STOCHASTICALLY BOUNDED SOLUTIONS OF A LINEAR NONHOMOGENEOUS STOCHASTIC DIFFERENTIAL EQUATION

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Abstract. Conditions for the existence of a stochastically bounded solution of a linear nonhomogeneous stochastic differential equation are found in the paper. The stationary and periodic cases are considered.

The qualitative behavior of solutions of stochastic differential equations has recently been studied intensively. One problem that has been of permanent interest is to find conditions for the existence of stochastically bounded solutions, especially in view of the fact that stationary and periodic solutions possess this property.

A criterion for the existence of a unique stochastically bounded solution of a linear nonhomogeneous stochastic differential equation is obtained in this paper. It turns out that the existence of a unique stochastically bounded solution depends on whether a solution of the homogeneous equation is exponentially $p$-stable for some $p > 0$ (see [3] for the definition). Note however that another condition (mean square stability) is common for problems of this kind (see [6, 7]). The main result of the paper is close to those well known in the case of deterministic systems (see, for example, [5]), and this indicates that it is definitive. We also show that the solution inherits properties of the coefficients of the equation if they are either stationary or periodic.

Consider the stochastic differential equation

$$dx(t) = (bx(t) + f(t))\,dt + \sum_{k=1}^{m} (\sigma_k x(t) + g_k(t)) \,dw_k(t),$$

where $b$ and $\sigma_k$ are real constants; $f(t), t \in \mathbb{R},$ and $g_k(t), t \in \mathbb{R},$ are bounded continuous real functions; $\sup_{t \in \mathbb{R}} \{|f(t)|, |g_k(t)|; k = 1, \ldots, m\} \leq K < +\infty; w_k(t)$ are one-dimensional independent Wiener processes, $t \in \mathbb{R}, k = 1, \ldots, m.$

A Wiener process $w(t), t \in \mathbb{R},$ is defined as a stochastic process with independent increments such that $w(0) = 0$ and $w(t) - w(s)$ is a Gaussian random variable for all $s, t \in \mathbb{R}$ such that

$$E(w(t) - w(s)) = 0, \quad E(w(t) - w(s))^2 = |t - s|.$$

In what follows we use the following flows of $\sigma$-fields:

$$\mathcal{F}_t = \sigma\{w_k(s_2) - w_k(s_1): s_1 \leq s_2 \leq t, k = 1, \ldots, m\}, \quad t \in \mathbb{R};$$

$$\mathcal{F}^t = \sigma\{w_k(s_2) - w_k(s_1): t \leq s_1 \leq s_2, k = 1, \ldots, m\}, \quad t \in \mathbb{R};$$

$$\mathcal{F}_{t-v} = \sigma\{w_k(s_2) - w_k(s_1): t - v \leq s_1 \leq s_2 \leq t, k = 1, \ldots, m\}, \quad v \geq 0.$$

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Proof of Lemma 1. Using properties of $s$

The latter equation for Lemma 1 is proved.

Along with (1) we consider the corresponding homogeneous equation

\begin{equation}
(2) \quad dh^t_s = bh^t_s dt + \sum_{k=1}^m \sigma_k h^t_s dw_k(t).
\end{equation}

The latter equation for $s \leq t$ and $h^s_s = 1$ has a solution

\[ h^s_s = \exp \left\{ \gamma (t - s) + \sum_{k=1}^m \sigma_k [w_k(t) - w_k(s)] \right\}, \quad \gamma = b - 2^{-1} \sum_{k=1}^m \sigma_k^2 \]

(see [2]). For an arbitrary $p \in \mathbb{R}$,

\begin{equation}
(3) \quad \mathbb{E}(h^s_s)^p = \exp \left\{ \left( \gamma + p 2^{-1} \sum_{k=1}^m \sigma_k^2 \right) (t - s)p \right\}.
\end{equation}

The solution $x_s(t), s \leq t$, of equation (1) can be represented in the following form:

\begin{equation}
(4) \quad x_s(t) = h^s_s \left[ x(s) + \int_s^t (h^u_s)^{-1} \left( f(u) - \sum_{k=1}^m \sigma_k g_k(u) \right) du 
\right.
\begin{aligned}
&+ \sum_{k=1}^m \int_s^t (h^u_s)^{-1} g_k(u) dw_k(u) 
\end{aligned}
\right]
\end{equation}

(see [2]). The behavior of $x_s(t)$ is determined by the integral terms in (1). Our current goal is to obtain properties of the integral terms.

