasi-uniform triangulation  $\mathcal{T}_h$ ,  $h = \max_{T \in \mathcal{T}_h} \text{diam } T$ , and  $\tilde{u}_h \in V_h$  satisfies

$$(1.10) \quad \int_{\Omega} \nabla \tilde{u}_h \cdot \nabla v dx = \int_{\Omega} f v dx \quad \forall v \in V_h.$$

It follows from (1.8) that for any  $\epsilon > 0$  we have

$$(1.11) \quad \|u - \tilde{u}_h\|_{H^1(\Omega)} \lesssim_\epsilon h^{(\pi/\omega) - \epsilon} \|f\|_{L^2(\Omega)},$$

and

$$(1.12) \quad \|u - \tilde{u}_h\|_{L^2(\Omega)} \lesssim_\epsilon h^{2(\pi/\omega) - \epsilon} \|f\|_{L^2(\Omega)}.$$

If  $\tilde{\kappa}_{j,h}$  is computed by (1.7) using  $\tilde{u}_h$ , then (1.5), (1.7) and (1.12) imply that

$$(1.13) \quad \begin{aligned} |\kappa_j - \tilde{\kappa}_{j,h}| &\leq \frac{1}{\pi} \int_{\Omega} |(u - \tilde{u}_h) \Delta s_{-j}| dx \\ &\lesssim \|u - \tilde{u}_h\|_{L^2(\Omega)} \\ &\lesssim_{\epsilon} h^{2(\pi/\omega) - \epsilon} \|f\|_{L^2(\Omega)}. \end{aligned}$$

Note that  $\Delta s_{-j} = 0$  near  $p_j$ , so the integration in (1.13) is only over a domain away from  $p_j$ , where  $s_{-j}$  is a smooth function. Also, the estimate (1.13) cannot be improved due to the pollution effect of the corner singularity (cf. [40], [52], [53]). Thus the lack of regularity adversely affects the accuracy of the finite element solution  $\tilde{u}_h$  and hence  $\tilde{\kappa}_{j,h}$ .

In this paper, we develop, on quasi-uniform grids, a multigrid method for the computation of the singular solution  $u$  and the stress intensity factors  $\kappa_j$  that obtains better estimates than (1.11)–(1.13). The basic idea is that (1.1) and (1.2) imply that  $w$ , the regular part of  $u$ , is the solution of

$$(1.14) \quad \begin{aligned} -\Delta w &= f + \sum_{j=1}^J \kappa_j \Delta s_j \quad \text{in } \Omega, \\ w &= 0 \quad \text{on } \partial\Omega. \end{aligned}$$

If the  $\kappa_j$ 's were known, we could solve (1.14) using piecewise linear finite elements, and the solution would have a good convergence rate since  $w \in H^2(\Omega)$ . Unfortunately, the  $\kappa_j$ 's are unknown, so we instead apply the finite element method on the  $k^{\text{th}}$  level to the following variational problem:

Find  $\hat{w}_k \in H_0^1(\Omega)$  such that

$$(1.15) \quad \int_{\Omega} \nabla \hat{w}_k \cdot \nabla v \, dx = \int_{\Omega} \left( f + \sum_{j=1}^J \kappa_{j,k} \Delta s_j \right) v \, dx \quad \forall v \in H_0^1(\Omega),$$

where the approximate stress intensity factors  $\kappa_{j,k}$  are computed by the extraction formula (1.5) using the approximate solution  $u_{k-1}$  obtained in the  $(k-1)^{\text{st}}$  level, i.e.,

$$(1.16) \quad \kappa_{j,k} = \frac{1}{\pi} \left\{ \int_{\Omega} f s_{-j} \, dx + \int_{\Omega} u_{k-1} \Delta s_{-j} \, dx \right\}.$$

We obtain, on the  $k^{\text{th}}$  level, a piecewise linear approximate solution  $w_k$  to  $\hat{w}_k$  by a standard multigrid algorithm. The approximate solution  $u_k$  to  $u$  is then defined to be

$$(1.17) \quad u_k = \sum_{j=1}^J \kappa_{j,k} s_j + w_k.$$

In other words, we have a full multigrid algorithm where the right-hand side of the finite element equation changes from level to level (cf. (1.15)) and we are really computing the regular part  $w$  of the solution. The improvement in the convergence rate is possible because  $w$  has better regularity than  $u$ . We will show

(cf. Theorem 4.1) that

$$(1.18) \quad |u - u_k|_{H^1(\Omega)} \lesssim h_k \|f\|_{L^2(\Omega)},$$

$$(1.19) \quad \sum_{j=1}^J |\kappa_j - \kappa_{j,k}| \lesssim_\epsilon h_k^{1+(\pi/\omega)-\epsilon} \|f\|_{L^2(\Omega)}.$$

The estimate (1.18) is optimal for the piecewise linear finite element space, and the estimate (1.19) improves the estimate in (1.13). The computational cost of our multigrid method is proportional to the dimension of  $V_h$ , i.e., is of order  $C_\epsilon h^{-2}$ .

We also consider a second multigrid method in the case where  $f \in H^1(\Omega)$ . Let  $\omega_1, \dots, \omega_N$  be the internal angles of  $\Omega$  which satisfy  $\pi/2 < \omega_j < 2\pi$ . When  $f \in H^1(\Omega)$ , the solution  $u$  of (1.1) can be written as (cf. [27], [23])

$$(1.20) \quad u = \sum_{j=1}^N \sum_{\ell \in \mathcal{L}_j} \kappa_{j,\ell} s_{j,\ell} + w,$$

where  $w \in H^{3-\epsilon}(\Omega) \cap H_0^1(\Omega)$  for any  $\epsilon > 0$ ,

$$(1.21) \quad \mathcal{L}_j = \{\ell \in \mathbb{N} : \ell(\pi/\omega_j) < 2\},$$

and in appropriate polar coordinates,

$$(1.22) \quad s_{j,\ell}(r_j, \theta_j) = \phi_j(r_j) r_j^{\ell(\pi/\omega_j)} \sin(\ell(\pi/\omega_j)\theta_j).$$

Moreover, the following regularity estimates hold:

$$(1.23) \quad \sum_{j=1}^N \sum_{\ell \in \mathcal{L}_j} |\kappa_{j,\ell}| \lesssim \|f\|_{H^1(\Omega)} \quad \text{and} \quad \|w\|_{H^{3-\epsilon}(\Omega)} \lesssim_\epsilon \|f\|_{H^1(\Omega)}.$$

The coefficient  $\kappa_{j,\ell}$  can be expressed in terms of  $u$  by

$$(1.24) \quad \kappa_{j,\ell} = \frac{1}{\ell\pi} \left\{ \int_{\Omega} f s_{j,-\ell} dx + \int_{\Omega} u \Delta s_{j,-\ell} dx \right\},$$

where the dual singular function  $s_{j,-\ell}$  is defined by

$$(1.25) \quad s_{j,-\ell}(r_j, \theta_j) = \phi_j(r_j) r_j^{-\ell\pi/\omega_j} \sin(\ell(\pi/\omega_j)\theta_j).$$

Using similar ideas and taking advantage of a superconvergence result for linear finite elements, we develop a multigrid method that produces, at a cost of  $C_\epsilon h_k^{-2}$ , an approximate solution  $u_k$  in the form

$$(1.26) \quad u_k = \sum_{j=1}^N \sum_{\ell \in \mathcal{L}_j} \kappa_{j,\ell,k} s_{j,\ell} + w_k,$$

where  $w_k$  is a piecewise linear function on the  $k^{\text{th}}$  level triangulation, and we show that (cf. Theorem 5.4)

$$(1.27) \quad |u - u_k|_{H^1(\Omega)} \lesssim h_k \|f\|_{H^1(\Omega)},$$

and

$$(1.28) \quad \sum_{j=1}^J \sum_{\ell \in \mathcal{L}} |\kappa_{j,\ell} - \kappa_{j,\ell,k}| \lesssim_\epsilon h_k^{2-\epsilon} \|f\|_{H^1(\Omega)}.$$

As a corollary (cf. Corollary 5.6), we obtain

$$(1.29) \quad \max_p |u(p) - u_k(p)| \lesssim_\epsilon h_k^{2-\epsilon} \|f\|_{H^1(\Omega)},$$

where the maximum is taken over all the vertices  $p$  of the  $k^{\text{th}}$  level triangulation.

Corner singularities can also be overcome by the method of local grid refinement (cf. [1], [2]). Using this method, the number of degrees of freedom is of order  $\mathcal{O}(h^{-2})$  and the error of the computed stress intensity factor is of order  $\mathcal{O}(h^2)$ . This method also has the advantage that it does not require the knowledge of the exact forms of the singular functions. However, it is more difficult in this approach to use multilevel techniques (cf. [57], [58], [59], [60], [45]).

Another method for the computation of the stress intensity factors is the dual singular function method (DSFM) (cf. [25], [7], [8]) where extraction formulas are also used. In each iterative step of the DSFM, a finite element equation of the form (1.15) is solved on the same grid. The algorithms developed in this paper can in some sense be viewed as a multigrid version of the DSFM.

We should also mention that in [38] a multigrid method based on an extrapolation technique is proposed, where  $\mathcal{O}(h^{2-\epsilon})$  convergence for the stress intensity factors with cost  $\mathcal{O}(h^{-2})$  is claimed. However, the result in [38] is obtained under the unproven assumption that the standard multigrid method using piecewise linear finite elements is a contraction with respect to the  $L^2$  norm in the presence of corner singularities. There are also no numerical results in [38] to corroborate the claim.

The rest of this paper is organized as follows. The multigrid algorithms are defined in Section 2 and the convergence analyses are carried out in Sections 3, 4, and 5. The results of numerical experiments are presented in Section 6. Section 7 contains some concluding remarks.

## 2. THE MULTIGRID ALGORITHMS

Let  $\{\mathcal{T}_k\}$ ,  $k \geq 1$ , be a family of triangulations of  $\Omega$ , where  $\mathcal{T}_{k+1}$  is obtained from  $\mathcal{T}_k$  by regular subdivision, i.e., by connecting the midpoints of the edges of the triangles in  $\mathcal{T}_k$ , and define  $h_k = \max_{T \in \mathcal{T}_k} \text{diam } T$ . Let  $V_k = \{v \in H_0^1(\Omega) : v|_T \in \mathcal{P}_1(T) \ \forall T \in \mathcal{T}_k\}$  be the piecewise linear finite element space associated with  $\mathcal{T}_k$ .

