

PERIODIC SOLUTIONS FOR PLANAR 2N-BODY PROBLEMS

SHIQING ZHANG AND QING ZHOU

(Communicated by Carmen C. Chicone)

ABSTRACT. In this paper we study some necessary conditions and sufficient conditions for the nested polygonal solutions of planar 2N-body problems.

1. MAIN RESULTS

This paper uses the same notations as those used in [6]. For $n \geq 2$ the equations of motion of the planar n -body problem ([1], [2], [3], [5], [6], [7]) can be written in the form

$$(1.1) \quad \ddot{z}_k = - \sum_{\substack{j=1 \\ j \neq k}}^n m_j \frac{z_k - z_j}{|z_k - z_j|^3},$$

where z_k is the complex coordinate of the k th mass m_k in an inertial coordinate system. Let ρ_k denote the N complex k th roots of unity, i.e.,

$$(1.2) \quad \rho_k = \exp(2\pi i k / N).$$

This equation will also serve to define ρ_k for any number k . We assume that the mass m_k ($k = 1, \dots, N$) is located at the vertex ρ_k of a regular polygon inscribed on the unit circle, and \tilde{m}_k ($k = 1, \dots, N$) is located at

$$(1.3) \quad \tilde{\rho}_k = a \rho_k \cdot e^{i\theta},$$

where $a > 0$, $0 \leq \theta \leq 2\pi$, and $a \neq 1$ when $\theta = 0$ or 2π .

Then the center of masses $m_1, \dots, m_N; \tilde{m}_1, \dots, \tilde{m}_N$ is

$$(1.4) \quad z_0 = \sum_j (m_j \rho_j + \tilde{m}_j \tilde{\rho}_j) / M$$

where $M = \sum_j (m_j + \tilde{m}_j)$. In (1.4) and throughout this paper, unless specially restricted, all indices and summations will range from 1 to N . The functions describing their rotation about z_0 with angular velocity ω are then given by

$$(1.5) \quad z_k(t) = (\rho_k - z_0) \exp(i\omega t), \quad k = 1, \dots, N,$$

Received by the editors November 7, 2001 and, in revised form, February 25, 2002.

2000 *Mathematics Subject Classification*. Primary 34C25, 34C15, 70F10.

Key words and phrases. 2N-body problems, nested regular polygon periodic solutions, circulant matrices.

This work was supported by the NSF of China.

and

$$(1.6) \quad \tilde{z}_k(t) = (a\rho_k e^{i\theta} - z_0) \exp(i\omega t), \quad k = 1, \dots, N.$$

Then the equations of motion of the planar 2N-body problem can be written in the following form:

$$(1.7) \quad \ddot{z}_k = \sum_{j \neq k} m_j \frac{z_j - z_k}{|z_j - z_k|^3} + \sum_j \tilde{m}_j \frac{\tilde{z}_j - z_k}{|\tilde{z}_j - z_k|^3}$$

and

$$(1.8) \quad \ddot{\tilde{z}}_k = \sum_j m_j \frac{z_j - \tilde{z}_k}{|z_j - \tilde{z}_k|^3} + \sum_{j \neq k} \tilde{m}_j \frac{\tilde{z}_j - \tilde{z}_k}{|\tilde{z}_j - \tilde{z}_k|^3}.$$

R. Moeckel and C. Simó ([5]) proved the following result:

Theorem (Moeckel-Simó). *If $\theta = 0$ and $m_1 = \dots = m_N$, $\tilde{m}_1 = \dots = \tilde{m}_N$, then for every mass ratio $b = \frac{\tilde{m}_1}{m_1}$, there are exactly two planar central configurations consisting of two nested regular N-gons. For one of these, the ratio of the sizes of the two polygons is less than 1, and for the other it is greater than 1.*

In this paper, we study the inverse problem of the theorem (Moeckel-Simó) and the following results are established.

Theorem 1. *If, for $N \geq 2$, the functions $z_k(t)$ and $\tilde{z}_k(t)$ given by (1.5) and (1.6) are solutions of the 2N-body problem (1.7) and (1.8), it follows that ω^2 satisfies*

$$(1.9) \quad \left[\frac{1}{4} \sum_{j \neq N} \csc\left(\frac{\pi j}{N}\right) - \frac{\omega^2}{M} N \right] \cdot \left[\frac{1}{4} a^{-2} \sum_{j \neq N} \csc\left(\frac{\pi j}{N}\right) - \frac{\omega^2}{M} a \cdot N \right] e^{i\theta} \\ = \left[\sum_j \frac{1 - a\rho_{j-1} e^{i\theta}}{|1 - a\rho_{j-1} e^{i\theta}|^3} - \frac{N\omega^2}{M} \right] \cdot \left[\sum_j \frac{ae^{i\theta} - \rho_{j-1}}{|ae^{i\theta} - \rho_{j-1}|^3} - \frac{\omega^2}{M} Nae^{i\theta} \right].$$

