

INFINITE-DIMENSIONAL WHITEHEAD AND VIETORIS THEOREMS IN SHAPE AND PRO-HOMOTOPY

BY

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ABSTRACT. In Theorem 3.3 and Remark 3.4 conditions are given under which an infinite-dimensional Whitehead theorem holds in pro-homotopy. Applications to shape theory are given in Theorems 1.1, 1.2, 4.1 and 4.2.

1. **Introduction.** Whitehead theorems in the shape theory of finite-dimensional spaces have been proved by Moszyńska [26] and by Mardešić [22], while in [7] we proved a Whitehead theorem in pro-homotopy theory for inverse systems of complexes whose dimensions are bounded. On first sight, the prospects for removing the hypotheses of finite dimension looked bleak, because of the counterexamples in [13], [11], [1, p. 35], [5] and [4]. However, by restricting ourselves just enough to avoid these counterexamples we have been able to prove reasonable theorems. We were led to them by reading the papers of Borsuk [31] and of Kozłowski and Segal [17]. For compact metric spaces (compacta) their theorem reads: a *movable compactum whose shape groups are trivial is shape equivalent to a point*. Our generalizations of this are Theorems 4.1 and 4.2 below. Confining ourselves in this introduction to the compact metric case, our theorem becomes:

THEOREM 1.1. *Let $\varphi: X \rightarrow Y$ be a pointed shape morphism between pointed connected compacta, which induces isomorphisms on the (inverse limit) shape groups. If X is movable and Y is an FANR (in the pointed sense) then φ is a pointed shape equivalence.*

This is proved by combining Theorem 4.2, below, with Theorem 5.1 of our paper [7].

Theorem 1.1 has a geometrical consequence of some interest. A map $f: X \rightarrow Y$ between compacta is called a *CE map* (or *cell-like map* or *Vietoris map*) if for each $y \in Y$, $f^{-1}(y)$ is shape equivalent to a point. If X and Y are ANR's then f must be a homotopy equivalence (see [12], [15] and the references

Received by the editors December 16, 1974 and, in revised form, May 16, 1975.

AMS (MOS) subject classifications (1970). Primary 55D99; Secondary 14F99.

⁽¹⁾ This work was done while the second-named author was visiting at the University of Georgia, whose hospitality he gratefully acknowledges. He was supported in part by N. S. F. Grant PO 38761.

therein). If X and Y are finite-dimensional compacta, f must be a shape equivalence (see [28] and [15]): Anderson (unpublished) was able to remove the requirement that X be finite dimensional. But if one also removes the requirement that Y be finite dimensional, counterexamples exist: Taylor [29] constructed a CE map from a nonmovable compactum onto the Hilbert Cube, while Keesling [14] modified this example to get a CE map from the Hilbert Cube onto a nonmovable compactum: clearly these cannot be shape equivalences. Kozłowski and Segal have gone further, by constructing [32] a CE map between movable compacta of different shapes. The theorems in this paper imply the following “infinite-dimensional Vietoris theorem” (which is proved by combining Theorem 1.1, above, with Theorem 2.3 of K. Kuperberg’s paper [18]).

THEOREM 1.2. *Let $f: (X, x) \rightarrow (Y, y)$ be a CE map between pointed connected compacta. If (X, x) is movable and (Y, y) is an FANR (in the pointed sense), then f is a pointed shape equivalence.*

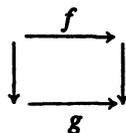
Our principal tool is a Whitehead theorem in pro-homotopy, Theorem 3.3. Roughly, it says that a weak equivalence in pro-homotopy from an inverse system $\{X_\alpha\}$ of finite-dimensional complexes to a finite-dimensional complex Y is an equivalence provided $\{X_\alpha\}$ is movable. The point is that the dimensions of the complexes X_α need not be bounded.

In Remarks 3.4 and 4.4 we indicate how the hypotheses on X and Y of Theorem 1.1 can be replaced by the hypothesis that φ be a “movable morphism.”

NOTE ADDED MAY 1, 1975. J. Dydak [39] has extended our shape theoretic results. It is not clear whether his methods can be adapted to improve our pro-homotopy results.

2. Notation, terminology and a lemma. We follow the notational conventions set out in §§2 and 3 of [7]. The principal items are listed below. Shape terminology is introduced in §4.

