# SPECTRAL GAP OF SCL IN FREE PRODUCTS 

LVZHOU CHEN<br>(Communicated by David Futer)


#### Abstract

Let $G={ }_{\lambda} G_{\lambda}$ be a free product of torsion-free groups, and let $g \in[G, G]$ be any element not conjugate into a $G_{\lambda}$. Then $\operatorname{scl}_{G}(g) \geq 1 / 2$. This generalizes and gives a new proof of a theorem of Duncan and Howie (1991).


## 1. Introduction

For any group $G$, let $[G, G]$ denote its commutator subgroup. For any $g \in[G, G]$, the commutator length $\operatorname{cl}(g)$ is the minimal number $n$ such that

$$
g=\left[a_{1}, b_{1}\right]\left[a_{2}, b_{2}\right] \cdots\left[a_{n}, b_{n}\right]
$$

for some $a_{i}, b_{i} \in G$, and the stable commutator length $\operatorname{scl}(g)$ is the limit

$$
\lim _{n \rightarrow \infty} \frac{\operatorname{cl}\left(g^{n}\right)}{n}
$$

The spectrum of scl is the set of values of $\operatorname{scl}(g)$ as $g$ runs over elements of $[G, G]$.
1.1. Main results. In this paper, our main result is the following.

Theorem A. Let $G=*_{\lambda} G_{\lambda}$ be a free product of torsion-free groups, and suppose $g \in[G, G]$ is not conjugate into any $G_{\lambda}$. Then

$$
\operatorname{scl}_{G}(g) \geq 1 / 2 .
$$

This statement must be modified when the factors have torsions. For instance, we have a lower bound $1 / 2-1 / N$ if every nontrivial element in each factor group has order at least $N \geq 2$; for details, see Theorem 3.1. The same statement and proof are still valid if the assumption $g \in[G, G]$ is weakened to $g^{n} \in[G, G]$ for some $n \geq 1$ since we use the geometric interpretation (see Section (2).

A special case is when each $G_{\lambda}=\mathbb{Z}$. In this case $G$ is free, and no $g \in[G, G] \backslash\{i d\}$ is conjugate into a factor. Thus we obtain a new proof of the following result.
Corollary B. If $F$ is free, and $g \in[F, F] \backslash\{i d\}$, then

$$
\operatorname{scl}(g) \geq 1 / 2
$$

Duncan-Howie [10] proved Theorem A] when $G_{\lambda}$ are locally indicable. Our proof is new even in that case.

A group $G$ with the property that either $\operatorname{scl}(g)=0$ or $\operatorname{scl}(g) \geq C$ for some $C=$ $C(G)>0$ for all $g \in[G, G]$ is said to have a spectral gap $C$ for scl. Residually free groups have spectral gap $1 / 2$ ([4, Corollary 4.113], using Duncan-Howie's result);

[^0]$\delta$-hyperbolic groups have a spectral gap that can be estimated by the number of generators and $\delta$ (Calegari-Fujiwara [5); finite index subgroups of mapping class groups also have a spectral gap (Bestvina-Bromberg-Fujiwara [1]); BaumslagSolitar groups have a spectral gap 1/12 (Clay-Forester-Louwsma [8); right angled Artin groups have a spectral gap $1 / 24$ (Fernós-Forester-Tao [11]).

Our results imply that $* G_{i}$ has a spectral gap $\min \{C, 1 / 2-1 / N\}(N \geq 3)$ if all $G_{i}$ have spectral gap $C$ and contain no $k$-torsion for $k<N$. Without the assumption on torsions, the spectral gap $\min \{C, 1 / 12\}$ has been obtained in [8, Theorem 6.9].

In fact we give two logically independent proofs of Corollary B.
Ivanov-Klyachko [12] recently independently obtained Theorem Atogether with other estimates related to Theorem 3.1 in terms of commutator length. Their argument uses a different language (diagrams) but the idea behind is similar, especially in the case of free groups. Corollary 3.7 provides the connection.
1.2. Contents of paper. Section 2 introduces the geometric language of fatgraphs, used to study scl in free groups. We give a new proof of Corollary B and discuss potential generalizations to integral chains.