Theorem 2. *For $N \geq 2$, $m_k, \tilde{m}_k > 0$, if the functions $z_k(t)$ and $\tilde{z}_k(t)$ given by (1.5) and (1.6) with ω^2 given by (1.9) are solutions of the 2N-body problem (1.7) and (1.8), then $m_1 = m_2 = \dots = m_N$ and $\tilde{m}_1 = \tilde{m}_2 = \dots = \tilde{m}_N$.*

Conversely, if $m_1 = m_2 = \dots = m_N$ and $\tilde{m}_1 = \tilde{m}_2 = \dots = \tilde{m}_N$, let $b = \tilde{m}_1/m_1$. If b, a and ω^2 satisfy

$$(1.10) \quad \frac{N\omega^2}{M} = \frac{1}{1+b} \left[\sum_{j=1}^{N-1} \frac{1 - \rho_j}{|1 - \rho_j|^3} + \sum_{j=0}^{N-1} \frac{b(1 - a\rho_j e^{i\theta})}{|1 - a\rho_j e^{i\theta}|^3} \right],$$

$$(1.11) \quad \frac{N\omega^2}{M} = \frac{e^{-i\theta}}{a(1+b)} \left[\sum_j \frac{ae^{i\theta} - \rho_j}{|ae^{i\theta} - \rho_j|^3} + \sum_{j \neq N} \frac{b(a - a\rho_j)e^{i\theta}}{|a - a\rho_j|^3} \right],$$

then $z_k(t)$ and $\tilde{z}_k(t)$ are solutions of (1.7) and (1.8).

Remark. It is not difficult to prove that “ ω^2 ” and “ a ” are positive real numbers if $\theta = 0$ or $\frac{\pi}{N}$, and it seems that only $\theta = 0$ or $\frac{\pi}{N}$, “ ω^2 ” and “ a ” are positive real numbers, but the proof seems difficult.

Corollary 1 (MacMillan-Bartky [3]). *Under the above assumptions,*

(i) *if $N = 2, \theta = 0, a > 1$ and $z_k(t)$ and $\tilde{z}_k(t)$ given by (1.5) and (1.6) with ω^2 satisfying*

$$(1.12) \quad \begin{aligned} & \left[\frac{1}{4} - \frac{2\omega^2}{M} \right] \cdot \left[\frac{1}{4}a^{-2} - \frac{\omega^2}{M} \cdot 2a \right] \\ &= \left[\frac{2(a^2 + 1)}{(a^2 - 1)^2} - \frac{\omega^2}{M} \cdot 2a \right] \cdot \left[\frac{-4a}{(a^2 - 1)^2} - \frac{2\omega^2}{M} \right] \end{aligned}$$

are solutions of the 2×2 -body problems (1.7) and (1.8), then $m_1 = m_2, \tilde{m}_1 = \tilde{m}_2$. Conversely, if $\omega^2 = (m_1 + m_2 + \tilde{m}_1 + \tilde{m}_2)\gamma/N$ satisfying (1.12) and

$$(1.13) \quad \frac{2\omega^2}{M} = \frac{1}{1 + b} \left[\frac{1}{4} - \frac{4ab}{(a^2 - 1)^2} \right]$$

where

$$(1.14) \quad b = \frac{a^7 - 2a^5 - 8a^4 + a^3 - 8a^2}{17a^4 - 2a^2 + 1},$$

then $z_k(t)$ and $\tilde{z}_k(t)$ given by (1.5) and (1.6) are solutions of (1.7) and (1.8).

(ii) *if $N = 2, \theta = 0, 0 < a < 1$ and $z_k(t)$ and $\tilde{z}_k(t)$ given by (1.5) and (1.6) with ω^2 satisfying*

$$(1.15) \quad \begin{aligned} & \left[\frac{1}{4} - \frac{2\omega^2}{M} \right] \cdot \left[\frac{1}{4}a^{-2} - \frac{\omega^2}{M} \cdot 2a \right] \\ &= \left[\frac{-4a}{(1 - a^2)^2} - \frac{\omega^2}{M} \cdot 2a \right] \cdot \left[\frac{2(1 + a^2)}{(1 - a^2)^2} - \frac{2\omega^2}{M} \right] \end{aligned}$$

