# WEIGHTED BECKMANN PROBLEM WITH BOUNDARY COSTS 

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Abstract. We show that a solution to a variant of the Beckmann problem can be obtained by studying the limit of some weighted $p$-Laplacian problems. More precisely, we find a solution to the following minimization problem:
$\min \left\{\int_{\Omega} k \mathrm{~d}|w|+\int_{\partial \Omega} g^{-} \mathrm{d} \nu^{-}-\int_{\partial \Omega} g^{+} \mathrm{d} \nu^{+}: w \in \mathcal{M}^{d}(\Omega), \nu \in \mathcal{M}(\partial \Omega),-\nabla \cdot w=f+\nu\right\}$, where $f, k$, and $g^{ \pm}$are given. In addition, we connect this problem to a formulation with Kantorovich potentials with Dirichlet boundary conditions.

1. Introduction. In this paper we consider a variant of the flow-minimization problem introduced by Beckmann in 1952 [2] as a particular case of a wider class of a convex optimization problem, of the form $\min \left\{\int H(w) \mathrm{d} x:-\nabla \cdot w=f^{+}-f^{-}\right\}$, for convex $H$. The case $H(z)=|z|$ is very interesting because of its equivalence with the Monge problem which deals with the optimal way of moving points from one mass distribution to another so that the total work done is minimized. In his work, the cost of moving one unit of mass from $x$ to $y$ is measured with the Euclidean distance $|x-y|$, even though many other cost functions were later studied.

Given two finite positive Borel measures $f^{+}$and $f^{-}$on a compact convex domain $\Omega \subset \mathbb{R}^{d}$, satisfying the mass balance condition $f^{+}(\Omega)=f^{-}(\Omega)$, then, the classical Monge optimal transportation problem [12] is the following:

$$
\begin{equation*}
\inf \left\{\int_{\Omega}|x-T(x)| \mathrm{d} f^{+}: T_{\#} f^{+}=f^{-}\right\} \tag{MP}
\end{equation*}
$$

where $T_{\#} f^{+}=f^{-} \Leftrightarrow f^{-}(A)=f^{+}\left(T^{-1}(A)\right)$ for every Borel set $A \subset \Omega$. The existence of optimal maps was addressed by many authors [1], [5], [8], [14, and [17]. Although this problem may have no solutions, its relaxed setting (which is the Kantorovitch problem

[^0][13]) always has one. The relaxed problem is the following:
\[

$$
\begin{equation*}
\min \left\{\int_{\Omega \times \Omega}|x-y| \mathrm{d} \gamma: \gamma \in \Pi\left(f^{+}, f^{-}\right)\right\}, \tag{KP}
\end{equation*}
$$

\]

where

$$
\Pi\left(f^{+}, f^{-}\right):=\left\{\gamma \in \mathcal{M}^{+}(\Omega \times \Omega):\left(\Pi_{x}\right)_{\#} \gamma=f^{+},\left(\Pi_{y}\right)_{\# \gamma}=f^{-}\right\},
$$

where $\Pi_{x}$ and $\Pi_{y}$ are the two projections of $\Omega \times \Omega$ onto $\Omega$. The authors of [15, 16] prove that the dual of (KP) is the following:

$$
\begin{equation*}
\max \left\{\int_{\Omega} u \mathrm{~d}\left(f^{+}-f^{-}\right): u \in \operatorname{Lip}_{1}(\Omega)\right\} . \tag{DP}
\end{equation*}
$$

The equality of the two optimal values implies that optimal $\gamma$ and $u$ satisfy $u(x)-$ $u(y)=|x-y|$ on the support of $\gamma$, which means that the potential $u$ decreases at the rate one as we move along the transport ray $[x, y]$ (note that the gradient of $u$ gives the direction of these transport rays). It is well known that there exists a non-negative Borel measure $\sigma$ over $\Omega$ (which is called transport density) such that ( $\sigma, u$ ) solves a particular PDE system, called the Monge-Kantorovitch system [15]:

$$
\begin{cases}-\nabla \cdot(\sigma \nabla u)=f:=f^{+}-f^{-} & \text {in } \Omega,  \tag{1.1}\\ \sigma \nabla u \cdot n=0 & \text { on } \partial \Omega, \\ |\nabla u| \leq 1 & \text { in } \Omega, \\ |\nabla u|=1 & \sigma-\text { a.e. }\end{cases}
$$

This measure $\sigma$ represents the amount of transport taking place in each region of $\Omega$, i.e., for a given Borel set $A, \sigma(A)$ stands for "how much" the transport takes place in $A$ if particles move from their origin $x$ to their destination $y$ on transport rays.

