

ON RIEMANNIAN CURVATURE OF HOMOGENEOUS SPACES

SIGURÐUR HELGASON

1. **Introduction.** When developing his theory of symmetric spaces, E. Cartan proved that a compact symmetric Riemannian space has sectional curvature everywhere ≥ 0 and that a noncompact irreducible symmetric Riemannian space has sectional curvature everywhere ≤ 0 . H. Samelson has recently [5] proved an analogue of Cartan's theorem for the compact case, namely that a homogeneous space G/K where G is a connected compact Lie group, K a closed subgroup, has sectional curvature everywhere ≥ 0 . Here the metric on G/K is the one that is obtained from a two-sided invariant metric on G by the natural projection. While Samelson's proof is simple and geometric it gives no information in the noncompact case.

In the present paper we give a proof of the theorem of Samelson by a method which furnishes some additional information and which can be used to prove Cartan's theorem for the noncompact case as well as for the compact case.

2. **Preliminaries.** Let G be a connected Lie group with Lie algebra \mathfrak{g} . Let $g \rightarrow \text{Ad}(g)$ denote the adjoint representation of G on \mathfrak{g} and let $X \rightarrow \text{ad}(X)$ denote the adjoint representation of \mathfrak{g} on \mathfrak{g} so $\text{ad}(X)(Y) = [X, Y]$. Suppose K is a closed subgroup of G such that $\text{Ad}_G(K)$ (the image of K under $g \rightarrow \text{Ad}(g)$) is compact. If the Lie algebra of K is \mathfrak{k} there exists a subspace $\mathfrak{m} \subset \mathfrak{g}$ such that $\mathfrak{g} = \mathfrak{m} + \mathfrak{k}$ (direct sum of vector spaces) and such that $\text{Ad}_G(k)\mathfrak{m} \subset \mathfrak{m}$ for all $k \in K$. The manifold G/K of left cosets gK can be given the structure of a Riemannian manifold whose metric is invariant under G , that is for each $x \in G$ the mapping $\tau(x): gK \rightarrow xgK$ of G/K onto G/K is an isometry. The natural projection π of G onto G/K maps \mathfrak{m} isomorphically onto the tangent space to G/K at $\pi(e)$ (e is the identity element of G) in such a way that the action of $\text{Ad}_G(K)$ on \mathfrak{m} corresponds to the action of $\tau(K)$ on the tangent space. Thus a Riemannian metric on G/K invariant under all $\tau(x)$, $x \in G$ is uniquely determined by a positive definite quadratic form on \mathfrak{m} , invariant under $\text{Ad}_G(K)$. The space G/K is called a *symmetric Riemannian homogeneous space* if the subspace \mathfrak{m} above satisfies $[\mathfrak{m}, \mathfrak{m}] \subset \mathfrak{k}$. For such a space we have then the relations

$$(1) \quad \mathfrak{g} = \mathfrak{m} + \mathfrak{k}, [\mathfrak{m}, \mathfrak{m}] \subset \mathfrak{k}, [\mathfrak{m}, \mathfrak{k}] \subset \mathfrak{m}, [\mathfrak{k}, \mathfrak{k}] \subset \mathfrak{k}.$$

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The space G/K will be called *irreducible* if $\text{Ad}_G(K)$ acts irreducibly on \mathfrak{m} .

3. The exponential mapping of a symmetric space. Let G/K be a symmetric Riemannian space. The subspace \mathfrak{m} of \mathfrak{g} can be identified with the tangent space to the complete Riemannian manifold G/K at $\pi(e)$. Let Exp denote the mapping of \mathfrak{m} into G/K which maps straight lines through 0 in \mathfrak{m} onto geodesics through $\pi(e)$ in G/K , preserving lengths of segments of each such line.

An important theorem in the theory of symmetric spaces states that each geodesic through $\pi(e)$ is an orbit of a one-parameter group of “transvections” (see [1; 4]) which can be expressed

$$(2) \quad \text{Exp } X = \pi \circ \exp X \quad \text{for } X \in \mathfrak{m}.$$

For each $X \in \mathfrak{m}$, let T_X denote the restriction of $(\text{ad } X)^2$ to \mathfrak{m} . From the relations (1) we see that T_X maps \mathfrak{m} into itself. We consider \mathfrak{m} as a manifold whose tangent space at each point is identified with \mathfrak{m} itself under the usual identification of parallel vectors.