We define the discrete inner product  $(\cdot, \cdot)_k$  by

$$(2.1) \quad (v_1, v_2)_k = h_k^2 \sum v_1(p)v_2(p) \quad \forall v_1, v_2 \in V_k,$$

where the summation is taken over all the vertices  $p$  of  $\mathcal{T}_k$ . The operators  $A_k : V_k \rightarrow V_k$  and  $I_k^{k-1} : V_k \rightarrow V_{k-1}$  are defined by

$$(2.2) \quad (A_k v_1, v_2)_k = \int_{\Omega} \nabla v_1 \cdot \nabla v_2 \, dx \quad \forall v_1, v_2 \in V_k,$$

and

$$(2.3) \quad (I_k^{k-1} v, w)_{k-1} = (v, w)_k \quad \forall v \in V_k, w \in V_{k-1} (\subseteq V_k).$$

Clearly,  $A_k$  is symmetric positive definite with respect to  $(\cdot, \cdot)_k$ . Since  $(v, v)_k$  is equivalent to  $\|v\|_{L^2(\Omega)}$  for  $v \in V_k$ , it follows from (2.2) and a standard inverse estimate (cf. [20], [16]) that the spectral radius  $\rho(A_k)$  satisfies  $\rho(A_k) \lesssim h_k^{-2}$ .

For the convergence analysis in Section 3, we also need the Ritz projection operator  $P_k : H_0^1(\Omega) \rightarrow V_k$  defined by

$$(2.4) \quad \int_{\Omega} \nabla(\zeta - P_k \zeta) \cdot \nabla v \, dx = 0 \quad \forall \zeta \in H_0^1(\Omega), v \in V_k.$$

It is easy to see that

$$(2.5) \quad I_k^{k-1} A_k = A_{k-1} P_{k-1}.$$

The following is the standard one-sided  $k^{\text{th}}$ -level multigrid iteration: For  $p = 1$ , this is the usual  $V(m, 0)$  cycle, and for  $p = 2$ , this is the usual  $W(m, 0)$  cycle.

**The  $k^{\text{th}}$  level iteration.** The  $k^{\text{th}}$  level iteration with initial guess  $z_0$  yields  $MG(k, z_0, g)$  as an approximate solution to the equation

$$(2.6) \quad A_k z = g.$$

For  $k = 1$ ,  $MG(1, z_0, g)$  is the solution obtained from an exact solver. In other words,

$$(2.7) \quad MG(1, z_0, g) = A_1^{-1} g.$$

For  $k > 1$ , there are two steps.

*Smoothing Step* Let  $z_l \in V_k$  ( $1 \leq l \leq m$ ) be defined recursively by the equations

$$(2.8) \quad z_l = z_{l-1} + \frac{1}{\Lambda_k} (g - A_k z_{l-1}), \quad 1 \leq l \leq m,$$

where  $m$  is a positive integer independent of  $k$ , and  $\Lambda_k := Ch_k^{-2}$  dominates the spectral radius of  $A_k$ .

*Correction Step* Let  $\bar{g} = I_k^{k-1}(g - A_k z_m)$  and  $q_i \in V_{k-1}$  ( $0 \leq i \leq p, p = 1$  or  $2$ ) be defined recursively by

$$(2.9) \quad q_0 = 0 \quad \text{and} \quad q_i = MG(k-1, q_{i-1}, \bar{g}), \quad 1 \leq i \leq p.$$

The output is obtained by combining the two steps:

$$(2.10) \quad MG(k, z_0, g) = z_m + q_p.$$

*Remark.* We use Richardson relaxation in (2.8) to simplify the analysis in Section 3. Other smoothers (cf. [37], [31], [4], [36], [10], [12]) can of course be used.

**Full multigrid algorithm I.** When  $f \in L^2(\Omega)$ , we use a nested iteration (where each  $k^{\text{th}}$  level iteration is applied  $n$  times) to compute  $\kappa_{j,k} \in \mathbb{R}$  ( $1 \leq j \leq J$ ) and  $w_k \in V_k$  so that  $\kappa_{j,k}$  is a good approximation of  $\kappa_j$ , and  $u_k = \sum_{j=1}^J \kappa_{j,k} s_j + w_k$  is a good approximation of the solution  $u$  of (1.1) (cf. (1.2)).

**The nested iteration.** For  $k = 1$ ,

$$(2.11) \quad w_1 = A_1^{-1} g_1,$$

where  $g_1 \in V_1$  is defined by

$$(2.12) \quad (g_1, v)_1 = \int_{\Omega} f v \, dx \quad \forall v \in V_1,$$

and we set

$$(2.13) \quad \kappa_{j,1} = 0 \quad \text{for} \quad 1 \leq j \leq J,$$

$$(2.14) \quad u_1 = w_1.$$

For  $k \geq 2$ , the numbers  $\kappa_{j,k} \in \mathbb{R}$  are computed by

$$(2.15) \quad \kappa_{j,k} = \frac{1}{\pi} \left\{ \int_{\Omega} f s_{-j} dx + \int_{\Omega} u_{k-1} \Delta s_{-j} dx \right\} \quad \text{for } 1 \leq j \leq J,$$

and  $w_k \in V_k$  is obtained recursively by

$$(2.16) \quad \begin{aligned} w_{k,0} &= w_{k-1}, \\ w_{k,l} &= MG(k, w_{k,l-1}, g_k) \quad \text{for } 1 \leq l \leq n, \\ w_k &= w_{k,n}, \end{aligned}$$

where  $n$  is a positive integer independent of  $k$ , and  $g_k \in V_k$  is defined by

$$(2.17) \quad (g_k, v)_k = \int_{\Omega} \left( f + \sum_{j=1}^J \kappa_{j,k} \Delta s_j \right) v dx \quad \forall v \in V_k.$$

We then define  $u_k$  by

$$(2.18) \quad u_k = \sum_{j=1}^J \kappa_{j,k} s_j + w_k.$$

**Full multigrid algorithm II.** When  $f \in H^1(\Omega)$ , we use a nested iteration (where each  $k^{\text{th}}$  level iteration is applied  $n$  times) to compute  $\kappa_{j,\ell,k} \in \mathbb{R}$  ( $1 \leq j \leq N$ ,  $\ell \in \mathcal{L}_j$ ) and  $w_k \in V_k$  so that  $\kappa_{j,\ell,k}$  is a good approximation of  $\kappa_{j,\ell}$ , and  $u_k = \sum_{j=1}^N \sum_{\ell \in \mathcal{L}_j} \kappa_{j,\ell,k} s_{j,\ell} + w_k$  is a good approximation of the solution  $u$  of (1.1) (cf. (1.20)).

**The nested iteration** For  $k = 1$ ,

$$(2.19) \quad w_1 = A_1^{-1} g_1,$$

where  $g_1 \in V_1$  is defined by

$$(2.20) \quad (g_1, v)_1 = \int_{\Omega} f v dx \quad \forall v \in V_1,$$

and we set

$$(2.21) \quad \kappa_{j,\ell,1} = 0 \quad \text{for } 1 \leq j \leq N, \ell \in \mathcal{L}_j,$$

$$(2.22) \quad u_1 = w_1.$$

For  $k \geq 2$ , the numbers  $\kappa_{j,\ell,k} \in \mathbb{R}$  are computed by

$$(2.23) \quad \kappa_{j,\ell,k} = \frac{1}{\ell\pi} \left\{ \int_{\Omega} f s_{j,-\ell} dx + \int_{\Omega} u_{k-1} \Delta s_{j,-\ell} dx \right\} \quad \text{for } 1 \leq j \leq N, \ell \in \mathcal{L}_j,$$

and  $w_k \in V_k$  is obtained recursively by

$$(2.24) \quad \begin{aligned} w_{k,0} &= I_{k-1}^k w_{k-1}, \\ w_{k,l} &= MG(k, w_{k,l-1}, g_k) \quad \text{for } 1 \leq l \leq n, \\ w_k &= w_{k,n}, \end{aligned}$$

where  $n$  is a positive integer independent of  $k$ , and  $g_k \in V_k$  is defined by

$$(2.25) \quad (g_k, v)_k = \int_{\Omega} \left( f + \sum_{j=1}^N \sum_{\ell \in \mathcal{L}_j} \kappa_{j,\ell,k} \Delta s_{j,\ell} \right) v dx \quad \forall v \in V_k.$$

We then define  $u_k$  by

$$(2.26) \quad u_k = \sum_{j=1}^N \sum_{\ell \in \mathcal{L}_j} \kappa_{j,\ell,k} s_{j,\ell} + w_k.$$

The intergrid transfer operator  $I_{k-1}^k : V_{k-1} \rightarrow V_k$  in (2.24) is defined as follows. We assume that  $\mathcal{T}_1$  is also obtained by connecting the midpoints of a coarser triangulation  $\mathcal{T}_0$ . Let  $Q_k \subset H_0^1(\Omega)$  ( $k = 0, 1, 2, \dots$ ) be the quadratic Lagrange finite element space associated with  $\mathcal{T}_k$ . Let  $\mathcal{I}_{k-2}^{k-1} : Q_{k-2} \rightarrow V_{k-1}$  and  $\mathcal{I}_{k-2}^k : Q_{k-2} \rightarrow V_k$  be the nodal interpolation operators. Since  $Q_{k-2}$  and  $V_{k-1}$  share the same nodal points, it is clear that  $\mathcal{I}_{k-2}^{k-1}$  is an isomorphism from  $Q_{k-2}$  onto  $V_{k-1}$ . We define, for  $k = 2, 3, \dots$ ,

$$(2.27) \quad I_{k-1}^k = \mathcal{I}_{k-2}^k \circ (\mathcal{I}_{k-2}^{k-1})^{-1}.$$

This more sophisticated intergrid transfer operator is needed to maintain a higher convergence rate for this full multigrid algorithm.

