

## A CHARACTERIZATION OF THE INVARIANT SUBSPACES OF DIRECT SUMS OF STRICTLY CYCLIC ALGEBRAS

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ABSTRACT. Two characterizations of the invariant subspace lattice of  $A^{(n)}$  for a strictly cyclic operator algebra  $A$  on a separable Hilbert space are proven.

We derive a characterization of the invariant subspaces of  $A^{(n)}$ , where  $A$  is an Abelian, hereditarily strictly cyclic operator algebra on a separable Hilbert space. A further characterization is derived in the case when  $A$  is generated by a single operator. The first result is also generalized to  $A^{(\infty)}$  when  $A$  has Donoghue lattice.

We will need some notation and definitions. Throughout this paper,  $H$  will be a separable, infinite-dimensional, complex Hilbert space, and  $B(H)$  the algebra of all bounded linear operators on  $H$ . If  $T \in B(H)$ , then  $A(T)$  is the weakly closed subalgebra of  $B(H)$  generated by  $T$  and the identity. If  $F \subset B(H)$ , then  $\text{Lat } F$  is the lattice of all invariant subspaces of  $F$ . We call  $F$  *transitive* if  $\text{Lat } F = \{\{0\}, H\}$ , and we call  $F$  *unicellular* if  $\text{Lat } F$  is totally ordered. By  $H^{(n)}$  we mean the direct sum of  $n$  copies of  $H$ . For  $T \in B(H)$ ,  $T^{(n)}$  is the operator on  $H^{(n)}$  defined by

$$T^{(n)}(x_1, x_2, \dots, x_n) = (Tx_1, Tx_2, \dots, Tx_n),$$

and  $F^{(n)} = \{T^{(n)}: T \in F\}$ . If  $M$  is a subspace of  $H^{(n)}$ , the  $i$ th *kernel* of  $M$  is the collection of all vectors in  $M$  whose  $i$ th coordinate is 0. Note that if  $M \in \text{Lat } T^{(n)}$ , then the  $i$ th kernel of  $M$  is invariant under  $T^{(n)}$ , and it is obviously isomorphic to an element of  $\text{Lat } T^{(n-1)}$ . If  $F^{(n)} \subset B(H^{(n)})$ , and if  $M \in \text{Lat } F^{(n)}$ , then  $M$  is an *invariant graph subspace of  $F^{(n)}$  on the  $i$ th coordinate* if  $M$  has the form

$$M = \{(T_1x, T_2x, \dots, T_{\lambda-1}x, x, T_{\lambda+1}x, \dots, T_nx): x \in D\}$$

for some linear manifold  $D$  of  $H$  and for linear transformations  $T_i$  with domain  $D$  and range contained in  $H$ . The  $T_i$ 's will be called *graph transformations for  $F$* . In general, the  $T_i$ 's need not be closed, although jointly they are closed since  $M$  is closed. If  $M$  and  $N$  are subspaces of  $H$ , we use  $M \vee N$  for the (closed linear) span of  $M$  and  $N$ .

Note that if  $M$  is an invariant subspace of  $F^{(n)}$ , then  $M$  is a graph subspace on the  $i$ th coordinate if and only if the  $i$ th kernel is  $\{0\}$ ; i.e., if and only if the  $i$ th coordinate of a vector determines the vector. Note also that the domain of a graph transformation for  $F$  is invariant under  $F$ , and the transformation commutes with

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every operator in  $F$ . In particular, if  $T$  is a graph transformation, so is  $T - \lambda$  for any scalar  $\lambda$ .

Recall that a subalgebra  $A$  of  $B(H)$  has *finite strict multiplicity* if there is a finite collection of vectors  $E = \{x_1, x_2, \dots, x_n\}$  such that

$$\{T_1x_1 + T_2x_2 + \dots + T_nx_n : T_i \in A\} = H.$$

The minimal cardinality of all such sets  $E$  is called the *strict multiplicity of  $A$* . If  $A$  has strict multiplicity 1,  $A$  is said to be *strictly cyclic*. An operator  $T$  has *finite strict multiplicity* if  $A(T)$  does, and  $T$  is *strictly cyclic* if  $A(T)$  is. An operator algebra  $A$  is said to be *hereditarily strictly cyclic* if the uniform closure of its restriction to every invariant subspace is strictly cyclic. The vector  $x$  is a *separating vector* for  $A$  if  $Tx = 0$  implies  $T = 0$  whenever  $T$  is an operator in  $A$ . Note that cyclic vectors for Abelian operator algebras are always separating.

The following propositions are known results which we will need.