THEOREM 1. *The differential of the mapping Exp satisfies*

$$(3) \quad d \text{Exp}_X = d\tau(\exp X) \circ \sum_{n=0}^{\infty} \frac{T_X^n}{(2n + 1)!} \quad \text{for } X \in \mathfrak{m}.$$

This theorem is useful because it describes the Exp -mapping by means of an isometry and a linear transformation of \mathfrak{m} which is given in terms of the Lie algebra.

We first prove a lemma which describes the analogous situation on G . This lemma is essentially equivalent to Cartan’s formula which expresses the Maurer-Cartan forms in canonical coordinates and is proved in [3, p. 157]. We give a different proof here.

For each $h \in G$, let $L(h)$ denote the left translation $g \rightarrow hg$ on G .

LEMMA 2. *Let G be a connected Lie group with Lie algebra \mathfrak{g} . Identifying \mathfrak{g} with its tangent space at each point we have*

$$(4) \quad d \exp_X = dL(\exp X) \circ \frac{1 - e^{-\text{ad}X}}{\text{ad}X} \quad \text{for } X \in \mathfrak{g}.$$

PROOF. If D is a linear operator on the space $C^\infty(G)$ of indefinitely differentiable functions on G and $F \in C^\infty(G)$, $[DF](g)$ will denote the value of DF at g . Each $Z \in \mathfrak{g}$ gives rise to a left invariant vector field on G and therefore to an operator $F \rightarrow ZF$ on $C^\infty(G)$ which commutes with left translations on G . The value of the function ZF at g is given by

$$[ZF](g) = \lim_{t \rightarrow 0} \frac{F(g \exp tZ) - F(g)}{t}.$$

It follows by a simple induction that $d^n/du^n F(\exp uZ) = [Z^n F](\exp uZ)$ which by Taylor's formula implies

$$(5) \quad f(g \exp tZ) = \sum_{n=0}^{\infty} \frac{t^n}{n!} [Z^n f](g)$$

if f is analytic in a neighborhood of g and t is sufficiently small. Also the Lie algebra element $[X, Y]$ induces in the same fashion the operator $XY - YX$. Now suppose f is analytic in a neighborhood V of e in G and that U is an open neighborhood of 0 in \mathfrak{g} such that $\exp U \subset V$. Let $X \in U$. Each $Y \in \mathfrak{g}$ gives by parallel translation a tangent vector to \mathfrak{g} at X and

$$[d \exp_X(Y)f](\exp X) = [Y(f \circ \exp)](X) = \left[\frac{d}{dt} f(\exp(X + tY)) \right]_{t=0} \quad (6)$$

$$= \frac{d}{dt} \left\{ \sum_0^{\infty} \frac{1}{n!} [(X + tY)^n f](e) \right\}_{t=0}.$$

Due to the analyticity of f the growth of its derivatives is so restricted that the series in the last expression above can be differentiated with respect to t , term by term. Only the first power of t gives a contribution so we obtain

$$(6) \quad [d \exp_X(Y)f](\exp X) = \sum_{n=0}^{\infty} \frac{1}{(n+1)!} [(YX^n + XYX^{n-1} + \dots + X^n Y)f](e).$$

To simplify this last expression we use the formula

$$(7) \quad YX^m = \sum_{p=0}^m (-1)^p C_{m,p} X^{m-p} (\text{ad} X)^p(Y) \quad X, Y \in \mathfrak{g}.$$

For $m=1$ this amounts to the definition of $\text{ad} X$ and for a general integer $m > 0$ it follows easily by induction. Using the relation $\sum_{p=0}^{n-k} C_{n-p,k} = C_{n+1,k+1}$ we obtain

$$YX^n + XYX^{n-1} + \dots + X^n Y = \sum_{p=0}^n X^p \sum_{k=0}^{n-p} (-1)^k C_{n-p,k} X^{n-p-k} (\text{ad} X)^k(Y)$$

$$= \sum_{k=0}^n C_{n+1,k+1} (-1)^k X^{n-k} (\text{ad} X)^k(Y)$$

which combined with (4) and (5) yields

$$\begin{aligned}
 [d \exp_X (Y)f](\exp X) &= \sum_{r=0}^{\infty} \left[\frac{X^r}{r!} \sum_{m=0}^{\infty} (-1)^m \frac{1}{(m+1)!} (\text{ad}X)^m(Y)f \right] (e) \\
 &= \left[\frac{1 - e^{-\text{ad}X}}{\text{ad}X} (Y)f \right] (\exp X).
 \end{aligned}$$

