

ON A QUESTION OF KALIMULLIN

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ABSTRACT. We prove that for every computable limit ordinal α there exists a computable structure \mathcal{A} which is Δ_α^0 -categorical and α is smallest such, but nonetheless for every isomorphic computable copy \mathcal{B} of \mathcal{A} there exists a $\beta < \alpha$ such that $\mathcal{A} \cong_{\Delta_\beta^0} \mathcal{B}$. This answers a question raised by Kalimullin in personal communication with the third author.

1. INTRODUCTION

Much of classical mathematics is concerned with classification of mathematical structures by their isomorphism types. Two mathematical structures are usually identified if they are isomorphic. However, such a classification blurs fine-grained distinctions related to the algorithmic nature of the structures. For example, it is easy to construct two algorithmically presented structures, both isomorphic to a simple structure like (\mathbb{N}, \leq) but with wildly differing computability-theoretic properties, such as decidability (or non-decidability) of the adjacency relation. On the other hand, sometimes computable isomorphism type coincides with classical isomorphism type, which is the case for a dense countable linear ordering or a finitely presented group.

Computable structure theory [AK00, EG00] has grown to understand the computability-theoretic properties of *computably presented* structures. Recall that a countably infinite algebraic structure is *computable* if its domain is the natural numbers \mathbb{N} and its operations are Turing computable functions. If an algebraic structure \mathcal{A} is isomorphic to a computable structure \mathcal{B} , then we say that \mathcal{B} is a computable copy, a computable presentation, or a constructivization of \mathcal{A} . As we noted above, an algebraic structure may have computable copies with wildly differing computability-theoretic properties. Based on this observation, Mal'cev [Mal61] suggested that computable structures should be studied under computable isomorphism. In particular, we say that a countably infinite structure is *computably categorical* if it has a unique computable copy up to computable isomorphism. Although computably categorical structures are “unclassifiable” in general (see [DKL⁺15]), computable categoricity tends to be very well-behaved within many standard algebraic classes. For instance, a Boolean algebra is computably categorical iff it has only finitely many atoms [Gon97, LaR77], and a torsion-free abelian group is computably categorical iff its rank is finite [Nur74]. For most of these “nice” algebraic classes, computable categoricity is equivalent to the stronger notion of

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relative computable categoricity; we omit the definition of relative computable categoricity; see [AK00]. In contrast to computable categoricity in general, relative computable categoricity admits a syntactical description, a so-called computably enumerable Scott family [AK00]. There have been many successful applications of various syntactical techniques to the study of relative computable categoricity and related notions; see, e.g., the recent work of Montalbán [Mon13, Mon15] that relate computable structure theory with descriptive set theory and model theory. On the other hand, the study of the more “wild” general computable categoricity enjoys applications of advanced recursion-theoretic techniques; it also often leads to novel methods and new results which are not necessarily related to categoricity questions (see, e.g., [DM13, Gon81]). One of the most remarkable theorems of this kind says that there is a structure with exactly two computable copies up to computable isomorphism; see Goncharov [Gon80], and see Hirschfeldt [Hir01] for further applications of the technique of Goncharov.

As we see, there are two main strands within modern computable structure theory. The first seeks to relate definability with effectivity [AK00], and the other tends to be concerned with properties which revolve around the specifics of the computation level and the structures concerned; see [EG00]. In this paper, we will be working on the interaction between the two strands. More specifically, we answer the following question of Kalimullin. A few years ago, Kalimullin asked whether a computable structure could be arithmetically categorical in the following unbounded way. Can there be a computable structure \mathcal{A} , such that for any computable structure \mathcal{B} isomorphic to \mathcal{A} , there is an n such that \mathcal{A} is Δ_n^0 -isomorphic to \mathcal{B} , but for each $m < \omega$ there is a computable \mathcal{C}_m with \mathcal{C}_n isomorphic to \mathcal{A} but *not* by a Δ_m^0 -isomorphism? In other words, can there be a computable structure such that every isomorphic computable structure is arithmetically isomorphic, but such that this fact is not witnessed by any fixed level of the arithmetic hierarchy? In this paper we answer this question affirmatively. In fact, we prove more.