*Remark.* A standard argument (cf. [5]) shows that the costs for both full multigrid algorithms are proportional to  $\dim V_k$ .

### 3. CONTRACTION PROPERTIES OF THE $k^{\text{TH}}$ LEVEL ITERATION

We have the following result (cf. [9], [10], [13], [14]) for the convergence of the  $k^{\text{th}}$  level iteration in the energy norm.

**Lemma 3.1.** *Let  $p = 1$  ( $V$ -cycle) or  $2$  ( $W$ -cycle) and  $m \geq 1$  in the  $k^{\text{th}}$  level iteration. Then there exists a  $\delta < 1$ , independent of  $k$ , such that*

$$(3.1) \quad |z - MG(k, z_0, g)|_{H^1(\Omega)} \leq \delta |z - z_0|_{H^1(\Omega)}.$$

*Remark.* The estimate (3.1) was obtained in [13] and [14] for the symmetric  $V$ -cycle algorithm. Since the finite element spaces  $V_k$  are conforming and nested, it also holds (cf. [37]) for the one-sided  $V$ -cycle and  $W$ -cycle algorithms described in Section 2. Moreover, the contraction number  $\delta$  for the  $W$ -cycle algorithm can be made arbitrarily small by increasing the number of smoothing steps  $m$  (cf. [5]).

We also have the following convergence result for the  $k^{\text{th}}$  level iteration in the  $\|\cdot\|_{H^{1-(\pi/\omega)+\epsilon}(\Omega)}$  norm.

**Lemma 3.2.** *Let  $p = 2$  ( $W$ -cycle),  $0 < \delta < 1$ ,  $0 < \epsilon < \pi/\omega$  and  $\alpha_\epsilon = 1 - (\pi/\omega) + \epsilon \neq 1/2$ . If the number of smoothing steps  $m$  in the  $k^{\text{th}}$  level iteration is sufficiently large, then we have*

$$(3.2) \quad \|z - MG(k, z_0, g)\|_{H^{\alpha_\epsilon}(\Omega)} \leq \delta \|z - z_0\|_{H^{\alpha_\epsilon}(\Omega)}.$$

*Proof.* We follow the methodology in [5]. First we consider the two-grid algorithm where  $q_p$  in (2.10) is replaced by (cf. (2.5))

$$(3.3) \quad q = A_{k-1}^{-1} \bar{g} = A_{k-1}^{-1} I_k^{k-1} A_k (z - z_m) = P_{k-1} (z - z_m).$$

Let  $R_k : V_k \rightarrow V_k$  be defined by

$$(3.4) \quad R_k = I - \frac{1}{\Lambda_k} A_k.$$

Then, by (2.8) and (3.4), we have

$$(3.5) \quad z - z_m = R_k^m(z - z_0).$$

It follows from (3.3) and (3.5) that the error of the output  $\tilde{z} = z_m + q$  of the two-grid method is given by

$$(3.6) \quad z - \tilde{z} = z - z_m - q = (I - P_{k-1})(z - z_m) = (I - P_{k-1})R_k^m(z - z_0).$$

For  $0 \leq s \leq 1$ , we define

$$(3.7) \quad \|v\|_s = \sqrt{(A_k^s v, v)_k} \quad \forall v \in V_k.$$

We immediately have

$$(3.8) \quad \|v\|_1 \leq [\rho(A_k^{1-s})]^{1/2} \|v\|_s \lesssim h_k^{s-1} \|v\|_s \quad \forall v \in V_k, 0 \leq s \leq 1,$$

and since  $\Lambda_k = Ch_k^{-2}$  dominates the spectral radius of  $A_k$ ,

$$(3.9) \quad \|R_k v\|_s \leq \|v\|_s \quad \forall v \in V_k, 0 \leq s \leq 1.$$

The effect of the smoothing step is measured by the following *smoothing property*:

$$(3.10) \quad \begin{aligned} \|R_k^m v\|_1 &= ((A_k R_k^m v, R_k^m v)_k)^{1/2} \\ &\leq \Lambda_k^{s/2} [\rho(\Lambda_k^{-s} A_k^s R_k^{2m})]^{1/2} (A_k^{1-s} v, v)_k^{1/2} \\ &\lesssim h_k^{-s} \left[ \sup_{0 \leq t \leq 1} t^s (1-t)^{2m} \right]^{1/2} \|v\|_{1-s} \\ &\lesssim h_k^{-s} m^{-s/2} \|v\|_{1-s} \quad \forall v \in V_k, 0 \leq s \leq 1. \end{aligned}$$

The effect of the correction step is given by the following *approximation property*:

$$(3.11) \quad \|v - P_{k-1} v\|_{H^{\alpha_\epsilon}(\Omega)} \lesssim_\epsilon h_k^{\pi/\omega - \epsilon} |v - P_{k-1} v|_{H^1(\Omega)} \quad \forall v \in H_0^1(\Omega).$$

We will establish (3.11) by a duality argument. Let  $\phi \in H^{-\alpha_\epsilon}(\Omega)$  and  $\zeta \in H_0^1(\Omega)$  satisfy

$$(3.12) \quad \int_\Omega \nabla \zeta \cdot \nabla v \, dx = \phi(v) \quad \forall v \in H_0^1(\Omega).$$

It is well known (cf. [23]) that  $\zeta \in H^{1+(\pi/\omega)-\epsilon}(\Omega)$  and

$$(3.13) \quad \|\zeta\|_{H^{1+(\pi/\omega)-\epsilon}(\Omega)} \lesssim_\epsilon \|\phi\|_{H^{-\alpha_\epsilon}(\Omega)}.$$

Let  $\Pi_k$  be the nodal interpolation operator associated with  $V_k$ . It follows from standard interpolation error estimates (cf. [20], [16]) and (3.13) that

$$(3.14) \quad |\zeta - \Pi_k \zeta|_{H^1(\Omega)} \lesssim_\epsilon h_k^{(\pi/\omega)-\epsilon} \|\phi\|_{H^{-\alpha_\epsilon}(\Omega)}.$$

Using (2.4), (3.12) and (3.14), we have

$$(3.15) \quad \begin{aligned} \phi(v - P_{k-1} v) &= \int_\Omega \nabla \zeta \cdot \nabla (v - P_{k-1} v) \, dx \\ &= \int_\Omega \nabla (\zeta - \Pi_{k-1} \zeta) \cdot \nabla (v - P_{k-1} v) \, dx \\ &\lesssim_\epsilon h_k^{(\pi/\omega)-\epsilon} \|\phi\|_{H^{-\alpha_\epsilon}(\Omega)} |v - P_{k-1} v|_{H^1(\Omega)}. \end{aligned}$$

The estimate (3.11) follows from (3.15) and the duality formula

$$(3.16) \quad \|\eta\|_{H^{\alpha_\epsilon}(\Omega)} = \sup [\phi(\eta) / \|\phi\|_{H^{-\alpha_\epsilon}(\Omega)}] \quad \forall \eta \in H_0^{\alpha_\epsilon}(\Omega),$$

where the supremum is taken over all  $\phi \in H^{-\alpha_\epsilon}(\Omega) \setminus \{0\}$ .

The final ingredient is the relation between the mesh dependent norm  $\|\cdot\|_s$  and the Sobolev norm  $\|\cdot\|_{H^s(\Omega)}$  on  $V_k$ . First of all, we have  $|v|_{H^1(\Omega)} = \|v\|_1$  and  $\|v\|_{L^2(\Omega)} \lesssim \|v\|_0$  for all  $v \in V_k$ . Interpolating these estimates (cf. [50]), we have

$$(3.17) \quad \|v\|_{H^s(\Omega)} \lesssim \|v\|_s \quad \forall v \in V_k, 0 \leq s \leq 1.$$

On the other hand, there exists (cf. [21], [48]) an interpolation operator  $\pi_k : L^2(\Omega) \rightarrow V_k$  such that

$$(3.18) \quad \|\pi_k v\|_0 \lesssim \|\pi_k v\|_{L^2(\Omega)} \lesssim \|v\|_{L^2(\Omega)} \quad \forall v \in L^2(\Omega),$$

$$(3.19) \quad \|\pi_k v\|_1 \lesssim \|\pi_k v\|_{H^1(\Omega)} \lesssim \|v\|_{H^1(\Omega)} \quad \forall v \in H_0^1(\Omega),$$

$$(3.20) \quad \pi_k v = v \quad \forall v \in V_k.$$

For  $0 < s < 1$  and  $s \neq 1/2$ , we can interpolate (3.18) and (3.19) (cf. [50]) to obtain

$$(3.21) \quad \|\pi_k v\|_s \lesssim \|v\|_{H^s(\Omega)} \quad \forall v \in H_0^s(\Omega).$$

Combining (3.20) and (3.21), we find

$$(3.22) \quad \|v\|_s \lesssim \|v\|_{H^s(\Omega)} \quad \forall v \in V_k, 0 \leq s \leq 1, s \neq 1/2.$$

In other words, the mesh dependent norm  $\|\cdot\|_s$  and the Sobolev norm  $\|\cdot\|_{H^s(\Omega)}$  are equivalent on  $V_k$  as long as  $s \neq 1/2$ .

