

A NOTE ON INPUT-OUTPUT SPECTRAL DENSITIES*

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If stationary noise $x(t)$ is applied to a linear time invariant system S with transfer function $H(j\omega)$, then the mean-square value σ^2 of the output noise $z(t)$ is given by the well known formula

$$\sigma^2 = \int_0^\infty |H(j\omega)|^2 w_x(f) df \quad (1)$$

where $w_x(f)$ is the spectral density of the input process $x(t)$. Apparently (1) has no simple analog when $x(t)$ is non-stationary. Of course, one can always write, even in the non-stationary case,

$$\sigma^2(t) = \mathcal{E}z^2(t) = \int_{-\infty}^\infty \int_{-\infty}^\infty h(t-z)h(t-\zeta)\psi_x(\xi, \zeta) d\xi d\zeta$$

where $h(t)$ is the impulsive response of S and $\psi_x(\xi, \zeta) = \mathcal{E}x(\xi)x(\zeta)$ is the correlation function of $x(t)$. However, in certain practical problems the formulation embodied in (1) is more convenient.

In this note we wish to deduce a formula similar to (1) in the case where the input $y(t)$ to S is of the form

$$y(t) = g(t)x(t) \quad (2)$$

and $x(t)$ is stationary noise while the modulation function $g(t)$ is of the form

$$g(t) = \sum_{n=1}^N a_n \cos(\omega_n t + \phi_n). \quad (3)$$

Such a situation may arise, for example, when a sinusoidal signal, corrupted by additive stationary noise, is applied to a square law detector followed by a linear filter S . If $K \cos \Omega t + \eta(t)$, where $\eta(t)$ is the noise, is applied to the square law detector, one of the terms in its output will be $(2K \cos \Omega t)\eta(t)$ —which is of the form (2). Thus, for example, if one wished to compute the signal-to-noise ratio at the output of the linear filter S , it would be necessary to compute (among other terms) the variance of the output of S corresponding to the input $y(t)$. This is precisely the problem we have set ourselves.

Returning to (2) we see from the definition of $g(t)$, cf. (3), that $y(t)$ is non-stationary, but of special form. We shall show that if $z(t)$ is the output of S corresponding to this input $y(t)$, then the mean-square value of the output noise $z(t)$ is

$$\sigma^2(t) = \frac{1}{4} \int_0^\infty |M(\omega) + \{M(-\omega)\}_C|^2 w_x(f) df, \quad (4)$$

where the subscript C indicates the conjugate complex quantity,

$$M(\omega) = \sum_{n=1}^N a_n H(j(\omega + \omega_n)) e^{j(\omega_n t + \phi_n)}, \quad (5)$$

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and $H(j\omega)$ is the transfer function of S . Certain generalizations can also be obtained. We begin by writing the output noise $z(t)$ of S arising from the input $y(t)$ as

$$z(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} H(j\omega) Y(j\omega) e^{i\omega t} d\omega$$

where $Y(j\omega)$ is the Fourier transform of $y(t)$:

$$Y(j\omega) = \int_{-\infty}^{\infty} y(t) e^{-i\omega t} dt. \tag{6}$$

A difficulty arises since $Y(j\omega)$ will not exist in the classical sense unless $g(t)e^{-i\omega t}$ is absolutely integrable—which it is not. This problem, as well as the subsequent use of the Dirac delta functional could be avoided. For example, we could replace a_n in (3) by $a_n e^{-\alpha|t|}$ with $\alpha > 0$, and then investigate the value of σ^2 as α approaches zero; or we could let $a_n = 0$ for $|t| > T$ and investigate the value of σ^2 as T increases without limit. However, it is more convenient to use the approach we employ below.