Theorem 1.1. *For every computable limit ordinal α there exists a computable structure \mathcal{A}_α such that:*

- *For every computable structure $\mathcal{M} \cong \mathcal{A}$, there exists a $\beta < \alpha$ such that $\mathcal{M} \cong_{\Delta_\beta^0} \mathcal{A}_\alpha$.*
- *For every $\beta < \alpha$, there exists a computable structure $\mathcal{B} \cong \mathcal{A}_\alpha$ such that $\mathcal{B} \not\cong_{\Delta_\beta^0} \mathcal{A}_\alpha$.*

We note that the structure \mathcal{A}_α witnessing Theorem 1.1 will be built up from structures that are themselves relatively Δ_β^0 -categorical. Although the isomorphism types of these substructures will depend on the construction, their nice uniform properties will allow us to exploit techniques borrowed from the “syntactical” strand, more specifically a result of Ash [Ash86]. The construction will be an iterated priority argument, along the lines of a “worker” argument. We believe that the easiest presentation is to give a direct proof rather than to try to use any of the existing metatheorems ([AK00, Mon14, LL97]), aside from using the above mentioned result of Ash.¹

¹Thanks to Noam Greenberg, we are aware that Asher Kach and Antonio Montalbán have (independently) announced the case $\alpha = \omega$. As far as we know, their proof has not yet been formally written or published.

From the algebraic standpoint, the structure \mathcal{A} witnessing Theorem 1.1 is an abomination. It was designed to prove the theorem. Can we find examples in nice classes?

Problem. Find structures with the property from Theorem 1.1 in natural non-universal classes, such as linear orders or abelian groups.

We strongly suspect that manufacturing examples of such linear orders should be doable. In contrast, we are not sure how to approach this problem in the class of abelian groups.

The remainder of this paper will be focused on proving Theorem 1.1.

2. PROOF

2.1. Setup and notation. Let α be a fixed computable limit ordinal. For notational convenience, when we wish to discuss Δ_β^0 constructions as oracle constructions, we will use $0_{(\beta)}$ as the name of the oracle which is equal to $0^{(\beta-1)}$ when $1 \leq \beta < \omega$, and is equal to the β' th jump (using specifically chosen Turing degree representatives that can uniformly resolve Δ_β^0 questions) when $\omega \leq \beta < \alpha$.

Let $\langle \alpha_n : n \in \omega \rangle$ be a computable increasing sequence of ordinals whose limit is α , with $\alpha_0 > 0$. For each n , let $\beta_n = 2 \cdot \alpha_n + 1$, and note that $\langle \beta_n : n \in \omega \rangle$ is also a computable increasing sequence of ordinals whose limit is α , but with $\beta_0 > 2$.

The signature of our structure will have an edge relation, an ordering relation, and a collection of unary predicates $(P_i)_{i \in \omega}$, denoting disjoint portions of the structure which we will use to meet diagonalization requirements. We will call the part of the structure restricted to one such P_i a P_i -box and sometimes simply a P -box. The ordering relation and edge relation will never hold between elements of different P -boxes.

2.1.1. The requirements. Let $\langle \mathcal{M}_n : n \in 1, 2, \dots \rangle$ be a listing of all the computable structures in our signature, which will be specified later. We will have isomorphism requirements and diagonalization requirements:

$$\mathcal{I}_n : \mathcal{M}_n \cong \mathcal{A} \rightarrow \mathcal{M}_n \cong_{\Delta_{\beta_{n-1}+1}^0} \mathcal{A},$$

$$\mathcal{D}_n : \exists \mathcal{B}_n (\mathcal{B}_n \text{ is computable} \ \& \ \mathcal{B}_n \cong \mathcal{A} \ \& \ \mathcal{B}_n \not\cong_{\Delta_{\beta_n}^0} \mathcal{A}).$$

Note that if we meet all of these requirements, then we will have proved the theorem. For trivial counting reasons (such as β_{n-1} in \mathcal{I}_n above) and without loss of generality, we may assume that n ranges over the positive natural numbers.