Therefore, from (3.6)–(3.11) and (3.22), we have the following error estimate for the two-grid algorithm:

$$(3.23) \quad \begin{aligned} \|z - \tilde{z}\|_{H^{\alpha_\epsilon}(\Omega)} &\lesssim_\epsilon h_k^{(\pi/\omega)-\epsilon} |R_k^m(z - z_m)|_{H^1(\Omega)} \\ &\lesssim_\epsilon m^{[-(\pi/\omega)+\epsilon]/2} \|z - z_0\|_{H^{\alpha_\epsilon}(\Omega)}. \end{aligned}$$

Now we estimate the error for the  $k^{\text{th}}$  level iteration. Let  $\gamma_m = m^{[-(\pi/\omega)+\epsilon]/2}$ , and suppose that the error of the  $(k-1)^{\text{st}}$  level iteration in the  $H^{\alpha_\epsilon}(\Omega)$  norm is reduced by a factor  $\eta$ . Then it follows from (2.9) and (3.23) that

$$(3.24) \quad \begin{aligned} \|z - MG(k, z_0, g)\|_{H^{\alpha_\epsilon}(\Omega)} &\leq \|z - \tilde{z}\|_{H^{\alpha_\epsilon}(\Omega)} + \|q - q_2\|_{H^{\alpha_\epsilon}(\Omega)} \\ &\leq C_\epsilon \gamma_m \|z - z_0\|_{H^{\alpha_\epsilon}(\Omega)} + \eta^2 \|q\|_{H^{\alpha_\epsilon}(\Omega)}. \end{aligned}$$

From (3.8), (3.11) and (3.17), we have

$$(3.25) \quad \begin{aligned} \|P_{k-1}v\|_{H^{\alpha_\epsilon}(\Omega)} &\leq \|v - P_{k-1}v\|_{H^{\alpha_\epsilon}(\Omega)} + \|v\|_{H^{\alpha_\epsilon}(\Omega)} \\ &\lesssim_\epsilon h_k^{(\pi/\omega)-\epsilon} |v|_{H^1(\Omega)} + \|v\|_{\alpha_\epsilon} \\ &\lesssim_\epsilon \|v\|_{\alpha_\epsilon} \quad \forall v \in V_k. \end{aligned}$$

Combining (3.5), (3.9) and (3.25), we obtain

$$(3.26) \quad \begin{aligned} \|q\|_{H^{\alpha_\epsilon}(\Omega)} &= \|P_{k-1}(z - z_m)\|_{H^{\alpha_\epsilon}(\Omega)} \\ &\leq C'_\epsilon \|z - z_0\|_{\alpha_\epsilon}. \end{aligned}$$

The estimates (3.22), (3.24) and (3.26) together imply that

$$(3.27) \quad \|z - MG(k, z_0, g)\|_{H^{\alpha_\epsilon}(\Omega)} \leq (C_\epsilon \gamma_m + C''_\epsilon \eta^2) \|z - z_0\|_{H^{\alpha_\epsilon}(\Omega)}.$$

For  $m$  sufficiently large, we have  $\gamma_m < (4C_\epsilon C''_\epsilon)^{-1}$  and

$$\eta_m = [1 - (1 - 4C_\epsilon C''_\epsilon \gamma_m)^{1/2}] / (2C''_\epsilon)$$

is a fixed point of the map  $T(\eta) = C_\epsilon \gamma_m + C_\epsilon'' \eta^2$ . Since the first level iteration is an exact solver, it follows from (3.27) and mathematical induction that

$$(3.28) \quad \|z - MG(k, z_0, g)\|_{H^{\alpha_\epsilon}(\Omega)} \leq \eta_m \|z - z_0\|_{H^{\alpha_\epsilon}(\Omega)} \quad \text{for } k \geq 1.$$

As  $\lim_{m \rightarrow \infty} \eta_m = 0$ , the lemma follows from (3.28).  $\square$

#### 4. CONVERGENCE ANALYSIS FOR THE FULL MULTIGRID ALGORITHM I

**Theorem 4.1.** *Let  $p = 2$ ,  $0 < \epsilon < \pi/\omega$ ,  $\alpha_\epsilon = 1 - (\pi/\omega) + \epsilon \neq 1/2$  and the number of smoothing steps  $m$  be sufficiently large so that (3.1) and (3.2) hold for  $0 < \delta < 1$ . If the number of nested iterations  $n$  is sufficiently large, then we have*

$$(4.1) \quad |w - w_k|_{H^1(\Omega)} \lesssim h_k \|f\|_{L^2(\Omega)},$$

$$(4.2) \quad \sum_{j=1}^J |\kappa_j - \kappa_{j,k}| \lesssim_\epsilon h_k^{1+(\pi/\omega)-\epsilon} \|f\|_{L^2(\Omega)},$$

$$(4.3) \quad \|w - w_k\|_{H^{\alpha_\epsilon}(\Omega)} \lesssim_\epsilon h_k^{1+(\pi/\omega)-\epsilon} \|f\|_{L^2(\Omega)},$$

where  $w_k$  and  $\kappa_{j,k}$  are computed by (2.11)–(2.18).

*Proof.* We will establish (4.2) and (4.3) through recursive estimates. It follows from (1.5) and (2.15) that, for  $1 \leq j \leq J$ ,

$$(4.4) \quad \begin{aligned} |\kappa_j - \kappa_{j,k}| &= \frac{1}{\pi} \left| \int_{\Omega} (u - u_{k-1}) \Delta s_{-j} dx \right| \\ &\lesssim \|u - u_{k-1}\|_{L^2(\Omega)} \|\Delta s_{-j}\|_{L^2(\Omega)} \\ &\lesssim \|\hat{w}_{k-1} - w_{k-1}\|_{H^{\alpha_\epsilon}(\Omega)}, \end{aligned}$$

where (cf. (1.2), (1.15) and (2.18))

$$(4.5) \quad \hat{w}_k = u - \sum_{j=1}^J \kappa_{j,k} s_j = \sum_{j=1}^J (\kappa_j - \kappa_{j,k}) s_j + w = (u - u_k) + w_k.$$

Let  $a_k = \sum_{j=1}^J |\kappa_j - \kappa_{j,k}|$  and  $b_k = \|\hat{w}_k - w_k\|_{H^{\alpha_\epsilon}(\Omega)}$ . We have proved that

$$(4.6) \quad a_k \lesssim b_{k-1}.$$

To estimate  $b_k$ , we begin with

$$(4.7) \quad b_k \leq \|\hat{w}_k - P_k \hat{w}_k\|_{H^{\alpha_\epsilon}(\Omega)} + \|P_k \hat{w}_k - w_k\|_{H^{\alpha_\epsilon}(\Omega)}.$$

Using (1.4), (3.11), (4.5) and standard finite element discretization error estimates (cf. [20], [16]), we find

$$(4.8) \quad \begin{aligned} &\|\hat{w}_k - P_k \hat{w}_k\|_{H^{\alpha_\epsilon}(\Omega)} \\ &\leq \sum_{j=1}^J |\kappa_j - \kappa_{j,k}| \|s_j - P_k s_j\|_{H^{\alpha_\epsilon}(\Omega)} + \|w - P_k w\|_{H^{\alpha_\epsilon}(\Omega)} \\ &\lesssim_\epsilon h_k^{(\pi/\omega)-\epsilon} \left[ \sum_{j=1}^J |\kappa_j - \kappa_{j,k}| |s_j - P_k s_j|_{H^1(\Omega)} + |w - P_k w|_{H^1(\Omega)} \right] \\ &\lesssim_\epsilon h_k^{2(\pi/\omega)-2\epsilon} a_k + h_k^{1+(\pi/\omega)-\epsilon} \|f\|_{L^2(\Omega)}. \end{aligned}$$

Since  $P_k \hat{w}_k \in V_k$  is the exact solution of the equation  $A_k z = g_k$  (where  $g_k$  is defined by (2.17)), it follows from (2.16) and (3.2) that

$$(4.9) \quad \|P_k \hat{w}_k - w_k\|_{H^{\alpha_\epsilon}(\Omega)} \leq \delta^n \|P_k \hat{w}_k - w_{k-1}\|_{H^{\alpha_\epsilon}(\Omega)}.$$

Note that (1.2) and (4.5) imply

$$(4.10) \quad w - \hat{w}_k = \sum_{j=1}^J (\kappa_{j,k} - \kappa_j) s_j.$$

From (4.8) and (4.10), we obtain

$$(4.11) \quad \begin{aligned} \|P_k \hat{w}_k - w_{k-1}\|_{H^{\alpha_\epsilon}(\Omega)} &\leq \|P_k \hat{w}_k - \hat{w}_k\|_{H^{\alpha_\epsilon}(\Omega)} + \|\hat{w}_k - w\|_{H^{\alpha_\epsilon}(\Omega)} \\ &\quad + \|w - \hat{w}_{k-1}\|_{H^{\alpha_\epsilon}(\Omega)} + \|\hat{w}_{k-1} - w_{k-1}\|_{H^{\alpha_\epsilon}(\Omega)} \\ &\lesssim_\epsilon h_k^{2(\pi/\omega)-2\epsilon} a_k + h_k^{1+(\pi/\omega)-\epsilon} \|f\|_{L^2(\Omega)} + a_k + a_{k-1} + b_{k-1}. \end{aligned}$$

It follows from (4.7)–(4.9) and (4.11) that

$$(4.12) \quad b_k \lesssim_\epsilon \delta^n (b_{k-1} + a_k + a_{k-1}) + h_k^{2(\pi/\omega)-2\epsilon} a_k + h_k^{1+(\pi/\omega)-\epsilon} \|f\|_{L^2(\Omega)}.$$

Combining (4.6) and (4.12), we find

$$(4.13) \quad \begin{bmatrix} a_k \\ b_k \end{bmatrix} \leq C_\epsilon \begin{bmatrix} 0 & 1 \\ \delta^n & \delta^n + h_k^{2(\pi/\omega)-2\epsilon} \end{bmatrix} \begin{bmatrix} a_{k-1} \\ b_{k-1} \end{bmatrix} + C_\epsilon h_k^{1+(\pi/\omega)-\epsilon} \|f\|_{L^2(\Omega)} \begin{bmatrix} 0 \\ 1 \end{bmatrix},$$

where the vector inequality is interpreted componentwise.