In addition, the flow $w:=\sigma \nabla u$ solves the Beckmann problem (see [15]), which is the following:

$$
\begin{equation*}
\min \left\{\int_{\Omega} \mathrm{d}|w|: w \in \mathcal{M}^{d}(\Omega),-\nabla \cdot w=f^{+}-f^{-}\right\} \tag{BP}
\end{equation*}
$$

and we have the following equalities:

$$
\min (\mathrm{BP})=\sup (\mathrm{DP})=\min (\mathrm{KP}) .
$$

An interesting variant of (KP), which is already present in [6,7,11, is to transport the mass $f^{+}$to another one $f^{-}$(which do not have a priori the same total mass) with the possibility of transporting some mass to/from the boundary, paying the transport cost that is assumed to be given by the Euclidean distance $|x-y|$ plus an extra cost $g^{-}(y)$ for each unit of mass that comes out from a point $y \in \partial \Omega$ or $-g^{+}(x)$ for each unit of mass that enters at the point $x \in \partial \Omega$. Yet, it is reasonable to consider a distance $d_{k}$ associated with a Riemannian metric $k$ (where $k$ is supposed to be positive and continuous), instead of the Euclidean distance, when we want to model a non-uniform cost for the movement (due to geographical obstacles or configurations). Recall that this distance $d_{k}$ is defined as follows:
$d_{k}(x, y):=\inf \left\{\int_{0}^{1} k(\omega(t))\left|\omega^{\prime}(t)\right| \mathrm{d} t: \omega \in \operatorname{Lip}([0,1], \Omega), \omega(0)=x, \omega(1)=y\right\} \forall x, y \in \Omega$.

Then, set

$$
\Pi b\left(f^{+}, f^{-}\right):=\left\{\gamma \in \mathcal{M}^{+}(\Omega \times \Omega):\left(\left(\Pi_{x}\right)_{\#} \gamma\right)_{\mid \Omega}=f^{+},\left(\left(\Pi_{y}\right)_{\#} \gamma\right)_{\mid \Omega}=f^{-}\right\}
$$

We minimize the quantity

$$
\begin{align*}
\min \left\{\int_{\Omega \times \Omega} d_{k}(x, y) \mathrm{d} \gamma+\int_{\partial \Omega} g^{-} \mathrm{d}\left(\Pi_{y}\right)_{\#} \gamma-\int_{\partial \Omega} g^{+} \mathrm{d}\left(\Pi_{x}\right)_{\#} \gamma\right. & : \\
& \left.\gamma \in \Pi b\left(f^{+}, f^{-}\right)\right\} \tag{KPb}
\end{align*}
$$

First of all, we assume that $g^{ \pm} \in C(\partial \Omega)$ with

$$
\begin{equation*}
g^{+}(x)-g^{-}(y)<d_{k}(x, y), \text { for all } x, y \in \partial \Omega \tag{1.2}
\end{equation*}
$$

Then, from [6], we can prove that (KPb) reaches a minimum and that its dual is the following:

$$
\begin{equation*}
\max \left\{\int_{\Omega} u \mathrm{~d}\left(f^{+}-f^{-}\right):|\nabla u| \leq k, g^{+} \leq u \leq g^{-} \text {on } \partial \Omega\right\} \tag{DPb}
\end{equation*}
$$

Note that, for this optimal transportation problem with boundary costs, the system (1.1) becomes

$$
\begin{cases}-\nabla \cdot(\sigma \nabla u)=f & \text { in } \Omega  \tag{1.3}\\ g^{+} \leq u \leq g^{-} & \text {on } \partial \Omega \\ |\nabla u| \leq k & \text { in } \Omega \\ |\nabla u|=k & \sigma \text { - a.e. }\end{cases}
$$

and, the problem (BP) becomes

$$
\begin{align*}
& \min \left\{\int_{\Omega} k \mathrm{~d}|w|+\int_{\partial \Omega} g^{-} \mathrm{d} \nu^{-}-\int_{\partial \Omega} g^{+} \mathrm{d} \nu^{+}:(w, \nu)\right. \\
&\left.\in \mathcal{M}^{d}(\Omega) \times \mathcal{M}(\partial \Omega),-\nabla \cdot w=f+\nu\right\} \tag{BPb}
\end{align*}
$$