Section 3 introduces some techniques to study surface maps into a wedge of spaces. We use these techniques to prove Theorem 3.1 which allows the factors to have torsion, then we deduce Theorem A.

## 2. Geometric definition of SCl

Our arguments are geometric and depend on an interpretation of scl in terms of maps of surfaces.

Let $G$ be a group. Let $X$ be a $K(G, 1)$. Each conjugacy class $g \in[G, G]$ corresponds to a free homotopy class of loop $\gamma: S^{1} \rightarrow X$.

An admissible surface for $g$ is a compact, oriented surface $R$ without disk or sphere components, together with a free homotopy class of map $f: R \rightarrow X$ for which the following diagram commutes:

and $\partial f$ is a positively oriented (possibly disconnected) covering (of degree $n(R)$ ).
These are sometimes called monotone admissible surfaces ([4, Definition 2.12]).
Lemma 2.1 (4, Proposition 2.10 and 2.13]).

$$
\operatorname{scl}(g)=\inf \frac{-\chi(R)}{2 n(R)}
$$

over all admissible surfaces for $g$.
This also defines $\operatorname{scl}(g)$ for $g \in G$ with $g^{n} \in[G, G]$ for some $n \geq 1$.
The following corollary is well known to people studying scl; we include it for readers interested in commutator length.
Corollary 2.2. Let $g_{i}$ be conjugates of $g$. Unless $m=1$ and $g_{1}^{n_{1}}=i d$, we have

$$
\operatorname{cl}\left(g_{1}^{n_{1}} \cdots g_{m}^{n_{m}}\right) \geq \operatorname{scl}(g)\left|\sum_{i=1}^{m} n_{i}\right|-\frac{m}{2}+1 .
$$



Figure 1. Fattening and Decoration

Proof. If $g_{1}^{n_{1}} \cdots g_{m}^{n_{m}}=i d$, then the inequality does not hold only when $m=1$. From now on, assume $g_{1}^{n_{1}} \cdots g_{m}^{n_{m}} \neq i d$ and can be written as a product of $k$ commutators. Then we obtain a surface $R$ of genus $k$ with $m$ boundary components and a map $f: R \rightarrow X$ such that the boundary components wrap $n_{i}$ times respectively around a loop $\gamma$ representing the conjugacy class $g$. Then $-\chi(R)=2 k+m-2$ and $R$ is not a disk by assumption. If all $n_{i}$ have the same sign, the inequality follows from Lemma [2.1] for the general case, apply Proposition 2.10 in [4] instead.

If $G$ is free, we can take $X$ to be a wedge of circles. In this case, any admissible $S$ can be compressed (reducing $-\chi(S)$ without changing $n(R)$ ) until it is represented by a fatgraph (see [9]). See [6] or [13] for an introduction to fatgraphs.

Informally, a fatgraph is a graph $Y$ with a cyclic ordering of edges at each vertex, which lets $Y$ embed canonically as the spine of a compact oriented surface $S(Y)$ (the fattening) which deformation retracts to $Y . \partial S(Y)$ has an induced simplicial structure.

If $Y$ comes with a simplicial map $f: Y \rightarrow X$, then we get a surface map $\bar{f}$ : $S(Y) \rightarrow X$, which is simplicial on $\partial S(Y)$, by pre-composing with the deformation retraction $S(Y) \rightarrow Y$. We decorate the oriented edges of $\partial S(Y)$ by generators of $F$ to indicate where they are mapped in $X$ by $\bar{f}$. See Figure 1 for an example.

Any cyclically reduced $g$ in a free group $F$ is represented by a simplicial immersion $\phi: C_{|g|} \rightarrow X$, where $|g|$ is the word length, and $C_{|g|}$ is the simplicial oriented $S^{1}$ with $|g|$ vertices. For an admissible fatgraph $Y$ (with a simplicial map $f: Y \rightarrow X$ ), the oriented covering map $\partial \bar{f}: \partial S(Y) \rightarrow C_{|g|}$ can be taken to be simplicial. Every admissible surface (up to compression and homotopy) can be put in this form.

