MODULI OF CONTINUITY IN $R^n$ AND $D \subset R^n$

BY
Z. DITZIAN

Abstract. The $r$ modulus of continuity for $f \in C(R^n)$ is expressed in terms of $r$ moduli of continuity in $n$ independent directions. Generalizations to other spaces of functions on $R^n$ or $D \subset R^n$ are also given.

1. For a function $f(x)$, $x \in R^n$, the $r$ modulus of continuity is given by

$$\omega_r(f, t) = \sup_{|h| \leq t} |\Delta_h f(x)|$$

where $\Delta_h f(x) \equiv f(x + h) - f(x)$ and $\Delta_h \equiv \Delta_h (\Delta_h^{-1})$.

Examining $\omega_r(f, t)$, one observes that

$$\omega_r(f, t) = \sup_{\epsilon \in S_{n-1}} \sup_{0 < |h| \leq t} |\Delta_{\epsilon h} f(x)|$$

In other words, the $r$ modulus of continuity is the supremum on all directional moduli of continuity which are given by

$$\omega_r(f, t, \epsilon) = \sup_{0 < |h| \leq t} |\Delta_{\epsilon h} f(x)|.$$

We will show in this paper that if $\omega_r(f, t, \epsilon_i) = O(t^\alpha)$, $\alpha < r$, for $n$ independent, $\epsilon_1, \ldots, \epsilon_n \in S_{n-1}$, then $\omega_r(f, t) = O(t^\alpha)$. It is obvious that the information for $n-1$ directions is not sufficient. It will be shown by example that $\omega_r(f, t, \epsilon_i) = O(t')$ for $n$ directions does not imply $\omega_r(f, t) = O(t')$. In fact, our "Marchaud-type" estimate will yield, in such a case, $\omega_r(f, t) = O(t' \log 1/\ell)$ and the examples will show that in the $C(R^n)$ norm this is sharp. These results remain true for function spaces defined on $R^n$ or $T^n$ (where $f$ defined on $T \equiv [-\pi, \pi]$ is $2\pi$ periodic) for which translation is an isometry and with appropriate choice of $\epsilon_1, \ldots, \epsilon_n$ to function spaces on $R^n$, for which translation is a contraction. (For $f(x)$, $x \in (R_+)^n$, or $x_i \geq 0$, we choose $\epsilon_1, \ldots, \epsilon_n \in R^n_+ \cap S_{n-1}$, where $S_{n-1}$ is the unit sphere in $R^n$.)

Finally the results will be proved in such a way that generalizations to $C(D)$ for some domains $D$ will follow as well as to $L_p(D)$ and other function spaces which are lattice compatible and satisfy some mild restrictions.

Received by the editors February 16, 1983.

1980 Mathematics Subject Classification. Primary 26B99, 46E35, 41A25; Secondary 41A63.

Key words and phrases. Moduli of continuity in $R^n$ smoothness of function spaces, multivariate semigroups of contractions.

1 Supported by NSERC grant of Canada A4816.
The key to these results is a "Marchaud-type" result for mixed differences. Mixed differences were expressed in terms of directional differences in the elegant Kemperman Lemma [3, pp. 123–124] but there an explicit use of all directional moduli of continuity is made and here only \( n \) directions are necessary.

2. Mixed differences. The main tool of our paper is a combinatorial estimate which is of the same nature as the Marchaud inequality in \( R \) that yields

\[
\omega_k(f, t) \leq c_k t^k \left( \int_0^1 \omega_{k+1}(f, u) \frac{du}{u^{k+1}} + \|f\| \right).
\]

The present result is different in content but similar in form. For example, for \( r = 2 \) in \( R^2 \) the mixed difference is given by

\[
\Delta_{he_1} \Delta_{ke_2} f(x) = f(x + he_1 + ke_2) - f(x + he_1) - f(x + ke_2) + f(x).
\]

We can now write

\[
\Delta_{he_1} \Delta_{ke_2} f(x) = \frac{1}{4} \Delta_{2he_1} \Delta_{2ke_2} f(x) = \frac{1}{8} \Delta_{he_1}^2 f(x) + \frac{3}{8} \Delta_{ke_2}^2 f(x) - \frac{1}{4} \Delta_{he_1}^2 f(x + ke_2) - \frac{1}{4} \Delta_{ke_2}^2 f(x + he_1) - \frac{1}{4} \Delta_{he_1}^2 f(x + 2ke_2) - \frac{1}{4} \Delta_{ke_2}^2 f(x + 2he_1).
\]