Since  $\delta^n$  and  $h_k^{2(\pi/\omega)-2\epsilon}$  are both small for  $n$  and  $k$  large, we can consider the matrix in (4.13) to be a perturbation of the nilpotent matrix  $\begin{bmatrix} 0 & C_\epsilon \\ 0 & 0 \end{bmatrix}$ . Therefore, for  $n$  sufficiently large and  $k > k_\epsilon$ , we have

$$(4.14) \quad \begin{bmatrix} a_k \\ b_k \end{bmatrix} \leq \mathbf{C} \begin{bmatrix} a_{k-1} \\ b_{k-1} \end{bmatrix} + C_\epsilon h_k^{1+(\pi/\omega)-\epsilon} \|f\|_{L^2(\Omega)} \begin{bmatrix} 0 \\ 1 \end{bmatrix},$$

where the constant matrix  $\mathbf{C}$  has nonnegative components and satisfies

$$(4.15) \quad \|\mathbf{C}^n\|_\infty \lesssim \frac{1}{4^n}.$$

By iterating (4.14), for  $k > k_\epsilon$ , we obtain

$$(4.16) \quad \begin{aligned} \left\| \begin{bmatrix} a_k \\ b_k \end{bmatrix} \right\|_\infty &\lesssim_\epsilon \left( h_k^{1+(\pi/\omega)-\epsilon} + \frac{1}{4} h_{k-1}^{1+(\pi/\omega)-\epsilon} + \frac{1}{4^2} h_{k-2}^{1+(\pi/\omega)-\epsilon} + \dots \right) \|f\|_{L^2(\Omega)} \\ &\quad + \left( \frac{1}{4} \right)^{k-k_\epsilon} \left\| \begin{bmatrix} a_{k_\epsilon} \\ b_{k_\epsilon} \end{bmatrix} \right\|_\infty. \end{aligned}$$

Since  $h_{k-1} = 2h_k$  and  $1 + (\pi/\omega) - \epsilon < 2$ , it follows from (4.16) that

$$(4.17) \quad \left\| \begin{bmatrix} a_k \\ b_k \end{bmatrix} \right\|_\infty \lesssim_\epsilon h_k^{1+(\pi/\omega)-\epsilon} \|f\|_{L^2(\Omega)} + \left( \frac{1}{4} \right)^{k-k_\epsilon} \left\| \begin{bmatrix} a_{k_\epsilon} \\ b_{k_\epsilon} \end{bmatrix} \right\|_\infty.$$

On the other hand, from (1.4) and (2.11)–(2.14) we have

$$(4.18) \quad a_1 = \sum_{j=1}^J |\kappa_j| \lesssim \|f\|_{L^2(\Omega)},$$

$$(4.19) \quad b_1 = \|u - P_1 u\|_{H^{\alpha_\epsilon}(\Omega)} \lesssim \|u\|_{H^1(\Omega)} \lesssim \|f\|_{L^2(\Omega)}.$$

It follows from (4.13), (4.18) and (4.19) that

$$(4.20) \quad \left\| \begin{bmatrix} a_k \\ b_k \end{bmatrix} \right\|_{\infty} \lesssim_{\epsilon} \|f\|_{L^2(\Omega)} \lesssim_{\epsilon} h_k^{1+(\pi/\omega)-\epsilon} \|f\|_{L^2(\Omega)} \quad \text{for } 1 \leq k \leq k_{\epsilon}.$$

Combining (4.17) and (4.20), we find

$$(4.21) \quad \left\| \begin{bmatrix} a_k \\ b_k \end{bmatrix} \right\|_{\infty} \lesssim_{\epsilon} h_k^{1+(\pi/\omega)-\epsilon} \|f\|_{L^2(\Omega)} \quad \text{for } k \geq 1.$$

We have established (4.2), and the estimate (4.3) follows from (4.10) and (4.21).

Repeating the arguments in (4.7)–(4.11) with respect to the  $|\cdot|_{H^1(\Omega)}$  norm and using (4.2) with an  $\epsilon < \pi/\omega$ , we find

$$(4.22) \quad |\hat{w}_k - w_k|_{H^1(\Omega)} \lesssim \delta^n |\hat{w}_{k-1} - w_{k-1}|_{H^1(\Omega)} + h_k \|f\|_{L^2(\Omega)}.$$

We obtain from iterating (4.22) that

$$(4.23) \quad |\hat{w}_k - w_k|_{H^1(\Omega)} \lesssim h_k \|f\|_{L^2(\Omega)}.$$

The estimate (4.1) follows from (4.2) (with  $\epsilon < \pi/\omega$ ), (4.10) and (4.23).  $\square$

The following corollary is immediate.

**Corollary 4.2.** *Under the assumptions of Theorem 4.1, we have*

$$(4.24) \quad |u - u_k|_{H^1(\Omega)} \lesssim h_k \|f\|_{L^2(\Omega)}.$$

## 5. CONVERGENCE ANALYSIS FOR THE FULL MULTIGRID ALGORITHM II

Since we are really computing the regular part of the singular solution in our approach, it is possible to exploit superconvergence results. This idea will be demonstrated by the following analysis of the full multigrid algorithm II.

We first investigate the properties of the intergrid transfer operator  $I_{k-1}^k$ .

**Lemma 5.1.** *The following estimates hold for the intergrid transfer operator defined by (2.27):*

$$(5.1) \quad |I_{k-1}^k v|_{H^1(\Omega)} \lesssim |v|_{H^1(\Omega)} \quad \forall v \in V_{k-1},$$

$$(5.2) \quad |\Pi_k \zeta - I_{k-1}^k \Pi_{k-1} \zeta|_{H^1(\Omega)} \lesssim h_k^{1+t} \|\zeta\|_{H^{2+t}(\Omega)} \quad \forall \zeta \in H^{2+t}(\Omega) \cap H_0^1(\Omega),$$

where  $\Pi_k$  is the nodal interpolation operator associated with  $V_k$  and  $0 \leq t \leq 1$ .

*Proof.* Let  $T$  be a triangle,  $\eta$  be a quadratic polynomial, and  $\eta^I$  be the linear interpolant of  $\eta$  with respect to the subdivision of  $T$  obtained by connecting the midpoints of the sides of  $T$ . A standard scaling argument shows that

$$(5.3) \quad C_1 |\eta^I|_{H^1(T)} \leq |\eta|_{H^1(T)} \leq C_2 |\eta^I|_{H^1(T)},$$

where the constants  $C_1$  and  $C_2$  depend only on the angles of  $T$ .

Recall that  $Q_k \subset H_0^1(\Omega)$  ( $k = 0, 1, 2, \dots$ ) is the quadratic Lagrange finite element space associated with  $\mathcal{T}_k$ , and  $\mathcal{I}_{k-2}^{k-1}$  (resp.,  $\mathcal{I}_{k-2}^k$ ) is the nodal interpolation operator from  $Q_{k-2}$  into  $V_{k-1}$  (resp.,  $V_k$ ). We deduce from (5.3) that, for  $k \geq 2$ ,

$$(5.4) \quad |\mathcal{I}_{k-2}^k q|_{H^1(\Omega)} \lesssim |q|_{H^1(\Omega)} \lesssim |\mathcal{I}_{k-2}^{k-1} q|_{H^1(\Omega)} \quad \forall q \in Q_{k-2}.$$

The estimate (5.1) follows from (2.27) and (5.4).

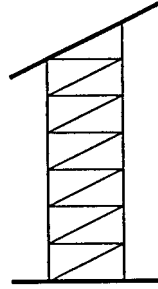


FIGURE 1

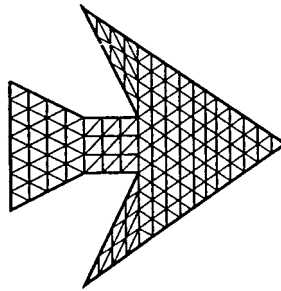


FIGURE 2

Let  $T$  be a triangle in  $\mathcal{T}_{k-2}$  and  $q$  be a polynomial of degree  $\leq 2$ . By restricting all the definitions to  $T$ , we find

$$(5.5) \quad \begin{aligned} \Pi_k q - I_{k-1}^k \Pi_{k-1} q &= \Pi_k q - \mathcal{I}_{k-2}^k (\mathcal{I}_{k-2}^{k-1})^{-1} \Pi_{k-1} q \\ &= \Pi_k q - \mathcal{I}_{k-2}^k q = 0. \end{aligned}$$

By the Bramble-Hilbert lemma (cf. [11]) and a standard scaling argument we deduce from (5.5) that

$$(5.6) \quad |\Pi_k \zeta - I_{k-1}^k \Pi_{k-1} \zeta|_{H^1(\Omega)} \lesssim h_k^2 \|\zeta\|_{H^3(\Omega)} \quad \forall \zeta \in H^3(\Omega) \cap H_0^1(\Omega),$$

$$(5.7) \quad |\Pi_k \zeta - I_{k-1}^k \Pi_{k-1} \zeta|_{H^1(\Omega)} \lesssim h_k \|\zeta\|_{H^2(\Omega)} \quad \forall \zeta \in H^2(\Omega) \cap H_0^1(\Omega).$$

The estimate (5.2) follows from interpolating (5.6) and (5.7) (cf. [50]).  $\square$

Next we discuss a superconvergence result for the linear finite element. A *uniform band* in a triangulation is a collection of triangles between two parallel lines such that any two triangles sharing a common side form a parallelogram (cf. Figure 1), and the boundary of the band consists of the two parallel lines and parts of  $\partial\Omega$ . We say that a triangulation satisfies the *uniform band condition* if it can be divided completely into uniform bands (cf. Figure 2). Note that one can always find a triangulation satisfying the uniform band condition for any polygonal domain whose vertices all have rational coordinates, and the uniform band condition is preserved by regular subdivision.

The proof of the following result can be found in [18] (cf. also [34], [41], [61], [19], [35]).

**Lemma 5.2.** *Suppose the triangulations  $\mathcal{T}_k$  satisfy the uniform band condition and  $\zeta \in H^3(\Omega) \cap H_0^1(\Omega)$ . Then*

$$(5.8) \quad |\Pi_k \zeta - P_k \zeta|_{H^1(\Omega)} \lesssim h_k^2 \|\zeta\|_{H^3(\Omega)}.$$

**Corollary 5.3.** *Suppose the triangulations  $\mathcal{T}_k$  satisfy the uniform band condition and  $\zeta \in H^{2+t}(\Omega) \cap H_0^1(\Omega)$  for  $0 \leq t \leq 1$ . Then*

$$(5.9) \quad |\Pi_k \zeta - P_k \zeta|_{H^1(\Omega)} \lesssim h_k^{1+t} \|\zeta\|_{H^{2+t}(\Omega)}.$$

*Proof.* The estimate (5.9) follows from interpolating (5.8) and the obvious estimate

$$|\Pi_k \zeta - P_k \zeta|_{H^1(\Omega)} \lesssim h_k \|\zeta\|_{H^2(\Omega)} \quad \forall \zeta \in H^2(\Omega) \cap H_0^1(\Omega).$$

□

We now establish the convergence properties of the full multigrid algorithm II.