We will discuss two different diagonalization strategies. The “attempted diagonalization strategy” will be the naive attempt of meeting a \mathcal{D}_n requirement, in isolation. The “actual diagonalization strategy” will be different from the attempted one due to interactions between requirements. The isomorphism-building strategy \mathcal{I}_n will be formally described simultaneously with the tree of strategies, but we will give some intuition already in the next subsection.

2.2. One diagonalization strategy in isolation. In this subsection, we describe the attempted diagonalization strategy that will have to be modified before placing it onto the tree.

2.2.1. *The result of Ash.* Our primary tool for the attempted diagonalization strategy will be the following result of Ash (Theorem 18.15 of [AK00]).

Theorem 2.1 (Ash). *Let γ be a computable ordinal, and suppose L is a $\Delta^0_{2\gamma+1}$ linear ordering. Then we can uniformly produce a computable presentation $F(L)$ of $\omega^\gamma \cdot L$.*

It will be crucial that the proof of Theorem 2.1 is uniform as long as L does not have a least element. Moreover, there is a $\Delta^0_{2\gamma+1}$ function f taking $a \in L$ to the first element of the corresponding copy of ω^γ in $F(L)$. The $\Delta^0_{2\gamma+1}$ index of the function is also uniform in (the notation for) γ and the index for L .

Remark 2.2. Using the uniformity of Theorem 2.1 we will shortly define our attempted diagonalization strategy on P_i . In the proof of the main result, all such P_i will be put together onto a priority tree. At every node of the tree, we will use the uniform version of Theorem 2.1 to produce copies of linear orders (they will be slightly modified, but with all possible uniformity). One could use the recursion theorem to make the proof work. We remark that the recursion theorem is not really necessary here. We could simply dynamically outsource the task of building $F(L)$ to the construction from Theorem 2.1 whose index is known (by the s-m-n Theorem).

For our attempted diagonalization strategy on P_i , we begin by constructing two linear orders in \mathcal{A} and \mathcal{B}_n , that we will ensure are isomorphic, but not via a $\Delta^0_{\beta_n}$ isomorphism. This will be done by constructing linear orderings L_0 and L_1 , computably in $0_{(\beta_n)}$, both of order type ω^* , and then constructing $F(L_0)$ as our linear ordering in P_i of \mathcal{A} and $F(L_1)$ as our linear ordering in P_i of \mathcal{B}_n . Here, we are using Theorem 2.1 with $\gamma = \alpha_n$, and hence $2\gamma + 1 = \beta_n$.

2.2.2. *The construction of $F(L_0)$ and $F(L_1)$.* We build two $\Delta^0_{\beta_n}$ -copies of ω^* . We diagonalize against the e 'th potential $\Delta^0_{\beta_n}$ isomorphism $f_e : L_0 \rightarrow L_1$, as follows. Construct ω^* in both L_0 and L_1 , initially letting $x_{0,e}$ and $x_{1,e}$ be adjacent elements in L_0 . Wait for f_e to converge on $x_{0,e}$ and $x_{1,e}$. If the images are adjacent, insert one extra point between them, and preserve the interval. Note that this construction is computable in $0_{(\beta_n)}$. Both L_0 and L_1 have no least element, so that we can apply Theorem 2.1 with all possible uniformity. In particular, we obtain $F(L_0)$ and $F(L_1)$ which are isomorphic, but not by a $\Delta^0_{\beta_n}$ -map.

For each element of our linear orders $F(L_0)$ and $F(L_1)$, we will have one extra element that is attached to it by the edge relation. The additional elements will not be related to any elements via the ordering relation.