This proves the lemma for all $X \in U$. Its validity for all of \mathfrak{g} is obtained by analytic continuation as follows: Let Y_1, \dots, Y_n be a basis of \mathfrak{g} and for each $X \in \mathfrak{g}$ put $Y_i^* = dL(\exp X)(Y_i)$; then $Y_i^*, i = 1, 2, \dots, n$ is a basis for the tangent space to G at $\exp X$. Define the functions $t_{ij}(X)$ by $d \exp_X (Y_i) = \sum_j t_{ij}(X) Y_j^*$. Then each $t_{ij}(X)$ is an analytic function on \mathfrak{g} . On the other hand

$$\frac{1 - e^{-\text{ad}X}}{\text{ad}X} (Y_i) = \sum_j s_{ij}(X) Y_j$$

where $s_{ij}(X)$ are analytic functions on \mathfrak{g} . We have proved that $t_{ij}(X) = s_{ij}(X)$ for all $X \in U$ and all i, j . But since t_{ij} and s_{ij} are analytic functions on \mathfrak{g} this last equation holds for all X and the lemma follows.

Theorem 1 now follows easily. From the relation $\pi \circ L(\mathfrak{g}) = \tau(\mathfrak{g}) \circ \pi$ and (2) we obtain for $Y \in \mathfrak{m}$

$$\begin{aligned}
 d \text{Exp}_X (Y) &= d\pi \circ d \exp_X (Y) = d\pi \circ dL(\exp X) \circ \frac{1 - e^{-\text{ad}X}}{\text{ad}X} (Y) \\
 &= d\tau(\exp X) \circ d\pi \sum_0^{\infty} (-1)^m \frac{(\text{ad}X)^m}{(m+1)!} (Y).
 \end{aligned}$$

From the relations (1) it follows that

$$d\pi \circ (\text{ad}X)^m(Y) = \begin{cases} (T_X)^n & \text{if } m = 2n, \\ 0 & \text{if } m \text{ is odd} \end{cases}$$

which proves Theorem 1.

4. The Riemannian curvature of a symmetric space. Let M be a Riemannian manifold, m a point in M , M_m the tangent space to M at m . The mapping Exp_m maps a neighborhood of 0 in M_m onto a neighborhood of m in M in a one-to-one fashion such that line segments through 0 go into geodesics through m in M . Let S be a two-dimensional subspace of M_m and $K(S)$ the corresponding sectional curvature. In order to apply Theorem 1 it is convenient to derive a new expression for $K(S)$.

LEMMA 3. Let Δ denote the Laplacian of the metric vector space S above and let f be the Radon-Nikodym derivative of the restriction of Exp_m to S (the ratio of the volume elements in $\text{Exp}_m(S)$ and S) normalized by $f(0) = 1$. Then

$$K(S) = -\frac{3}{2} \Delta f(0).$$

PROOF. Let A_0 denote a small disk in S with center at 0 and radius r and we put $A = \text{Exp}_m(A_0)$. Let $A_0(r)$ and $A(r)$ denote the corresponding areas. Then

$$A(r) = \int_{A_0} f(X) dX = A_0(r) \left\{ f(0) + \frac{1}{8} r^2 [\Delta f](0) + \dots \right\}.$$

Applying Vermeil's formula

$$K(S) = \lim_{r \rightarrow 0} 12 \frac{A_0(r) - A(r)}{r^2 A_0(r)},$$

[2, p. 253], we get Lemma 3 immediately.

