A LIFTING FORMULA FOR THE HILBERT SYMBOL

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Abstract. The Hilbert symbol in an extension field is expressed in terms of norms, traces and Hilbert symbols in the ground field.

1. Introduction. We use the terminology of O'Meara's book [2]. Let \((\cdot, \cdot)_L\) and \(S_L(\cdot)\) denote the Hilbert and Hasse symbols over a local field \(L\). The lifting formula is

**Theorem 1.** Let \(K\) be an extension of the local field \(k\). For \(\lambda \in K\) define the matrix \(A(\lambda)\) by \(a_{ij}(\lambda) = \text{tr}_{K/k} \lambda \alpha_i \alpha_j\) where \(\alpha\) is a basis for \(K\) over \(k\). Then

\[
\begin{align*}
(\lambda, \mu)_K &= S_k(A(1))S_k(A(\lambda))S_k(A(\mu))S_k(A(\lambda\mu))(N_{K/k}\lambda, N_{K/k}\mu)_k.
\end{align*}
\]

**Corollary.** Suppose \(b, c \in k\), then

\[
(\lambda, b)_K = (N_{K/k}\lambda, b)_k
\]

and

\[
(b, c)_K = (b, c)_k, \quad [K:k] \text{ odd},
\]

\[
= +1, \quad [K:k] \text{ even}.
\]

When \(k\) is dyadic the theorem provides a method for computing Hilbert symbols over \(K\) such that the amount of work is bounded by a polynomial in \([K:k]\). The work involved in a direct approach grows exponentially.

2. The proof. Let \(X\) be a symmetric matrix with entries in \(K\). The determinant of \(X\) is written \(|X|\) and the dimension of \(X\) is written \(\dim X\). Let \(A(X)\) be the matrix obtained by replacing \(x_{ij}\) with \(A(x_{ij})\).

We will deduce Theorem 1 from

**Theorem 2.** Suppose \(X\) and \(Y\) are nonsingular symmetric matrices with entries in \(K\) such that \(\dim X = \dim Y\) and \(|X|/|Y|\) is a square in \(K\). Then

\[
S_K(X)S_K(Y) = S_k(A(X))S_k(A(Y)).
\]

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We first prove Theorem 1. It is easily seen that

(a) \((\lambda, \mu)_K = S_K(1 \oplus \lambda \mu)S_K(\lambda \oplus \mu),\)

(b) \(S_k(A(\beta \oplus \gamma)) = S_k(A(\beta))S_k(A(\gamma))(|A(\beta)|, |A(\gamma)|),\)

(c) \(|A(\beta)| = |A(1)| N_K/k \beta.\)

Using these observations it is easy to deduce Theorem 1 from Theorem 2. The corollary follows easily from (1), (3) (c) and \(A(b \beta) = b A(\beta).\)

The rest of this paper is devoted to a proof of Theorem 2.

Suppose that \(V\) and \(W\) are symmetric matrices with entries in \(K\) and that \(V\) and \(W\) are "congruent" over \(K\) (i.e., \(TVT^t = W\) for some matrix \(T\) with entries in \(K\)). We will show that \(A(V)\) and \(A(W)\) are congruent over \(k\). Thus it will be possible to replace a matrix by a congruent one at any time. In particular the choice of the basis \(\alpha\) is irrelevant. By assumption \(w_{ij} = \sum \tau_{im}v_{mn}\tau_{jn}\) for some \(\tau_{ij} \in K\). (It is understood throughout that we sum over repeated indices.) Write \(\tau_{ij} = \sum t_{ij}^m a_m \) and \(\alpha_i \alpha_j = \sum a_{ij}^m a_m\) where \(t_{ij}, a_{ij}^m \in k\). Since

\[
tr_{K/k} w_{mn} \alpha_i \alpha_j = \sum d_{ij}^{p_\sigma} (tr_{K/k} v_{su} a_{i\alpha_j} a_{i\alpha_j}) d_{j\alpha_j}^{q_{\alpha_j}}
\]

where \(d_{ij}^{p_\sigma} = \sum t_{mi}^{\alpha_j} a_{ij}^{\alpha_j}\), the claim follows.