Remark 2.3. At this stage we owe the reader an informal explanation of why we need this extra edge relation. The idea is as follows. Suppose at stage s our linear order that we've built in P_i of \mathcal{A} looks as follows:

$$\widehat{a}_0 < \widehat{a}_1 < \widehat{a}_3 < \widehat{a}_4,$$

where the hat indicates that a point carries a label, i.e., it is adjacent to an extra point via the edge relation. (The i th extra point is specific and unique for each such a_i and is not connected to anything else.) We will also attempt to build a *computable* isomorphism from \mathcal{M} onto \mathcal{A} . At stage s we would have built a partial map $f_s : \mathcal{M}_s \rightarrow \mathcal{A}_s$.

According to our dynamic definition of the linear order in P_i , we will attempt to extend P_i by adding one more point, say b . We add the point without a label:

$$\widehat{a}_0 < b < \widehat{a}_1 < \widehat{a}_3 < \widehat{a}_4,$$

and then wait for \mathcal{M} to respond. Note the location of b is uniquely determined by its current position. If \mathcal{M} gives us some other configuration, we permanently “kill” \mathcal{M} by, say, freezing our enumeration in P_i . In particular, if \mathcal{M} is too quick in its enumeration, then it will be “killed”. As soon as we see a suitable candidate for $f^{-1}(b)$ (if ever), we define f_s on b accordingly. Only then we put a label onto b :

$$\widehat{a}_0 < \widehat{b} < \widehat{a}_1 < \widehat{a}_3 < \widehat{a}_4,$$

and wait for $f^{-1}(b)$ to be assigned a label (in \mathcal{M}). Once it is found, we extend f to that label. Repeat.

This way we force \mathcal{M} to follow \mathcal{A} very closely lagging at most one step behind us. At the end \mathcal{M} is either dead (i.e., not isomorphic to \mathcal{A}) or is forced to copy us via the *computable* isomorphism f , at least when restricted to the P -box.

We will implement the idea from Remark 2.3 later, in the full construction. But, in isolation, the strategy within its P_i in both \mathcal{A} and \mathcal{B}_n look essentially the same (with L_0 replaced by L_1 in \mathcal{B}_n). We give the details below.

2.2.3. *Attempted \mathcal{D}_n strategy.* Recall that the diagonalization strategy works within its P_i -box. We describe our actions in \mathcal{A} .

During the first stage, we declare $F(L_0)$ empty. After this, each time we wish to add a new element to $F(L_0)$, we will do so over the course of two substages. At the beginning of the first substage, there will be a finite number of elements in $F(L_0)$, each with an element attached by an edge.

Substage 1: Add a new element x to $F(L_0)$.

Substage 2: Create a new element and attach by an edge to x .

At the end of the construction, we will have constructed $F(L_0)$ with an extra element attached to each element of $F(L_0)$. (This ends the strategy.)

In \mathcal{B}_n we slowly build a (labeled) copy of $F(L_1)$, unless interrupted.

Remark 2.4. The structure \mathcal{B}_n will be computably copying \mathcal{A} everywhere except for the diagonalization location. In the actual construction, the diagonalization strategy can either be forever left inactive or declared initialized. In each of these cases we may end up with $\mathcal{B}_n \not\cong \mathcal{A}$, but this is fine since some other version of the strategy will successfully build its own version of \mathcal{B}_n .

As we have already noted above, the actual strategy may be interrupted by higher priority requirements, and thus may never finish building its P_i block in both \mathcal{A} and \mathcal{B}_n . The straightforward lemma below describes what happens in the absence of such interaction, i.e., when it acts as intended.

Lemma 2.5. *The attempted diagonalization strategy on P_i in \mathcal{A} satisfies the following properties:*

- (1) *The attempted diagonalization strategy in P_i is uniform (in i).*
- (2) *If the attempted diagonalization strategy is completed, then \mathcal{A} is not isomorphic to \mathcal{B}_n via a $\Delta^0_{\beta_n}$ map.*
- (3) *If the attempted diagonalization strategy is completed in P_i , then the restriction of \mathcal{A} to P_i is relatively $\Delta^0_{\beta_n+1}$ -categorical.*

Proof. (1) The uniformity follows from the fact that the sequence $\langle \alpha_n \rangle$ is computable, as well as the fact that the proof of Theorem 2.1 is uniform. (Also, see Remark 2.2 above.)