If C is a category, $\text{pro-}C$ denotes a certain category of inverse systems in C indexed by directed sets: for a description of the morphisms and other properties of $\text{pro-}C$ see [5] or [22]; for the original more general version see the Appendix of [1]. C_{maps} denotes the category whose objects are the morphisms of C and whose morphisms from an object f to an object g are the commutative square diagrams



in C . There is an obvious functor $\text{pro-}(C_{\text{maps}}) \rightarrow (\text{pro-}C)_{\text{maps}}$ and we say that the object $\{X_\alpha \xrightarrow{f_\alpha} Y_\alpha\}$ of $\text{pro-}(C_{\text{maps}})$ “induces” its image $\{X_\alpha\} \xrightarrow{\{f_\alpha\}} \{Y_\alpha\}$ under this functor: see §3 of [7].

We suppress bonding morphisms and the indexing directed set, denoting an object of pro- \mathcal{C} by $\{X_\alpha\}$. $\{X_\alpha\}$ is *movable* if for each α there exists $\beta \geq \alpha$ such that for all $\gamma \geq \beta$ the bond $p_{\alpha\beta}: X_\beta \rightarrow X_\alpha$ factors as $p_{\alpha\beta} = p_{\alpha\gamma} \circ r^{\beta\gamma}$ where $r^{\beta\gamma}: X_\beta \rightarrow X_\gamma$ is a morphism of \mathcal{C} . $\{X_\alpha\}$ is *uniformly movable* if for each α there exists $\beta \geq \alpha$ such that the bond $p_{\alpha\beta}$ factors as $p_{\alpha\beta} = p_\alpha \circ r^\beta$ where $r^\beta: X_\beta \rightarrow \{X_\alpha\}$ is a morphism of pro- \mathcal{C} and $p_\alpha: \{X_\alpha\} \rightarrow X_\alpha$ is the projection morphism of pro- \mathcal{C} . (\mathcal{C} is, of course, embedded as a full subcategory of pro- \mathcal{C} .)

A directed set is *closure finite* if each element has only finitely many predecessors.

Categories used include: Groups (groups and homomorphisms); T_0 (pointed connected topological spaces and pointed continuous functions); HT_0 (the homotopy category corresponding to T_0); CW_0 (pointed connected CW complexes and pointed continuous functions); H_0 (the homotopy category corresponding to CW_0); $HT_{0,pairs}$ (pointed pairs of connected spaces and pointed homotopy classes of maps); $H_{0,pairs}$ (pointed pairs of connected CW complexes and pointed homotopy classes of maps).

We call an object of pro-Groups a *pro-group*. We always suppress base points of spaces.

The definition of uniform movability becomes simpler in the case of pro-groups. A pro-group $G \equiv \{G_\alpha\}$ is (clearly) uniformly movable if and only if for each α there exists $\beta \geq \alpha$ such that the bond $p_{\alpha\beta}: G_\beta \rightarrow G_\alpha$ factors as $p_{\alpha\beta} = p_\alpha \circ r^\beta$ where $r^\beta: G_\beta \rightarrow \varprojlim G$ is a homomorphism and $p_\alpha: \varprojlim G \rightarrow G_\alpha$ is projection on the α factor.

LEMMA 2.1. *Let $G \equiv \{G_\alpha\}$ be a uniformly movable pro-group. Let H be a group, let $f: G \rightarrow H$ be a morphism of pro-Groups and let $p: \varprojlim G \rightarrow G$ be the projection morphism. If $\tilde{f} \equiv f \circ p$ is an isomorphism (of groups) then f is an isomorphism (of pro-groups).*

PROOF. The required inverse to f is $p \circ \tilde{f}^{-1}$. It is trivial that $f \circ (p \circ \tilde{f}^{-1})$ is the identity of G . To show that $(p \circ \tilde{f}^{-1}) \circ f$ is the identity of $\{G_\alpha\}$ it is enough to show that given α there exists $\gamma \geq \alpha$ such that $p_\alpha \circ \tilde{f}^{-1} \circ f_\beta \circ p_{\beta\gamma} = p_{\alpha\gamma}$. Since G is uniformly movable the above remark implies that there exist $\beta \geq \alpha$ and $r^\beta: G_\beta \rightarrow \varprojlim G$ such that $p_{\alpha\beta} = p_\alpha \circ r^\beta$. Let f be represented by homomorphisms $f_\alpha: G_\alpha \rightarrow H$. Choose $\gamma \geq \beta$ such that $f_\beta \circ p_{\beta\gamma} = f_\alpha \circ p_{\alpha\beta} \circ p_{\beta\gamma}$. Then

$$f_\beta \circ p_{\beta\gamma} = f_\alpha \circ p_\alpha \circ r^\beta \circ p_{\beta\gamma} = \tilde{f} \circ r^\beta \circ p_{\beta\gamma}.$$