If \(S_K(X) = S_K(Y)\), then \(X\) and \(Y\) are congruent over \(K\). By the previous paragraph (2) holds.

Suppose \(|X| = \lambda\) and \(X\) and \(Y\) are not congruent over \(K\). Define

\[
M_1 = I_2 \oplus -I_2 = I_2 \otimes (-1 \oplus 1),
\]

\[
M_2 = M_2(K) = (-\Delta \oplus 1) \otimes (-\Pi \oplus 1)
\]

where \(I_2\) is the 2 dimensional identity matrix, \(\Pi\) is any prime of \(K\), and \(\Delta\) is any unit of quadratic defect 4o in \(K\). By [2, 63:11a], \(S_K(M_1)S_K(M_2) = -1\). Hence \(X \oplus I_5\) and \(Y \oplus I_5\) are congruent over \(K\) to \(\lambda \oplus I_n \oplus M_1\) and \(\lambda \oplus I_n \oplus M_2\) in some order where \(n = \text{dim} X\). Since \(|X|/|Y|\) is a square in \(K\), it follows easily from (3) (c) that \(|A(X)|/|A(Y)|\) is a square in \(k\). By some simple calculations

\[
S_k(A(X))S_k(A(Y)) = S_k(A(X \oplus I_5))S_k(A(Y \oplus I_5))
\]

\[
= S_k(A(M_1))S_k(A(M_2)).
\]

Therefore (2) holds in general if it holds for \(X = M_1, Y = M_2\).

We may regard the theorem as a statement about \(K/k\). Suppose Theorem 2 holds for \(K/L\) and for \(L/k\). We will show that it holds for \(K/k\). To distinguish the fields involved, write \(A(\lambda; K/k)\) for the \(A(\lambda)\) defined in
Theorem 1. We must show that

\[(a) \quad S_L(A(M_1; K/L)) \neq S_L(A(M_2(K); K/L)),\]
\[(b) \quad S_k(A(M_1; L/k)) \neq S_k(A(M_2(L); L/k))\]

Together imply

\[(5) \quad S_k(A(M_1; K/L); L/k)) \neq S_k(A(M_2(K); K/L); L/k)).\]

Note that \(|A(M_1; K/L)|\) is a square. By (4) (a), \(A(M_1; K/L)\) and \(A(M_2(K); K/L)\) are congruent over \(L\) to \(I \oplus M_1\) and \(I \oplus M_2(L)\) in some order. Equation (5) follows from (4) (b).

By the previous paragraph we need only prove the theorem for pure ramified and pure inertial extensions. In this case we may take one of \(\Delta\) and \(\Pi\) to be in \(k\). Call it \(\gamma\) and call the other \(\Gamma\). Then

\[A(M_1) = A(-1 \oplus 1) \otimes I_2, \quad A(M_2) = A(-\Gamma \oplus 1) \otimes (-\gamma \oplus 1).\]

After a little computation

\[S_k(A(M_1)) = (-1, (-1)^m)_k, \quad S_k(A(M_2)) = (-1, (-1)^m)_k(\gamma, N_{K/k}^\Gamma)_k\]

where \(m = [K:k]\). It suffices to show that \((\gamma, N_{K/k}^\Gamma)_k = -1\).

We will show that \(\gamma\) and \(N_{K/k}^\Gamma\) equal \(\delta\) and \(\pi\) in some order where \(\delta\) is a unit of quadratic defect \(4\alpha\) in \(k\) and \(\pi\) is a prime of \(k\). By [2, 63:11a] this completes the proof. If \(K/k\) is pure ramified, \(\Gamma = \Pi\) and \(N_{K/k}^\Gamma\) is a prime of \(k\). If \(K/k\) is pure inertial, we can choose \(\delta \in k\) and \(\Delta \in K\) such that \(\delta \equiv \Delta \equiv 1 \pmod{4}\), \(\delta\) has quadratic defect \(4\alpha\) in \(k\), and \(N_{K/k}^\Delta \equiv \delta\) (see [1, p. 129]). Since \(\delta\) is not a square, neither is \(\Delta\). Hence \(\Delta\) has quadratic defect \(4\alpha\) in \(K\).

REFERENCES


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