(2) Any isomorphism between \mathcal{A} and \mathcal{B}_n must also be an isomorphism when restricted to P_i , and must therefore also be an isomorphism when restricted to the linear order part of P_i . In our construction, we ensured that $F(L_0)$ and $F(L_1)$ were not isomorphic by the i th Δ_β^0 map, for each i .

(3) This folklore fact follows at once from a straightforward definability analysis (see the book [AK00]). \square

2.3. Construction. As we noted above, the attempted diagonalization strategy needs to be modified in the actual construction.

2.3.1. The tree of strategies, and an informal discussion. The construction will be phrased as a tree construction. The tree of strategies is $\{\infty, fin\}^{<\infty}$. Each level of the tree will be monitoring the n th partial computable structure \mathcal{M}_n .

Each of the two outcomes of the isomorphism-building strategy at σ will be associated with a version of the diagonalization strategy. We will call these versions the finitary and the infinitary diagonalization strategy of σ , respectively. (Instead, we could introduce a node for each of them below the respective outcome of an isomorphism-building σ , and also assume each such extra node has exactly one outcome which is always played.)

Remark 2.6. The true path can be approximated in the usual Π_2^0 -fashion. The outcomes at level n will reflect our current guess on whether the n th partial computable structure has followed us for one more step or not, in the sense of Remark 2.3.

The non-standard feature of this proof is that each diagonalization strategy at level n will be working relative to $0_{(\beta_n)}$ within its P -box, and thus the complexity of the strategies is going up as n increases. Using the construction of Ash (Theorem 2.1), we will attempt to uniformly extend the $0_{(\beta_n)}$ -linear order produced by the strategy to an infinite labeled computable linear order. If the process is interrupted or forever paused we will end up with a finite (partially) labeled linear order in the P -box.

2.3.2. The isomorphism-building strategy. Each node at this level will attempt to build a *computable* partial isomorphism on the P -boxes (in \mathcal{A} and \mathcal{M}_n) which are controlled by requirements of priorities no stronger than the priority of σ . This will be done as follows. Every time the diagonalization strategy of σ , or any weaker priority diagonalization strategy below σ , puts a new point into their part of \mathcal{A} , we wait for \mathcal{M}_n to respond by giving us the exact same configuration, restricted to the respective P -box of \mathcal{M}_n .

There will be another, finitary diagonalization requirement assigned with node σ and played when σ *fin* is visited. This diagonalization strategy and every weaker priority diagonalization strategy below will ignore \mathcal{M}_n .

The exact actions of the diagonalization strategies at σ will be clarified shortly. But regardless of the actions, it is clear how to define the notion of σ -expansionary stage and thus the notion of the current true path at stage s (we leave it to the reader).

2.3.3. Assignment of P -boxes to diagonalization strategies. Recall that each such strategy is working within its P -box. If σ is at level n , then at stage s at which σ

is active the first time after initialization, we assign P_i (with i least never used for this purpose) for the infinitary diagonalization strategy of σ . We denote this P -box of σ by P_σ^∞ .

Remark 2.7. We will be pressing $\mathcal{M} = \mathcal{M}_n = \mathcal{M}_{|\sigma|}$ to follow \mathcal{A} computably within P_σ^∞ by pausing our actions within P_σ^∞ of \mathcal{A} (thus, of \mathcal{B} as well) until the P_σ^∞ -box of \mathcal{M} is extended to be isomorphic to P_σ^∞ of \mathcal{A} built so far. We will give formal details of the modified diagonalization strategy in the next paragraph, but we have already seen the main idea in Remark 2.3. Since \mathcal{M} may never respond, we have to restart the diagonalization strategy within some fresh $P_{n,j}$, under the assumption that $\mathcal{M}_n \not\cong \mathcal{A}$.

The finitary version of the diagonalization strategy below σ will be working within its own P -box, we denote it P_σ^{fin} . If we play σ^{fin} and P_σ^{fin} is undefined, then pick P_j (where j is least never used for this purpose so far) and declare $P_\sigma^{fin} = P_j$.