So

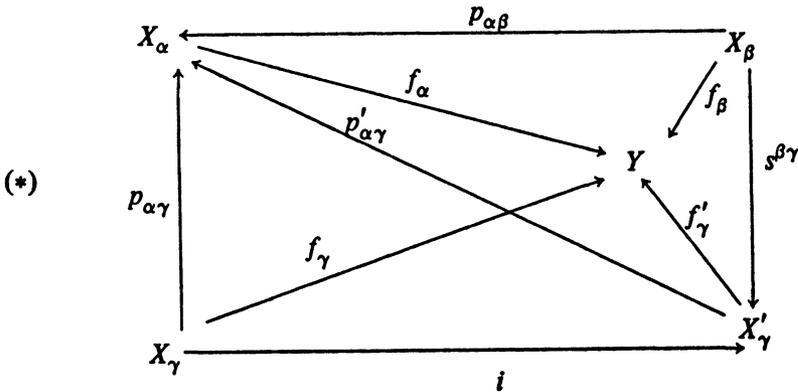
$$p_\alpha \circ \tilde{f}^{-1} \circ f_\beta \circ p_{\beta\gamma} = p_\alpha \circ r^\beta \circ p_{\beta\gamma} = p_{\alpha\beta} \circ p_{\beta\gamma} = p_{\alpha\gamma}. \quad \square$$

3. **A Whitehead theorem in pro-homotopy.** The principal result here is Theorem 3.3. Lemma 3.1 and Proposition 3.2 are the modifications needed to obtain an infinite-dimensional Whitehead theorem from [22] and [7].

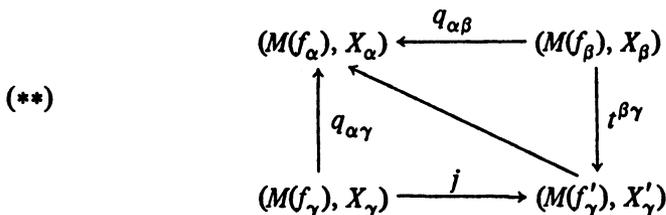
If $f: X \rightarrow Y$ is a morphism of T_0 , $M(f)$ denotes the reduced mapping cylinder of f , and X is regarded as a subset of $M(f)$ in the usual manner. Thus $(M(f), X)$ is an object of $T_{0, \text{pairs}}$. If $f \equiv \{X_\alpha \xrightarrow{f_\alpha} Y_\alpha\}$ is an object of $\text{pro-}(T_{0, \text{maps}})$ then $M(f) \equiv \{(M(f_\alpha), X_\alpha)\}$ is a well-defined object of $\text{pro-}(T_{0, \text{pairs}})$ and so induces an object of $\text{pro-}(HT_{0, \text{pairs}})$; see §3 of [7].

LEMMA 3.1. *Let $f \equiv \{X_\alpha \xrightarrow{f_\alpha} Y_\alpha\}$ be an object of $\text{pro-}(CW_{0, \text{maps}})$ whose domain $\{X_\alpha\}$ is movable in $\text{pro-}H_0$ and whose range $\{Y_\alpha\}$ is such that every Y_α is the same (pointed) complex Y , and every bond $Y_\beta \rightarrow Y_\alpha$ is the identity map. Then $\{(M(f_\alpha), X_\alpha)\}$ is movable in $\text{pro-}(HT_{0, \text{pairs}})$.*

