

## A LIOUVILLE TYPE THEOREM FOR THE SCHRÖDINGER OPERATOR

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ABSTRACT. In this paper we prove that the equation  $\Delta u(x) + h(x)u(x) = 0$  on a complete Riemannian manifold of dimension  $n$  without boundary and with nonnegative Ricci curvature admits no positive solution provided that  $h$  is a  $C^2$  function satisfying  $\limsup_{r \rightarrow \infty} r^{-2} \inf_{x \in B_p(r)} h(x) \geq -b_n a^2$  and  $\Delta h(x) \geq -c_n a^2$  where  $0 \leq a < \sup_{x \in M} h(x)$ , and  $b_n, c_n$  are constants depending only on the dimension, thus generalizing similar results in P. Li and S. T. Yau (Acta Math. **156** (1986), 153–201), J. Li (J. Funct. Anal. **100** (1991), 233–256) and E. R. Negrin (J. Funct. Anal. **127** (1995), 198–203) in all of which  $h$  is assumed to be subharmonic. We also give a generalization in case the Ricci curvature of  $M$  is not necessarily positive but its negative part has quadratic decay under the additional assumption that  $h$  is unbounded from above.

### 1. INTRODUCTION

We will be concerned with the following differential equation,

$$(1.1) \quad \Delta u(x) + h(x)u(x) = 0,$$

on a complete Riemannian manifold without boundary and with nonnegative Ricci curvature. P. Li and S. T. Yau (cf. [5, Corollary 1.1]) proved the following Liouville type theorem.

**Theorem 1.1.** *Let  $M$  be a complete Riemannian manifold without boundary. Suppose that the Ricci curvature of  $M$  is nonnegative, and that  $h$  is a  $C^2$  function defined on  $M$  such that  $\Delta h(x) \geq 0$  for all  $x \in M$ , there exists a point  $x_0 \in M$  with  $h(x_0) > 0$  and*

$$(1.2) \quad \lim_{r \rightarrow \infty} r^{-1} \cdot \sup_{x \in B_p(r)} |\nabla h|(x) = 0,$$

where  $B_p(r)$  denotes the geodesic ball of radius  $r$  centered at some fixed point  $p \in M$ . Then the equation (1.1) does not have a positive smooth solution on  $M$ .

Later J. Li (cf. Theorem A of [4] and the remark following that theorem) proved that Theorem 1.1 holds if condition (1.2) is replaced by

$$(1.3) \quad \forall x \in M, \quad h(x) \geq 0,$$

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and more recently E. R. Negrin (cf. Theorem 2.1 of [6]) replaced (1.3) by

$$(1.4) \quad \lim_{r \rightarrow \infty} r^{-2} \cdot \inf_{x \in B_p(r)} h(x) = 0$$

which is weaker than (1.2) and (1.3) as explained in the remark following Theorem 2.1 of [6]. However all these theorems assume that  $h$  is subharmonic.

In this paper we will prove the following

**Theorem 1.2.** *Let  $M$  be a complete Riemannian manifold without boundary of dimension  $n$ . Suppose that the Ricci curvature of  $M$  is nonnegative, and that  $h$  is a  $C^2$  function defined on  $M$  such that there exists a point  $x_0 \in M$  with  $h(x_0) > 0$ ,*

$$(1.5) \quad \limsup_{r \rightarrow \infty} r^{-2} \cdot \inf_{x \in B_p(r)} h(x) \geq -b_n a^2$$

where  $B_p(r)$  denotes the geodesic ball of radius  $r$  centered at some fixed point  $p \in M$  and

$$(1.6) \quad \Delta h(x) \geq -c_n a^2$$

for all  $x \in M$  where  $0 \leq a < \sup_{x \in M} h(x)$ , and  $b_n, c_n$  are positive constants depending only on the dimension. Then the equation  $\Delta u(x) + h(x)u(x) = 0$  does not have a positive smooth solution on  $M$ .