Remark 2.8. Within this box, we will implement the attempted diagonalization strategy that ignores \mathcal{M} .

2.3.4. The modified diagonalization strategy. Suppose $|\sigma| = n$. Each P_i -box will be eventually assigned to either P_σ^∞ or P_σ^{fin} . For each $u \in \sigma$, the P_σ^x -box will attempt to implement the diagonalization strategy and also build its own version of \mathcal{B}_n , we denote it by \mathcal{B}_σ^u . Outside its P_σ^u -box the structure \mathcal{B}_σ^u will be copying \mathcal{A} , making one more step in its approximation every time σ^u is visited again.

Within P_σ^u , we need to modify the “attempted diagonalization strategy” (Section 2.2.3) as follows. We follow the notation of Section 2.2.3. Between Substage 1 and Substage 2, P_σ^u will wait for every $\mathcal{M}_{|\tau|}$ with $\tau^\infty \subseteq \sigma^u$ to reveal such an x from Substage 1. After Substage 2 is finished, it will also wait for each such $\mathcal{M}_{|\tau|}$ to reveal the extra element now attached to x by an edge. This pause also applies to the respective P -box of \mathcal{B}_σ^u .

As we noted above, the definition of the current true path is standard.

2.3.5. Initialization. We declare P_σ^u initialized if the current true path moves to the left of σ^u . We set P_σ^u undefined, and we also declare \mathcal{B}_σ^u empty.

At stage 0, initialize all strategies. At stage s of the construction, we simply let the strategies along the current true path act according to their instructions.

2.4. Verification. The plan is as follows. Recall that every version of the diagonalization strategy builds its own version of \mathcal{B}_n , and it copies \mathcal{A} everywhere outside of its (eventually stable) P -box. We will argue that $\mathcal{M}_n \cong \mathcal{A}$ implies that the true outcome of the node σ at level n of the true path is ∞ . The strategy of σ cannot control the finitely many nodes above it, but this won’t be a problem. For each strategy τ at deeper levels of the tree, there are only two possibilities. The first possibility is that such a P -box will be eventually left finite, in which case the box will be Δ_3^0 -uniformly Δ_2^0 -categorical. Otherwise, each box controlled by $\tau^u \supseteq \sigma$ will have to respect \mathcal{M}_n and wait for it to respond before acting again. Therefore, all such boxes will be working towards building a computable isomorphism between their respective boxes \mathcal{M}_n to \mathcal{A} . Note that $0'$ can compute the true path. Thus, σ can ensure that almost all P -boxes of \mathcal{M} are uniformly $\Delta_{\beta_{n-1}+1}^0$ -isomorphic to the respective boxes of \mathcal{A} (see Lemma 2.5(3)).

We give the formal details. The definitions of the true path and the true outcome were standard. The guessing procedure that determines the current true path is merely Π_2^0 . The tree does not depend on our diagonalization actions whose outcomes are not even put onto the tree. It is clear that $\mathcal{M}_{|\sigma|}$ can either follow \mathcal{A} or not follow \mathcal{A} , and this is exactly what each node measures. (The same can be said if we restrict our guessing to a computable collection of P -boxes.) We conclude that there are only two possible (true) outcomes of the guessing procedure. It is thus straightforward that the true path is infinite.

We need to argue that, for every $\hat{\sigma}x$ along the true path (where $x \in \{\infty, fin\}$), the diagonalization requirement $\mathcal{D}_{|\sigma|}$ is met within P_σ^x and with the help of its version \mathcal{B}_σ^x of \mathcal{B}_n . We also need to check that, if $\mathcal{M}_{|\sigma|}$ is isomorphic to \mathcal{A} , then it is isomorphic to \mathcal{A} via an isomorphism strictly computationally simpler than $0_{(\alpha)}$.