PROOF. Let $p_{\alpha\beta}: X_\beta \rightarrow X_\alpha$ denote the appropriate bond of $\{X_\alpha\}$. Given α , there exists $\beta \geq \alpha$ such that for all $\gamma \geq \beta$ there is a pointed map $r^{\beta\gamma}: X_\beta \rightarrow X_\gamma$ with the property that $p_{\alpha\beta}$ is pointedly homotopic to $p_{\alpha\gamma} \circ r^{\beta\gamma}$. By Theorem 2.8.9 of [37], $p_{\alpha\gamma}$ may be replaced by a fibration: to be precise, there exist a pointed fibration $p'_{\alpha\gamma}: X'_\gamma \rightarrow X_\alpha$, and an inclusion $i: X_\gamma \rightarrow X'_\gamma$ as a pointed strong deformation retract, such that $p'_{\alpha\gamma} \circ i = p_{\alpha\gamma}$. Since $p'_{\alpha\gamma}$ is a fibration, there is a pointed map $s^{\beta\gamma}: X_\beta \rightarrow X'_\gamma$ such that $p_{\alpha\gamma} \circ s^{\beta\gamma} = p_{\alpha\beta}$. Letting $f'_\gamma = f_\alpha \circ p'_{\alpha\gamma}$ we have a commutative diagram in CW_0 :



From it, we obtain a commutative diagram in $T_{0, \text{pairs}}$:



j induces pointed homotopy equivalences $M(f_\gamma) \rightarrow M(f'_\gamma)$ and $X_\gamma \rightarrow X'_\gamma$; by Lemma 1 of [34], we could deduce that j induces an isomorphism in $HT_{0,pairs}$ if we knew that $(M(f_\gamma), X_\gamma)$ and $(M(f'_\gamma), X'_\gamma)$ were isomorphic in $HT_{0,pairs}$ to pointed CW pairs. It is not hard to show that $(M(f_\gamma), X_\gamma)$ has this property (f_γ is homotopic to a cellular map; use Lemma 3.9 of [7]). But it is not clear that the same is true of $(M(f'_\gamma), X'_\gamma)$. To avoid the problem, we apply the composite functor "geometric realization of the singular complex" [33], $|\cdot| \circ S: T_0 \rightarrow CW_0$, to the diagram (*), and thus obtain the following commutative diagram in $CW_{0,pairs}$, analogous to (**):

$$\begin{array}{ccc}
 (M(|Sf_\alpha|), |SX_\alpha|) & \xleftarrow{\bar{q}_{\alpha\beta}} & (M(|Sf_\beta|), |SX_\beta|) \\
 \uparrow \bar{q}_{\alpha\gamma} & \swarrow & \downarrow \bar{t}^{\beta\gamma} \\
 (M(|Sf_\gamma|), |SX_\gamma|) & \xrightarrow{\bar{j}} & (M(|Sf'_\gamma|), |SX'_\gamma|)
 \end{array}$$

where the maps are obtained from those of (**) in the obvious way. Now, Lemma 1 of [34] implies that \bar{j} induces an isomorphism in $HT_{0,pairs}$. It follows that $\bar{q}_{\alpha\beta}$ can be lifted in $HT_{0,pairs}$ through $\bar{q}_{\alpha\gamma}$, so that $\{(M(|Sf_\alpha|), |SX_\alpha|)\}$ is movable in $HT_{0,pairs}$ (where the bonds are induced by the maps $\bar{q}_{\alpha\beta}$). The argument is completed by observing that $\{(M(|Sf_\alpha|), |SX_\alpha|)\}$ is isomorphic in pro- $HT_{0,pairs}$ to $\{(M(f_\alpha), X_\alpha)\}$. To see this, observe that there is a commutative diagram in $T_{0,pairs}$

$$\begin{array}{ccc}
 (M(f_\alpha), X_\alpha) & \xleftarrow{\quad} & (M(|Sf_\alpha|), |SX_\alpha|) \\
 \uparrow q_{\alpha\beta} & & \uparrow \bar{q}_{\alpha\beta} \\
 (M(f_\beta), X_\beta) & \xleftarrow{\quad} & (M(|Sf_\beta|), |SX_\beta|)
 \end{array}$$

whose horizontal morphisms are induced by the canonical maps $|SX_\alpha| \rightarrow X_\alpha$, $|SY| \rightarrow Y$, etc. As explained above $(M(f_\alpha), X_\alpha)$ is isomorphic in $HT_{0,pairs}$ to a pointed CW pair; and $(M(|Sf_\alpha|), |SX_\alpha|)$ is itself a pointed CW pair. So, by Lemma 1 of [34], the horizontal morphisms are isomorphisms in $HT_{0,pairs}$. Since $\{M(f_\alpha)\}$ is isomorphic to a movable object, it is itself movable. \square

