THE EQUATION $L(E, X^{**}) = L(E, X)^{**}$ AND THE PRINCIPLE OF LOCAL REFLEXIVITY

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ABSTRACT. A new derivation of the equation $L(E, X^{**}) = L(E, X)^{**}$ is given, for $\dim(E) < \infty$ and X a Banach space. From this equation the principle of local reflexivity is derived.

- 0. Introduction. The principle of local reflexivity [6] in the somewhat stronger form found in [5] is derived here from the equation $L(E, X)^{**} = L(E, X^{**})$. This equation is found explicitly in Schatten's monograph [7, pp. 40, 41] and at least implicitly in [3, p. 13]. Thus it is a classic formula in the theory of tensor products of Banach spaces. In §3 we use nontensor product methods to derive the equation $L(E, X^{**}) = L(E, X)^{**}$. The argument is easily accessible to students in a first functional analysis course.
- 1. Notation and preliminaries. Always X, Y, Z are Banach spaces and A, E, F are finite dimensional Banach spaces. All operators S, T, U, V, W are continuous linear operators and the Banach space of operators from X to Y is denoted by L(X, Y). Always X is identified with its natural embedding in X^{**} . If $T \in L(X, Y^{**})$ and $(T_{\alpha}) = L(X, Y)$ is a net such that $\lim_{x \to \infty} f(T_{\alpha}x) = Tx(f)$ for each f in Y^{*} , x in X write w^{*} -op $\lim_{x \to \infty} T_{\alpha} = T(T_{\alpha} \to T)$ in the weak-star operator topology).
- LEMMA 1. Let (T_{α}) be a net in L(X, Y) and T in $L(X, Y^{**})$ with $||T_{\alpha}|| \le ||T||$ for each α . Suppose $A \subseteq X$, $TA \subseteq Y$ and w^{*} -op $\lim_{\alpha} T_{\alpha} = T$. Then, to $\varepsilon > 0$, there is a net $(S_{\alpha}) \subseteq L(X, Y)$ such that $||S_{\alpha}|| < ||T|| + \varepsilon$, w^{*} -op $\lim_{\alpha} S_{\alpha} = T$ and $S_{\alpha} = T$ for each a in A.

PROOF. For each a in A, $(T_{\alpha}a)$ converges weakly to Ta. Since $\dim(A) < \infty$, using standard techniques (e.g. [2, p. 477]), a net of convex combinations of (T_{α}) , say (U_{α}) , converges in norm on A, and w^* -lim $U_{\alpha} = T$. Write $X = A \oplus Z$ and set $S_{\alpha}(a+f) = Ta + U_{\alpha}f$. Then $S_{\alpha} \in L(X, Y)$ and $\|S_{\alpha} - U_{\alpha}\|^{\frac{\alpha}{2}} \to 0$. Thus, for large α , $\|S_{\alpha}\| < \|T\| + \varepsilon$.

If $\dim(E)=1$, then $L(E,X)^{**}=L(E,X^{**})$ is simply the statement that the unit ball $U_1(X)=\{x, ||x|| \le 1\}$ is weak-star dense in $U_1(X^{**})$. As

Received by the editors December 1, 1972.

AMS (MOS) subject classifications (1970). Primary 46B10, 47A65.

Key words and phrases. Local reflexivity, operator, Banach, dual, reflexive.