are solutions of (1.7) and (1.8), then $m_1 = m_2, \tilde{m}_1 = \tilde{m}_2$. Conversely, if $\omega^2 = M\gamma/N$ satisfying (1.15) and

$$(1.16) \quad \gamma = \frac{1}{1 + b} \left[\frac{1}{4} + \frac{2b(a^2 + 1)}{(a^2 - 1)^2} \right]$$

where

$$(1.17) \quad b = \frac{a^7 - 2a^5 + 17a^3}{-8a^5 + a^4 - 8a^3 - 2a^2 + 1},$$

then $z_k(t)$ and $\tilde{z}_k(t)$ given by (1.5) and (1.6) are solutions of (1.7) and (1.8).

Corollary 2 (MacMillan-Bartky [3]). (i) *For $N = 2$ and $\theta = \frac{\pi}{2}$, then (1.10) and (1.11) imply*

$$(1.18) \quad b = [(1 + a^2)^{-3/2} - 2^{-3}] \cdot [(1 + a^2)^{-3/2} - (2a)^{-3}]^{-1}.$$

(ii) *For $N = 2$ and $\theta = \frac{\pi}{2}, b = 1$ if and only if $a = 1$. That is, z_k, \tilde{z}_k are solutions of (1.7) and (1.8). If $m_1 = m_2, \tilde{m}_1 = \tilde{m}_2$, then $m_1 = m_2 = \tilde{m}_1 = \tilde{m}_2$ if and only if $m_1, m_2, \tilde{m}_1, \tilde{m}_2$ are at the vertices of a square.*

(iii) *For $N = 2$ and $\theta = \frac{\pi}{2}, m_1 = m_2, \tilde{m}_1 = \tilde{m}_2$ are at the vertices of a diamond. Then $m_1, m_2, \tilde{m}_1, \tilde{m}_2$ form a central configuration if and only if $\frac{\sqrt{3}}{3} < a < \sqrt{3}$, where a stands for the ratio of its diagonals and the ratio b of masses is determined uniquely by (1.18); especially considering the degenerate central configuration, when $b = \infty, a = \frac{\sqrt{3}}{3}$, and when $a = \sqrt{3}, b = 0$.*

Corollary 3 (Perko-Walter [6]). For $N \geq 2$, $m_k, \tilde{m}_k > 0$, if $a = 1$ and $\theta = \frac{\pi}{N}$, then $z_k(t)$ and $\tilde{z}_k(t)$ given by (1.5) and (1.6) with $\omega^2 = M\gamma/N$ and ω^2 given by (1.9) are solutions of the $2N$ -body problem (1.7) and (1.8). Then $m_1 = m_2 = \dots = m_N = \tilde{m}_1 = \dots = \tilde{m}_N$.

Corollary 4. If $N = 3$, $\theta = 0$. If $z_k(t)$ and $\tilde{z}_k(t)$ given by (1.5) and (1.6) with ω^2 satisfying

$$(1.19) \quad \omega^2 = \left[\frac{\sqrt{3}}{M}(a + a^{-2}) - \frac{3}{M} \left(\sum_{j=1}^3 \frac{a - \rho_{j-1}}{|a - \rho_{j-1}|^3} + a \sum_{j=1}^3 \frac{1 - a\rho_{j-1}}{|1 - a\rho_{j-1}|^3} \right) \right]^{-1} \\ \cdot \left[\frac{1}{3}a^{-2} - \left(\sum_{j=1}^3 \frac{a - \rho_{j-1}}{|a - \rho_{j-1}|^3} \right) \left(\sum_{j=1}^3 \frac{1 - a\rho_{j-1}}{|1 - a\rho_{j-1}|^3} \right) \right]$$

are the solution of the nested 2×3 -body problems (1.7) and (1.8), then $m_1 = m_2 = m_3, \tilde{m}_1 = \tilde{m}_2 = \tilde{m}_3$.

Conversly, if $m_1 = m_2 = m_3, \tilde{m}_1 = \tilde{m}_2 = \tilde{m}_3$, let $b = \frac{\tilde{m}_1}{m_1}$. If ω^2 satisfies (1.19) and a and b have the relation

$$(1.20) \quad b = \left(\frac{\sqrt{3}}{3}a^{-3} - \sum_{j=1}^3 \frac{1 - a\rho_{j-1}}{|1 - a\rho_{j-1}|^3} \right)^{-1} \left(\frac{\sqrt{3}}{3} - a^{-1} \sum_{j=1}^3 \frac{a - \rho_{j-1}}{|a - \rho_{j-1}|^3} \right),$$

then $z_k(t)$ and $\tilde{z}_k(t)$ defined by (1.5) and (1.6) are solutions of (1.7) and (1.8).