The conditions of the above theorem are much weaker than the conditions in the previous theorems. One can take any function  $h^*$  satisfying the conditions of Theorem 2.1 of [6] and add to it appropriate smooth cut-off functions supported in the set  $\{x \in M: |h^*(x)| > 1\}$  to produce a nonsubharmonic function  $h$  satisfying the conditions of Theorem 1.2. Also condition (1.5) allows the negative part of  $h$  to have some quadratic growth as  $r \rightarrow \infty$ . However some restriction on the constants  $b_n$  and  $c_n$  in (1.5) and (1.6) is necessary as is seen by taking  $M$  to be  $\mathbf{R}^n$  with the Euclidean metric,  $u(x) = e^{-|x|^2} > 0$  and  $h(x) = -e^{|x|^2} \Delta e^{-|x|^2} = 2n - 4|x|^2$ . Then it is easy to see that this  $h$  satisfies all the conditions of Theorem 1.2 with  $b_n$  and  $c_n$  replaced by numbers slightly larger than  $1/n^2$  and  $2/n$ , respectively, without of course satisfying its conclusion. Moreover by taking  $n = 1$ ,

$$(1.7) \quad u(x) = \exp\left(-\frac{x^2}{\log(x^2 + 2)}\right)$$

and  $h = -u^{-1} \cdot u''$ , one can check that  $h$  satisfies the stronger condition (1.4) and condition (1.6) with  $c_n$  replaced by another constant but still does not satisfy the conclusion of Theorem 1.2.

Theorem 1.2 has the following

**Corollary 1.3.** *Let  $M$  be a complete Riemannian manifold without boundary. Suppose that the Ricci curvature of  $M$  is nonnegative, and that  $h$  is a  $C^2$  function defined on  $M$  that is unbounded from above and has the property that the functions  $\Delta h(x)$  and  $(1 + d(x, p))^{-2} h(x)$  (where  $d(x, p)$  denotes the geodesic distance from  $x$  to a fixed point  $p \in M$ ) are bounded from below on  $M$ . Then equation (1.1) does not have a positive smooth solution.*

*Proof.* Since  $\sup_{x \in M} h(x) = +\infty$  we can take  $a$  in Theorem 1.2 to be sufficiently large so that both (1.5) and (1.6) are satisfied, which is possible since the quantities appearing there are by assumption bounded from below.  $\square$

The proof of Theorem 1.2 uses the maximum principle as originated first in Yau [7] and Cheng and Yau [2].

2. A GRADIENT ESTIMATE IMPLYING THE LIOUVILLE PROPERTY

We will start with the following lemma which provides a gradient type estimate. Here  $C_1, C_2, \dots$ , will denote universal constants (independent of the dimension).

**Lemma 2.1.** *Let  $M$  be a complete Riemannian manifold of dimension  $n$ . Suppose that  $p \in M$  and  $R > 0$  are such that  $B_p(2R)$  does not meet  $\partial M$  (if nonempty) and that  $-K(2R)$  is a lower bound of the Ricci curvature on  $B_p(2R)$  with  $K(2R) \geq 0$ . Also let  $\varepsilon, \delta$  be positive numbers satisfying*

$$(2.1) \quad \varepsilon + 2\delta < \frac{2}{n}.$$

Suppose that  $a \geq 0$  and  $h$  is a  $C^2$  function defined on  $M$  such that

$$(2.2) \quad 0 \leq a < \max_{x \in B_p(R)} h(x).$$

Suppose also that  $h$  satisfies

$$(2.3) \quad - \min_{x \in B_p(2R)} h(x) < C_1 R^2 \delta^2 a^2$$

and

$$(2.4) \quad \Delta h(x) \geq - \left( \frac{2}{n} - \varepsilon - 2\delta \right) a^2,$$

for all  $x \in B_p(2R)$ .

If  $u(x)$  is a smooth positive function defined on  $M$  and satisfying the equation

$$(2.5) \quad \Delta u(x) + h(x)u(x) = 0$$

on  $M$ , then we have

$$(2.6) \quad \frac{|\nabla u|^2}{u^2} + h \leq \min \left\{ \frac{C_4 n(1 + \sqrt{K(2R)R})}{\delta R^2}, \frac{C_3 \delta \sqrt{K(2R)R} a}{\sqrt{\varepsilon}} + \frac{2}{\varepsilon} K(2R) \right\}$$

on  $B_p(R)$ , provided that  $R$  satisfies

$$(2.7) \quad R \geq \max \left( \frac{C_4}{\delta \sqrt{a}}, 1 \right).$$

*Proof.* Define  $f(x) = \log u(x)$  and

$$(2.8) \quad F(x) = |\nabla f(x)|^2 + h(x),$$

on  $M$ . We have  $\Delta f = -F$ , and by the well known Bochner–Lichnerowicz formula ([3]) we conclude that

$$(2.9) \quad \Delta F \geq \frac{2}{n} F^2 - 2\nabla f \cdot \nabla F - 2K(2R)|\nabla f|^2 + \Delta h,$$

on  $B_p(2R)$ , because of the bound on the Ricci curvature.

