

SLICES IN TRANSFORMATION GROUPS

BY
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1. Introduction. If (X, T, π) is a transformation group with T a compact Lie group and X a completely regular space, then it is well known (see Palais [4]) that there exists a slice at every point $x \in X$. Existence of slices facilitates the study of transformation groups since, for example, it enables the reduction of global questions about transformation groups to local ones.

In topological dynamics, transformation groups (X, T, π) are studied where T is not compact. In general circumstances like this, it is no longer true that a slice exists at each point of X . Generalizing the case when T is compact, Palais [4] showed that if (X, T, π) is a Cartan transformation group then slices still exist at each point. Finally Chu [1] showed that if (X, T, π) has certain dynamical properties, then there exists some sort of slice through each point.

We investigate what can be said further about the existence of slices in a transformation group (X, T, π) where T is not compact.

An example of a transformation group is given which does not fall into the categories studied by Palais or Chu but which nonetheless has a slice at each point. The next example has the same group and phase space with a somewhat different action and we show that there are no slices at any point. Hence, unlike the compact case, the question of existence of slices depends on more than the nature of the group and of the phase space.

Let (X, T, π) be a transformation group and H a closed subgroup of T . Then (X, H, π) is a transformation group. If S is a slice at $x \in X$ in (X, H, π) , necessary and sufficient conditions are given for S to be a slice at x in (X, T, π) . Application of this result gives existence of slices in certain non-Cartan tgs. The author especially wishes to thank the referee for suggesting Example 3, an example which illustrates one such application.

We further exhibit necessary and sufficient conditions for a slice S at x in (X, H, π) to give a slice S' at x in the transformation group (X, T, π) with S' not necessarily equal to S .

If S_1 and S_2 are two slices in (X, T, π) then in the general case their union is not again a slice, even if S_1 and S_2 are disjoint. The notion of a closed slice, somewhat more restrictive than a slice, is introduced and a method of combining closed slices, in certain transformation groups at least, is developed. In this way, if $T = VK$, semidirect product of a vector group and a compact normal subgroup, then the

existence of a slice at each point of (X, T, π) implies the existence of a global slice.

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2. Definitions and examples. A transformation group is a triple (X, T, π) where X is a Hausdorff space, T a topological group and $\pi: X \times T \rightarrow X$ a continuous map such that $(x, 1)\pi = x$ for $x \in X$ and 1 the identity of T and $((x, t)\pi, s)\pi = (x, ts)\pi$ for $t, s \in T$ and $x \in X$. To facilitate notation, xt is written for $(x, t)\pi$. The isotropy subgroup at $x \in X$, denoted T_x is equal to $\{t \in T \mid xt = x\}$. $xT = \{xt \mid t \in T\}$ is the orbit of x . The set consisting of all orbits is denoted by X/T and given the usual quotient topology. For L a closed subgroup of T , $T/L = \{Lt \mid t \in T\}$ denotes the space of right cosets. If $S \subset X$ and $F \subset T$ then $SF = \{sf \mid s \in S, f \in F\}$. If (X, T, π) and (Y, T, ρ) are two transformation groups then $f: X \rightarrow Y$ is said to be equivariant if for $t \in T, x \in X, f(xt) = [f(x)]t$.

Henceforth the term transformation group will be abbreviated tg and the tg (X, T, π) will be denoted by (X, T) provided that there is no possibility of ambiguity.

In what follows, let (X, T) be a tg and L a closed subgroup of T . If H is a subset of T and A and B are subsets of X then $H(A, B) = \{t \in H \mid At \cap B \neq \emptyset\}$.

$S \subset X$ is an L -slice in the tg (X, T) if

- (i) $SL = S$.
- (ii) $T(S, S) \subset L$.
- (iii) If U is open in T , then SU is open in X .

If $x \in X, L = T_x$ and $x \in S$ then S is said to be a slice at x .

S is a global L -slice if S is an L -slice and in addition $ST = X$. The following remark indicates that this definition of slice is equivalent to that used by Palais [4].