described below, the equation means that, for each T in $L(E, X^{**})$, there is a net $(T_{\alpha}) \subset L(E, X)$ such that $\|T_{\alpha}\| \leq \|T\|$ and w^{*} -op $\lim T_{\alpha} = T$. To see that this is the meaning of the equation let e_{1}, \dots, e_{n} be a basis for E and identify each T in L(E, X) with the n-tuple (Te_{i}) . In $Y = \prod_{i=1}^{n} X$ use the usual coordinatewise vector and scalar operations and set $\|(x_{i})\| = \sup\{\|\sum a_{i}x_{i}\|, \|\sum a_{i}e_{i}\| \leq 1\}$, so that the identification is an isometry between L(E, X) and Y. Then $Y^{*} = \prod_{i=1}^{n} X^{*}$ with

$$\|(x_i^*)\| = \sup \{ \sum x_i^*(x_i) \mid \|(x_i)\| < 1 \}$$

and $Y^{**}=\prod_{i=1}^{n}X^{**}$ with $\|(x_{i}^{**})\|=\sup\{\sum x_{i}^{**}(x_{i}^{*})\|\|(x_{i}^{*})\|\leq 1\}$. Now associate each element (x_{i}^{**}) of $\prod_{i=1}^{n}X^{**}$ with the operator T such that $Te_{i}=x_{i}^{**}$. If $\|(x_{i}^{**})\|=1$ and $\|(x_{i}^{\alpha})\|\leq 1$ such that $\sum x_{i}^{*}(x_{i}^{\alpha})\to \sum x_{i}^{**}(x_{i}^{*})$ for each (x_{i}^{*}) in Y^{*} , then $x^{*}(\sum b_{i}x_{i}^{\alpha})\to (\sum b_{i}x_{i}^{**})(x^{*})$ for each x^{*} in X^{*} . Thus $\lim\|\sum b_{i}x_{i}^{\alpha}\|\geq\|\sum b_{i}x_{i}^{**}\|$. It easily follows that, if $\varepsilon>0$, $\|(x_{i}^{\alpha})\|=\sup\{\|\sum b_{i}x_{i}^{\alpha}\|, \|\sum b_{i}e_{i}\|\leq 1\}\geq (1-\varepsilon)\|T\|$ for large α or $\|(x_{i}^{**})\|\geq \|T\|$.

In summary, the mapping $(x_i^{**}) \rightarrow T$ is a norm decreasing mapping from $L(E, X)^{**}$ onto $L(E, X^{**})$ which is continuous with the weak-star topology on $L(E, X)^{**}$ and the weak-star operator topology on $L(E, X^{**})$. Further it is the identity on L(E, X). The equation $L(E, X^{**}) = L(E, X)^{**}$ means this mapping is an isometry.

2. Local reflexivity. Let F be subspace of X^* with basis $\{f_1, \dots, f_k\}$ and let $T \in L(E, X^{**})$ with E having basis $\{e_1, \dots, e_n\}$ such that $[e_1, \dots, e_m] = E \cap X$. The pairs (f_i, e_j) define functionals on L(E, X) by $(f_i, e_i)(S) = f_i(Se_i)$ (it is easy to compute that $\|(f_i, e_j)\| = \|f_i\| \|e_i\|$). Using Helly's theorem (e.g. $[\mathbf{8}, p. 103]$), and the equation $L(E, X)^{**} = L(E, X^{**})$ there is an S such that $\|S\| < \|T\| + \varepsilon$ and $(f_i, e_j)(S) = Te_j(f_i)$ for each i, j. Thus f(Se) = Te(f) for every f in F, e in E. (This argument is used in Lemma 1, $[\mathbf{4}]$.) One may assume, by enlarging F if necessary, that for each e there is a norm one f in F such that $(1-\varepsilon)\|Te\| < Te(f)$. Constructing $S = S_G$ for each $G \supset F$ such that g(Se) = Te(g) for each g in G, e in E, and such that $\|S_G\| < \|T\|(1+\varepsilon)$, then w^* -op $\lim_G S_G = T$. By Lemma 1 there is a net $(T_a) \subset L(E, X)$ such that w^* -op $\lim_G T_a = T$, $T_a e_i = e_i$ if $i \le m$, $f(T_a e) = Te(f)$ for each e in E, f in F, and $\|T_a\| < \|T\|(1+2\varepsilon)$. Further, $(1-\varepsilon)\|Te\| < \|T_a e\| < \|T\|(1+2\varepsilon)$ if $\|e\| \le 1$.

