

ON A RESULT OF G. D. BIRKHOFF ON LINEAR DIFFERENTIAL SYSTEMS

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We give a simple example to show that a result on the equivalent singular points of systems of ordinary linear differential equations due to G. D. Birkhoff [3; 5, pp. 252-257] needs amendment. In matrix notation, in which Y, P , etc. denote $n \times n$ matrix-valued functions of a complex variable z , this result is as follows.

A. Result. *Every linear differential system*

$$(1) \quad Y'(z) = P(z)Y(z)$$

with a singular point of rank $q+1$ at $z = \infty$ ($q \geq -1$) is equivalent at $z = \infty$ to a canonical system

$$(\bar{1}) \quad \bar{Y}'(z) = \bar{P}(z)\bar{Y}(z)$$

in which $z\bar{P}(z)$ is a polynomial of degree less than or equal to $q+1$.

B. Definitions.¹ (a) *The equation (1) is said to have a singular point of rank $q+1$ at ∞ , if and only if the function P has a pole of order q at ∞ , i.e.*

$$(2) \quad P(z) = \sum_{k=-q}^{\infty} P_k z^{-k} \quad P_{-q} \neq 0.$$

In case $q = -1$, i.e. the rank is 0, we say that (1) has a regular singular point at ∞ .

(b) *We call equations (1) and $(\bar{1})$ equivalent at ∞ , if and only if a matrix-valued function A , holomorphic at ∞ and with $\det A(\infty) \neq 0$, can be found such that the substitution*

$$(3) \quad Y(z) = A(z)\bar{Y}(z)$$

carries (1) into $(\bar{1})$.

C. Example. Consider the 2×2 matrix equation with a regular singular point at ∞ , i.e. with $q = -1$:

$$(4) \quad Y'(z) = \left\{ \frac{1}{z} \begin{bmatrix} -1 & 0 \\ 0 & 0 \end{bmatrix} + \frac{1}{z^2} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \right\} Y(z).$$

According to Result A, this is equivalent at $z = \infty$ to an equation

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¹ Due to Poincaré and Birkhoff, respectively.

$$(4) \quad \bar{Y}'(z) = \frac{\bar{P}_1}{z} \bar{Y}(z), \quad \bar{P}_1 \neq 0.$$

From (3) it follows that \bar{P}_1 is similar to the coefficient of $1/z$ in (4); in fact

$$\bar{P}_1 = A_0^{-1} \begin{bmatrix} -1 & 0 \\ 0 & 0 \end{bmatrix} A_0, \quad A_0 = A(\infty).$$

Now as z completes a positive circuit about the point ∞ , the solution Y of (4) gets post-multiplied by a matrix M , called the *monodromic matrix* of (4) associated with the singularity at ∞ . Likewise, \bar{Y} gets post-multiplied by a matrix \bar{M} when z completes a positive circuit of ∞ . But since the values of the function $\bar{P}(z) = \bar{P}_1/z$ commute, \bar{M} is similar to $\exp(-2\pi i \bar{P}_1)$,² i.e. to

$$A_0^{-1} \exp \left(2\pi i \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \right) A_0.$$

The matrix within the exponential being idempotent, it follows that $\bar{M} = I$. On the other hand, we find by direct integration that (4) has a matrix solution

$$Y(z) = \begin{bmatrix} (\log z)/z, & 1/z \\ 1 & 0 \end{bmatrix}.$$

Since any matrix solution of (4) will be of the form $Y(z) \cdot C$, where $\det C \neq 0$, it follows that

$$M = C^{-1} \begin{bmatrix} 1 & 0 \\ -2\pi i & 1 \end{bmatrix} C.$$

Thus $M \neq \bar{M}$. This shows that Y and \bar{Y} cannot be connected by an equation of the type (3) in which the function A is (single-valued) holomorphic and invertible at ∞ . The result A thus fails for the equation (4).

D. Remarks. In 1909 Birkhoff [1] discussed Result A in non-degenerate cases, and stated [5, p. 201] that he hoped to deal later with the case in which $q = -1$ and the eigenvalues of the matrix P_{-q} in (2) differ by integers. Example C shows that the result is incorrect precisely in this case. In a nutshell the trouble is that M depends on all Laurent coefficients of P and not just on the coefficient of z^{-1} —the residue, cf. [6, §4].

² Cf. e.g. [6, 2.2 (d), 4.2]; the minus sign in this expression arises from the fact that a positive circuit of ∞ is a negative circuit of 0.

In his 1913 paper [3], Birkhoff stated Result A in the general form given above, and gave a complete proof for the case in which M can be diagonalized by a similarity transformation, i.e. when M has simple elementary divisors. We may thus conclude:

The Result A is valid under the assumption that the monodromic matrix M of (1) associated with the singularity at ∞ has simple elementary divisors.

It remains to be investigated to what extent this assumption can be weakened. But the necessity for some such assumption shows that the notion of *equivalence* introduced by Birkhoff is not as useful in reducing the complexity of linear differential systems as has been believed.

In his 1913 paper [3] Birkhoff also gave the outlines of a proof of Result A for the case in which M cannot be diagonalized [5, pp. 256–257]. If a proof along these lines were possible, Example C would also disprove the following deep matrix-function-theoretic result on which Birkhoff's entire argument rests, and which he uses in his other work, e.g. in [4]:

BIRKHOFF'S LEMMA [2]. *Every $n \times n$ matrix-valued function F , which is holomorphic and invertible on $[|z| \geq 1]$ admits the factorization*

$$F(z) = F_+(z)F_-(z)R(z)$$

where F_+ , F_- are holomorphic and invertible on $[|z| < \infty]$ and $[1 < |z| \leq \infty]$ respectively, and $R(z)$ is a diagonal matrix with entries z^{k_1}, \dots, z^{k_n} , in which k_1, \dots, k_n are integers.

This lemma seems to be correct, however. At any rate the writer's attempts to construct a proof of Result A in the degenerate case along the lines suggested by Birkhoff have failed.

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