REMARK. S is an L -slice in the tg (X, T) if and only if there exists a continuous equivariant map $f: ST \rightarrow T/L$ such that $f^{-1}(L) = S$ and ST is open in X .

It is known that a slice exists at each point $x \in X$ of a tg (X, T) if T is a compact Lie group. Palais generalized this result to a larger class of tgs, namely to Cartan tgs.

A tg (X, T) is *Cartan* if for $x \in X$ there is a neighborhood U of x such that $T(U, U)$ is contained in a compact set.

THEOREM (PALAIS). *Let (X, T) be a tg with T a Lie group and X a completely regular space. Then (X, T) is Cartan if and only if for $x \in X, T_x$ is compact and there is a slice at x .*

In order to prove this theorem it was necessary to introduce the notion of a proper tg which is a more restrictive property than that of being Cartan.

A tg (X, T) is *proper* if for $x \in X$ there exists a neighborhood U of x such that for any $y \in X$ there is a neighborhood V of y such that $T(U, V)$ is contained in a compact set where U depends only on x and not on the choice of y .

The following examples give some indication of the complexity of the problem of determining whether slices exist in tgs.

EXAMPLE 1. Let X be the Euclidean plane and $H=K$ be the additive group of real numbers. Let $T=H \times K$, direct product. We make (X, T) a tg by defining the action of T on X to be vertical translation as follows: for $(x, y) \in X$, $(h, k) \in T$ define $(x, y)(h, k) = (x, y+h-k)$. It is easy to see that (X, T) is not a Cartan tg yet there exists a slice at every point of X .

EXAMPLE 2. Let X and T be as in Example 1. Define the action of T on X as follows: for $(h, k) \in T$, $(x, y) \in X$ define $(x, y)(h, k) = (x, y-h+kx)$. It turns out that in this tg there is no slice at any point. In fact, assuming a slice S exists at some point it can be shown that S consists of a single point which clearly gives rise to a contradiction. Observe further that the tgs (X, H) and (X, K) each have a slice at every point of X .

3. Slices in non-Cartan transformation groups. Let (X, T, π) be a tg and H a closed subgroup of T . Then (X, H, π_H) is also a tg where π_H is the restriction of π to $X \times H$. (X, H, π_H) , written (X, H) when no ambiguity results, is called a *subtransformation group*, abbreviated stg, of (X, T) .

It is possible for a stg (X, H) of (X, T) to be Cartan while (X, T) is not. Examples 1 and 2 both give instances of this possibility. Hence it is conceivable that a stg (X, H) of (X, T) may have a slice at each point while (X, T) does not. Example 2 is such an example.

In this section we provide necessary and sufficient conditions for the existence of a slice in a stg to imply the existence of a slice in the tg.

THEOREM 1. *Let (X, T) be a tg and H a closed subgroup of T . Let $x \in X$ and S be a slice at x in the stg (X, H) . Suppose in addition that ST is connected. Then the following statements are equivalent:*

- (a) (i) S is a slice at x in (X, T) .
- (ii) $T_x H$ is closed in T .
- (b) (i) $ST = SH$.
- (ii) $T(S, S) \subset T_x$.
- (c) (i) $ST_x = S$.
- (ii) $T = T_x H$.

Proof. In order to show that (a) implies (b) consider the equivariant map defining the slice S ; i.e., $f: ST \rightarrow T/T_x$. Since $T_x H$ is closed in T , it follows that if $\rho: T \rightarrow T/T_x$ is the natural projection then $\rho(H)$ is closed and $f^{-1}[\rho(H)] = SH$ is closed in ST . On the other hand since S is a slice in (X, T) , SH is open in X and a fortiori open in ST . Since ST is connected $ST = SH$. Finally (a) (i) immediately gives (b) (ii).

For the converse, one first observes by using a standard net argument (see for example the proof of Corollary 1 below) that SH closed in ST implies $T_x H$ is closed in T . To show that S is a slice at x in (X, T) , a continuous equivariant map $f: ST \rightarrow T/T_x$ is constructed by composing the following maps.