Lemma 2.9. *For every n , the diagonalization requirement \mathcal{D}_n is met within the P_σ^x -box, where $\hat{\sigma}x$ lies at the true path and $|\sigma| = n$.*

Proof. For simplicity, we first consider the highest priority diagonalization requirement. If there were no higher priority \mathcal{I} -requirements to respect, this would be exactly Lemma 2.5. However, according to our setup, $\sigma = e$ (the empty string) must respect \mathcal{M}_0 . But if the true outcome of \mathcal{I}_0 is ∞ , then \mathcal{M}_0 always responds by copying us at the intermediate stage; see the description of the actual diagonalization strategy in the previous section. Thus, the diagonalization strategy within P_e^∞ will be acting at infinitely many stages. Apart from pausing at the intermediate stage, the actual diagonalization strategy (see Section 2.3.4) is no different from the attempted one (see Section 2.2.3). Thus, we can appeal to Lemma 2.5 and conclude that \mathcal{D}_0 is met within the P_e^∞ -box.

On the other hand, if \mathcal{M}_0 eventually either never responds or proves to be non-isomorphic, then we implement the diagonalization strategy within some other, fresh box P_e^{fin} which (eventually) will never be initialized. The strategy will ignore \mathcal{M}_0 and will be exactly the same as the attempted one (see Section 2.2.3). We thus can safely appeal to Lemma 2.5.

We also note here that each version of the diagonalization strategy builds its own version of \mathcal{B}_n that computably copies \mathcal{A} everywhere except for the P -box controlled by the strategy.

The general case of $n > 0$ is not very much different from the basic case $n = 0$. It is sufficient to take σ with $|\sigma| = n$ along the true path and consider the box P_σ^x , where x is the true outcome of σ . The only difference is that the strategy within P_σ^x will have to respect only those M_τ with $\tau^\infty \subseteq \sigma^x$. □

Recall that $(\beta_n)_{n \in \mathbb{N}^+}$ has the property $0_{(\beta_n)} \geq_T 0''$, for each n .

Lemma 2.10. *For every n , if $\mathcal{M}_n \cong \mathcal{A}$, then $\mathcal{M}_n \cong_{\Delta_{\beta_{n-1}+1}^0} \mathcal{A}$. (That is, \mathcal{I}_n is met.)*

Proof. Consider \mathcal{M}_n and assume that $\mathcal{M}_n \cong \mathcal{A}$. There are several types of P -boxes that we need to consider. We argue that in each case we can (uniformly) produce an isomorphism of complexity at most $\Delta_{\beta_{n-1}+1}^0$ between the respective boxes in \mathcal{A} and \mathcal{M}_n .

Suppose $m < n$. Then $P_{m,i}$ is either eventually permanently assigned to P_τ^x for some τ of length m along the true path, or is eventually left finite. With the help of $0''$ we can see which case applies to each such $P_{m,i}$, $m < n$. It follows that $0''$

can uniformly build an isomorphism when restricted to each finite P -box. By the choice of the sequence of $(\beta_n)_{n \in \omega}$, $0''$ is no greater than each such β_m , thus the isomorphism within each $P_{m,i}$ is (uniformly) computable in $0_{(\beta_n)}$. By Lemma 2.5, for the finitely many τu along the true path with $|\tau| < n$, P_τ^u of \mathcal{A} is relatively $\Delta_{\beta_{n-1}+1}^0$ -categorical. It follows that the collection of all $P_{m,i}$, $m < n$, is $\Delta_{\beta_{n-1}+1}^0$ -categorical, with the finite initial segment of the true path being the parameter of uniformity.

If $m \geq n$, then we appeal to the intermediate stage of the actual diagonalization strategy (Section 2.3.4). Again, each P -box is either eventually left finite or is stably controlled by one of the diagonalization strategies along the true path. As above, with the help of $0''$ we can see it. If the box is eventually initialized, then this means that the substructure within it is finite, and thus $0''$ can uniformly and fully reconstruct its open diagram. If it is never initialized, then suppose it is permanently declared P_τ^x for some τ of length $m \geq n$. Consider σ of length n along the true path. Then σ monitors \mathcal{M}_n , and it must be the case that the true outcome of σ is ∞ . In particular, $\sigma \hat{\infty} \subseteq \tau$, for otherwise τ would have to be eventually initialized. This means that the actual diagonalization strategy of P_τ^x will not add another point to the box unless $\mathcal{M}_{|\sigma|}$ responds by giving the previous point; see Section 2.3.4. At every such stage, P_τ^x will be a finite linear order with at most one element not labeled. We will define a *computable* isomorphism between P_τ^x in $\mathcal{M}_{|\sigma|} = \mathcal{M}_n$ and P_τ^x in \mathcal{A} by stages, as follows.