Now we prove the spectral gap $1 / 2$ for free groups.
Corollary B. If $F$ is free, and $g \in[F, F] \backslash\{i d\}$, then

$$
\operatorname{scl}(g) \geq 1 / 2
$$

Proof. Take any fatgraph $Y$ with fattening $S=S(Y)$ admissible of degree $n$ for $g$. Label the vertices of $C_{|g|}$ cyclically as $1,2, \ldots,|g|$. Pull back the labels to $\partial S$ via the covering map $\partial \bar{f}$; then each edge on $\partial S$ also gets labeled as $(i, i+1)$ for $i<|g|$ or $(|g|, 1)$.

Two (distinct) edges of $\partial S$ are paired if they are mapped to the same edge of $Y$ under the deformation retraction. Two (distinct) vertices of $\partial S$ are paired if they are end points of a pair of paired edges that correspond to some edge $e$ in $Y$ and these two vertices correspond to the same end point of $e$. In Figure $1 v_{4}$ and $v_{5}$ are paired vertices; $v_{1}, v_{2}$ and $v_{3}$ are mutually paired; $v_{6}$ is paired with $v_{7}$ and $v_{9}$ but not with $v_{8}$.

Claim 2.3. Paired vertices have distinct labels.
Proof. Suppose not. Then we will have two paired edges mapped to two consecutive edges of $C_{|g|}$ under $\partial \bar{f}$. But paired edges are decorated by inverse letters, so the cyclic word decorating $\partial S$ is not cyclically reduced, contrary to the assumption.

Now construct a directed graph $G$ (possibly with multiedge) as follows. The vertex set is $\{1,2, \ldots,|g|\}$. Whenever we have a pair of paired edges on $\partial S$ labeled as $(i, i+1)$ and $(j, j+1)$, respectively, add a directed edge from $i+1$ to $j$ and another from $j+1$ to $i$. We say a directed edge from $i$ to $j$ is descending if $i>j$. See Figure 2 for an example. The graph $G$ resembles the turn graph introduced by Brady-Clay-Forester [2] to compute scl in free groups.


Figure 2. The pull back label on a fatgraph that is admissible for $g=a b a B a B A A A b \in F_{2}$, and the corresponding graph $G$ with descending edges thickened.

For each vertex $v$ of $Y$, let $d(v)$ denote the valence.
Claim 2.4.

$$
\sum d(v)=n|g|, \text { where the sum is over all vertices of } Y .
$$

Proof. For each vertex $v$ of $Y$ with valence $d(v)$, there are exactly $d(v)$ vertices on $\partial S$ that deformation retract to $v$. Thus $\sum d(v)$ is the number of vertices of $\partial S$, which equals the number of edges on $\partial S$, which is $n|g|$.

Claim 2.5.

$$
\#(\text { vertices in } Y) \leq n\left(\frac{1}{2}|g|-1\right) .
$$

Proof. In the proof above, we see that there are exactly $d(v)$ vertices on $\partial S$ that deformation retract to $v$. These vertices contribute to exactly $d(v)$ directed edges in $G$ which form a directed cycle. This gives a decomposition of $G$ into cycles as
$v$ ranges over all vertices of $Y$. Note that each directed cycle in $G$ must contain a descending edge since there is no self loop according to Claim 2.3. Therefore, the number of vertices in $Y$ is no more than the number of descending edges in $G$.

On the other hand, for each pair of paired edges on $\partial S$ labeled as $(i, i+1)$ and $(j, j+1)$, respectively, if neither of $i, j$ is $|g|$, then exactly one of the two directed edges in $G$ contributed by this pair is descending; if $i=|g|$ or $j=|g|$, then neither of the two directed edges is descending. Thus the number of descending edges in $G$ is $n(|g| / 2-1)$.

Combining the results above, we have

$$
\begin{aligned}
-\chi(S)=-\chi(Y)=\sum \frac{d(v)-2}{2} & =\frac{1}{2} \sum d(v)-\#(\text { vertices of } Y) \\
& \geq \frac{1}{2} n|g|-n\left(\frac{1}{2}|g|-1\right) \\
& =n
\end{aligned}
$$

for all admissible fatgraphs, which implies $\operatorname{scl}(g) \geq 1 / 2$.
scl is extended to integral chains (formal sums of elements) in [4].
Conjecture 2.6 (Calegari).

$$
\operatorname{scl}(c) \geq \frac{1}{2}
$$

for any integral chain c in a free group, unless an admissible surface of $c$ is annuli (in which case $\operatorname{scl}(c)=0$ ).