The mean-square value of the output noise is given by

$$\sigma^2(t) = \mathcal{E}z^2(t) = \mathcal{E} \frac{1}{4\pi^2} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} H(j\omega) H(j\beta) Y(j\omega) Y(j\beta) e^{i\omega t} e^{i\beta t} d\omega d\beta. \tag{7}$$

Substituting the right-hand side of (6) for $Y(j\omega)$ and $Y(j\beta)$ in (7) we obtain

$$\sigma^2(t) = \frac{1}{4\pi^2} \mathcal{E} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} H(j\omega) H(j\beta) y(\xi) y(\zeta) e^{-i\omega \xi} e^{-i\beta \zeta} e^{i\omega t} e^{i\beta t} d\omega d\beta d\xi d\zeta. \tag{8}$$

Now,

$$\mathcal{E}y(\xi)y(\zeta) = g(\xi)g(\zeta)\psi_x(\xi - \zeta),$$

where ψ_x is the correlation function of $x(t)$. Thus (8) may be written as

$$\sigma^2(t) = \frac{1}{4\pi^2} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} H(j\omega) H(j\beta) e^{i\omega t} e^{i\beta t} X(\omega, \beta) d\omega d\beta, \tag{9}$$

where

$$X(\omega, \beta) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(\xi)g(\zeta)\psi_x(\xi - \zeta) e^{-i\omega \xi} e^{-i\beta \zeta} d\xi d\zeta.$$

Since

$$g(\xi)g(\zeta) = \sum_{n=1}^N \sum_{m=1}^N a_n a_m \cos(\omega_n \xi + \phi_n) \cos(\omega_m \zeta + \phi_m),$$

we may write

$$X(\omega, \beta) = \sum_{n=1}^N \sum_{m=1}^N a_n a_m X_{nm}(\omega, \beta), \tag{10}$$

where

$$X_{nm}(\omega, \beta) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \cos(\omega_n \xi + \phi_n) \cos(\omega_m \zeta + \phi_m) \psi_x(\xi - \zeta) e^{-i\omega \xi} e^{-i\beta \zeta} d\xi d\zeta.$$

If we make the change of variable $u = \xi - \zeta, v = \zeta$ with unity Jacobian in $X_{nm}(\omega, \beta)$, we obtain

$$X_{nm}(\omega, \beta) = \int_{-\infty}^{\infty} \cos(\omega_m v + \phi_m) e^{-i v (\omega + \beta)} dv \int_{-\infty}^{\infty} \cos(\omega_n u + \phi_n) \psi_x(u) e^{-i \omega u} du. \tag{11}$$

The second integral is readily evaluated as

$$\int_{-\infty}^{\infty} \cos(\omega_n u + \omega_n v + \phi_n) \psi_x(u) e^{-i\omega u} du = \frac{1}{2} w_x(f + f_n) e^{-i(\omega_n v + \phi_n)} + \frac{1}{2} w_x(f - f_n) e^{i(\omega_n v + \phi_n)}, \tag{12}$$

where $f = \omega/2\pi$, $f_n = \omega_n/2\pi$, $1 \leq n \leq N$, and

$$w_x(f) = 2 \int_{-\infty}^{\infty} \psi_x(u) e^{-i\omega u} du$$

is the spectral density of $x(t)$. Substituting (12) in (11) we obtain

$$X_{nm}(\omega, \beta) = \frac{\pi}{4} w_x(f + f_n) [\delta(\omega + \beta + \omega_n - \omega_m) e^{i(\phi_m - \phi_n)} + \delta(\omega + \beta + \omega_n + \omega_m) e^{-i(\phi_m + \phi_n)}] + \frac{\pi}{4} w_x(f - f_n) [\delta(\omega + \beta - \omega_n - \omega_m) e^{i(\phi_m + \phi_n)} + \delta(\omega + \beta - \omega_n + \omega_m) e^{-i(\phi_m - \phi_n)}]. \tag{13}$$

From (10), we may write σ^2 [cf. (9)] as

$$\begin{aligned} \sigma^2 &= \frac{1}{4\pi^2} \sum_{n,m} a_n a_m \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} H(j\omega) H(j\beta) e^{i\omega t} e^{i\beta t} X_{nm}(\omega, \beta) d\omega d\beta \\ &= \frac{1}{4\pi^2} \sum_{n,m} a_n a_m Y_{nm}, \end{aligned} \tag{14}$$

where

$$Y_{nm} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} H(j\omega) H(j\beta) e^{i\omega t} e^{i\beta t} X_{nm}(\omega, \beta) d\omega d\beta.$$