**PROPOSITION 1 (HERRERO [7]).** *A uniformly closed operator algebra of finite strict multiplicity has no dense invariant manifolds other than  $H$ .*

**PROPOSITION 2 (LAMBERT [11]).** *If  $T$  is an operator in an Abelian strictly cyclic algebra, then the spectrum of  $T$  consists entirely of compression spectrum. (Recall that the compression spectrum of  $T$  is the set of complex numbers  $\lambda$  such that the range of  $T - \lambda$  is not dense in  $H$ .)*

**PROPOSITION 3 (HERRERO [8]).** *Every densely defined linear transformation commuting with every operator in an algebra of finite strict multiplicity is bounded.*

**PROPOSITION 4 (ROSENTHAL [20]).** *Let  $T$  be strictly cyclic. If  $T$  is unicellular, then  $T$  has one-point spectrum. Conversely, if  $T$  is hereditarily strictly cyclic, and if  $T$  has one-point spectrum, then  $T$  has Donoghue lattice (i.e., there is an orthonormal basis  $\{e_i\}_{i=0}^\infty$  of  $H$  such that the nontrivial invariant subspaces of  $T$  are the subspaces  $M_k = \bigvee_{i=k}^\infty e_i$  for positive integers  $k$ ).*

**THEOREM 1.** *Let  $A$  be an Abelian, unicellular, hereditarily strictly cyclic algebra. Then every element of  $\text{Lat } A^{(n)}$  can be expressed as the span of at most  $n$  invariant graph subspaces whose domains are in  $\text{Lat } A$ .*

**PROOF.** Let  $M \in \text{Lat } A^{(n)}$ , and let  $P_i$  be the  $i$ th coordinate projection. Since  $\text{Lat } A$  is totally ordered and each  $\overline{P_i M}$  (the closure of  $P_i M$ ) is in  $\text{Lat } A$ , we can choose  $i_0$  such that  $P_i M \subset \overline{P_{i_0} M}$  for  $i = 1, 2, \dots, n$ .

**CLAIM.**  $P_{i_0} M$  is closed.

**PROOF OF CLAIM.** Let  $\tilde{A}$  be the closure of  $A/\overline{P_{i_0} M}$ , and let  $N = \overline{P_{i_0} M}^{(n)}$ . The algebra  $A$  is strictly cyclic by hypothesis, and, obviously,  $\tilde{A}^{(n)}$  is the (uniform) closure of  $A^{(n)}/N$ . In particular,  $M \in \text{Lat } \tilde{A}^{(n)}$ , so  $P_{i_0} M$  is invariant under  $\tilde{A}$ . Of course,  $P_{i_0} M$  is dense in  $\overline{P_{i_0} M}$ , and so by Proposition 1,  $P_{i_0} M = \overline{P_{i_0} M}$ , and the claim is proven.

The above conclusion implies that we can choose a vector  $x_0 \in P_{i_0} M$  which is strictly cyclic for  $\tilde{A}$ . Choose  $f_0 \in M$  such that  $P_{i_0} f_0 = x_0$ , and let

$$G_0 = A^{(n)}f_0, \quad G = \tilde{A}^{(n)}f_0.$$

Every vector in  $G$  is a limit of vectors in  $G_0$  since every operator in  $\tilde{A}$  is a limit of operators in  $A/P_{i_0}M$ . Hence,  $G$  is invariant under  $A^{(n)}$ . If we show that  $G$  is a graph on the  $i_0$ th coordinate, we will know that  $G$  is closed since its graph transformations will be densely defined and commute with every operator in an Abelian strictly cyclic algebra; Proposition 3 then implies that they will be bounded. Since the domain of  $G$  is  $P_{i_0}M$ , its domain is in  $\text{Lat } A$ .

To show that  $G$  is a graph on the  $i$ th coordinate, it is enough to show that if  $(y_1, y_2, \dots, y_n)$  is in  $G$  with  $y_{i_0} = 0$ , then  $y_i = 0$  for  $i = 1, 2, \dots, n$ . But this is clear since  $x_0$  is a separating vector; i.e., if  $Tx_0 = y_{i_0} = 0$ , then  $T = 0$ , so  $T^{(n)}f_0 = 0$ .