Lemma 1. Assume that $\varphi(t)$ is a continuous function of $t \in \mathbb{R}$. Then the following reverse integration formula holds for stochastic integrals with $s \leq t$:

\begin{equation}
(5) \quad h^s_s \int_s^t (h^u_s)^{-1} \varphi(u) dw_k(u) = - \int_t^s h^t_u \varphi(u) dw_k(u) - \sigma_k \int_t^s h^t_u \varphi(u) du.
\end{equation}

Proof of Lemma 1. Using properties of $h^t_s$, we have that, for $\Delta = (t - s)/n, u_i = s + i\Delta, \Delta w_k(u_i) = w_k(u_{i+1}) - w_k(u_i), i = 0, \ldots, n - 1,$

\[ h^s_s \int_s^t (h^u_s)^{-1} \varphi(u) dw_k(u) = \text{l.i.p.} h^s_s \sum_{i=0}^{n-1} (h^u_s)^{-1} \varphi(u_i) \Delta w_k(u_i) \]

\[ = \text{l.i.p.} \sum_{i=0}^{n-1} h^t_{u_i} \varphi(u_i) \Delta w_k(u_i) \]

\[ = \text{l.i.p.} \sum_{i=0}^{n-1} h^t_{u_i} \left( 1 + \sum_{r=1}^m \sigma_r \Delta w_r(u_i) \right) \varphi(u_{i+1}) \Delta w_k(u_i) \]

\[ = - \text{l.i.p.} \sum_{i=0}^{n-1} h^t_{u_n-i} \varphi(u_{n-i})(w_k(u_{n-(i+1)}) - w_k(u_{n-i}))) \]

\[ - \sigma_k \text{l.i.p.} \sum_{i=0}^{n-1} h^t_{u_n-i} \varphi(u_{n-i})(-1)(\Delta w_k(u_{n-(i+1)}))^2 \]

\[ = - \int_t^s h^t_u \varphi(u) dw_k(u) - \sigma_k \int_t^s h^t_u \varphi(u) du. \]

Lemma 1 is proved. \( \square \)
Taking (5) into account one can rewrite (2) in the form

$$\lim_{s \to -\infty} \int_t^s h_u^t \varphi(u) \, du$$

exists almost surely for all $t \in \mathbb{R}$.

Proof of Lemma 3. By the Borel–Cantelli lemma it is sufficient to prove that the series

$$\sum_{n=1}^{\infty} \mathbb{P} \left\{ \int_{t-T(n+1)}^{t-Tn} h_u^t \varphi(u) \, du > 2^{-n} \right\}$$

converges for some $T > 0$. This result follows from Lemma 2 for $r = 1$. Lemma 3 is proved.

Lemma 4. Let the assumptions of Lemma 2 hold. Then the limit

$$\lim_{s \to -\infty} \int_t^s h_u^t \varphi(u) \, du$$

exists almost surely for all $t \in \mathbb{R}$. 

Proof of Lemma 4. Let the assumptions of Lemma 2 hold. Then the limit

$$\lim_{s \to -\infty} \int_t^s h_u^t \varphi(u) \, dw_k(u)$$

exists almost surely for all $t \in \mathbb{R}$.
Proof of Lemma 4. Consider the process
\[ m_k^t(v) = \int_t^{t-v} h^t_u \varphi(u) \, dw_k(u) = \int_0^{v} h^t_{t-u} \varphi(t-u) \, dw_k(u), \quad v \geq 0; \]

where \( w_k(u) = w_k(t-u) - w_k(t), \ u \geq 0. \) This is a martingale whose characteristic with respect to the flow \( F_{t-v}, \ v \geq 0, \) is given by
\[ \langle m_k^t \rangle(v) = -\int_t^{t-v} (h^t_u \varphi(u))^2 \, du = \int_0^{v} (h^t_{t-u} \varphi(t-u))^2 \, du. \]

The proof of the existence of the limit
\[ \langle m_k^t \rangle(+\infty) = \lim_{v \to +\infty} \langle m_k^t \rangle(v) = \int_0^{+\infty} (h^t_{t-u} \varphi(t-u))^2 \, du \]
is similar to that of Lemma 3. This means that the square integrable martingale \( m_k^t(v) \) is closed and therefore the limit \( \mathbb{E} \) exists for this process. Lemma 4 is proved.

\[ \square \]