Corollary 5. Assume $N = 3, \theta = \frac{\pi}{3}$. If $z_k(t)$ and $\tilde{z}_k(t)$ given by (1.5) and (1.6) with ω^2 satisfying

$$(1.21) \quad \omega^2 = \frac{M}{3} \left[\frac{\sqrt{3}}{3}(a + a^{-2}) - \left(\sum_{j=1}^3 \frac{a - e^{-\frac{\pi}{3}\sqrt{-1}}\rho_{j-1}}{|a - e^{-\frac{\pi}{3}\sqrt{-1}}\rho_{j-1}|^3} + a \sum_{j=1}^3 \frac{1 - ae^{\frac{\pi}{3}\sqrt{-1}}\rho_{j-1}}{|1 - ae^{\frac{\pi}{3}\sqrt{-1}}\rho_{j-1}|^3} \right) \right]^{-1} \\ \cdot \left[\frac{1}{3}a^{-2}e^{\frac{\pi}{3}\sqrt{-1}} - \left(\sum_{j=1}^3 \frac{a - e^{-\frac{\pi}{3}\sqrt{-1}}\rho_{j-1}}{|a - e^{-\frac{\pi}{3}\sqrt{-1}}\rho_{j-1}|^3} \right) \left(\sum_{j=1}^3 \frac{1 - ae^{\frac{\pi}{3}\sqrt{-1}}\rho_{j-1}}{|1 - ae^{\frac{\pi}{3}\sqrt{-1}}\rho_{j-1}|^3} \right) \right]$$

are the solution of the twisted 2×3 -body problems (1.7) and (1.8), then $m_1 = m_2 = m_3, \tilde{m}_1 = \tilde{m}_2 = \tilde{m}_3$.

Conversly, if $m_1 = m_2 = m_3, \tilde{m}_1 = \tilde{m}_2 = \tilde{m}_3$, let $b = \frac{\tilde{m}_1}{m_1}$. If ω^2 satisfies (1.21) and a and b have the following relation:

$$(1.22) \quad b = \left(\frac{\sqrt{3}}{3}a^{-2} - \sum_{j=1}^3 \frac{a(1 - ae^{\frac{\pi}{3}\sqrt{-1}}\rho_{j-1})}{|1 - ae^{\frac{\pi}{3}\sqrt{-1}}\rho_{j-1}|^3} \right)^{-1} \left(\frac{\sqrt{3}}{3}a - \sum_{j=1}^3 \frac{a - e^{-\frac{\pi}{3}\sqrt{-1}}\rho_{j-1}}{|a - e^{-\frac{\pi}{3}\sqrt{-1}}\rho_{j-1}|^3} \right),$$

then $z_k(t)$ and $\tilde{z}_k(t)$ defined by (1.5) and (1.6) are solutions of (1.7) and (1.8).

2. EIGENVALUES AND EIGENVECTORS FOR CIRCULANT MATRICES

Definition 2.1 ([4]). If $N \times N$ matrix $A = (a_{i,j})$ satisfies

$$(2.1) \quad a_{i,j} = a_{i-1,j-1}, \quad 1 \leq i, j \leq N,$$

where we assume $a_{i,0} = a_{i,N}$ and $a_{0,j} = a_{N,j}$. Then we call A a circulant matrix.

Lemma 2.1 ([4]). *If A and B are $N \times N$ circulant matrices, then $A+B$, $A-B$, $A \cdot B$ are also circulant matrices and $AB = BA$.*

Lemma 2.2 ([4]). *Let $A = (a_{i,j})$ be an $N \times N$ circulant matrix. The eigenvalues λ_k and the eigenvectors \vec{v}_k of A are*

$$(2.2) \quad \lambda_k(A) = \sum_j a_{1,j} \rho_{k-1}^{j-1}$$

and

$$(2.3) \quad \vec{v}_k = (\rho_{k-1}, \rho_{k-1}^2, \dots, \rho_{k-1}^N)^T.$$

Lemma 2.3 ([4]). *Let A, B be circulant matrices, where $\lambda_k(A), \lambda_k(B)$ are eigenvalues of A, B . Then the eigenvalues of $A+B, A-B, A \cdot B$ are $\lambda_k(A) + \lambda_k(B), \lambda_k(A) - \lambda_k(B), \lambda_k(A) \cdot \lambda_k(B)$.*

The following useful lemma can be simply proved using the properties of circulant matrices.