Let $i: ST \rightarrow SH$ be the identity map. That is, for $t \in T$, $s \in S$, $i(st) = s_1 h$ where $h \in H$ and $s_1 \in S$ so that $st = s_1 h$. Let $f_1: SH \rightarrow H/H_x$ be the continuous equivariant

EXAMPLE 3. Let $T=GL(n+1, \mathbf{R})/\text{center}$, the projective linear group (where the center is the collection of scalar matrices). Let $\mathbf{R}P^n$ be projective n -space represented as the collection of lines through the origin in \mathbf{R}^{n+1} . T acts smoothly on $\mathbf{R}P^n$ and so acts on its tangent bundle $X=T(\mathbf{R}P^n)$.

If x is any point of the zero section of X , say over the base point $p \in \mathbf{R}P^n$, let S be the fiber of X at p . If $H=SO(n+1) \subset T$ then S is a global slice at x in (X, H) and since $T(S, S) \subset T_x$, S is a global slice at x in (X, T) .

Since, for example T_x is isomorphic to $GL(n)/\text{center}$ and so not compact (X, T) is not Cartan. Moreover, Corollary 2 does not cover this situation since no homomorphism $f: T \rightarrow H$ as called for in the corollary exists because the only nontrivial normal subgroups of T contain H .

If (X, T) is a tg, H a closed subgroup of T and (X, H) a Cartan stg of (X, T) , then T_xH is closed in T . If the hypothesis that (X, H) is Cartan is removed, then T_xH is no longer necessarily closed in T . In what follows, the hypothesis that T_xH be closed is removed and replaced by that of H being a normal subgroup of T .

THEOREM 2. *Let (X, T) be a tg where T is connected and let H be a closed normal subgroup of T . Let $x \in X$ and S be a connected slice at x in the stg (X, H) . Then S is a slice at x in (X, T) if and only if $ST=SH$ and $T(S, S) \subset T_x$.*

Proof. That S is a slice at x in (X, T) follows directly from Theorem 1. The proof of the converse is broken up into two cases.

Case 1. If T_xH is closed in T then again Theorem 1 applies.

Case 2. T_xH is not closed. Let S be the slice at x in tgs (X, T) and (X, H) . Since H is a normal subgroup of T , T_xH is itself a subgroup. Hence T_xH is not open in T and so xH is not open in xT . Therefore S cannot be a slice at x in (X, T) and we conclude that Case 2 is impossible.

Up to this point, only the question of when a slice S in (X, H) at a point $x \in X$ is a slice at x in (X, T) has been considered. We now investigate when the existence of a slice in (X, H) implies the existence of an L -slice S' in (X, T) where S does not equal S' in general and $L \neq T_x$.

THEOREM 3. *Let (X, T) be a tg and (X, H) a stg, for H a closed subgroup of T . Let K be a closed subgroup of T . If S is an L -slice containing x in (X, H) , L a closed subgroup of H , then let $S' = SK$. If $T(S, S) \subset K$ then S' is a K -slice in the tg (X, T) .*

Proof. If we can show that U open in T implies that $S'U$ is open in X , then it is clear that S' is indeed a slice in (X, T) . Suppose therefore that U is open in T . For $t \in T$, define $U^t = U \cap Ht$. $U^t t^{-1}$ is open in H and since $U = \bigcup_{t \in T} U^t$, $SU^t t^{-1}$ is open in X and so SU is open. If U is open in T , KU is open and so $S'U$ is open in X .

COROLLARY. *Let (X, T) be a tg and (X, H) a stg for H a closed subgroup of T . Let S be a slice at x in (X, H) . If $T(S, S) = K$ is a closed subgroup of T then $S' = SK$ is a K -slice in (X, T) .*

We conclude this section with an example that shows that if the hypothesis of the corollary holds then $K=T(S, S)$ may not be closed and may not be a subgroup of T .