In [8], the authors prove that a solution to (1.1) (or equivalently, to (BP)) can be constructed by studying the $p$-Laplacian equation

$$
-\nabla \cdot\left(\left|\nabla u_{p}\right|^{p-2} \nabla u_{p}\right)=f
$$

in the limit as $p \rightarrow \infty$. In this paper, we prove that a solution to (1.3) (or equivalently, to $(\mathrm{BPb})$ ) can be constructed by studying the limit as $p \rightarrow \infty$ of the following weighted $p$-Laplacian problem:

$$
\begin{cases}-\nabla \cdot\left(k^{-p}\left|\nabla u_{p}\right|^{p-2} \nabla u_{p}\right)=f & \text { in } \Omega  \tag{1.4}\\ \frac{\partial u_{p}}{\partial \mathbf{n}}=0 & \text { on }\left\{g^{+}<u_{p}<g^{-}\right\} \\ \frac{\partial u_{p}}{\partial \mathbf{n}} \geq 0 & \text { on }\left\{u_{p}=g^{+}\right\} \\ \frac{\partial u_{p}}{\partial \mathbf{n}} \leq 0 & \text { on }\left\{u_{p}=g^{-}\right\} \\ g^{+} \leq u_{p} \leq g^{-} & \text {on } \partial \Omega\end{cases}
$$

Using this approach, We also prove the following:

$$
\min (\mathrm{BPb})=\sup (\mathrm{DPb})=\min (\mathrm{KPb})
$$

This paper is organized as follows. In Section 2 we introduce the weighted $p$-Laplacian problems that we use to approximate a maximizer of ( DPb ). In Section 3, we prove the existence of a solution to (1.3). This means that we want to find a non-negative Borel measure $\sigma$ such that $\left(\sigma, u_{\infty}\right)$ solves (1.3). Finally, in Section 4 we prove that $\min (\mathrm{BPb})=\sup (\mathrm{DPb})$ and we find a minimizer to $(\mathrm{BPb})$.

## 2. Uniform estimates on the solutions of the weighted $p$-Laplacian prob-

 lems. In this section, the aim is to obtain estimates, independent of $p$, on the solution of (1.4). First of all, we note that the unique (may be up to a constant) weak solution $u_{p}$ of (1.4) is found as the minimizer of the functional$$
\mathcal{J}_{p}(u):=\frac{1}{p} \int_{\Omega} k^{-p}|\nabla u|^{p} \mathrm{~d} x-\int_{\Omega} u f \mathrm{~d} x
$$

over all $u \in W^{1, p}(\Omega), g^{+} \leq u \leq g^{-}$on $\partial \Omega$. Under the assumption (1.2), we have the following.

Proposition 2.1. Let $u_{p}$ be the solution of (1.4). Then, up to a subsequence, $u_{p} \rightarrow u_{\infty}$ uniformly as $p \rightarrow \infty$, where $u_{\infty}$ solves ( DPb ).

Proof. Set

$$
v(y):=\max _{x \in \partial \Omega}\left\{g^{+}(x)-d_{k}(x, y)\right\} \text { for all } y \in \Omega .
$$

Then, it is easy to see that $v$ is $\operatorname{Lip}_{1}$ according to the distance $d_{k}$ and then, $|\nabla v| \leq k$. In addition, (1.2) gives that

$$
g^{+} \leq v<g^{-} \text {on } \partial \Omega .
$$

From the optimality of $u_{p}$, we have

$$
\mathcal{J}_{p}\left(u_{p}\right) \leq \mathcal{J}_{p}(v) \leq \frac{|\Omega|}{p}+C
$$

where $C$ is a constant independent of $p$. As

$$
g^{+} \leq u_{p} \leq g^{-} \text {on } \partial \Omega
$$

then, it is easy to check that

$$
\left\|u_{p}\right\|_{L^{\infty}(\Omega)} \leq C(d, \operatorname{diam}(\Omega))\left\|\nabla u_{p}\right\|_{L^{p}\left(\Omega, \mathbb{R}^{d}\right)}+\|g\|_{L^{\infty}(\partial \Omega)}
$$