We also fix  $\eta$  to be a  $C^2$  function on  $[0, \infty)$  satisfying  $\eta(t) = 1$  for  $0 \leq t \leq 1$ ,  $\eta(t) = 0$  for  $t \geq 2$  and  $0 \leq \eta(t) \leq 1$ ,  $-C_5 \eta^{1/2}(t) \leq \eta'(t) \leq 0$  and  $\eta''(t) \geq -C_5$  for all  $t \geq 0$ . Let  $d(x, p)$  denote the geodesic distance between  $p$  and  $x$ , and define  $\phi(x) = \eta(d(x, p)/R)$ . Using the well known argument of Calabi [1] we can assume that the point  $x_1 \in B_p(2R)$  where the function  $\phi(x)F(x)$  attains its maximum is not in the cut locus of  $p$  and therefore  $\phi$  is  $C^2$  near  $x_1$ . Hence at  $x_1$  we have

$$(2.10) \quad \nabla(\phi F) = 0, \quad \Delta(\phi F) \leq 0, \quad \phi F \geq \max_{x \in B_p(R)} h(x) > a,$$

the last inequality holding since  $\phi$  is identically equal to 1 on  $B_p(R)$  and  $F(x) \geq h(x)$  for every  $x \in M$ . We also have [1]

$$(2.11) \quad |\nabla\phi|^2 \leq \frac{C_6}{R^2}\phi, \quad \Delta\phi \geq -\frac{C_6}{R^2}n(1 + \sqrt{K(2R)}/R)$$

and since from (2.10),  $\nabla F = -F\nabla\phi/\phi$  at  $x_1$ , we have by (2.9)

$$\begin{aligned} 0 &\geq \phi\Delta(\phi F) = \phi^2\Delta F - 2F|\nabla\phi|^2 + \phi F\Delta\phi \\ &\geq \frac{2}{n}(\phi F)^2 - 2\phi F|\nabla f| |\nabla\phi| + \phi^2\Delta h - 2K(2R)\phi^2|\nabla f|^2 - 2F|\nabla\phi|^2 + \phi F\Delta\phi \\ &\geq \frac{2}{n}(\phi F)^2 + \phi^2\Delta h - \frac{C_7n(1 + \sqrt{K(2R)R})}{R^2}\phi F - \frac{C_7}{R}(\phi F)\sqrt{\phi(F-h)} \\ &\quad - 2K(2R)\phi^2(F-h) \end{aligned}$$

at  $x_1$  because  $|\nabla f|^2 = F-h$ , and so since  $\phi \leq 1$  we have at  $x_1$ ,

$$(2.12) \quad \begin{aligned} \frac{2}{n}(\phi F)^2 + \phi^2\Delta h &\leq \frac{C_7n(1 + \sqrt{K(2R)R})}{R^2}\phi F \\ &\quad + \frac{C_7}{R}(\phi F)\sqrt{\phi(F-h)} + 2K(2R)\phi(F-h). \end{aligned}$$

But since  $x_1 \in B_p(2R)$  conditions (2.3) and (2.7) with (2.10) imply that

$$(2.13) \quad \begin{aligned} \phi(F-h) &\leq \phi F - \min_{x \in B_p(2R)} h(x) \\ &< \phi F + C_1R^2\delta^2a^2 \leq \phi F(1 + C_1R^2\delta^2a) \\ &\leq \frac{\delta^2a}{C_7^2}R^2\phi F \leq \frac{\delta^2}{C_7^2}R^2(\phi F)^2 \end{aligned}$$

at  $x_1$ , provided we have chosen  $C_1$  in (2.3) sufficiently small and  $C_4$  in (2.7) sufficiently large. Also by (2.4) we have

$$(2.14) \quad \Delta h \geq -\left(\frac{2}{n} - \varepsilon - 2\delta\right)a^2 > -\left(\frac{2}{n} - \varepsilon - 2\delta\right)(\phi F)^2$$