**Theorem 5.4.** *Let  $f \in H^1(\Omega)$ . Assume that the triangulations  $\mathcal{T}_k$  satisfy the uniform band condition,  $p = 1$  or  $2$ , and  $m \geq 1$ . If the number of nested iterations  $n$  is sufficiently large, then we have*

$$(5.10) \quad |\Pi_k w - w_k|_{H^1(\Omega)} \lesssim_\epsilon h_k^{2-\epsilon} \|f\|_{H^1(\Omega)},$$

$$(5.11) \quad \sum_{j=1}^N \sum_{\ell \in \mathcal{L}_j} |\kappa_{j,\ell} - \kappa_{j,\ell,k}| \lesssim_\epsilon h_k^{2-\epsilon} \|f\|_{H^1(\Omega)},$$

where  $w_k$  and  $\kappa_{j,\ell,k}$  are computed by (2.19)–(2.26).

*Proof.* It follows from (1.24), (2.23), (2.26) and the Poincaré inequality that

$$(5.12) \quad \begin{aligned} |\kappa_{j,\ell} - \kappa_{j,\ell,k}| &= \frac{1}{\ell\pi} \left| \int_{\Omega} (\hat{w}_{k-1} - w_{k-1}) \Delta s_{j,-\ell} dx \right| \\ &\lesssim \left| \int_{\Omega} (\hat{w}_{k-1} - \Pi_{k-1} \hat{w}_{k-1}) \Delta s_{j,-\ell} dx \right| \\ &\quad + \left| \int_{\Omega} (\Pi_{k-1} \hat{w}_{k-1} - w_{k-1}) \Delta s_{j,-\ell} dx \right| \\ &\lesssim \|\hat{w}_{k-1} - \Pi_{k-1} \hat{w}_{k-1}\|_{L^2(\Omega)} + |\Pi_{k-1} \hat{w}_{k-1} - w_{k-1}|_{H^1(\Omega)}, \end{aligned}$$

where

$$(5.13) \quad \begin{aligned} \hat{w}_k &= u - \sum_{j=1}^N \sum_{\ell \in \mathcal{L}_j} \kappa_{j,\ell,k} s_{j,\ell} = (u - u_k) + w_k \\ &= \sum_{j=1}^N \sum_{\ell \in \mathcal{L}_j} (\kappa_{j,\ell} - \kappa_{j,\ell,k}) s_{j,\ell} + w. \end{aligned}$$

Let  $a_k = \sum_{j=1}^N \sum_{\ell \in \mathcal{L}_j} |\kappa_{j,\ell} - \kappa_{j,\ell,k}|$  and  $b_k = |\Pi_k \hat{w}_k - w_k|_{H^1(\Omega)}$ . Since  $s_{j,\ell} \in H^{1+(\pi/\omega)-\epsilon}(\Omega)$  and  $w \in H^{3-\epsilon}(\Omega)$ , we have from (1.23), (5.13) and standard interpolation error estimates that

$$(5.14) \quad \begin{aligned} \|\hat{w}_{k-1} - \Pi_{k-1} \hat{w}_{k-1}\|_{L^2(\Omega)} &\leq \sum_{j=1}^N \sum_{\ell \in \mathcal{L}_j} |\kappa_{j,\ell} - \kappa_{j,\ell,k-1}| \|s_{j,\ell} - \Pi_{k-1} s_{j,\ell}\|_{L^2(\Omega)} \\ &\quad + \|w - \Pi_{k-1} w\|_{L^2(\Omega)} \\ &\lesssim_\epsilon h_{k-1}^{1+(\pi/\omega)-\epsilon} a_{k-1} + h_{k-1}^2 \|f\|_{H^1(\Omega)}. \end{aligned}$$

It follows from (5.12) and (5.14) that

$$(5.15) \quad a_k \lesssim_\epsilon h_k^{1+(\pi/\omega)-\epsilon} a_{k-1} + b_{k-1} + h_k^2 \|f\|_{H^1(\Omega)}.$$

On the other hand, we have

$$(5.16) \quad b_k \leq |\Pi_k \hat{w}_k - P_k \hat{w}_k|_{H^1(\Omega)} + |P_k \hat{w}_k - w_k|_{H^1(\Omega)},$$

and from (1.23), (5.9), (5.13) and a standard interpolation error estimate,

$$(5.17) \quad \begin{aligned} |\Pi_k \hat{w}_k - P_k \hat{w}_k|_{H^1(\Omega)} &\leq \sum_{j=1}^N \sum_{\ell \in \mathcal{L}_j} |\kappa_{j,\ell} - \kappa_{j,\ell,k}| |\Pi_k s_{j,\ell} - P_k s_{j,\ell}|_{H^1(\Omega)} \\ &\quad + |\Pi_k w - P_k w|_{H^1(\Omega)} \\ &\lesssim_\epsilon h_k^{(\pi/\omega)-\epsilon} a_k + h_k^{2-\epsilon} \|f\|_{H^1(\Omega)}. \end{aligned}$$

Since  $P_k \hat{w}_k \in V_k$  is the exact solution of  $A_k z = g_k$  (where  $g_k$  is defined by (2.25)), it follows from (2.24) and Lemma 3.1 that

$$(5.18) \quad |P_k \hat{w}_k - w_k|_{H^1(\Omega)} \leq \delta^n |P_k \hat{w}_k - I_{k-1}^k w_{k-1}|_{H^1(\Omega)},$$

for some  $\delta < 1$ .

It follows from (1.23), (5.1), (5.2) and (5.13) that

$$(5.19) \quad \begin{aligned} |P_k \hat{w}_k - I_{k-1}^k w_{k-1}|_{H^1(\Omega)} &\leq |P_k(\hat{w}_k - w)|_{H^1(\Omega)} + |P_k w - \Pi_k w|_{H^1(\Omega)} \\ &\quad + |\Pi_k w - I_{k-1}^k \Pi_{k-1} w|_{H^1(\Omega)} + |I_{k-1}^k(\Pi_{k-1} w - w_{k-1})|_{H^1(\Omega)} \\ &\lesssim_\epsilon a_k + h_k^{2-\epsilon} \|f\|_{H^1(\Omega)} + |\Pi_{k-1} w - w_{k-1}|_{H^1(\Omega)} \\ &\lesssim_\epsilon a_k + h_k^{2-\epsilon} \|f\|_{H^1(\Omega)} + |\Pi_{k-1}(w - \hat{w}_{k-1})|_{H^1(\Omega)} \\ &\quad + |\Pi_{k-1} \hat{w}_{k-1} - w_{k-1}|_{H^1(\Omega)} \\ &\lesssim_\epsilon a_k + a_{k-1} + b_{k-1} + h_k^{2-\epsilon} \|f\|_{H^1(\Omega)}. \end{aligned}$$

Using (5.16)–(5.19) we obtain

$$(5.20) \quad b_k \lesssim_\epsilon (h_k^{(\pi/\omega)-\epsilon} + \delta^n) a_k + \delta^n (a_{k-1} + b_{k-1}) + h_k^{2-\epsilon} \|f\|_{H^1(\Omega)}.$$

As in the proof of Theorem 4.1, by iterating (5.15) and (5.20) we have

$$(5.21) \quad a_k \lesssim_\epsilon h_k^{2-\epsilon} \|f\|_{H^1(\Omega)},$$

$$(5.22) \quad b_k \lesssim_\epsilon h_k^{2-\epsilon} \|f\|_{H^1(\Omega)}.$$

The estimate (5.11) is the same as (5.21). We deduce from (5.13) that

$$(5.23) \quad \begin{aligned} |\Pi_k w - w_k|_{H^1(\Omega)} &\leq |\Pi_k(w - \hat{w}_k)|_{H^1(\Omega)} + |\Pi_k \hat{w}_k - w_k|_{H^1(\Omega)} \\ &\lesssim a_k + b_k. \end{aligned}$$

The estimate (5.10) follows from (5.21)–(5.23).  $\square$

*Remark.* By exploiting superconvergence we are able to perform the analysis in the proof of Theorem 5.4 using the energy norm and still obtain a higher rate of convergence. The use of the energy norm also makes it possible to apply Lemma 3.1 (instead of Lemma 3.2) to demonstrate convergence even for the  $V$ -cycle algorithm with one smoothing step.

The following corollary is immediate.

**Corollary 5.5.** *Under the assumptions of Theorem 5.4, we have*

$$(5.24) \quad |u - u_k|_{H^1(\Omega)} \lesssim h_k \|f\|_{H^1(\Omega)}.$$

**Corollary 5.6.** *Under the assumptions of Theorem 5.4, we have*

$$(5.25) \quad \max_p |u(p) - u_k(p)| \lesssim_\epsilon h_k^{2-\epsilon} \|f\|_{H^1(\Omega)},$$

where the maximum is taken over all the vertices  $p$  of  $\mathcal{T}_k$ .

*Proof.* It suffices to estimate  $\|\Pi_k(u - u_k)\|_{L^\infty(\Omega)}$ . By (1.17), (2.26), (5.10), (5.11) and the discrete Sobolev inequality (cf. [46], [61]), we have

$$(5.26) \quad \begin{aligned} \|\Pi_k(u - u_k)\|_{L^\infty(\Omega)} &\leq \sum_{j=1}^N \sum_{\ell \in \mathcal{L}_j} |\kappa_{j,\ell} - \kappa_{j,\ell,k}| \|\Pi_k s_{j,\ell}\|_{L^\infty(\Omega)} + \|\Pi_k w - w_k\|_{L^\infty(\Omega)} \\ &\lesssim \sum_{j=1}^N \sum_{\ell \in \mathcal{L}_j} |\kappa_{j,\ell} - \kappa_{j,\ell,k}| + |\ln h_k|^{1/2} \|\Pi_k w - w_k\|_{H^1(\Omega)} \\ &\lesssim_\epsilon h_k^{2-\epsilon} \|f\|_{H^1(\Omega)}. \end{aligned}$$

□

*Remark.* If none of the angles of  $\Omega$  is an integer multiple of  $\pi/2$ , then the regular part  $w$  in (1.20) actually belongs to  $H^3(\Omega)$  (cf. [27], [23]). For such  $\Omega$  the  $\epsilon$ -dependence in (1.23), (5.9) and (5.10) disappears, and the estimate (5.25) becomes

$$\max_p |u(p) - u_k(p)| \lesssim h_k^2 |\ln h_k|^{1/2} \|f\|_{H^1(\Omega)}.$$

*Remark.* It is well known (cf. [47], [44], [16]) that

$$\|u - \tilde{u}_h\|_{L^\infty(\Omega)} \lesssim h^2 |\ln h| \|u\|_{W_\infty^2(\Omega)},$$

where  $\tilde{u}_h$  is the P1 finite element solution of (1.1). It is interesting to see that a multigrid method can produce similar results for singular solutions.