THEOREM 1 (LOCAL REFLEXIVITY). Let $E \subset X^{**}$, $A = E \cap X$, and $F \subset X^*$. To $\delta > 0$, there is an S in L(E, X) such that $(1 - \delta) \|e\| < \|Se\| < (1 + \delta) \|e\|$, Sa = a for each a in A, and f(Se) = e(f) for each e in E, f in F.

PROOF. As in the calculation preceding Theorem 1, enlarging F if necessary, assume $(1-\delta/2)\|e\| < \sup\{e(f) \mid \|f\| \le 1, f \in F\}$. Letting T be the identity operator from E to X^{**} construct (T_α) such that $(1-\delta/2) < 1$

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 $||T_{\alpha}e|| < (1+\delta)$ if ||e|| = 1. Then $(1-\delta/2)||e|| < ||T_{\alpha}e|| < ||e||(1+\delta)$ for every e and set $S = T_{\alpha}$ for some α .

3. The derivation of $L(E, X^{**}) = L(E, X)^{**}$. If $E = l_{1,n}$ then the derivation is as follows. Let $\{e_1, \cdots, e_n\}$ be the usual unit vector basis of $l_{1,n} = E$. For T in L(E, X), $||T|| = \sup\{||\sum \alpha_i T e_i||, \sum |\alpha_i| \le 1\} \le \max\{||T e_i||\}$. But $||T|| \ge \max ||T e_i||$ since $||e_i|| = 1$ for each i. Thus $Y = \prod_{i=1}^n X$ has norm $||(x_i)|| = \max\{||x_i||\}$. Then $Y^* = \prod_{i=1}^n X^*$ has norm, $||(x_i^*)|| = \max\{||x_i^*||\}$. The latter is the norm for $L(E, X^{**})$ so that the mapping of Y^{**} to $L(E, X^{**})$ in §1 is an isometry.

Now let $E, \varepsilon>0$ be given and let V be an operator on $l_{1,n}$ to E such that $V(\{u \mid \|u\|<1+\varepsilon\})\supset \{e \mid \|e\|\leq 1\}$. That such $l_{1,n}$, V exist may be seen by embedding E^* into an $l_{\infty,k}$ in such a way that $\|e^*\| \ge \|Ue^*\| \ge (1-\alpha)\|e^*\|$ and choosing α small and $V=U^*$. If $T\in L(E,X^{**})$, then $TV\in L(l_{1,n},X^{**})$ and $\|TV\|\le \|T\|$. Set $A=\{u \mid TVu\in X\}$. There is a net (S_α) in $L(l_{1,n},X)$ such that $\|S_\alpha\|\le \|TV\|(1+\varepsilon)$, w^* -op $\lim S_\alpha=TV$, and by Lemma 1 we find S_α such that $S_\alpha u=TVu$ if $u\in A$. In particular if Vu=0 then $S_\alpha u=0$. Define $T_\alpha\in L(E,X)$ by letting $T_\alpha e=S_\alpha u$ if Vu=e. Because Vu=0 implies $S_\alpha u=0$ one has that T_α is well defined and in L(E,X). Moreover $T_\alpha V=S_\alpha$. If $\|e\|\le 1$ and $\|u\|<1+\varepsilon$ such that Vu=e, then $\|T_\alpha e\|=\|S_\alpha u\|\le \|S_\alpha\|(1+\varepsilon)\le \|TV\|(1+\varepsilon)^2\le \|T\|(1+\varepsilon)^2$. Finally $x^*(T_\alpha Vu)\to (TVu)x^*$ and so $x^*(T_\alpha e)\to (Te)(x^*)$ for every e in X^* . Thus w^* -op $\lim T_\alpha=T$. Since $\varepsilon>0$ is arbitrary the mapping from $L(E,X)^{**}$ to $L(E,X^{**})$ at the end of §1 is an isometry. This concludes the derivation.

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