Remark 2.7. Using the argument above, any ordering of the vertices on $C_{|g|}$ gives a lower bound on $\operatorname{scl}(g)$, which also works for chains. However, few orderings provide the correct lower bound $1 / 2$, and it seems difficult to show that such good orderings exist for general chains. Computer experiments give evidence for Conjecture 2.6.

Remark 2.8. Duncan-Howie's proof depends on the existence of a left-ordering on torsion-free one-relator quotients of the free groups. There is no analogy of their argument for integral chains. Thus one motivation of our work is to find a new proof of their result which does not depend on orderability.

Remark 2.9. Spectral gap $1 / 2$ is often useful to certify extremal surfaces (those admissible surfaces realizing the infimum in the geometric interpretation). For example, Corollary B implies that the once-punctured torus bounding $[x, y]$ is extremal when $x, y \in F$ do not commute. Similarly, the special case $c=x^{-1}+y^{-1}+x y$ in Conjecture 2.6 is asking whether the thrice-punctured sphere bounding $c$ is extremal when $x, y$ do not commute, which is still open.

## 3. Free product case

In this section we prove Theorem A. This will follow by induction and a finiteness argument from the following theorem.

Theorem 3.1. Let $G=A * B$ and $g=a_{1} b_{1} \cdots a_{L} b_{L}$ with $a_{i} \in A \backslash\{i d\}, b_{i} \in B \backslash\{i d\}$, and $L \geq 1$ such that $g \in[G, G]$. Let $N \geq 2$ be the minimal order of $a_{i}$ and $b_{i}$; then

$$
\operatorname{scl}_{G}(g) \geq 1 / 2-1 / N
$$



Figure 3. $R_{A}$ and $R_{B}$ with inessential arcs thickened and corners represented by dots.

The formalism of fatgraphs is inadequate when factors are not free; thus we introduce a new formalism following [3].

If $G=A * B$, then we can build a $K(G, 1)$ by taking $X:=K(A, 1) \vee K(B, 1)$ to be a wedge. Then an admissible surface $R \rightarrow X$ decomposes into subsurfaces $R_{A} \rightarrow K(A, 1)$ and $R_{B} \rightarrow K(B, 1) . R_{A}$ and $R_{B}$ are surfaces with corners, each of which contributes $1 / 4$ to $-\chi$.

Calegari [3] shows how to compute scl in certain free products by a pair of linear programming problems, one for each of $A$ and $B$.

When $A, B$ are abelian (the case Calegari considers), the contribution of $R_{A}$ to scl comes from a linear term, together with a nonlinear contribution from disk components, i.e., components of $R_{A}$ which are homeomorphic to $D^{2}$.
Example 3.2. Let $R$ be the fatgraph admissible for $g=a b a B a B A^{3} b \in \mathbb{Z} * \mathbb{Z}$ in Figure 2 It decomposes into $R_{A}$ and $R_{B}$ as in Figure 3 $R_{A}$ contributes

$$
1 / 4 \# \text { corners }-\# \text { disks }=2-1=1
$$

to $-\chi(R)$, and similarly the contribution of $R_{B}$ is 0 . In general, to minimize $-\chi(R) / 2 n$ is to maximize the number of disk components-a nonlinear problem.

For arbitrary $A, B$ we obtain a lower bound on scl by ignoring the (positive) contribution to $-\chi$ of nondisk components of $R_{A}$ and $R_{B}$. Equality holds (by a covering argument; see [3] or [7) when scl vanishes on both $A$ and $B$. Formally, fix $G$ and $g$ as in Theorem 3.1.