Let  $K$  be the  $i_0$ th kernel of  $M$ . Trivially,  $K \in \text{Lat } A^{(n)}$ ; and if  $x \in M$ , there exists a  $y$  in  $G$  such that  $P_{i_0}x = P_{i_0}y$  (since  $P_{i_0}G = P_{i_0}M$ ), so  $x - y \in K$ . Thus,  $y + (x - y) \in M$ , so  $M = G \vee K$ . We can now perform the same procedure on  $K$ . Since  $P_{i_0}K = \{0\}$ , the index chosen will be different from  $i_0$ , and the next kernel chosen will have at least two coordinate projections which are  $\{0\}$ . We continue in this manner getting  $n$  invariant graph subspaces of  $A^{(n)}$ . Since the number of zero coordinate projections increases at each step, and since  $M$  is obviously the span of these subspaces, we are done.

A little more can be said about the structure of the graphs. If  $G_1, G_2, \dots, G_n$  are the graph subspaces in the order chosen in the proof, then  $G_n$  is a coordinate subspace;  $G_{n-1}$  is 0 on the domain slots of  $G_1, \dots, G_{n-2}$ ;  $G_{n-2}$  is 0 on the domain slots of  $G_1, \dots, G_{n-3}$ ; and so on. (Of course, some of the  $G_i$ 's may be 0.)

Nikolskii [15] has shown that if  $T$  is a weighted shift with  $p$ -summable weights ( $p > 0$ ) which go monotonically to 0, then  $T$  has Donoghue lattice (Nikolskii actually obtains more general conditions for unicellularity). Lambert [11] has shown that such an operator is strictly cyclic. Since the restriction of  $T$  to any invariant subspace is another such operator, the algebra generated by  $T$  satisfies the hypothesis of the theorem. Nordgren [17] has shown that every Donoghue operator  $T$  has the property that each of the invariant subspaces of  $(T^*)^{(n)}$  is a span of finite-dimensional invariant subspaces. The following theorem shows that this is true for a much wider class of operators.

**THEOREM 2.** *Let  $T$  be hereditarily strictly cyclic with  $\sigma(T) = \{\lambda\}$ . Then if  $M \in \text{Lat } (T^*)^{(n)}$ ,  $M$  is a span of finite-dimensional invariant subspaces of  $(T^*)^{(n)}$ . Equivalently, if  $M \in \text{Lat } T^{(n)}$ ,  $M$  is an intersection of invariant subspaces of  $T^{(n)}$  of finite codimension.*

**PROOF.** Replacing  $T$  by  $T - \lambda$  if necessary, we can assume that  $\lambda = 0$ . By Theorem 1 we need only consider invariant graph subspaces whose domains are subspaces of  $H$ . So let

$$G = \{(x, T_1x, T_2x, \dots, T_{n-1}x) : x \in D\}$$

be a graph subspace of  $T^{(n)}$ . The subspace  $D$  is in  $\text{Lat } T$  and, by Proposition 4, has the form  $D = \bigvee_{i=k}^\infty e_i$  for an orthonormal basis  $\{e_i\}_{i=0}^\infty$ .

Let  $M_j = \bigvee_{i=j}^\infty e_i$  (so  $D = M_k$ ). Then, for each  $j$ ,  $M_j^{(n)}$  is invariant under  $T^{(n)}$  and has finite codimension. Let

$$f_k = (e_k, T_1e_k, \dots, T_{n-1}e_k) \quad \text{and} \quad f_k^i = (T^{(n)})^i f_k.$$

Then  $f_k \in G$ , and so  $f_k^i \in G$  since  $G \in \text{Lat } T^{(n)}$ . Since the spectrum of any strictly cyclic operator consists entirely of compression spectrum, by Proposition 2,  $TM_j \subset M_{j+1}$  for every  $j$ . Thus, since  $f_k \in M_k^{(n)}$ , we have  $f_k^i = (T^{(n)})^i f_k \in M_{k+j}$ . Let

$$N_j = f_k \vee f_k^1 \vee f_k^2 \vee \dots \vee f_k^j \vee M_{k+j+1}^{(n)}.$$

Then  $N_j$  has finite codimension (since  $M_{k+j+1}^{(n)}$  has finite codimension). Also,  $N_j \in \text{Lat } T^{(n)}$  since  $M_{k+j+1}^{(n)} \in \text{Lat } T^{(n)}$  and  $T^{(n)} f_k^i = f_k^{i+1}$ .

We will be done if we can show that  $G = \bigcap_{j=1}^\infty N_j$ . Now, since  $\bigcap_{j=1}^\infty M_{k+j+1}^{(n)} = \{0\}$ , it follows that

$$\bigcap_{j=1}^\infty N_j = f_k \vee \left( \bigvee_{i=1}^\infty f_k^i \right).$$

Hence, by the definition of  $f_k^i$ ,  $\bigcap_{j=1}^\infty N_j$  is the smallest invariant subspace of  $T^{(n)}$  containing  $f_k$ , which is exactly the definition of  $G$ . This completes the proof.