**Theorem 1.** In order that, for given continuous functions \( f(t) \) and \( g_k(t), \ k = 1, \ldots, m, \) bounded on the real axis, there exist a unique stochastically bounded solution \( \tilde{x}(t) \), \( t \in \mathbb{R}, \) of equation (11) it is necessary and sufficient that \( \gamma \neq 0. \) In the case of the existence, this solution is given by
\[ \tilde{x}(t) = \begin{cases} -\int_t^t \int_0^t h^t_u f(u) \, du - \sum_{k=1}^m \int_t^t h^t_u g_k(u) \, dw_k(u), & \gamma < 0; \\
-\int_t^t \int_0^t (h^t_u)^{-1} (f(u) - \sum_{k=1}^m g_k(u)) \, du \\
-\sum_{k=1}^m \int_t^t (h^t_u)^{-1} g_k(u) \, dw_k(u), & \gamma > 0. \end{cases} \]

Moreover
\[ (9) \quad \sup_{t \in \mathbb{R}} \mathbb{E} |\tilde{x}(t)|^p < +\infty \]

for \( 0 < p < p_0. \)

Remark. The condition \( \gamma \neq 0 \) means that, given \( 0 < p < p_0, \) the solution \( h^t_s \) of equation (2) is exponentially \( p \)-stable (if \( \gamma < 0 \)) or it is exponentially \( p \)-unstable (if \( \gamma > 0 \)). This follows immediately from (3). The number \( p_0 \) is called the stability index (see [1]).

Recall that a solution \( h_s^t \) is exponentially \( p \)-stable (exponentially \( p \)-unstable), \( p > 0, \) if there exists a constant \( \lambda > 0 \) such that
\[ \mathbb{E}(h_s^t)^p \leq e^{-\lambda(t-s)}, \quad (\mathbb{E}(h_s^t)^{-p} \leq e^{-\lambda(t-s)}) \]

(see [3]).

Proof. Sufficiency. We consider the cases of \( \gamma < 0 \) and \( \gamma > 0 \) separately.

1) Let \( \gamma < 0. \) Put
\[ (10) \quad x_{-\infty}(t) = -\int_t^t h^t_u f(u) \, du - \sum_{k=1}^m \int_t^t h^t_u g_k(u) \, dw_k(u), \quad t \in \mathbb{R}. \]

The right-hand side of (10) exists for all \( t \) by Lemmas 3 and 4. Putting \( x(s) = 0 \) in (10) and approaching the limit as \( s \to -\infty, \) we prove that \( x_{-\infty}(t) \) is a solution of equation (11).

The process \( x_{-\infty}(t) \) is measurable with respect to the flow \( F_t. \)

Now we show that the process \( x_{-\infty}(t), \ t \in \mathbb{R}, \) is stochastically bounded. Since
\[ P \left\{ |x_{-\infty}(t)| > N \right\} \leq P \left\{ \left| \int_t^t h^t_u f(u) \, du \right| > N/m + 1 \right\} \]
\[ + \sum_{k=1}^m P \left\{ \left| \int_t^t h^t_u g_k(u) \, dw_k(u) \right| > N/m + 1 \right\}, \]

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it is sufficient to prove that every term in (10) is stochastically bounded. We have

\begin{equation}
\Pr\left\{ \left| \int_{t}^{\infty} (h^t u f(u))^r \, du \right| > N^r \right\} \leq L_2 N^{-p}
\end{equation}

for \( r = 1, 2, \) \( 0 < p < p_0, \) and \( L_2 = L_2(p) < +\infty, \) where the integral is defined for almost all trajectories. Indeed, by Lemma 2

\begin{align*}
\Pr\left\{ \left| \int_{t}^{\infty} (h^t u f(u))^r \, du \right| > N^r \right\} & \leq \Pr\left\{ \sum_{n=0}^{\infty} \left( \int_{t-T(n+1)}^{t-Tn} (h^t u f(u))^r \, du > N^r 2^{-(n+1)} \right) \right\} \\
& \leq \sum_{n=0}^{\infty} \Pr\left\{ \int_{t-T(n+1)}^{t-Tn} (h^t u f(u))^r \, du > N^r 2^{-(n+1)} \right\} \\
& \leq 2^p L_1 (1 - q)^{-1} N^{-p}.
\end{align*}

We also have the following inequality for the distribution of stochastic integrals:

\begin{equation}
\Pr\left\{ \left| \int_{t}^{\infty} h^t u g_k(u) \, dw_k(u) \right| > N \right\} \leq L_3 N^{-p},
\end{equation}

where \( 0 < p < p_0 \) and \( L_3 = L_3(p) < +\infty. \)