PROPOSITION 3.2. *Let $\{(P_\alpha, P'_\alpha)\}$ be a movable object of pro- $(H_{0,pairs})$ indexed by a closure finite directed set. Assume that each P_α is a finite-dimensional simplicial complex and that P'_α is a subcomplex of P_α . If $\{\pi_k(P_\alpha, P'_\alpha)\}$ is trivial for all k , then the "inclusion" $\{P'_\alpha\} \rightarrow \{P_\alpha\}$ is an isomorphism in pro- H_0 .*

PROOF. The proof is almost identical to that of Theorem 2 of [22]. Movability makes unnecessary the hypothesis in [22] that the dimensions of the complexes P_α be bounded. For each α choose $\beta(\alpha) \geq \alpha$ such that for every $\gamma \geq \beta(\alpha)$ there exists a morphism of $H_{0, \text{pairs}}$, $s^{\beta\gamma}: (P_\beta, P'_\beta) \rightarrow (P_\gamma, P'_\gamma)$, such that $q_{\alpha\gamma} \circ s^{\beta\gamma} = q_{\alpha\beta}$ where $q_{\lambda\mu}: (P_\lambda, P'_\lambda) \rightarrow (P_\mu, P'_\mu)$ denotes the appropriate bonding morphism. Following 2.3 of [22], assume $\beta(\alpha) \leq \beta(\bar{\alpha})$ whenever $\alpha \leq \bar{\alpha}$.

Claim 1. For each α , each pointed pair of finite-dimensional simplicial complexes (K, K') and each pointed map $\varphi: (K, K') \rightarrow (P_{\beta(\alpha)}, P'_{\beta(\alpha)})$ there exists a pointed map $\psi: K \rightarrow P'_\alpha$ such that $(\text{inclusion}) \circ \psi$ is pointedly homotopic to $(\text{bond}) \circ \varphi$ in P_α and $\psi|_{K'}$ is pointedly homotopic to $(\text{bond}) \circ \varphi|_{K'}$ in P'_α .

PROOF OF CLAIM 1. Apply Lemma 1 (§6.2) of [22] with $n + 1 = \dim K$ and $\alpha^* \geq \beta(\alpha)$: movability implies that φ can be lifted to $(P_{\alpha^*}, P'_{\alpha^*})$, hence ψ exists.

Claim 2. Given α and a pointed finite-dimensional complex L , let $\varphi_0, \varphi_1: L \rightarrow P'_{\beta(\alpha)}$ be pointed maps such that $(\text{inclusion}) \circ \varphi_0$ and $(\text{inclusion}) \circ \varphi_1$ are pointedly homotopic in $P_{\beta(\alpha)}$. Then $(\text{bond}) \circ \varphi_0$ and $(\text{bond}) \circ \varphi_1$ are pointedly homotopic in P'_α .

PROOF OF CLAIM 2. Apply Lemma 2 (§6.3) of [22] with $n = \dim L$: movability implies that φ_0 and φ_1 can be lifted to P'_{α^*} , and the claim follows.

The remainder of the proof is similar to the corresponding proof in §6.4 of [22]. Claims 1 and 2 are used in place of Lemmas 1 and 2 of [22]. \square

THEOREM 3.3. Let Y be a pointed complex, $\{X_\alpha\}$ an object of pro-CW_0 and $g: X \rightarrow Y$ a morphism of pro-H_0 . Assume Y and each X_α are finite dimensional, and that the object of pro-H_0 induced by $\{X_\alpha\}$ is movable. If $g_\#: \{\pi_k(X_\alpha)\} \rightarrow \pi_k(Y)$ is an isomorphism (in the category pro-Groups) for every k , then g induces an isomorphism of pro-H_0 .