Lemma 2.4. *If $A = (a_{i,j})$ is an $N \times N$ circulant matrix, and $A \cdot X = 0$, where $X = (x_1, \dots, x_n)^T$, $\sum_i x_i \neq 0$, then*

$$(2.4) \quad \begin{aligned} a_{1,j} + \dots + a_{N,j} &= 0, \quad 1 \leq j \leq N, \\ a_{i,1} + \dots + a_{i,N} &= 0, \quad 1 \leq i \leq N. \end{aligned}$$

3. PROOF OF THE MAIN RESULTS

For two nested regular polygons, we define

$$(3.1) \quad \rho_k = \exp(2\pi ik/N),$$

$$(3.2) \quad \tilde{\rho}_k = a \exp(2\pi ik/N) e^{i\theta},$$

$$(3.3) \quad z_0 = \sum_j (m_j \rho_j + \tilde{m}_j \tilde{\rho}_j) / M,$$

where

$$(3.4) \quad M = \sum_j (m_j + \tilde{m}_j),$$

$$(3.5) \quad z_k(t) = (\rho_k - z_0) \exp(i\omega t), \quad k = 1, \dots, N,$$

and

$$(3.6) \quad \tilde{z}_k(t) = (a\rho_k e^{i\theta} - z_0) \exp(i\omega t), \quad k = 1, \dots, N.$$

Proof of Theorem 1. (3.1)–(3.6) imply that the $z_k(t)$ and $\tilde{z}_k(t)$ are the solutions of (1.7) and (1.8) if and only if

$$(3.7) \quad (\rho_k - z_0)\omega^2 \exp(i\omega t) = \left(\sum_{j \neq k} m_j \frac{\rho_k - \rho_j}{|\rho_k - \rho_j|^3} + \sum_j \tilde{m}_j \frac{\rho_k - \tilde{\rho}_j}{|\rho_k - \tilde{\rho}_j|^3} \right) \exp(i\omega t)$$

and

(3.8)

$$(\tilde{\rho}_k - z_0)\omega^2 \exp(i\omega t) = \left(\sum_j m_j \frac{\tilde{\rho}_k - \rho_j}{|\tilde{\rho}_k - \rho_j|^3} + \sum_{j \neq k} \tilde{m}_j \frac{\tilde{\rho}_k - \tilde{\rho}_j}{|\tilde{\rho}_k - \tilde{\rho}_j|^3} \right) \exp(i\omega t)$$

or if and only if

(3.9)

$$\sum_{j \neq k} m_j \left(\frac{1}{|\rho_k - \rho_j|^3} - \frac{\omega^2}{M} \right) (\rho_k - \rho_j) + \sum_j \tilde{m}_j \left(\frac{1}{|\rho_k - \tilde{\rho}_j|^3} - \frac{\omega^2}{M} \right) (\rho_k - \tilde{\rho}_j) = 0$$

and

(3.10)

$$\sum_j m_j \left(\frac{1}{|\tilde{\rho}_k - \rho_j|^3} - \frac{\omega^2}{M} \right) (\tilde{\rho}_k - \rho_j) + \sum_{j \neq k} \tilde{m}_j \left(\frac{1}{|\tilde{\rho}_k - \tilde{\rho}_j|^3} - \frac{\omega^2}{M} \right) (\tilde{\rho}_k - \tilde{\rho}_j) = 0.$$

Multiplying both sides by ρ_{N-k} and noting that $|\rho_k - \rho_j| = |\rho_k||1 - \rho_{j-k}| = |1 - \rho_{j-k}|$ and using $\tilde{\rho}_k = a\rho_k e^{i\theta}$,

$$(3.11) \quad \sum_{j \neq k} m_j \left(\frac{1}{|1 - \rho_{j-k}|^3} - \frac{\omega^2}{M} \right) (1 - \rho_{j-k}) + \sum_j \tilde{m}_j \left(\frac{1}{|1 - a\rho_{j-k}e^{i\theta}|^3} - \frac{\omega^2}{M} \right) (1 - a\rho_{j-k}e^{i\theta}) = 0$$

and

$$(3.12) \quad \sum_j m_j \left(\frac{1}{|ae^{i\theta} - \rho_{j-k}|^3} - \frac{\omega^2}{M} \right) (ae^{i\theta} - \rho_{j-k}) + \sum_{j \neq k} \tilde{m}_j \left(\frac{1}{|a - a\rho_{j-k}|^3} - \frac{\omega^2}{M} \right) (a - a\rho_{j-k})e^{i\theta} = 0.$$