To check (13) we use the notation of Lemma 4 and put \( \varphi(u) = g_k(u). \) Then

\begin{align*}
\Pr\left\{ \left| \int_{t}^{\infty} h^t u g_k(u) \, dw_k(u) \right| > N \right\} & \leq \lim_{V \to +\infty} \Pr\left\{ \sup_{v < V} |m^t_k(v)| > N \right\} \\
& \leq \lim_{V \to +\infty} N^{-p} E \left( \sup_{v < V} |m^t_k(v)| \right)^p \\
& \leq \lim_{V \to +\infty} N^{-p} c_p E \left( m^t_k \right)^{p/2} (V) \\
& \leq N^{-p} c_p E \left( - \int_{t}^{\infty} (h^t u g_k(u))^2 \, du \right)^{p/2}
\end{align*}

for some \( c_p < +\infty \) (see [4]). It remains to show that

\[ E \left( - \int_{t}^{\infty} (h^t u g_k(u))^2 \, du \right)^{p/2} < +\infty, \quad t \in \mathbb{R}, \ 0 < p < p_0. \]

We apply inequality (12) for \( p + \delta, \delta = (p_0 - p)/2, \) \( f(u) = g_k(u), \) and \( r = 2: \)

\begin{align*}
E \left( - \int_{t}^{\infty} (h^t u g_k(u))^2 \, du \right)^{p/2} & \leq \sum_{n=0}^{\infty} 2^p (n+1) \Pr\left\{ 4^n < - \int_{t}^{\infty} (h^t u g_k(u))^2 \, du \leq 4^{n+1} \right\} \\
& \leq \sum_{n=0}^{\infty} 2^p (n+1) \Pr\left\{ 4^n < - \int_{t}^{\infty} (h^t u g_k(u))^2 \, du \right\} \\
& \leq \sum_{n=0}^{\infty} 2^p (n+1) L_2 2^{-(p+\delta)n} \leq \sum_{n=0}^{\infty} L_2 2^p 2^{-\delta n} < +\infty.
\end{align*}

Now we prove relation (9). It follows from (11), (12) for \( r = 1, \) and (13) that

\begin{equation}
\Pr\{ |x_{-\infty}(t)| > N \} \leq L_3 N^{-p},
\end{equation}
0 < p < p_0, L_3 = L_3(p) < +\infty. Using (14) for p + \delta and \delta = (p_0 - p)/2 we get
\begin{align*}
E|x_{-\infty}(t)|^p &\leq \sum_{n=0}^{\infty} 2^{p(n+1)} P\left\{2^n < |x_{-\infty}(t)| \leq 2^{n+1}\right\} \\
&\leq \sum_{n=0}^{\infty} 2^{p(n+1)} P\left\{2^n < |x_{-\infty}(t)|\right\} \\
&\leq \sum_{n=0}^{\infty} 2^{p(n+1)} L_3 2^{-(p+\delta)n} \leq \sum_{n=0}^{\infty} L_3 2^{p-\delta n} < +\infty.
\end{align*}

We have already proved that the process \(x_{-\infty}(t), t \in \mathbb{R}\), is a stochastically bounded solution of equation (1), and inequality (9) holds for it if \(\gamma < 0\). A stochastically bounded solution is unique, since
\[
P\left\{ \lim_{s \to -\infty} h_s^t = +\infty \right\} = 1.
\]