EXAMPLE 4. Let $T=\mathbf{R}$ and $X=\mathbf{R}$. T acts on X by translation. That is, for $t \in T$, $x \in X$, $xt=x+t$. Let $H=Z$ be the integer group and let $x=0$. It is easy to see that $S=\{x \in X \mid |x| < \frac{1}{2}\}$ is a slice at 0 in the stg (X, Z) .

$$K = \mathbf{R}(S, S) = \{r \in \mathbf{R} \mid r+s \in S, \text{ for some } s \in S\} = \{r \in \mathbf{R} \mid |r| < 1\}.$$

4. **Closed slices.** Consider the tg (X, T) as in Example 4. For each $x \in X$, $T_x=\{0\}$. Let $S_1=\{x \in X \mid |x| < \frac{1}{4}\}$ and $S_2=\{x \in X \mid |x-1| < \frac{1}{4}\}$. Since S_1 and S_2 are open intervals each of length one-half it follows that S_1 and S_2 are $\{0\}$ -slices in the tg (X, T) . $S_1 \cap S_2 = \emptyset$ yet $S_1 \cup S_2$ is not a $\{0\}$ -slice since $T(S_1 \cup S_2, S_1 \cup S_2) \neq \{0\}$. In fact, the only subgroup containing all of $T(S_1 \cup S_2, S_1 \cup S_2)$ is T itself.

So in general, the union of two slices is not again a slice. It would be desirable to have a method of combining slices in some way to obtain larger slices so that, for example, a slice at each point of a tg would imply the existence of a global slice.

The notion of a closed slice in a tg is introduced in this section in order to develop, at least in certain special cases, a process for combining slices to obtain larger ones.

S is a *closed L -slice* in the tg (X, T) , for L a closed subgroup of T if

- (i) $SL=S$.
- (ii) $T(S, S) \subset L$.
- (iii) If U is open in T , then SU is open in ST .
- (iv) ST is closed.
- (v) There exists an $S^1 \subset S$ such that S^1T is open.

S is a *closed slice at $x \in X$* if S is a closed L -slice with $L=T_x$ and $x \in S^1$. The notions of global closed slice and global slice coincide.

REMARK. Let S be a closed L -slice in (X, T) , for L a closed subgroup of T with $S^1 \subset S$ as required by the definition. Then $S^1L=S_1 \subset S$ is an L -slice. Conversely if S is an L -slice and $x \in S$ then there exists a closed L -slice $S_2 \subset S$, $x \in S_2$ if the space X/T of orbits is regular.

This section was prefaced with the remark that the union of slices is not in general a slice. In what sense then can we speak of larger slices?

If S_1 and S_2 are two slices and if S is a slice such that $ST=S_1T \cup S_2T$ then S is said to be *larger than S_1 and S_2* . This condition amply compensates for the larger slice S not being the union of S_1 and S_2 .

The first theorem gives a method for combining closed slices. The following is a preliminary lemma.

LEMMA. Let X be a normal space and (X, T) a tg with T a vector group. Let S_1 and S_2 be two closed 1-slices where 1 is the identity of T . Then there exists a closed 1-slice $S \supset S_1$ that is larger than S_1 and S_2 .

Proof. Since $S_i, i=1, 2$ are closed 1-slices, there exist continuous equivariant maps $f_i: S_i T \rightarrow T$ with $f_i^{-1}(1) = S_i$. Let $g: S_1 T \cap S_2 \rightarrow T$ be the continuous map defined by $g(s_1 t) = t^{-1}$ for $t \in T, s_1 \in S_1$. Since $S_1 T \cap S_2$ is closed, X is a normal space and T is a vector group, Tietze's Extension Theorem extends g in a continuous fashion to all of S_2 . For ease of notation, the extension will be called g also. Define $G: S_2 \rightarrow X$ by $G(s) = sg(s)$ for $s \in S_2$. G is continuous since g is. Let $S = S_1 \cup G(S_2)$. By exhibiting a continuous equivariant map $f: ST \rightarrow T$ with $f^{-1}(1) = S$ one easily shows that S is the desired larger closed 1-slice.

REMARK. In the above lemma, S is not equal to the union of S_1 and S_2 but rather to the union of S_1 and a homeomorphic image of S_2 contained in $S_2 T$.