## 6. NUMERICAL EXPERIMENTS

In this section, we report the results of some numerical experiments for (1.1) performed on the  $\Gamma$ -shaped domain  $\Omega$  (cf. Figures 3 and 4) with vertices  $(0, 0)$ ,  $(0, 1)$ ,  $(1, 1)$ ,  $(-1, 1)$ ,  $(-1, -1)$  and  $(0, -1)$ . We use the P1 Lagrange finite element in the experiments. All the computations are done using a  $W$ -cycle  $k^{\text{th}}$  level iteration with 5 smoothing steps, and the number of nested iterations in the full multigrid algorithms is also 5. The mesh size  $h_k$  for the  $k^{\text{th}}$  level grid is taken to be  $2^{-k}$ . We first describe the experiments; comments on the numerical results are given near the end of this section.

*Remark.* Convergence of the algorithms has been observed for  $m = n = 1$ . We choose to report the results for  $m = n = 5$ , since the numerical results do not appear to improve for any larger  $m$  or  $n$ .

The two singular functions for this  $\Gamma$ -shaped domain are:

$$(6.1) \quad s_1(r, \theta) = \phi(r) r^{2/3} \sin((2/3)\theta),$$

$$(6.2) \quad s_2(r, \theta) = \phi(r) r^{4/3} \sin((4/3)\theta),$$

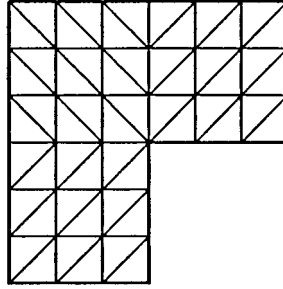


FIGURE 3

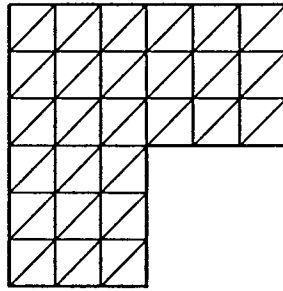


FIGURE 4

where the cut-off function  $\phi(r)$  is defined by

$$(6.3) \quad \phi(r) = \begin{cases} 1 & 0 \leq r \leq 1/4, \\ -192r^5 + 480r^4 - 440r^3 + 180r^2 - \frac{135}{4}r + \frac{27}{8} & 1/4 \leq r \leq 3/4, \\ 0 & 3/4 \leq r. \end{cases}$$

In the first set of experiments, we solve the Poisson equation (1.1) with  $f = -\Delta s_1 - \Delta s_2 + 6x(y^2 - y^4) + (x - x^3)(12y^2 - 2)$ . The exact solution is therefore

$$(6.4) \quad u = s_1 + s_2 + (x - x^3)(y^2 - y^4).$$

In the first experiment, we solve (1.1) using the standard full multigrid algorithm (where the right-hand sides of the discrete equations on all levels come from  $f$ ) on the grids depicted in Figure 3. The approximate stress intensity factors  $\kappa_k$  are computed by the extraction formula (1.7) using the P1 finite element solution  $u_k$  obtained by the standard full multigrid method. The error  $e_k$  in the energy norm is defined by  $e_k = |\Pi_k u - u_k|_{H^1(\Omega)}$ . The rate of convergence  $\sigma_k$  for the stress intensity factor and the rate of convergence  $\epsilon_k$  in the energy norm are computed by

$$(6.5) \quad \sigma_k = \log_2 \left( \frac{|\kappa_{k-1} - 1|}{|\kappa_k - 1|} \right),$$

$$(6.6) \quad \epsilon_k = \log_2 \left( \frac{e_{k-1}}{e_k} \right).$$

The results are tabulated in Table 1.

In the second experiment, we solve (6.1) using the full multigrid algorithm I described in Section 2 on the grids depicted in Figure 3. This algorithm computes

TABLE 1. Results for the standard full multigrid algorithm with  $f = -\Delta s_1 - \Delta s_2 + 6x(y^2 - y^4) + (x - x^3)(12y^2 - 2)$ 

$k$	$\kappa_k$	$\sigma_k$	$e_k$	$\epsilon_k$
1	1.6999229601	–	$1.27093 \times 10^0$	–
2	1.2589102299	1.43	$5.91072 \times 10^{-1}$	1.1045
3	1.1036407706	1.32	$1.61387 \times 10^{-1}$	1.8728
4	1.0287080790	1.85	$5.74371 \times 10^{-2}$	1.4905
5	1.0073492045	1.97	$2.76732 \times 10^{-2}$	1.0535
6	1.0020544785	1.84	$1.64752 \times 10^{-2}$	0.7482
7	1.0005531037	1.89	$1.02811 \times 10^{-2}$	0.6803
8	1.0001571227	1.82	$6.46930 \times 10^{-2}$	0.6683
9	1.0000458701	1.78	$4.07502 \times 10^{-3}$	0.6668
10	1.0000142397	1.69	$2.56715 \times 10^{-3}$	0.6666
11	1.0000046460	1.62	$1.61722 \times 10^{-3}$	0.6666

TABLE 2. Results for the full multigrid algorithm I with  $f = -\Delta s_1 - \Delta s_2 + 6x(y^2 - y^4) + (x - x^3)(12y^2 - 2)$ 

$k$	$\kappa_k$	$\sigma_k$	$e_k$	$\epsilon_k$
1	–	–	$7.929 \times 10^{-1}$	–
2	1.69992296014	–	$8.364 \times 10^{-1}$	–0.07
3	0.82132136706	1.97	$2.322 \times 10^{-1}$	1.85
4	1.02037630458	3.13	$3.456 \times 10^{-2}$	2.75
5	0.99943755129	5.18	$6.236 \times 10^{-3}$	2.47
6	1.00003984026	3.82	$1.595 \times 10^{-3}$	1.97
7	1.00000536058	2.89	$4.200 \times 10^{-4}$	1.93
8	1.00000234005	1.20	$1.170 \times 10^{-4}$	1.84
9	1.00000057569	2.02	$3.567 \times 10^{-5}$	1.71
10	1.00000012632	2.19	$1.204 \times 10^{-5}$	1.57
11	1.00000002876	2.13	$4.397 \times 10^{-6}$	1.45
12	1.00000000746	1.95	–	–

$\kappa_k \in \mathbb{R}$  and  $w_k \in V_k$  which are approximations of the stress intensity factor  $\kappa = 1$  and the regular part of the solution in (6.4), namely,  $w = s_2 + (x - x^3)(y^2 - y^4)$ . The error  $e_k$  in the energy norm is defined by  $e_k = |\Pi_k w - w_k|_{H^1(\Omega)}$ . The convergence rates  $\sigma_k$  and  $\epsilon_k$  are again computed by (6.5) and (6.6). The results are tabulated in Table 2.

In the third experiment, we solve (1.1) by the full multigrid algorithm II described in Section 2 on the uniform grids depicted in Figure 4. This algorithm computes  $\kappa_{1,k} \in \mathbb{R}$ ,  $\kappa_{2,k} \in \mathbb{R}$  and  $w_k \in V_k$  which are approximations of the stress intensity factors  $\kappa_1 = 1$ ,  $\kappa_2 = 1$  and the regular part of the solution in (6.4), namely,  $w = (x - x^3)(y^2 - y^4)$ . The error  $e_k$  in the energy norm is defined by  $e_k = |\Pi_k w - w_k|_{H^1(\Omega)}$ . The convergence rates  $\sigma_{1,k}$  ( $\sigma_{2,k}$ ) and  $\epsilon_k$  are computed as in (6.5) and (6.6). The results are tabulated in Table 3.

TABLE 3. Results for the full multigrid algorithm II with  $f = -\Delta s_1 - \Delta s_2 + 6x(y^2 - y^4) + (x - x^3)(12y^2 - 2)$

$k$	$\kappa_{1,k}$	$\sigma_{1,k}$	$\kappa_{2,k}$	$\sigma_{2,k}$	$e_k$	$\epsilon_k$
1	–	–	–	–	$1.124 \times 10^0$	–
2	1.6229151283	–	1.17131298888	–	$7.361 \times 10^{-1}$	0.61
3	0.8859991798	2.45	0.99336080108	4.69	$1.417 \times 10^{-1}$	2.38
4	1.0091773397	3.63	1.00029662538	4.48	$1.131 \times 10^{-2}$	3.65
5	0.9999856171	9.32	1.00023130682	0.36	$5.829 \times 10^{-4}$	4.28
6	1.0000653041	–2.18	1.00002651087	3.13	$1.551 \times 10^{-4}$	1.91
7	1.0000136298	2.26	1.00000976600	1.44	$3.636 \times 10^{-5}$	2.09
8	1.0000044994	1.60	1.00000116447	3.07	$9.574 \times 10^{-6}$	1.93
9	1.0000011279	2.00	1.00000029598	1.98	$2.376 \times 10^{-6}$	2.01
10	1.0000002659	2.08	1.00000008791	1.75	$5.810 \times 10^{-7}$	2.03
11	1.0000000638	2.06	1.00000002475	1.82	$1.433 \times 10^{-7}$	2.02
12	1.0000000163	1.97	1.00000000585	2.08	–	–