at  $x_1$ , and now from (2.12), (2.13) and (2.14) we have

$$(2.15) \quad (\varepsilon + \delta)(\phi F)^2 < 2K(2R)\phi(F-h) + \frac{C_7n(1 + \sqrt{K(2R)R})}{R^2}\phi F$$

at  $x_1$ , and hence either

$$(2.16) \quad \delta \max_{x \in B_p(2R)} \phi(x)F(x) \leq \frac{C_7n(1 + \sqrt{K(2R)R})}{R^2}$$

or

$$(2.17) \quad \varepsilon(\phi F)^2 < 2K(2R)\phi(F-h)$$

at  $x_1$ , which by (2.4) and (2.10) gives

$$(2.18) \quad \begin{aligned} \max_{x \in B_p(2R)} \phi(x)F(x) &< \frac{K(2R)}{\varepsilon} + \sqrt{\frac{K(2R)^2}{\varepsilon^2} - \frac{h(x_1)}{\varepsilon}} \\ &\leq \frac{2K(2R)}{\varepsilon} + \frac{\sqrt{C_1}\delta\sqrt{K(2R)Ra}}{\sqrt{\varepsilon}}. \end{aligned}$$

Now by taking  $x \in B_p(R)$ , in (2.16) and (2.18) we get (2.6) and this proves the lemma.  $\square$

From the above lemma we can prove Theorem 1.2 as follows.

*Proof of Theorem 1.2.* We suppose that  $b_n$  and  $c_n$  are positive numbers satisfying

$$(2.19) \quad c_n < \frac{2}{n}, \quad b_n < \frac{C_1}{8} \left( \frac{1}{n} - \frac{c_n}{2} \right)^2$$

where  $C_1$  is as in (2.3) and then we choose  $\varepsilon > 0$  and  $\delta > 0$  to satisfy (2.1) and

$$(2.20) \quad \frac{2}{n} - \varepsilon - 2\delta = c_n, \quad C_1\delta^2 > 8b_n.$$

We will use Lemma 2.1 now with  $a$  as in Theorem 1.2,  $K(2R) = 0$  and  $R$  sufficiently large to satisfy (2.7), (2.2) (possible since  $a < \sup_{x \in M} h(x)$  by assumption) and

$$(2.21) \quad (2R)^{-2} \cdot \inf_{x \in B_p(2R)} h(x) \geq -2b_n a^2,$$

which is possible since (1.5) implies that there are arbitrarily large  $R$  satisfying (2.21). Then all the assumptions of the lemma are satisfied and therefore (2.6) gives

$$(2.22) \quad \max_{x \in B_p(R_j)} h(x) \leq \max_{x \in B_p(R_j)} \left( \frac{|\nabla u(x)|^2}{u^2(x)} + h(x) \right) \leq \frac{C_3 n}{R_j^2}$$

for a sequence of  $R_j$  with  $R_j \rightarrow +\infty$ , which obviously contradicts (2.2) and hence proves the theorem.  $\square$

*Remark 1.* The above proof produces a contradiction at a finite stage, that is, for some sufficiently large  $R$ . Therefore the proof can be modified to show the nonexistence of positive smooth solutions of (1.1) in the case when  $M$  has nonnegative Ricci curvature outside a compact set  $X$ , provided that the other conditions of Theorem 2.1 are satisfied (with a smaller  $b_n$ ) and that there exists a sequence of points  $p_j \in M$  such that  $d(p_j, p) \rightarrow \infty$  and  $\limsup h(p_j) > a$ . The value of  $b_n$  must be adjusted because we will be using the lemma with base point  $p_j$  for some large  $j$  and  $R$  such that  $B_{p_j}(2R)$  does not meet  $X$  and to produce (2.3) from (1.5) (which is based at  $p$ ) we must apply (1.5) on  $B_p(10R)$  for  $R$  sufficiently large to ensure  $B_{p_j}(2R) \subset B_p(10R)$ . This situation is in contrast with the case of positive harmonic functions which might exist in such manifolds. We will push this contrast even more in Theorem 2.2 below.

*Remark 2.* As is seen from the examples in the introduction the inequality (2.17) for  $c_n$  is in a sense best possible. Also the value of  $b_n$  depends on how close to  $2/n$  we take  $c_n$ , and is (for  $c_n = 1/n$ ) of the order of  $1/n^2$ .

From the proof of Lemma 2.1 we have the following generalization of Corollary 1.3.