Hence,

$$
\begin{aligned}
\int_{\Omega} k^{-p}\left|\nabla u_{p}\right|^{p} \mathrm{~d} x & \leq p \int_{\Omega} u_{p} f \mathrm{~d} x+C p \\
& \leq C p\left(\int_{\Omega} k^{-p}\left|\nabla u_{p}\right|^{p} \mathrm{~d} x\right)^{\frac{1}{p}}+C p
\end{aligned}
$$

Yet, this implies that

$$
\left(\int_{\Omega} k^{-p}\left|\nabla u_{p}\right|^{p} \mathrm{~d} x\right)^{\frac{1}{p}} \leq(C p)^{\frac{1}{p}}
$$

and then, for $m<p$,

$$
\left(\int_{\Omega} k^{-m}\left|\nabla u_{p}\right|^{m} \mathrm{~d} x\right)^{\frac{1}{m}} \leq(C p)^{\frac{1}{p}}|\Omega|^{\frac{1}{m}-\frac{1}{p}}
$$

Hence, up to a subsequence, $u_{p} \rightharpoonup u_{\infty}$ in $W^{1, m}(\Omega)$ for all $m \in \mathbb{N}^{\star}$, and then, $u_{p} \rightarrow u_{\infty}$ uniformly in $\Omega$. In addition, we have

$$
\left(\int_{\Omega} k^{-m}\left|\nabla u_{\infty}\right|^{m} \mathrm{~d} x\right)^{\frac{1}{m}} \leq|\Omega|^{\frac{1}{m}} \text { for all } m \in \mathbb{N}^{\star}
$$

and then,

$$
\left|\nabla u_{\infty}\right| \leq k
$$

On the other hand, for any admissible function $\varphi$ in ( DPb ), we have, from the optimality of $u_{p}$, that

$$
-\int_{\Omega} u_{p} f \mathrm{~d} x \leq \mathcal{J}_{p}\left(u_{p}\right) \leq \mathcal{J}_{p}(\varphi) \leq \frac{|\Omega|}{p}-\int_{\Omega} \varphi f \mathrm{~d} x
$$

When $p \rightarrow \infty$, we infer that $u_{\infty}$ solves (DPb).
3. The limit of the weighted $p$-Laplacian problems. For all $p>d$, set

$$
w_{p}:=k^{-p}\left|\nabla u_{p}\right|^{p-2} \nabla u_{p}
$$

where $u_{p}$ is the solution of (1.4). So, the aim of this section is to study the limit as $p \rightarrow \infty$ of $\left(w_{p}\right)_{p}$. In particular, we show that $w_{p} \rightharpoonup w$ in the sense of measures and that $\left(\sigma, u_{\infty}\right)$ solves (1.3) with $\sigma:=k^{-1}|w|$.

Lemma 3.1. For all $p>d$, there exists a measure $\nu_{p}$, which is concentrated on the boundary of $\Omega$, such that

$$
\int_{\Omega} w_{p} \cdot \nabla \varphi \mathrm{~d} x=\int_{\Omega} \varphi f \mathrm{~d} x+\int_{\partial \Omega} \varphi \mathrm{d} \nu_{p} \text { for every } \varphi \in W^{1, p}(\Omega)
$$

In addition, we have

$$
\operatorname{spt} \nu_{p}^{ \pm} \subset\left\{u_{p}=g^{ \pm}\right\}
$$

Proof. Take $\varphi \in C^{\infty}(\Omega)$ with

$$
\operatorname{spt}(\varphi) \cap\left\{u_{p}=g^{ \pm}\right\}=\emptyset
$$

As $u_{p} \in C(\Omega)$, then there exists $\varepsilon_{0}>0$ such that $g^{+} \leq u_{p}+\varepsilon \varphi \leq g^{-}$on $\partial \Omega$ for all $|\varepsilon|<\varepsilon_{0}$. Yet, from the optimality of $u_{p}$, we have

$$
\mathcal{J}_{p}\left(u_{p}\right) \leq \mathcal{J}_{p}\left(u_{p}+\varepsilon \varphi\right)
$$

and when $\varepsilon \rightarrow 0$, we get

$$
\int_{\Omega} w_{p} \cdot \nabla \varphi \mathrm{~d} x=\int_{\Omega} \varphi f \mathrm{~d} x
$$