Notice that every step from (3.7) to (3.12) can be conversed, respectively. Now we define the $N \times N$ circulant matrices $C = [c_{k,j}]$, $A = [a_{k,j}]$, $B = [b_{k,j}]$, $D = [d_{k,j}]$ as follows:

$$(3.13) \quad c_{k,j} = 0, \quad \text{for } k = j, \\ c_{k,j} = \left(\frac{1}{|1 - \rho_{j-k}|^3} - \frac{\omega^2}{M} \right) (1 - \rho_{j-k}), \quad \text{for } k \neq j,$$

$$(3.14) \quad a_{k,j} = \left(\frac{1}{|1 - a\rho_{j-k}e^{i\theta}|^3} - \frac{\omega^2}{M} \right) (1 - a\rho_{j-k}e^{i\theta}),$$

$$(3.15) \quad b_{k,j} = \left(\frac{1}{|ae^{i\theta} - \rho_{j-k}|^3} - \frac{\omega^2}{M} \right) (ae^{i\theta} - \rho_{j-k}),$$

$$d_{k,j} = 0, \quad \text{for } k = j,$$

$$(3.16) \quad d_{k,j} = \left(\frac{1}{|a - a\rho_{j-k}|^3} - \frac{\omega^2}{M} \right) (a - a\rho_{j-k})e^{i\theta} \quad \text{for } k \neq j.$$

Then (3.11) and (3.12) hold if and only if the matrix equation

$$(3.17) \quad \begin{pmatrix} C & A \\ B & D \end{pmatrix} \begin{pmatrix} m_1 \\ \vdots \\ m_N \\ \tilde{m}_1 \\ \vdots \\ \tilde{m}_N \end{pmatrix} = 0$$

has a positive solution.

Let

$$(3.18) \quad m = (m_1, \dots, m_N)^T, \tilde{m} = (\tilde{m}_1, \dots, \tilde{m}_N)^T.$$

Then (3.17) is equivalent to

$$(3.19) \quad C \cdot m + A \cdot \tilde{m} = 0,$$

$$(3.20) \quad B \cdot m + D \cdot \tilde{m} = 0.$$

By (3.19) and (3.20) we have

$$(3.21) \quad (CD - BA) \cdot m = 0,$$

$$(3.22) \quad (AB - CD) \cdot \tilde{m} = 0.$$

We notice that (3.21) and (3.22) have a solution is equivalent to that $AB - CD$ has a positive real eigenvector corresponding to eigenvalue 0. By Lemma 2.3 we have

$$(3.23) \quad \begin{aligned} & \lambda_k(AB - CD) \\ &= \lambda_k(AB) - \lambda_k(CD) \\ &= \lambda_k(A)\lambda_k(B) - \lambda_k(C)\lambda_k(D). \end{aligned}$$

Hence

$$(3.24) \quad \lambda_k(AB - CD) = 0$$

for some $1 \leq k \leq N$ if and only if

$$(3.25) \quad \lambda_k(A)\lambda_k(B) = \lambda_k(C)\lambda_k(D).$$

Also, we notice by Lemma 2.2 and Lemma 2.4 $\lambda_1(AB - CD) = 0$. Hence by Lemma 2.2 we have

$$(3.26) \quad \begin{aligned} & \left[\sum_{j \neq 1} \left(\frac{1}{|1 - \rho_{j-1}|^3} - \frac{\omega^2}{M} \right) (1 - \rho_{j-1}) \right] \cdot \left[\sum_{j \neq 1} \left(\frac{1}{|a - a\rho_{j-1}|^3} - \frac{\omega^2}{M} \right) (a - a\rho_{j-1}) e^{i\theta} \right] \\ &= \left[\sum_j \left(\frac{1}{|1 - a\rho_{j-1} e^{i\theta}|^3} - \frac{\omega^2}{M} \right) (1 - a\rho_{j-1} e^{i\theta}) \right] \\ & \quad \cdot \left[\sum_j \left(\frac{1}{|ae^{i\theta} - \rho_{j-1}|^3} - \frac{\omega^2}{M} \right) (ae^{i\theta} - \rho_{j-1}) \right]. \end{aligned}$$