Definition 3.3. Let $W$ be a vector space formally spanned by the set of ordered pairs $(i, j), 1 \leq i, j \leq L$. Let

$$
\begin{aligned}
& V:=\left\{\sum_{1 \leq i, j \leq L} x_{i j}(i, j) \text { such that } x_{i j} \geq 0, \sum_{i} x_{i j}=1, \sum_{j} x_{i j}=1\right\} \subset W, \\
& \mathcal{D}_{A}:=\left\{\sum_{j=1}^{k}\left(i_{j}, i_{j+1}\right) \text { such that } i_{k+1}=i_{1}, \prod_{j=1}^{k} a_{i_{j}}=1 \in A, k>0\right\} \subset W .
\end{aligned}
$$

Each element in $\mathcal{D}_{A}$ is called a disk vector in $A$. For any $v \in V$, define

$$
\kappa_{A}(v):=\sup \left\{\sum t_{i} \mid v=\sum t_{i} d_{i}+\sum x_{i j}^{\prime}(i, j), t_{i} \geq 0, d_{i} \in \mathcal{D}_{A}, x_{i j}^{\prime} \geq 0\right\} .
$$

Define $\mathcal{D}_{B}$ and $\kappa_{B}$ similarly. Finally define $\phi: V \rightarrow V$ to be the affine map given by $\phi(i, j)=(j-1, i)$ (replace $j-1$ by $L$ if $j=1$ ).

Up to compression of $R$, the boundary $\partial R_{A}$ alternates between arcs mapped to one of $a_{i}$ and inessential arcs (mapped to the wedge point). Encode $R_{A}$ as $v_{A}=\sum x_{i j}(i, j) \in V$, where $x_{i j}$ is the number, divided by $n(R)$, of inessential arcs on $\partial R_{A}$ that go from $a_{i}$ to $a_{j}$. Disk components contribute to disk vectors. Such an encoding cannot reconstruct $R_{A}$ but is enough to bound from below the contribution of $R_{A}$ to $-\chi(R)$, and $\kappa_{A}\left(v_{A}\right)$ is the (normalized) maximal number of disk components $R_{A}$ can have.

Note that $R_{A}$ and $R_{B}$ can be glued up along inessential arcs such that $a_{i}$ should be followed by $b_{i}$ and $b_{j-1}$ should be followed by $a_{j}$. Thus the vectors $v_{A}$ and $v_{B}$ corresponding to $R_{A}$ and $R_{B}$ satisfy $v_{B}=\phi\left(v_{A}\right)$. Based on these, $\operatorname{scl}_{G}$ can be estimated using the following lemma.

Lemma 3.4. Under the notation above,

$$
2 \cdot \operatorname{scl}_{G}(g) \geq L-\sup _{v_{A} \in V}\left\{\kappa_{A}\left(v_{A}\right)+\kappa_{B}\left(\phi\left(v_{A}\right)\right)\right\}
$$

Equality holds if $\mathrm{scl}_{A}$ and $\mathrm{scl}_{B}$ are identically zero.
This is Corollary 4.17 in [7] in the case $G_{1}=A, G_{2}=B$, and $z=g$ since $\left(v_{A}, v_{B}\right) \in Y_{l}$ means $v_{B}=\phi\left(v_{A}\right)$ in our notation and we have $\left|v_{A}\right|=\left|v_{B}\right|=L$.

Now we are ready to prove Theorem 3.1.
Proof of Theorem 3.1. By Lemma 3.4, it suffices to show

$$
\kappa_{A}\left(v_{A}\right)+\kappa_{B}\left(\phi\left(v_{A}\right)\right) \leq L-1+2 / N
$$

for any $v_{A}=\sum x_{i j}(i, j) \in V$.
Claim 3.5. For all $v=\sum x_{i j}(i, j) \in V$ we have

$$
\kappa_{A}(v) \leq \frac{1}{N} \sum_{i \geq j} x_{i j}+\left(1-\frac{1}{N}\right) \sum_{i<j} x_{i j}, \text { and similarly for } \kappa_{B}(v)
$$

Proof. Suppose $v=\sum t_{i} d_{i}+\sum x_{i j}^{\prime}(i, j)$ with $t_{i} \geq 0, d_{i} \in \mathcal{D}_{A}$, and $x_{i j}^{\prime} \geq 0$. It suffices to show that each $d_{i}$ contributes at least 1 to the right hand side of the inequality.