THEOREM 2. Let G/K be a symmetric Riemannian space, Q the quadratic form on \mathfrak{m} that gives the invariant metric on G/K . Let S be a two-dimensional subspace of \mathfrak{m} spanned by the orthonormal vectors Y and Z . Then

$$K(S) = -Q(T_Y(Z), Z).$$

PROOF. Let X_1, \dots, X_n be a basis of \mathfrak{m} such that $Q(X_i, X_j) = \delta_i^j$ and such that $X_1 = Y, X_2 = Z$. Each $X \in S$ can be represented $X = x_1 X_1 + x_2 X_2$ and the Laplacian Δ on S has the form

$$\Delta = \frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}.$$

If a and b are two vectors in a metric vector space we denote by $a \vee b$ the parallelogram spanned by a and b and by $|a \vee b|$ the area. We write $A_X = \sum_0^\infty [(2n+1)!]^{-1} T_X^n$ and $A_X(X_i) = v_i, i = 1, 2$. Since the mapping $\tau(\text{exp } X)$ is an isometry we see from Theorem 1

$$f(X) = \frac{|v_1 \vee v_2|}{|X_1 \vee X_2|} = |v_1 \vee v_2|.$$

If A_X has the matrix (A_{ij}) with respect to the basis X_1, \dots, X_n ,

$$\begin{aligned} f(X) &= |(A_{11}X_1 + \dots + A_{n1}X_n) \vee (A_{12}X_1 + \dots + A_{n2}X_n)| \\ &= [(A_{11}A_{22} - A_{12}A_{21})^2 + \dots + (A_{i1}A_{j2} - A_{j1}A_{i2})^2 + \dots]^{1/2} \end{aligned}$$

since $|A_{i1}A_{j2} - A_{j1}A_{i2}|$ is the area of the projection of $v_1 \vee v_2$ on the (X_i, X_j) -plane. In computing $\Delta f(0)$ from the expression for $f(X)$ we only have to consider terms of second order in x_1 and x_2 . Since the matrix elements T_{ij} of T_X are either 0 or are of second order in x_1 and x_2 we find easily

$$\begin{aligned} [\Delta f](0) &= [\Delta A_{11}A_{22}](0) = \left[\Delta \left(1 + \frac{1}{3!} T_{11} \right) \left(1 + \frac{1}{3!} T_{22} \right) \right](0) \\ &= \frac{1}{3!} [\Delta(T_{11} + T_{22})](0) \end{aligned}$$

and since $T_X = (\text{ad}(x_1X_1 + x_2X_2))^2$ restricted to \mathfrak{m} ,

$$\begin{aligned} [\Delta f](0) &= \frac{1}{3} [Q(T_Y(Z), Z) + Q(T_Z(Y), Y) + Q(T_Y(Y), Y) \\ &\quad + Q(T_Z(Z), Z)]. \end{aligned}$$

Here the last two terms vanish, the two first are equal and the theorem follows from Lemma 3.

THEOREM 3. *Let G/K be an irreducible symmetric Riemannian space.*

- (i) *If G/K is compact the sectional curvature is everywhere ≥ 0 .*
- (ii) *If G/K is noncompact the sectional curvature is everywhere ≤ 0 .*

PROOF. We can assume that G acts effectively on G/K ; it is well known [4, p. 56] that either \mathfrak{g} is semi-simple or $[\mathfrak{m}, \mathfrak{m}] = 0$. In the latter case Theorem 3 is obvious so we assume \mathfrak{g} is semi-simple. Let B denote the Killing form on \mathfrak{g} . By the irreducibility

$$(7) \quad B(X, X) = \lambda Q(X, X) \quad \text{for all } X \in \mathfrak{m}$$

where λ is a constant. Let D be a positive definite quadratic form on \mathfrak{f} invariant under $\text{Ad}_G(K)$. The form $\Phi(Z, Z) = Q(X, X) + D(Y, Y)$ ($Z = X + Y$, $X \in \mathfrak{m}$, $Y \in \mathfrak{f}$) is positive definite and invariant under $\text{Ad}_G(K)$; hence if $Y \in \mathfrak{f}$, the linear transformation $\text{ad } Y$ has a skew symmetric matrix with respect to Φ and

$$(8) \quad B(Y, Y) = \text{Tr}(\text{ad } Y \text{ ad } Y) \leq 0.$$

Now let Z denote the center of G . Then the compact group $\text{Ad}_G(K)$ is isomorphic to $K/(Z \cap K)$. But $Z \cap K = e$ since G acts effectively so K is compact. The constant λ is negative in the case (i) and positive in case (ii). Using the notation of Theorem 2 we obtain from (8) $B(T_Y(Z), Z) = -B([Y, Z], [Y, Z]) \geq 0$. Theorem 3 now follows from (7).