We notice that

$$\begin{aligned}
 (3.27) \quad & \left[\sum_{j \neq 1} \frac{1 - \rho_{j-1}}{|1 - \rho_{j-1}|^3} - \frac{\omega^2}{M} \sum_j (1 - \rho_{j-1}) \right] \\
 & \cdot \left[a^{-2} \sum_{j \neq 1} \frac{1 - \rho_{j-1}}{|1 - \rho_{j-1}|^3} - \frac{\omega^2}{M} a \cdot \sum_j (1 - \rho_{j-1}) \right] \cdot e^{i\theta} \\
 & = \left[\frac{1}{4} \sum_{j \neq N} \csc\left(\frac{\pi j}{N}\right) - \frac{\omega^2}{M} \cdot N \right] \cdot \left[\frac{1}{4} a^{-2} \sum_{j \neq N} \csc\left(\frac{\pi j}{N}\right) - \frac{\omega^2}{M} \cdot a \cdot N \right] \cdot e^{i\theta},
 \end{aligned}$$

$$\begin{aligned}
 (3.28) \quad & \sum_j \left[\frac{1 - ae^{i\theta} \rho_{j-1}}{|1 - ae^{i\theta} \rho_{j-1}|^3} - \frac{\omega^2}{M} \cdot (1 - ae^{i\theta} \rho_{j-1}) \right] \\
 & \cdot \sum_j \left[\frac{ae^{i\theta} - \rho_{j-1}}{|ae^{i\theta} - \rho_{j-1}|^3} - \frac{\omega^2}{M} (ae^{i\theta} - \rho_{j-1}) \right] \\
 & = \left[\sum_j \frac{1 - ae^{i\theta} \rho_{j-1}}{|1 - ae^{i\theta} \rho_{j-1}|^3} - \frac{\omega^2 \cdot N}{M} \right] \cdot \left[\sum_j \frac{ae^{i\theta} - \rho_{j-1}}{|ae^{i\theta} - \rho_{j-1}|^3} - \frac{\omega^2}{M} \cdot Nae^{i\theta} \right].
 \end{aligned}$$

Proof of Theorem 2. $\lambda_1(AB - CD) = 0$ is simple so $\vec{v}_1 = (1, 1, \dots, 1)^T$ is the only positive real eigenvector for $\lambda_1 = 0$.

Assume $m_1 = m_2 = \dots = m_N > 0$ and $\tilde{m}_1 = m_2 = \dots = \tilde{m}_N > 0$, ω^2 is determined by (1.9) and a, b is determined by (1.10) and (1.11). Then $(m_1, \dots, m_1)^T$ is a solution of (3.11) and (3.12) or (1.7) and (1.8), since

$$\begin{aligned}
 (3.29) \quad & \sum_{j \neq k} m_j \left(\frac{1}{|1 - \rho_{j-k}|^3} - \frac{\omega^2}{M} \right) (1 - \rho_{j-k}) \\
 & + \sum_j b m_j \left(\frac{1}{|1 - a\rho_{j-k}e^{i\theta}|^3} - \frac{\omega^2}{M} \right) (1 - a\rho_{j-k}e^{i\theta})
 \end{aligned}$$

$$\begin{aligned}
 (3.30) \quad & = m_1 \left[\sum_{j \neq k} \left(\frac{1}{|1 - \rho_{j-k}|^3} - \frac{\omega^2}{M} \right) (1 - \rho_{j-k}) \right. \\
 & \left. + \sum_j b \left(\frac{1}{|1 - a\rho_{j-k}e^{i\theta}|^3} - \frac{\omega^2}{M} \right) (1 - a\rho_{j-k}e^{i\theta}) \right]
 \end{aligned}$$

(3.31)

$$= m_1 \left[\sum_{j \neq N} \left(\frac{1}{|1 - \rho_j|^3} - \frac{\omega^2}{M} \right) (1 - \rho_j) + \sum_j b \left(\frac{1}{|1 - a\rho_j e^{i\theta}|^3} - \frac{\omega^2}{M} \right) (1 - a\rho_j e^{i\theta}) \right] = 0,$$

and the same results for (3.12) are easily obtained. Thus the proof is completed.

Corollary 1 is obvious from Theorem 2.

Proof of Corollary 2. (i) For $N = 2$ and $\theta = \frac{\pi}{2}$, b and a have the following relationship:

$$(3.32) \quad b = \frac{\left(\sum_{j=0}^{N-1} \frac{ae^{i\theta} - \rho_j}{|ae^{i\theta} - \rho_j|^3} - \sum_{j=1}^{N-1} \frac{ae^{i\theta}(1 - \rho_j)}{|1 - \rho_j|^3} \right)}{\left(\sum_{j=0}^{N-1} \frac{ae^{i\theta}(1 - a\rho_j e^{i\theta})}{|1 - a\rho_j e^{i\theta}|^3} - \sum_{j=1}^{N-1} \frac{ae^{i\theta}(1 - \rho_j)}{a^3|1 - \rho_j|^3} \right)}.$$