For any disk vector $d=\sum_{j=1}^{k}\left(i_{j}, i_{j+1}\right)$, if all $i_{j}$ are equal, then $k \geq N$, and thus the contribution of $d$ to the right hand side is $k / N \geq 1$.

Suppose there are at least two distinct $i_{j}$ 's. Then there exist $j_{1}$ and $j_{2}$ such that $i_{j_{1}}>i_{j_{1}+1}$ and $i_{j_{2}}<i_{j_{2}+1}$. Thus the contribution of $d$ to the right hand side is at least $1 / N+(1-1 / N)=1$.

Geometrically, each $v \in V$ can be thought of as an $L \times L$ doubly stochastic matrix. Since each row sums to 1 , the estimate in the claim above is equivalent to saying that $\kappa_{A}(v)-L / N$ and $\kappa_{B}(v)-L / N$ are at most $(1-2 / N)$ times the sum of entries in the strictly upper triangular region $U$. The pull back $\phi^{-1}(U)$ and $U$ together form $L-1$ columns (Figure 4 illustrates the case $L=5$ ), in which the entries sum to $L-1$. Combining these, we get the desired inequality.


Figure 4. Matrix illustration

Formally, by the claim above, for any $v_{A}=\sum x_{i j}(i, j) \in V$, we have

$$
\begin{aligned}
\kappa_{A}\left(v_{A}\right)+\kappa_{B}\left(\phi\left(v_{A}\right)\right) & \leq \frac{2 L}{N}+\left(1-\frac{2}{N}\right) \sum_{i<j} x_{i j}+\left(1-\frac{2}{N}\right) \sum_{1 \leq j-1<i} x_{i j} \\
& =\frac{2 L}{N}+\left(1-\frac{2}{N}\right)\left[\sum_{i<j} x_{i j}+\sum_{2 \leq j \leq i} x_{i j}\right] \\
& =\frac{2 L}{N}+\left(1-\frac{2}{N}\right) \sum_{2 \leq j \leq L} x_{i j} \\
& =\frac{2 L}{N}+\left(1-\frac{2}{N}\right)(L-1) \\
& =L-1+\frac{2}{N}
\end{aligned}
$$

as desired.

Remark 3.6. The estimate in Theorem 3.1 is sharp, since we have ( 7 , Proposition 5.6])

$$
\operatorname{scl}_{G_{1} * G_{2}}([a, b])=\frac{1}{2}-\frac{1}{\min \left(n_{a}, n_{b}\right)},
$$

where $a \in G_{1} \backslash\{i d\}, b \in G_{2} \backslash\{i d\}$ and $n_{a}, n_{b}$ are the orders of $a, b$, respectively.
Now we apply Theorem 3.1 with $N=+\infty$ to prove the following.
Theorem A. Let $G=*_{\lambda} G_{\lambda}$ be a free product of torsion-free groups, and suppose $g \in[G, G]$ is not conjugate into any $G_{\lambda}$, then

$$
\operatorname{scl}_{G}(g) \geq 1 / 2
$$

Proof. First notice that for each $g \in[G, G]$, there are finitely many $\lambda_{1}, \lambda_{2}, \ldots, \lambda_{n}$ such that $g \in[H, H]$, where $H=*_{i=1}^{n} G_{\lambda_{i}} \leq G$. Moreover, we have $\operatorname{scl}_{H}(g)=$ $\operatorname{scl}_{G}(g)$ since $H$ is a retract of $G$ and scl is monotone under homomorphism. Thus it suffices to show $\operatorname{scl}_{H}(g) \geq 1 / 2$.

Now we induct on $n$. The case $n=2$ directly follows from Theorem 3.1. Now suppose $n>2$. Then $G$ is the free product of two torsion-free groups $*_{i=1}^{n-1} G_{\lambda_{i}}$ and $G_{\lambda_{n}}$. If $g$ is not conjugate into either of them, then the result follows from Theorem 3.1] Otherwise, by assumption, $g$ is conjugate into $*_{i=1}^{n-1} G_{\lambda_{i}}$ but not any $G_{\lambda_{i}}$. Then the result follows from the inductive assumption.