REMARK. The conclusion of (i) in Theorem 3 holds whether or not

G/K is irreducible. This can be seen by decomposing \mathfrak{m} into irreducible subspaces invariant under $\text{Ad}_G(K)$ and orthogonal with respect to Q . On each of those subspaces B is a nonpositive multiple of Q and we can proceed as before.

5. Compact homogeneous spaces. The theorem of H. Samelson mentioned in the introduction can be stated as follows.

THEOREM 4. *Let G be a compact connected Lie group, K a closed subgroup. Let Q be a positive definite quadratic form on the Lie algebra \mathfrak{g} invariant under $\text{Ad}(G)$ and let \mathfrak{m} be the orthogonal complement to the subalgebra \mathfrak{k} . The restriction of Q to \mathfrak{m} defines a Riemannian metric on G/K invariant under G , and with respect to this metric the sectional curvature is everywhere ≥ 0 .*

PROOF. In the two-sided invariant metric on G given by Q the geodesics are the cosets of one-parameter subgroups. This is a special case of (2) applied to the symmetric space $G = (G \times G)/D$ where D is the diagonal of $G \times G$, the symmetry automorphism of $G \times G$ being $(x, y) \rightarrow (y, x)$ and each $(g, g_1) \in G \times G$ giving the isometry $x \rightarrow xg_1g^{-1}$ of G . The geodesics in G/K through $\pi(e)$ are again projections of certain one-parameter subgroups in G , that is

$$(9) \quad \text{Exp } X = \pi \circ \exp X \quad \text{for } X \in \mathfrak{m}.$$

(See [4, Theorem 13.2]. In [5] a simple geometric proof was based on comparison between lengths of curves in G and their projections in G/K .) Now let S be a two-dimensional subspace of \mathfrak{m} . We can then find an orthonormal base (X_i) of \mathfrak{m} and an orthonormal base (X_α) of \mathfrak{k} such that X_1 and X_2 span S . Each $X \in S$ can be written $X = x_1X_1 + x_2X_2$ and the Laplacian on S is

$$\Delta = \frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}.$$

We also put $[X_i, X_j] = \sum_k c_{ijk}X_k + \sum_\rho c_{i\rho}X_\rho$ and $A_X = (\text{ad } X)^{-1} \cdot (1 - e^{-\text{ad } X})$. Let f and F denote the Radon-Nikodym derivative of the restrictions of \exp and Exp to S . Then

$$f(X) = \frac{|A_X(X_1) \vee A_X(X_2)|}{|X_1 \vee X_2|}$$

and

$$F(X) = \frac{|d\pi \cdot A_X(X_1) \vee d\pi \cdot A_X(X_2)|}{|X_1 \vee X_2|}.$$

Now it is easily seen, that on cancelling terms of order ≥ 2 in x_1 and x_2

$$\begin{aligned} A_X(X_1) &= (1 + p_1)X_1 + p_2X_2 + \cdots + p_nX_n + \cdots + p_\rho X_\rho + \cdots, \\ A_X(X_2) &= q_1X_1 + (1 + q_2)X_2 + \cdots + q_nX_n + \cdots + q_\sigma X_\sigma + \cdots \end{aligned}$$

where the coefficients p and q are polynomials in x_1 and x_2 of degree ≥ 1 without constant terms. Moreover $p_\rho = -c_{21\rho}x_2/2$, $q_\sigma = -c_{12\sigma}x_\sigma/2$. The expressions for $d\pi \cdot A_X(X_1)$ and $d\pi A_X(X_2)$ are obtained by cancelling the X_α from the expressions above. By a computation similar to the one used in the proof of Theorem 2 we find

$$(10) \quad \Delta f(0) = \Delta F(0) + \frac{1}{2} \sum_{\rho} c_{12\rho}^2.$$

By the remark following Theorem 3 ($G \times G/D$ has curvature everywhere ≥ 0 ; by Lemma 3 $\Delta f \leq 0$ and by (10) $\Delta F \leq 0$). This proves Theorem 4.

REMARK. From relation (10) it is easily seen that in the situation described in Theorem 4, the curvatures of G and G/K are the same for all sections of \mathfrak{m} if and only if $c_{ij\rho} \equiv 0$, that is \mathfrak{m} is a subalgebra, hence an ideal in \mathfrak{g} .

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