TABLE 4. Results for the standard full multigrid algorithm with  $f = 1$

$k$	$\kappa_k$	$\sigma_k$	$e_k$	$\epsilon_k$
1	0.40404781	–	$2.513 \times 10^{-1}$	–
2	0.40105510	2.46	$1.378 \times 10^{-1}$	0.866
3	0.40051009	–2.07	$7.465 \times 10^{-2}$	0.885
4	0.40280457	1.62	$4.104 \times 10^{-2}$	0.863
5	0.40205736	6.72	$2.313 \times 10^{-2}$	0.827
6	0.40205027	–3.50	$1.338 \times 10^{-2}$	0.790
7	0.40197036	1.87	$7.919 \times 10^{-3}$	0.756
8	0.40194849	1.08	$4.776 \times 10^{-3}$	0.729
9	0.40193815	1.29	$2.922 \times 10^{-3}$	0.709
10	0.40193393	1.28	$1.805 \times 10^{-3}$	0.695
11	0.40193219	–	–	–

In the second set of experiments, we solve the Poisson equation

$$(6.7) \quad \begin{aligned} -\Delta u &= 1 \quad \text{in } \Omega, \\ u &= 0 \quad \text{on } \partial\Omega. \end{aligned}$$

In the fourth experiment, we apply the standard full multigrid algorithm to (6.7) on the grids in Figure 3. The error  $e_k$  in the energy norm is defined by  $e_k = |u_k - u_{k+1}|_{H^1(\Omega)}$ . The convergence rates  $\epsilon_k$  and  $\sigma_k$  are computed by (6.6) and

$$(6.8) \quad \sigma_k = \log_2 \left( \frac{|\kappa_k - \kappa_{k-1}|}{|\kappa_k - \kappa_{k+1}|} \right).$$

The results are tabulated in Table 4.

In the fifth experiment, we apply the full multigrid algorithm I to (6.7) on the grids depicted in Figure 3. The error  $e_k$  in energy norm is now defined by  $e_k = |w_k - w_{k+1}|_{H^1(\Omega)}$ . The convergence rates  $\sigma_k$  and  $\epsilon_k$  are computed by (6.8) and (6.6) respectively. The results are tabulated in Table 5.

TABLE 5. Results for the full multigrid algorithm I with  $f = 1$ 

$k$	$\kappa_k$	$\sigma_k$	$e_k$	$\epsilon_k$
1	–	–	$4.138 \times 10^{-1}$	–
2	0.40404781	–	$2.565 \times 10^{-1}$	0.690
3	0.29704637	0.55	$1.603 \times 10^{-1}$	0.678
4	0.37020221	1.73	$8.073 \times 10^{-2}$	0.990
5	0.39218469	1.65	$4.042 \times 10^{-2}$	0.998
6	0.39918799	1.78	$2.014 \times 10^{-2}$	1.005
7	0.40123227	1.98	$1.005 \times 10^{-2}$	1.003
8	0.40174937	1.92	$5.022 \times 10^{-3}$	1.001
9	0.40188560	2.00	$2.511 \times 10^{-3}$	1.000
10	0.40191976	2.01	$1.255 \times 10^{-3}$	1.000
11	0.40192822	2.00	–	–
12	0.40193032	–	–	–

TABLE 6. Results for the full multigrid algorithm II with  $f = 1$ 

$k$	$\kappa_{1,k}$	$\sigma_{1,k}$	$\kappa_{2,k}$	$\sigma_{2,k}$	$e_k$	$\epsilon_k$
1	–	–	–	–	$3.938 \times 10^{-1}$	–
2	0.34080586	–	$-2.0614706 \times 10^{-17}$	–	$1.829 \times 10^{-1}$	1.11
3	0.33610413	–3.14	$-1.2218483 \times 10^{-2}$	0.32	$8.644 \times 10^{-2}$	1.08
4	0.37747233	1.18	$-2.4317474 \times 10^{-3}$	2.47	$3.634 \times 10^{-2}$	1.25
5	0.39567246	2.02	$-6.6497401 \times 10^{-4}$	1.83	$1.054 \times 10^{-2}$	1.79
6	0.40014791	1.75	$-1.6711078 \times 10^{-4}$	1.99	$3.307 \times 10^{-3}$	1.67
7	0.40147892	2.00	$-4.2006249 \times 10^{-5}$	1.99	$1.028 \times 10^{-3}$	1.69
8	0.40181127	1.89	$-1.0519784 \times 10^{-5}$	2.00	$3.384 \times 10^{-4}$	1.60
9	0.40190104	1.99	$-2.6327556 \times 10^{-6}$	2.00	$1.140 \times 10^{-4}$	1.57
10	0.40192361	2.02	$-6.5851034 \times 10^{-7}$	2.00	$3.923 \times 10^{-5}$	1.54
11	0.40192918	2.00	$-1.6466864 \times 10^{-7}$	2.00	–	–
12	0.40193057	–	$-4.1172418 \times 10^{-8}$	–	–	–

In the sixth experiment, we apply the full multigrid algorithm II to (6.7) on the grids depicted in Figure 4. The error  $e_k$  in the energy norm is defined by  $e_k = |w_{k+1} - I_k^{k+1} w_k|_{H^1(\Omega)}$ . The convergence rates  $\sigma_{1,k}$  ( $\sigma_{2,k}$ ) and  $\epsilon_k$  are computed by (6.8) and (6.6), respectively. The results are tabulated in Table 6.

Experiments 1 and 4 are performed for the sake of comparison with the new algorithms. The convergence rates in the energy norm tend to  $2/3$  in both experiments. The convergence rates for the stress intensity factors in experiment 4 tend to  $1.3 \sim 4/3$ . In fact, if we extrapolate from Table 6 the value 0.40193103 for the stress intensity factor and compute the convergence rates again, then the last three rates become 1.29, 1.30 and 1.32. The rates for the stress intensity factors in experiment 1 are also decreasing towards  $4/3$ .

Experiments 2 and 5 show the improvement of the full multigrid algorithm I over the standard full multigrid algorithm. The performance of this algorithm is actually better than the prediction of our theory. Note that in both cases the right-hand side of the Poisson equation is smooth and hence the regular part  $w$  belongs to  $H^{(7/3)-\epsilon}(\Omega)$  instead of just  $H^2(\Omega)$ . This higher regularity of  $w$  and some sort

TABLE 7.  $L^2$  convergence of the full multigrid algorithm II with  $f = 1$ 

$k$	$\mu_k$	$\delta_k$
1	$4.028096 \times 10^{-2}$	–
2	$1.420687 \times 10^{-2}$	1.50
3	$7.475676 \times 10^{-3}$	0.93
4	$3.121328 \times 10^{-3}$	1.26
5	$7.693137 \times 10^{-4}$	2.02
6	$2.272332 \times 10^{-4}$	1.76
7	$5.608381 \times 10^{-5}$	2.02
8	$1.499267 \times 10^{-5}$	1.90
9	$3.770565 \times 10^{-6}$	1.99
10	$9.353645 \times 10^{-7}$	2.01

of superconvergence result are probably responsible for the better than expected performance of this algorithm.

The convergence rates of both of the stress intensity factors tend to 2 in experiments 3 and 6, as predicted by the theory. The convergence rates in energy norm also tend to 2 in experiment 3, again in agreement with the theory. Note that  $|s_1|_{H^1(\Omega)} \sim 1.176$  and  $|s_2|_{H^1(\Omega)} \sim 0.768$ , and hence the energy norm error  $|u - (\kappa_{1,11}s_1 + \kappa_{2,11}s_2 + w_{11})|_{H^1(\Omega)}$  in experiment 3 is of order  $10^{-7}$ , whereas in experiment 1 the energy norm error at level 11 is only of order  $10^{-3}$ .

The convergence rates in energy norm in experiment 6 do not approach 2. This may be explained as follows. The order 2 convergence in energy norm depends on a delicate superconvergence result, and the rates computed by (6.6) will tend to the correct order only if there is an asymptotic expansion for the energy norm error instead of just a bound. In experiment 3, the regular part is actually  $C^\infty$  and such an asymptotic expansion exists. Hence the order 2 convergence is observed there. On the other hand, the regular part in experiment 6 is only in  $H^{3-\epsilon}(\Omega)$  and therefore the asymptotic expansion is absent. Consequently the order 2 convergence in energy norm is not observed.

Note that the estimate (5.10) and the Poincaré inequality imply that we have  $\mathcal{O}(h^{2-\epsilon})$   $L^2$ -norm convergence for the full multigrid algorithm II. Since the existence of an asymptotic expansion for the  $L^2$ -norm error usually requires less regularity, the  $L^2$ -norm errors in experiment 6 may still show a convergence rate of 2. We have computed the  $L^2$ -norm errors  $\mu_k = \|w_k - w_{k+1}\|_{L^2(\Omega)}$  and calculated their rates of convergence  $\delta_k = \log_2(\mu_{k-1}/\mu_k)$ . The results are displayed in Table 7. It shows that the rate of convergence in the  $L^2$ -norm is indeed 2.

## 7. CONCLUDING REMARKS

The multigrid methods in this paper use the simplest finite element. They can be easily implemented by modifying existing multigrid codes for the P1 finite element. Since the grids are generated by connecting midpoints, it is also easy to parallelize these algorithms. The extension of these methods to domains with cracks is carried out in [17].

For more regular  $f$ , there exist singular function representations (cf. [27], [24], [23], [39]) where the regular part  $w$  is also more regular. In such cases multigrid

methods with higher orders of convergence can be developed using higher order elements. The generalization of the results of this paper to higher order elements is carried out in [15].

Since the multigrid methods in this paper compute the regular part of the singular solution, superconvergence results (cf. [61], [54], [19], [35]) which require unrealistic regularity on nonsmooth domains become relevant in this approach. Note that other superconvergence results which are less restrictive than the one based on the “uniform band” condition can also be used as they become available.

These methods can also be applied to elasticity problems, transmission problems, problems with mixed Dirichlet and Neumann boundary conditions and fourth order problems. The only prerequisite is the knowledge of the singular function representation, which may not always be readily available. However, in any applications where the stress intensity factors are sought, the singular function representation must be known, as otherwise the concept of stress intensity factors cannot even be defined. We also point out that there exist many algorithms for the computation of the singular functions (cf. [33], [51], [42], [43], [55], [56], [22]).

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