Finally, Corollary 2.2 and Theorem 3.1 together imply the following result about commutator length, similar to the results obtained by Ivanov-Klyachko 12.
Corollary 3.7. Let $G=A * B$ and $g=a_{1} b_{1} \cdots a_{L} b_{L}$ with $a_{i} \in A \backslash\{i d\}, b_{i} \in$ $B \backslash\{i d\}$, and $L \geq 1$ such that $g \in[G, G]$. Let $N \geq 2$ be the minimal order of $a_{i}$ and $b_{i}$, and let $g_{i}$ be conjugates of $g$. Then

$$
2 \cdot \operatorname{cl}\left(g_{1}^{n_{1}} \ldots g_{m}^{n_{m}}\right)-2 \geq \sum_{i=1}^{m}\left(n_{i}-1\right)-\left[\frac{2}{N} \sum_{i=1}^{m} n_{i}\right]
$$

where $[x]$ denotes the largest integer no greater than $x$.

## Acknowledgments

The author would like to thank his advisor Danny Calegari, Sergei Ivanov, Anton Klyachko, Alden Walker, and the anonymous referee for reading earlier versions of this paper and giving great suggestions.

## References

[1] Mladen Bestvina, Ken Bromberg, and Koji Fujiwara, Stable commutator length on mapping class groups (English, with English and French summaries), Ann. Inst. Fourier (Grenoble) 66 (2016), no. 3, 871-898. MR3494163
[2] Noel Brady, Matt Clay, and Max Forester, Turn graphs and extremal surfaces in free groups, Topology and geometry in dimension three, Contemp. Math., vol. 560, Amer. Math. Soc., Providence, RI, 2011, pp. 171-178, DOI 10.1090/conm/560/11098. MR 2866930
[3] Danny Calegari, scl, sails, and surgery, J. Topol. 4 (2011), no. 2, 305-326, DOI 10.1112/jtopol/jtr001. MR2805993
[4] Danny Calegari, scl, MSJ Memoirs, vol. 20, Mathematical Society of Japan, Tokyo, 2009. MR 2527432
[5] Danny Calegari and Koji Fujiwara, Stable commutator length in word-hyperbolic groups, Groups Geom. Dyn. 4 (2010), no. 1, 59-90, DOI 10.4171/GGD/75. MR2566301
[6] Danny Calegari and Alden Walker, Surface subgroups from linear programming, Duke Math. J. 164 (2015), no. 5, 933-972, DOI 10.1215/00127094-2877511. MR 3332895
[7] L. Chen, Scl in free products, preprint: arXiv:1611.07463v3.
[8] Matt Clay, Max Forester, and Joel Louwsma, Stable commutator length in Baumslag-Solitar groups and quasimorphisms for tree actions, Trans. Amer. Math. Soc. 368 (2016), no. 7, 4751-4785, DOI 10.1090/tran/6510. MR 3456160
[9] Marc Culler, Using surfaces to solve equations in free groups, Topology 20 (1981), no. 2, 133-145, DOI 10.1016/0040-9383(81)90033-1. MR605653
[10] Andrew J. Duncan and James Howie, The genus problem for one-relator products of locally indicable groups, Math. Z. 208 (1991), no. 2, 225-237, DOI 10.1007/BF02571522. MR1128707
[11] T. Fernós, M. Forester, and J. Tao, Effective quasimorphisms on right-angled Artin groups, preprint: arXiv:1602.05637.
[12] S. Ivanov and A. Klyachko, Quasiperiodic and mixed commutator factorizations in free products of groups, preprint: arXiv:1702.01379.
[13] R. C. Penner, Perturbative series and the moduli space of Riemann surfaces, J. Differential Geom. 27 (1988), no. 1, 35-53. MR 918455

Department of Mathematics, University of Chicago, Chicago, Illinois 60637
Email address: lzchen@math.uchicago.edu


[^0]:    Received by the editors Nov. 28, 2016 and, in revised form, May 19, 2017, and July 19, 2017. 2010 Mathematics Subject Classification. Primary 57M07; Secondary 20E06, 20E05, 20F12, 20F65, 20 J 06.