THEOREM 4. *Let X be a normal space and (X, T) a tg where $T = KV$, semidirect product of V , a vector group and K a compact normal subgroup of T . Suppose S_1 is a closed L_1 -slice and S_2 is a closed L_2 -slice where L_1 and L_2 are closed subgroups of K . Then there is a closed K -slice $S \supset S_1$ such that S is larger than S_1 and S_2 .*

Proof. Let $\bar{T} = T/K$ and $\bar{X} = X/K$, the space of K -orbits of X . It is known that \bar{T} is a vector group and that \bar{X} is a normal space. If $p: X \rightarrow \bar{X}$ defined by $p(x) = \bar{x} = xK$ for $x \in X$ is the natural projection then p is open, continuous and closed. For $\bar{x} \in \bar{X}, \bar{t} = tK \in \bar{T}$, define $\bar{x} \cdot \bar{t} = \overline{xt} = p(xt)$. This action is well defined since K is a normal subgroup of T and so (\bar{X}, \bar{T}) is a tg since (X, T) is.

Now it follows in a straightforward manner that $p(S_1) = \bar{S}_1$ and $p(S_2) = \bar{S}_2$ are closed \bar{T} -slices in the tg (\bar{X}, \bar{T}) where \bar{T} represents the trivial subgroup of \bar{T} . The lemma applies now and we have a closed \bar{T} -slice \bar{S} with $\bar{S}\bar{T} = \bar{S}_1\bar{T} \cup \bar{S}_2\bar{T}$. Let $S = p^{-1}(\bar{S})$ and again it follows that S is a closed K -slice in the tg (X, T) with the property that $S \supset S_1$ and $ST = S_1 T \cup S_2 T$.

THEOREM 5. *Let X be a normal Lindelöf space and (X, T) a tg with $T = KV$, a semidirect product of K a compact normal Lie subgroup of T and V a vector group. Then (X, T) is a proper tg if and only if X has a global K -slice.*

Proof. Since (X, T) is a proper tg all isotropy subgroups are compact and so lie in K . From results of Palais [4], there is a slice at each point of X and X/T is regular. Consequently, if S is a slice at $x \in X$ there is a closed slice S_x at x with $S_x \subset S$. By definition of closed slice there is an $S_x^1 \subset S_x$ such that $x \in S_x^1$ and $S_x^1 T$ is open. It follows then since there is a slice at each point of X that $\{S_x^1 T\}_{x \in X}$ covers X . X is Lindelöf so that a countable subcollection $\{S_{x_i}^1 T\}_{i=1}^\infty$ still covers X . Let S_{x_i} be the closed slice corresponding to $S_{x_i}^1$. We now construct a sequence of closed K -slices whose union is a global K -slice.

Let $S(1) = S_{x_1}$. $S(2)$ is the closed slice obtained from $S(1)$ and S_{x_2} by means of Theorem 4, with $S(2) \supset S(1)$. Continuing inductively, $S(n)$ is the closed slice obtained from $S(n-1)$ and S_{x_n} with $S(n) \supset S(n-1)$. It is easy to see that for any n , $S(n)T \supset \bigcup_{i=1}^n S_{x_i}^1 T$. Define $S = \bigcup_{i=1}^\infty S(i)$. We claim that S is a global K -slice. In fact, it is clear that $ST = X$ and that there is an equivariant map $f: ST \rightarrow T/K$ with

$f^{-1}(K)=S$. We show that f is continuous. Let $t \in T$, $s \in S$ with $st \in ST$. There exists an integer i with $st \in S(i)T$ such that $S(i)T$ is a neighborhood of st . Let $f(i): S(i)T \rightarrow T/K$ be the continuous equivariant map defining the closed K -slice $S(i)$. It is clear that $f|_{S(i)T} = f(i)$ and so f is continuous on $S(i)T$, a neighborhood of st . We conclude that f is therefore continuous and the proof of this implication is complete.

For the converse statement, let S be a global K -slice. By a result of Palais [4], there exists a neighborhood U of S such that the closure of $T(U, U)$ is compact. Hence $UT = X$ and (X, T) is a proper tg.

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