**Theorem 2.2.** *Let  $M$  be a complete Riemannian manifold without boundary. Suppose that the Ricci curvature of  $M$  is bounded from below by  $-Cd(x, p)^{-2}$  for  $d(x, p) \geq 1$  where  $C$  is some positive constant and  $d(x, p)$  is the geodesic distance from  $x$  to a fixed point  $p \in M$ , and that  $h$  is a  $C^2$  function defined on  $M$  that is unbounded from above and has the property that the functions  $\Delta h(x)$  and  $(1 + d(x, p))^{-2}h(x)$  are bounded from below on  $M$ . Then the equation  $\Delta u(x) + h(x)u(x) = 0$  does not have a positive smooth solution.*

*Proof.* Since the functions  $\Delta h(x)$  and  $(1 + d(x, p))^{-2}h(x)$  are bounded from below we can choose  $a > 0$  sufficiently large so that both conditions (2.3) and (2.4) in Lemma 2.1 are satisfied (fixing some positive  $\varepsilon$  and  $\delta$  satisfying (2.1)). Next we choose  $R$  sufficiently large so that (2.2) and (2.7) are satisfied which is possible since  $\sup_{x \in M} h(x) = +\infty$ . Note also that  $K(2R)$  is bounded, say by  $K$  which is independent of  $R$ . Then from Lemma 2.1 the gradient estimate (2.6) holds. What is important here is that by examining the proof of the lemma,  $K(2R)$  in the *second* argument of  $\min$  in (2.6) can be replaced by  $K(x_1)$  which is a lower bound for the Ricci curvature *at the point*  $x_1$  where the function  $\phi F$  assumes its maximum. The reason for this is that  $K(2R)$  there comes from the last term  $2K(2R)\phi(F - h)$  in (2.12) which in turn comes from (2.9) so from the Bochner-Lichnerovicz formula *evaluated at*  $x_1$ . Hence by the assumption on the Ricci curvature, if  $d(x_1, p) \geq 1$  we have

$$(2.23) \quad h \leq \frac{|\nabla u|^2}{u^2} + h \leq \min \left\{ \frac{C_4 n(1 + \sqrt{K}R)}{\delta R^2}, \frac{C_3 \delta \sqrt{C}Ra}{\sqrt{\varepsilon}d(x_1, p)} + \frac{2C}{\varepsilon d(x_1, p)} \right\}$$

on  $B_p(R)$ . Hence if  $R/2 \leq d(x_1, p)$ , (2.23) gives

$$(2.24) \quad \max_{x \in B_p(R)} h(x) \leq \min \left\{ \frac{C_4 n(1 + \sqrt{K}R)}{\delta R^2}, \frac{C_3 \delta \sqrt{2Ca}}{\sqrt{\varepsilon}} + \frac{8C}{\varepsilon R^2} \right\},$$

which gives a contradiction for  $R$  sufficiently large since  $\max_{x \in B_p(R)} h(x) \rightarrow +\infty$  as  $R \rightarrow +\infty$ . Therefore there exists a positive number  $R_0$  such that for every  $R \geq 2R_0$  the function

$$(2.25) \quad G_R(x) = \phi_R(x)F(x) = \eta \left( \frac{d(x, p)}{R} \right) \cdot \left( \frac{|\nabla u(x)|^2}{u^2(x)} + h(x) \right)$$

assumes its maximum value only at points in  $B_p(\frac{R}{2})$ . But since  $\phi_R(x) = 1$  on  $B_p(R)$  this implies that

$$(2.26) \quad \max_{x \in B_p(R) \setminus B_p(\frac{R}{2})} F(x) < \max_{x \in B_p(\frac{R}{2})} F(x),$$

for all  $R \geq 2R_0$ . Hence for all  $R \geq 2R_0$  we have

$$(2.27) \quad \max_{x \in B_p(R)} F(x) = \max_{x \in B_p(\frac{R}{2})} F(x)$$

which by an easy induction gives

$$(2.28) \quad \max_{x \in B_p(2^k R_0)} F(x) = \max_{x \in B_p(R_0)} F(x),$$

for all integers  $k \geq 1$ . Hence we have

$$(2.29) \quad h(x) \leq \frac{|\nabla u(x)|^2}{u^2(x)} + h(x) \leq \max_{x \in B_p(R_0)} F(x) = C_0,$$

for all  $x \in M$  which is a contradiction since  $h$  is unbounded from above and this proves the theorem. □

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