Let $\varphi^{ \pm} \geq 0$ be in $C^{\infty}(\Omega)$ with

$$
\operatorname{spt}\left(\varphi^{+}\right) \cap\left\{u_{p}=g^{-}\right\}=\emptyset
$$

and

$$
\operatorname{spt}\left(\varphi^{-}\right) \cap\left\{u_{p}=g^{+}\right\}=\emptyset .
$$

Working as above, we get

$$
\int_{\Omega} w_{p} \cdot \nabla \varphi^{+} \mathrm{d} x \geq \int_{\Omega} \varphi^{+} f \mathrm{~d} x
$$

and

$$
\int_{\Omega} w_{p} \cdot \nabla \varphi^{-} \mathrm{d} x \leq \int_{\Omega} \varphi^{-} f \mathrm{~d} x
$$

Now, it is easy to conclude the proof.
Under the assumption (1.2), we have the following.
Proposition 3.2. $w_{p} \rightharpoonup w$ and $\nu_{p} \rightharpoonup \nu$ in the sense of measures.
Proof. Set

$$
v^{+}(x):=\min _{y \in \partial \Omega}\left\{g^{-}(y)+d_{k}(x, y)\right\} \text { for all } x \in \Omega .
$$

Then, it is clear that $g^{+}<v^{+} \leq g^{-}$on $\partial \Omega$ and $\left|\nabla v^{+}\right| \leq k$. In addition, we have the following equality:

$$
\int_{\Omega} w_{p} \cdot \nabla\left(u_{p}-v^{+}\right) \mathrm{d} x=\int_{\Omega}\left(u_{p}-v^{+}\right) f \mathrm{~d} x+\int_{\partial \Omega}\left(u_{p}-v^{+}\right) \mathrm{d} \nu_{p} .
$$

Hence,

$$
\begin{aligned}
\int_{\partial \Omega}\left(v^{+}-u_{p}\right) \mathrm{d} \nu_{p}+\int_{\Omega} k^{-p}\left|\nabla u_{p}\right|^{p} \mathrm{~d} x & =\int_{\Omega} w_{p} \cdot \nabla v^{+} \mathrm{d} x+\int_{\Omega}\left(u_{p}-v^{+}\right) f \mathrm{~d} x \\
& \leq \int_{\Omega} w_{p} \cdot \nabla v^{+} \mathrm{d} x+C
\end{aligned}
$$

where $C$ is a constant independent of $p$. As $v^{+}-g^{+} \geq c>0$ on $\partial \Omega$, then, by Lemma 3.1. we get

$$
\begin{aligned}
c \int_{\partial \Omega} \mathrm{d} \nu_{p}^{+}+\int_{\Omega} k^{-p}\left|\nabla u_{p}\right|^{p} \mathrm{~d} x & \leq \int_{\Omega} k^{-(p-1)}\left|\nabla u_{p}\right|^{p-2} \nabla u_{p} \cdot k^{-1} \nabla v^{+} \mathrm{d} x+C \\
& \leq|\Omega|^{\frac{1}{p}}\left(\int_{\Omega} k^{-p}\left|\nabla u_{p}\right|^{p} \mathrm{~d} x\right)^{1-\frac{1}{p}}+C \\
& \leq\left(1-\frac{1}{p}\right) \int_{\Omega} k^{-p}\left|\nabla u_{p}\right|^{p} \mathrm{~d} x+C
\end{aligned}
$$

Finally, we infer that

$$
c \int_{\partial \Omega} \mathrm{d} \nu_{p}^{+}+\frac{1}{p} \int_{\Omega} k^{-p}\left|\nabla u_{p}\right|^{p} \mathrm{~d} x \leq C .
$$