Then

$$(3.33) \quad \begin{aligned} \sum_{j=0}^{N-1} \frac{ae^{i\theta} - \rho_j}{|ae^{i\theta} - \rho_j|^3} - \sum_{j=1}^{N-1} \frac{ae^{i\theta}(1 - \rho_j)}{|1 - \rho_j|^3} &= \frac{ai - 1}{|ai - 1|^3} + \frac{ai + 1}{|ai + 1|^3} - \frac{ai(1 + 1)}{|2|^3} \\ &= \frac{ai - 1}{(a^2 + 1)^{3/2}} + \frac{ai + 1}{(a^2 + 1)^{3/2}} - \frac{2ai}{8} \\ &= \frac{2ai}{(a^2 + 1)^{3/2}} - \frac{2ai}{8} = 2ai \left(\frac{1}{(a^2 + 1)^{3/2}} - \frac{1}{8} \right) \end{aligned}$$

and

$$(3.34) \quad \begin{aligned} \sum_{j=0}^{N-1} \frac{ae^{i\theta}(1 - a\rho_j e^{i\theta})}{|1 - a\rho_j e^{i\theta}|^3} - \sum_{j=1}^{N-1} \frac{ae^{i\theta}(1 - \rho_j)}{a^3|1 - \rho_j|^3} \\ = \frac{ai(1 - ai)}{|1 - ai|^3} + \frac{ai(1 - a(-1)i)}{|1 - a(-1)i|^3} - \frac{ai(1 + 1)}{|2a|^3} \\ = 2ai \left(\frac{1}{(a^2 + 1)^{3/2}} - \frac{1}{8a^3} \right), \end{aligned}$$

so

$$(3.35) \quad b = [(1 + a^2)^{-3/2} - 2^{-3}] \cdot [(1 + a^2)^{-3/2} - (2a)^{-3}]^{-1}.$$

(ii) That $b = 1$ if and only if $a = 1$ can be obtained directly from (1.18).

(iii) Since (1.11) holds and b must be greater than zero, we have

$$(3.36) \quad \begin{cases} (1 + a^2)^{-3/2} - 2^{-3} > 0, \\ (1 + a^2)^{-3/2} - (2a)^{-3} > 0, \end{cases}$$

or

$$(3.37) \quad \begin{cases} (1 + a^2)^{-3/2} - 2^{-3} < 0, \\ (1 + a^2)^{-3/2} - (2a)^{-3} < 0. \end{cases}$$

Then the result of (iii) is easily obtained.

Proof of Corollary 3. Under the assumptions of Corollary 3, we have $b = 1$.

ACKNOWLEDGMENTS

The authors sincerely thank the referee for some helpful suggestions, which improved the paper.

REFERENCES

- [1] R. Abraham and J. Marsden, Foundations of Mechanics, 2nd ed. Benjamin/Cummings, London, 1978. MR **81e**:58025
- [2] B. Elmabsout, Sur L'existence des certaines configurations d'équilibre relatif dans le probleme des N corps, *Celest. Mech.* 41(1988), 131-151. MR **89j**:70014
- [3] W. D. MacMillan and W. Bartky, Permanent configurations in the problem of four bodies, *Trans. AMS* 34 (1932), 838-874.
- [4] M. Marcus and H. Minc, A survey of matrix theory and matrix inequalities, Allyn and Bacon, Boston, Mass, 1964. MR **29**:112
- [5] R. Moeckel and C. Simó, Bifurcation of spatial central configurations from planar ones, *SIAM J. Math. Anal.* 26 (1995), 978-998. MR **96d**:70015
- [6] L. M. Perko and E. L. Walter, Regular polygon solutions of the N-body problem, *Proc. AMS* 94(1985), 301-309. MR **86e**:70004
- [7] Xie Zhifu and Zhang Shiqing, A simpler proof of regular polygon solutions of the N-body problem, *Physics Letters A*, 277(2000), 156-158.
- [8] S. Q. Zhang and Q. Zhou, Nested regular polygon solutions for planar 2N-body problems, Preprint, October, 2001.

DEPARTMENT OF MATHEMATICS, CHONGQING UNIVERSITY, CHONGQING 400044, PEOPLE'S REPUBLIC OF CHINA

Current address: Department of Mathematics, Shanghai Jiaotong University, Shanghai 200030, People's Republic of China

E-mail address: zhangshiqing@hotmail.msn.com

DEPARTMENT OF MATHEMATICS, EAST CHINA NORMAL UNIVERSITY, SHANGHAI 200062, PEOPLE'S REPUBLIC OF CHINA