In the next theorem, we extend Theorem 1. It will be convenient to introduce some terminology. We define  $H^{(\infty)}$  to be the collection of all square-summable sequences of vectors from  $H$ , and if  $T \in B(H)$ , we define  $T^{(\infty)}$  on  $H^{(\infty)}$  by  $T^{(\infty)}(x_1, x_2, \dots) = (Tx_1, Tx_2, \dots)$ . It is straightforward to verify that  $H^{(\infty)}$  is a Hilbert space, and that  $T^{(\infty)}$  is bounded. If  $A$  is a subalgebra of  $B(H)$ , then  $A^{(\infty)}$  is defined to be  $\{T^{(\infty)}: T \in A\}$ . If  $A$  has Donoghue lattice  $\{\{0\}, N_n\}$ , if  $M \in \text{Lat } A^{(\infty)}$  and  $M \neq \{0\}$ , and if  $n$  is the largest nonnegative integer such that  $N_n$  contains every coordinate projection of  $M$ , then  $n$  will be called the *order of  $M$* . (Such an  $n$  must exist since  $N_0 = H$ .)

**THEOREM 3.** *If  $A$  is an Abelian, hereditarily strictly cyclic algebra with Donoghue lattice  $\{\{0\}, N_n\}$ , then every element of  $\text{Lat } A^{(\infty)}$  is a span of invariant graph subspaces.*

**PROOF.** Let  $M \in \text{Lat } A^{(\infty)}$ . Choose a graph subspace  $G_{0,1} \subset M$  as we did in the proof of Theorem 1. In that proof, we chose the domain of  $G$  by taking a coordinate projection of  $M$  which contained every other coordinate projection. Here we modify that procedure by insisting that the coordinate index  $i_0$  of the domain of  $G_{0,1}$  be as small as possible (there may be more than one coordinate projection of  $M$  which could be chosen). As in that earlier proof, if  $K_{0,1}$  is the  $i_0$ th kernel of  $M$ ,  $M = G_{0,1} \vee k_{0,1}$ . Continuing in this manner, we get a sequence of graph subspaces and a sequence of kernels such that

$$\begin{aligned} M &= G_{0,1} \vee K_{0,1} = G_{0,1} \vee G_{0,2} \vee K_{0,2} \\ &= G_{0,1} \vee G_{0,2} \vee \dots \vee G_{0,i} \vee K_{0,i}. \end{aligned}$$

If  $\bigcap_{i=1}^\infty K_{0,i} = \{0\}$ , we are done. If not, let  $M_1 = \bigcap_{i=1}^\infty K_{0,i}$ . Then  $M = (\bigvee_{i=1}^\infty G_{0,i}) \vee M_1$ .

**CLAIM.** The order of  $M_1$  is greater than the order of  $M$ .

**PROOF OF CLAIM.** Let  $r$  be the order of  $M_1$  and  $s$  the order of  $M$ . If  $r \not> s$ , i.e. if  $r = s$ , then there is an index  $i$  such that the  $i$ th coordinate projection of  $M_1$  is  $N_s$ . Since  $N_s$  contains every coordinate projection of  $M$ , and since we chose the domain

for every graph by choosing the coordinate projection with lowest possible index, the  $i$ th projection must have been one of the choices. But then  $N_s$  could not be a projection of  $M_1$ . This contradiction proves the claim.

Now we proceed with  $M_1$  as we did with  $M$ , getting a sequence of graphs and kernels so that

$$M_1 = G_{1,1} \vee K_{1,1} = G_{1,1} \vee G_{1,2} \vee \cdots \vee G_{1,i} \vee K_{1,i}.$$

If  $\bigcap_{i=1}^{\infty} K_{1,i} = \{0\}$ , we are done. If not, let  $M_2 = \bigcap_{i=1}^{\infty} K_{1,i}$ . We continue inductively, getting a sequence of graph subspaces and a sequence  $\{M_i\}$  of intersections of kernels, where the order of  $M_{i+1}$  is greater than the order of  $M_i$  for all  $i$ . We have, for each  $k$ ,

$$M = \bigvee_{i=0}^k \left( \bigvee_{j=1}^{\infty} G_{i,j} \right) \vee M_k.$$

Finally, since the orders of the  $M_k$ 's go to infinity,

$$\bigcap_{k=1}^{\infty} M_k = \{0\} \quad \text{and} \quad M = \bigvee_{i=0}^{\infty} \left( \bigvee_{j=1}^{\infty} G_{i,j} \right),$$

and the proof is complete.

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