PROOF. The proof is similar to that of Theorem 3.1 of [7]. Since Y is a complex, we may represent g by a morphism of pro-CW_0 and hence replace it by an object $f \equiv \{X'_\gamma \xrightarrow{f_\gamma} Y'_\gamma\}$ of $\text{pro-(CW}_{0, \text{maps}})$ indexed by a closure finite directed set such that: $\{X'_\gamma\}$ is movable, each X'_γ is finite dimensional, each Y'_γ is Y , and each bond of $\{Y'_\gamma\}$ is the identity map; see §3 of [7]. $f_\#: \{\pi_k(X'_\gamma)\} \rightarrow \{\pi_k(Y'_\gamma)\}$ is an isomorphism of pro-groups for each k . By Lemma 3.8 of [7], $\{\pi_k(M(f_\gamma), X'_\gamma)\}$ is trivial, where $\{M(f_\gamma)\}$ is the reduced mapping cylinder object of pro-CW_0 corresponding to f (see §3 of [7]). Each $M(f_\gamma)$ is finite dimensional. By Lemma 3.1, above, $\{(M(f_\gamma), X'_\gamma)\}$ is movable in $\text{pro-(HT}_{0, \text{pairs}})$. The rest of the proof is as in [7], except that Proposition 3.12 of [7] is replaced by the above Proposition 3.2. \square

REMARK 3.4. There is a variation on Theorem 3.3. Following [9], define $H\text{-CW}_{0, \text{maps}}$ to be the category whose objects are those of $\text{CW}_{0, \text{maps}}$ and whose

morphisms are homotopy classes of morphisms of $CW_{0, \text{maps}}$, where two morphisms (a_1, a_2) and (b_1, b_2) from $f: X \rightarrow Y$ to $f': X' \rightarrow Y'$ are defined to be *homotopic* if there is a morphism (θ_1, θ_2) from $f \times 1: X \times I \rightarrow Y \times I$ to $f': X' \rightarrow Y'$ such that θ_i is a homotopy between a_i and $b_i, i = 1, 2$. Call an object $\{X_\gamma \xrightarrow{f_\gamma} Y_\gamma\}$ of $\text{pro-}CW_{0, \text{maps}}$ *H-movable* if it induces a movable object of $\text{pro-}(HCW_{0, \text{maps}})$. Call a morphism $g: \{X_\alpha\} \rightarrow \{Y_\beta\}$ of $\text{pro-}CW_0$ *movable* if g is isomorphic in $(\text{pro-}H_0)_{\text{maps}}$ to the object of $(\text{pro-}H_0)_{\text{maps}}$ induced by such an *H-movable* $\{f_\gamma\}$. *If each X_α and each Y_β is finite dimensional, if g is movable, and if g induces isomorphisms of homotopy pro-groups, then g induces an isomorphism in $\text{pro-}H_0$.* The proof is similar to that of Theorem 3.3. The hypotheses make it possible to by-pass Lemma 3.1: clearly $\{(M(f_\gamma), X'_\gamma)\}$ is movable in $\text{pro-}(HT_{0, \text{pairs}})$.

4. **Whitehead theorems in shape.** All spaces mentioned will be paracompact Hausdorff, so our shape theory may be understood either in the sense of [21] or [27], since these two theories agree on such spaces [19], [25]. For compact Hausdorff spaces these theories agree with that of [23], and for compact metric spaces they agree with that of [3] (see [24]).

We refer the reader to [25] or to §3 of [22] for an account of how the shape theory of spaces is fully and faithfully reflected in pro-homotopy theory. In particular, if X and Y are pointed connected spaces, there is a functorial bijection between the (pointed) shape morphisms from X to Y and the morphisms of $\text{pro-}H_0$ from $\{X_\alpha\}$ to $\{Y_\beta\}$, where $\{X_\alpha\}$ and $\{Y_\beta\}$ are objects of $\text{pro-}H_0$ (unique up to isomorphism) which are “associated” with X and Y respectively. A shape morphism $\varphi: X \rightarrow Y$ is a *weak shape equivalence* if the corresponding $f: \{X_\alpha\} \rightarrow \{Y_\beta\}$ induces isomorphisms $f_\#: \{\pi_k(X_\alpha)\} \rightarrow \{\pi_k(Y_\beta)\}$ in pro-Groups for each $k \geq 1$. φ is a *very weak shape equivalence* if

$$f_\#: \varprojlim_{\alpha} \{\pi_k(X_\alpha)\} \rightarrow \varprojlim_{\beta} \{\pi_k(Y_\beta)\}$$

is an isomorphism in Groups for each $k \geq 1$. X is *movable* [resp. *uniformly movable*] if $\{X_\alpha\}$ is movable [resp. uniformly movable] in $\text{pro-}H_0$.