Therefore,

$$
\int_{\partial \Omega} \mathrm{d} \nu_{p}^{+} \leq C
$$

Replacing $v^{+}$by $v^{-}$, where

$$
v^{-}(y):=\max _{x \in \partial \Omega}\left\{g^{+}(x)-d_{k}(x, y)\right\} \text { for all } y \in \Omega,
$$

we also get that

$$
\int_{\partial \Omega} \mathrm{d} \nu_{p}^{-} \leq C
$$

Yet, we have

$$
\int_{\Omega} k^{-p}\left|\nabla u_{p}\right|^{p} \mathrm{~d} x=\int_{\Omega} u_{p} f \mathrm{~d} x+\int_{\partial \Omega} u_{p} \mathrm{~d} \nu_{p}
$$

Hence, the sequence $\left(w_{p}\right)_{p}$ (resp., $\left.\left(\nu_{p}\right)_{p}\right)$ is bounded in $\mathcal{M}^{d}(\Omega)$ (resp., $\mathcal{M}(\partial \Omega)$ ) and so there exists a vector measure $w$ (resp., a measure $\nu$ supported on $\partial \Omega$ ) such that $w_{p} \rightharpoonup w$ (resp. $\nu_{p} \rightharpoonup \nu$ ) in the sense of measures.

We conclude this section by proving the existence of a solution to (1.3).
Proposition 3.3. There exists a non-negative Borel measure $\sigma$ over $\Omega$ such that ( $\sigma, u_{\infty}$ ), where $u_{\infty}$ is a maximizer for $(\mathrm{DPb})$, is a solution to (1.3).

Proof. By Lemma 3.1 and Proposition 3.2 for all $\varphi \in C^{1}(\Omega)$, we have

$$
\begin{equation*}
\int_{\Omega} \nabla \varphi \cdot \mathrm{d} w=\int_{\Omega} \varphi f \mathrm{~d} x+\int_{\partial \Omega} \varphi \mathrm{d} \nu \tag{3.1}
\end{equation*}
$$

Set

$$
\sigma:=k^{-1}|w| .
$$

Now, consider a sequence $\left(\varphi_{n}\right)_{n} \subset C^{\infty}(\Omega)$ such that $\varphi_{n} \rightarrow u_{\infty}$ uniformly and $\nabla \varphi_{n} \rightarrow$ $\nabla_{\sigma} u_{\infty}$ in $L_{\sigma}^{2}\left(\Omega, \mathbb{R}^{d}\right)$, where $\nabla_{\sigma}$ is the tangential gradient operator with respect to $\sigma$ defined in [4].

By (3.1), we get

$$
\begin{aligned}
\int_{\Omega} \nabla_{\sigma} u_{\infty} \cdot \mathrm{d} w & =\int_{\Omega} u_{\infty} f \mathrm{~d} x+\int_{\partial \Omega} u_{\infty} \mathrm{d} \nu \\
& =\int_{\Omega} u_{\infty} f \mathrm{~d} x+\int_{\partial \Omega} g^{+} \mathrm{d} \nu^{+}-\int_{\partial \Omega} g^{-} \mathrm{d} \nu^{-}
\end{aligned}
$$

Yet,

$$
\begin{aligned}
\int_{\Omega} k \mathrm{~d}|w| & \leq \liminf _{p} \int_{\Omega} k\left|w_{p}\right| \mathrm{d} x \\
& =\liminf _{p} \int_{\Omega} k^{-(p-1)}\left|\nabla u_{p}\right|^{p-1} \mathrm{~d} x \\
& \leq \liminf _{p}|\Omega|^{\frac{1}{p}}\left(\int_{\Omega} k^{-p}\left|\nabla u_{p}\right|^{p} \mathrm{~d} x\right)^{1-\frac{1}{p}} .
\end{aligned}
$$

In addition, we have

$$
\begin{aligned}
\int_{\Omega} k^{-p}\left|\nabla u_{p}\right|^{p} \mathrm{~d} x & =\int_{\Omega} u_{p} f \mathrm{~d} x+\int_{\partial \Omega} u_{p} \mathrm{~d} \nu_{p} \\
& =\int_{\Omega} u_{p} f \mathrm{~d} x+\int_{\partial \Omega} g^{+} \mathrm{d} \nu_{p}^{+}-\int_{\partial \Omega} g^{-} \mathrm{d} \nu_{p}^{-} \\
& \rightarrow \int_{\Omega} u_{\infty} f \mathrm{~d} x+\int_{\partial \Omega} g^{+} \mathrm{d} \nu^{+}-\int_{\partial \Omega} g^{-} \mathrm{d} \nu^{-}=\int_{\Omega} \nabla_{\sigma} u_{\infty} \cdot \mathrm{d} w .
\end{aligned}
$$