2) Let \(\gamma > 0\). We show that in this case there is no stochastically bounded solutions of (1) that are measurable with respect to the flow \(\mathcal{F}_t\). Consider relation (4). Since \(-\gamma < 0\), one can use the same method as that in Lemmas 3 and 4 and prove that the limit
\[
g(s) = \lim_{t \to -\infty} \left[ \int_s^t (h_t^u)^{-1} \left(f(u) - \sum_{k=1}^{m} \sigma_k g_k(u)\right) du + \sum_{k=1}^{m} \int_s^t (h_t^u)^{-1} g_k(u) dw_k(u) \right]
\]
exists almost surely for all \(s \in \mathbb{R}\). It follows from \(P\{\lim_{t \to -\infty} h_t^s = +\infty\} = 1\) that if \(x(s), s \in \mathbb{R}\), is stochastically bounded, then \(x(s) = g(s)\) almost surely. This means that the random variable \(x(s)\) is \(\mathcal{F}_t\)-measurable. To construct an \(\mathcal{F}_t\)-measurable stochastically bounded solution, we use a representation for the solution \(x^s(t), t \leq s\), determined by its value \(x(s)\) at the moment \(s\). Applying formula (5) to equality (1) and interchanging \(s\) and \(t\) we get
\begin{equation}
x^s(t) = (h_t^s)^{-1} \left[ x(s) + \int_s^t h_t^u f(u) du + \sum_{k=1}^{m} \int_s^t h_t^u g_k(u) dw_k(u) \right]
\end{equation}
for \(t \leq s\). Taking (5) into account we rewrite (15) as follows:
\[
x^s(t) = (h_t^s)^{-1} x(s) - \int_t^s \left( h_t^u \right)^{-1} \left(f(u) - \sum_{k=1}^{m} \sigma_k g_k(u)\right) du \\
- \sum_{k=1}^{m} \int_t^s \left( h_t^u \right)^{-1} g_k(u) dw_k(u), \quad t \leq s.
\]
Put \(x(s) = 0\). Reasoning as in the proofs of Lemmas 3 and 4 we prove the existence of the limit as \(s \to +\infty\). As a result we obtain a solution of equation (1),
\begin{equation}
x^{+\infty}(t) = - \int_t^{+\infty} \left( h_t^u \right)^{-1} \left(f(u) - \sum_{k=1}^{m} \sigma_k g_k(u)\right) du \\
- \sum_{k=1}^{m} \int_t^{+\infty} \left( h_t^u \right)^{-1} g_k(u) dw_k(u).
\end{equation}
The process \(x^{+\infty}(t)\) is \(\mathcal{F}_t\)-measurable. Similarly to the case of \(\gamma < 0\), we check that the solution \(x^{+\infty}(t), t \in \mathbb{R}\), is stochastically bounded and possesses the \(p\)th moment for \(0 < p < p_0\). Since \(P\{\lim_{t \to -\infty} (h_t^s)^{-1} = +\infty\} = 1\), the solution is unique.
To complete the proof we put
\[
\tilde{x}(t) = \begin{cases} 
  x_{-\infty}(t), & \gamma < 0; \\
  x^{+\infty}(t), & \gamma > 0.
\end{cases}
\]

The necessity is proved by contradiction. Let \( \gamma = 0 \). We show that there exist continuous and bounded functions \( f(t) \) and \( g_k(t) \), \( k = 1, \ldots, m \), such that equation (1) has no stochastically bounded solution. Consider the equation
\[
(17) \quad dx(t) = (x(t) + 1) \, dt + \sqrt{2} x(t) \, dw(t).
\]

The solution of equation (17) for \( t \geq s \) is of the form
\[
x_s(t) = \exp\left\{ \sqrt{2} w(t) \right\} \left[ x(s) + \int_0^t \exp\left\{ -\sqrt{2} w(u) \right\} \, du \right].
\]

The total time spent by the trajectory of the Wiener process \(-w(t)\) in the positive half-plane tends to \(+\infty\) as \( t \to +\infty \), whence for arbitrary \( x(s) \)
\[
\lim_{t \to +\infty} \left[ x(s) + \int_0^t \exp\left\{ -\sqrt{2} w(u) \right\} \, du \right] = +\infty
\]

almost surely and therefore in probability. Since
\[
P\left\{ \exp\left\{ \sqrt{2} w(t) \right\} \geq 1 \right\} = 1/2,
\]
we conclude that there is no stochastically bounded solutions of equation (17). Therefore \( \gamma \neq 0 \). Theorem 1 is proved.

Theorem 2. Suppose the functions
\[
f(t) = f, \quad g_k(t) = g_k, \quad k = 1, \ldots, m,
\]
in equation (1) do not depend on \( t \). A unique stationary solution of equation (1) exists if and only if \( \gamma \neq 0 \).

Theorem 3. Suppose the functions
\[
f(t), \quad g_k(t), \quad k = 1, \ldots, m,
\]
in equation (1) are continuous and periodic with period \( T \). A unique \( T \)-periodic solution of equation (1) exists if and only if \( \gamma \neq 0 \).

Proof of Theorems 2 and 3. Stationary and periodic solutions of equation (1) are stochastically bounded. Thus, to prove Theorems 2 and 3, one must check the corresponding properties of the distributions of \( x_{-\infty}(t) \) and \( x^{+\infty}(t) \). This can be done in a standard way (see [3]). Theorems 2 and 3 are proved.

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