Let $P[s]$ denote the substructure of \mathcal{A} restricted to the P_τ^x -box, at stage s . Similarly, $P'[s]$ will denote the respective substructure of \mathcal{M}_n , also at stage s . Suppose we have already defined an isomorphism $f_s : P[s] \rightarrow P'[s]$. We may assume that $P[s]$ is either empty (in which case f_s is also empty) or it is a finite linear order all of whose elements are labeled using the edge relation. (See Section 2.2.2 for the description of labels.)

At the next stage s^* at which τ is visited again, we will expand $P[s]$ by one extra point b to get $P[s^*]$. For now, we will keep this extra point not labeled. Here is a “typical” configuration within $P[s^*]$:

$$\widehat{a}_0 < \dots < \widehat{a}_i < b < \widehat{a}_{i+1} < \dots < \widehat{a}_{k(s)},$$

where only the elements that carry a hat are labeled. The hatted elements and the auxiliary elements that use to label them together form the domain of f_s . Since f_s is an isomorphism onto $P'[s]$, in $\mathcal{M}_n[s^*]$ we have

$$\widehat{f_s(a_0)} < \dots < \widehat{f_s(a_i)} < \widehat{f_s(a_{i+1})} < \dots < \widehat{f_s(a_{k(s)})},$$

where the auxiliary elements labelling each of the $\widehat{f_s(a_i)}$ have the auxiliary elements labelling the respective \widehat{a}_i as their f_s -preimages. After stage s^* , τ will enter the waiting phase (see Section 2.3.4). During this substage, it will be waiting for \mathcal{M}_n (and perhaps for finitely many other structures as well) to respond. More formally, it will wait until \mathcal{M}_n reveals a point c such that

$$\widehat{f_s(a_0)} < \dots < \widehat{f_s(a_i)} < c < \widehat{f_s(a_{i+1})} < \dots < \widehat{f_s(a_{k(s)})},$$

and so that it is currently not labeled. If \mathcal{M}_n never responds or gives some other configuration, we will permanently abandon the infinitary outcome of σ . This will be done by simply freezing this P -box of \mathcal{A} . This way we will make sure $\mathcal{A} \not\cong \mathcal{M}_n$ contradicting the assumption. It is *crucial* that the configuration of labels and the

linear order uniquely define the location of b . Thus, such a c must eventually be found in \mathcal{M}_n , and it must necessarily be between $\widehat{f_s(a_i)}$ and $\widehat{f_s(a_{i+1})}$. Once c is found, at stage t , we extend f_s to f_t by setting $f_t(b) = c$.

After this is done, we add a label to b by introducing an auxiliary y and declaring $E(b, y)$ on it. This element y will not be related to any other element in the construction by $<$, and it will not be connected to anything else via the edge relation E . Thus, similarly to how we argued that c can be found for b , we could argue that a z in \mathcal{M}_n can be found for y . It is also necessary that z labels c . We extend f accordingly.

Note that f is computable. Furthermore, f_s is an isomorphism of $P[s]$ onto $P'[s]$, for every s . It follows that f is a computable isomorphism from P_τ^x of \mathcal{A} to P_τ^x in \mathcal{M}_n . The index of f can be found uniformly in $0''$.

Thus, in each case we can $\Delta_{\beta_{n-1}+1}^0$ -uniformly (in i and n) find a $\Delta_{\beta_{n-1}+1}^0$ isomorphism between P_i -boxes in \mathcal{A} and \mathcal{M}_n . \square

We conclude that all requirements are met, and thus Theorem 1.1 is proved.

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