Finally, we get

$$
\int_{\Omega} k \mathrm{~d}|w| \leq \int_{\Omega} \nabla_{\sigma} u_{\infty} \cdot \mathrm{d} w
$$

Since $\left|\nabla u_{\infty}\right| \leq k$, hence

$$
\int_{\Omega} \nabla_{\sigma} u_{\infty} \cdot \mathrm{d} w=\int_{\Omega} k \mathrm{~d}|w|
$$

and

$$
w=\sigma \nabla_{\sigma} u_{\infty},\left|\nabla_{\sigma} u_{\infty}\right|=k \quad \sigma-\text { a.e. }
$$

4. Producing a solution to a variant of the Beckmann problem. Now, we are ready to find a solution to $(\mathrm{BPb})$. Let $w$ (resp., $\nu$ ) be the limit of $\left(w_{p}\right)_{p}$ (resp., $\left.\left(\nu_{p}\right)_{p}\right)$ as in Proposition 3.2. Then, we have the following.

Proposition 4.1. $(w, \nu)$ solves the problem $(\mathrm{BPb})$. Moreover, the minimal value of $(\mathrm{BPb})$ equals the maximal value of $(\mathrm{DPb})$.

Proof. We start from $\min (\mathrm{BPb}) \geq \sup (\mathrm{DPb})$. In order to do so, take an arbitrary function $\varphi \in C^{1}(\Omega)$ with $|\nabla \varphi| \leq k$ and $g^{+} \leq \varphi \leq g^{-}$on $\partial \Omega$. Consider that for any $(v, \chi) \in \mathcal{M}^{d}(\Omega) \times \mathcal{M}(\partial \Omega)$ with $-\nabla \cdot v=f+\chi$, we have

$$
\int_{\Omega} k \mathrm{~d}|v| \geq \int_{\Omega} \nabla \varphi \cdot \mathrm{d} v=\int_{\Omega} \varphi \mathrm{d}(f+\chi) \geq \int_{\Omega} \varphi f \mathrm{~d} x+\int_{\partial \Omega} g^{+} \mathrm{d} \chi^{+}-\int_{\partial \Omega} g^{-} \mathrm{d} \chi^{-}
$$

By an approximation argument, we can infer that

$$
\int_{\Omega} k \mathrm{~d}|v|+\int_{\partial \Omega} g^{-} \mathrm{d} \chi^{-}-\int_{\partial \Omega} g^{+} \mathrm{d} \chi^{+} \geq \sup (\mathrm{DPb})=\min (\mathrm{KPb})
$$

for any admissible $(v, \chi)$, i.e., $\min (\mathrm{BPb}) \geq \sup (\mathrm{DPb})$. Yet, by Proposition 3.3, we have

$$
\int_{\Omega} k \mathrm{~d}|w|+\int_{\partial \Omega} g^{-} \mathrm{d} \nu^{-}-\int_{\partial \Omega} g^{+} \mathrm{d} \nu^{+}=\int_{\Omega} u_{\infty} f \mathrm{~d} x
$$

Hence, $(w, \nu)$ solves $(\mathrm{BPb})$ and we have $\min (\mathrm{BPb})=\sup (\mathrm{DPb})=\min (\mathrm{KPb})$.
REMARK 4.1. Note that, from [10], we have $\sigma \in L^{1}$ as soon as $f \in L^{1}$ and $k \in C^{1,1}$, and then, the following problem:
$\min \left\{\int_{\Omega} k|w| \mathrm{d} x+\int_{\partial \Omega} g^{-} \mathrm{d} \nu^{-}-\int_{\partial \Omega} g^{+} \mathrm{d} \nu^{+}: w \in L^{1}\left(\Omega, \mathbb{R}^{d}\right), \nu \in \mathcal{M}(\partial \Omega),-\nabla \cdot w=f+\nu\right\}$ reaches a minimum.

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