Every object of $\text{pro-}CW_0$ gives rise to an object of $\text{pro-}H_0$, but (apart from the case of countably indexed systems) it is unknown whether every object of $\text{pro-}H_0$ “comes from” an object of $\text{pro-}CW_0$. The Vietoris functor [27] allows one to associate objects “coming from” $\text{pro-}CW_0$ with spaces, but the complexes involved are infinite dimensional. It is for these reasons that we confine ourselves to compact Hausdorff spaces in the theorems which follow.

THEOREM 4.1. *Let X be a movable pointed connected compact Hausdorff space, let Y be pointed shape equivalent to a pointed connected CW complex*

and let $\varphi: X \rightarrow Y$ be a pointed shape morphism. If φ is a weak shape equivalence, it is a pointed shape equivalence.

PROOF. Assume Y is a CW complex. First assume Y is a finite-dimensional complex. As we shall see, no generality is lost by this.

Let $\{X_\alpha\}$ be an object of pro-CW_0 whose inverse limit is homeomorphic to X . Then $\{X_\alpha\}$ is associated with X in the sense of [25]. Let $g: \{X_\alpha\} \rightarrow Y$ be a morphism of $\text{pro-}H_0$ associated with φ in the sense of [25]. By Theorem 3.3, g induces an isomorphism in $\text{pro-}H_0$. Hence, by [25], φ is a shape equivalence.

If Y is not finite dimensional we show that it must be (pointed) homotopy equivalent to a finite-dimensional complex. Since X is compact, g may be represented by a continuous map $g_{\alpha_0}: X_{\alpha_0} \rightarrow Y$ for some α_0 , and hence g factors through a finite subcomplex K of Y . So $\tilde{g}: \{\tilde{X}_\alpha\} \rightarrow \tilde{Y}$ factors through \tilde{K} (where we have applied the pointed universal cover functor $\tilde{}$). Since g is a weak equivalence in $\text{pro-}H_0$, so also is \tilde{g} . Hence g and \tilde{g} are \natural -isomorphisms [1, §4]; therefore, they induce isomorphisms on homology pro-groups and cohomology groups with every possible coefficient bundle (see 4.4 of [1]). Since K and \tilde{K} are finite dimensional, the homology of \tilde{Y} and the cohomology of Y vanish above the dimension of K . By Theorem E of [30], Y is homotopy equivalent (hence pointed homotopy equivalent) to a finite-dimensional complex. \square

THEOREM 4.2. *Let X be a uniformly movable pointed connected compact Hausdorff space, let Y be pointed shape equivalent to a pointed CW complex, and let $\varphi: X \rightarrow Y$ be a morphism in pointed shape. If φ is a very weak shape equivalence, it is a pointed shape equivalence. Furthermore, if X is metrizable it is only necessary to assume that X is movable.*

PROOF. By Lemma 2.1, φ is a weak shape equivalence, so the conclusion follows from Theorem 4.1. For metric compacta the concepts of “movable” and “uniformly movable” coincide, by [38] (see also Theorem 4.7 of [16] and Remark 6.7 of [35]) so the last statement is justified.

REMARK 4.3. Various criteria are available for deciding if a given space Y is shape equivalent to a CW complex (as required in Theorems 4.1 and 4.2). See [10], [6], [7], [8].

REMARK 4.4. Following Remark 3.4, one may define the notion of “movable shape morphism”: the special case of “movable map” is discussed in [9]. One may then prove that *if $\varphi: X \rightarrow Y$ is a movable pointed shape morphism between metric compacta and if φ is a very weak shape equivalence, then φ is a shape equivalence.* A remark on p. 4 of [2] (incorrect as stated, but correct in the countable case) is used instead of Lemma 2.1 to show that φ is a weak shape

equivalence. Then Remark 3.4 is used instead of Theorem 3.3 to complete the proof. Compare with [36].

REMARK 4.5. If one interchanges the properties of X and Y in Theorems 4.1 and 4.2, making Y movable (or uniformly movable) and X shape equivalent to a complex, the resulting "theorems" are false. Counterexamples are given in [5]. However, if one also requires X to be compact metric (or, equivalently, to be an FANR: see [6]) we do not know a counterexample. Added in proof: there is none; see [39].

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