Equation (13) may now be used to write Y_{nm} as

$$\begin{aligned} Y_{nm} &= \frac{\pi}{4} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} H(j\omega) H(j\beta) e^{i\omega t} e^{i\beta t} w_x(f + f_n) [\delta(\omega + \beta + \omega_n - \omega_m) e^{i(\phi_m - \phi_n)} \\ &\quad + \delta(\omega + \beta + \omega_n + \omega_m) e^{-i(\phi_m + \phi_n)}] d\omega d\beta, \\ &\quad + \frac{\pi}{4} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} H(j\omega) H(j\beta) e^{i\omega t} e^{i\beta t} w_x(f - f_n) [\delta(\omega + \beta - \omega_n - \omega_m) e^{i(\phi_m + \phi_n)} \\ &\quad + \delta(\omega + \beta - \omega_n + \omega_m) e^{-i(\phi_m - \phi_n)}] d\omega d\beta. \end{aligned}$$

Replacing $\omega + \omega_n$ by ω in the first integral and $\omega - \omega_n$ by ω in the second integral enables us to write Y_{nm} as

$$\begin{aligned} Y_{nm} &= \frac{\pi}{4} \int_{-\infty}^{\infty} H(j(\omega - \omega_n)) H(-j(\omega - \omega_m)) e^{i(\omega_m - \omega_n)t} w_x(f) d\omega e^{i(\phi_m - \phi_n)} \\ &\quad + \frac{\pi}{4} \int_{-\infty}^{\infty} H(j(\omega - \omega_n)) H(-j(\omega + \omega_m)) e^{-i(\omega_m + \omega_n)t} w_x(f) d\omega e^{-i(\phi_n + \phi_m)} \\ &\quad + \frac{\pi}{4} \int_{-\infty}^{\infty} H(j(\omega + \omega_n)) H(-j(\omega - \omega_m)) e^{i(\omega_n + \omega_m)t} w_x(f) d\omega e^{i(\phi_m + \phi_n)} \\ &\quad + \frac{\pi}{4} \int_{-\infty}^{\infty} H(j(\omega + \omega_n)) H(-j(\omega + \omega_m)) e^{i(\omega_n - \omega_m)t} w_x(f) d\omega e^{-i(\phi_m - \phi_n)}. \end{aligned}$$

This result and (14) then imply

$$\sigma^2 = \frac{1}{4} \int_0^\infty [M(\omega)M(-\omega) + M(\omega)\{M(\omega)\}_c + \{M(-\omega)\}_c M(-\omega) + \{M(-\omega)M(\omega)\}_c] w_x(f) df, \quad (15)$$

which immediately reduces to (4).

If in place of equation (7) we start with

$$\psi_x(t; \tau) = \varepsilon z(t)z(t + \tau)$$

and employ the Wiener-Khintchine relations¹ to write

$$w_x(t; f) = 2 \int_{-\infty}^\infty \psi_x(t; \tau) e^{-j\omega\tau} d\tau$$

as the time dependent spectral density, then using the above techniques we can show that

$$w_x(t; f) = \frac{1}{4} H(j\omega) \left\{ \sum_{m=1}^N a_m [\{M(\omega - \omega_m)\}_c + M(-\omega + \omega_m)] e^{j(\omega_m t + \phi_m)} w_x(f - f_m) + \sum_{m=1}^N a_m [\{M(\omega + \omega_m)\}_c + M(-\omega - \omega_m)] e^{-j(\omega_m t + \phi_m)} w_x(f + f_m) \right\}. \quad (16)$$

It is easily seen, then, that

$$\sigma^2 = \frac{1}{2} \int_{-\infty}^\infty w_x(t; f) df$$

where σ^2 is given by (4).

¹D. G. Lampard, *Generalization of the Wiener-Khintchine theorem to nonstationary processes*, J. Appl. Phys. 25, 802-803(1954)

Correction to the paper

DUALITY IN NONLINEAR PROGRAMMING

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There is an incorrect statement of a previous result. In particular the last sentence of the Converse Duality Theorem should read:

"If $\varphi(x)$ is quadratic and if $g(x)$ is linear, then a weaker converse theorem is also true if $\varphi(x)$ is merely convex and twice continuously differentiable."