To use (2.3) and similar estimates for \( L_p(D) \) where \( D \) is not \( R^n \) or \( R^n_+ \), we will use the fact that we have the difference at certain points related to \( x \) rather than the maximum, but just illustrate the type of results we recall that, in \( C(R^2) \), (2.3) implies

\[
\left| \Delta_{he_1} \Delta_{he_2} f(x) \right| \leq \frac{1}{4} \left| \Delta_{2he_1} \Delta_{2ke_2} f(x) \right| + \frac{3}{4} \omega_2(f, h, k) + \frac{3}{4} \omega_2(f, k, e_2)
\]

or

\[
\left| \Delta_{he_1} \Delta_{he_2} f(x) \right| \leq \frac{3}{4} \sum_{i=0}^n 4^{-i} \left[ \omega_2(f, 2^ih, e_1) + \omega_2(f, 2^ik, e_2) \right] + 4^{-n+1} \|f\|.
\]

Choosing \( n \) so that \( 2^n h = a, 2^n k = b \), we have

\[
\left| \Delta_{he_1} \Delta_{ke_2} f(x) \right| \leq C \left\{ h^2 \int_h^\infty \frac{\omega_2(f, u, e_1)}{u^3} du + k^2 \int_k^\infty \frac{\omega_2(f, u, e_2)}{u^3} du + h^2 \|f\| \right\}.
\]

It would be nice to have a closed formula like (2.3) for higher differences but I found such formulae only for \( r = 2, 3 \) and \( 4 \), and the estimate for \( r = 3, 4 \) would not
imply as good a result for a finite domain $D$ and for $R^n_+$ as that of $r = 2$ above or
the general case below.

We define $E(h)f(x) = f(x + h)$ and state our result for mixed differences.

**Theorem 2.1.** For a bounded function $f(x)$ defined on $x + B$ where $B$ is the
parallelepiped spanned by $a_i e_i, \Sigma_{i=1}^n k_i = r$, $k_i \geq 0$, and $2^p h_i = a_i$, we have

\[
|\Delta_{h_1 e_1} \cdots \Delta_{h_n e_n} f(x)| \leq C \left( \sum_{i=1}^n \left( \frac{h_i}{a_i} \right)^r A(a_1, \ldots, a_n) |f(x)| \right)
+ \sum_{i=1}^n \sum_{l=0}^{p-N} 2^{-lr} A_i(M2^l h_1, \ldots, M2^l h_n) \Delta_{2^l h_i e_i} f(x)|
\]

where $a_i = h_i = 0$ if $k_i = 0$, $N$ and $M$ are integers which depend only on $r$ and
$(k_1, \ldots, k_n)$, and $A_i$ is given by

\[
A_i(\eta_1, \ldots, \eta_n) = \sum_{j} w_{ij} E\left( \sum_{l} h_i e_i \right)
\]

where $w_{ij} \geq 0$, $\Sigma_j w_{ij} = 1$ and $0 \leq h_i \leq \eta_i$. Neither $A_i(\cdots)$ nor $C$ depend on $f$ or $x$.

**Remark 2.2.** (a) If the interest were just in showing that $\omega(f, t, e_i) = O(t^\alpha)$
implies $\omega(f, t) = O(t^\alpha)$ for $\alpha < r$, we could prove the theorem with only 2 dimen-
sions and the rest would follow easily.

(b) If the interest were just in $R^n$, $T^n$ or $R^n_+$ the expression would be simplified by
dropping the averages (and writing maxima of the differences instead). The same is
true for the theorem on $C(D)$, $D \subset R^n$, but not for $L_p(D)$, for example.

**3. Mixed differences; proof of the result.** In this section we will prove Theorem 2.1
in the general form that will be the basis for our results in later sections.

**Proof of Theorem 2.1.** We recall that in proving the one-dimensional
Marchaud-type inequality (see Timan [6, p. 105]) one has, for $x$ and $h$ in $R$,

\[
\Delta_{2h}^k f(x) - 2^k \Delta_{h}^k f(x) = \sum_{\mu=0}^{k-1} \sum_{\nu=\mu+1}^k \binom{k}{\mu} \Delta_{h}^{k+1} f(x + \nu h).
\]

We can, with no change in the proof, replace $x \in R$ by $x \in R^n$, and $h \in R$ by $he$, $e \in S_{n-1}$, and have
To estimate $\Delta_{h_1,e_1}^k \cdots \Delta_{h_n,e_n}^k f(x)$ we may proceed using (3.2) as long as $f$ is defined on $x + \sum p_j h_j e_j$ for the appropriate $p_j h_j e_j$ which will be guaranteed by the condition that $f$ is defined on $x + B$. We write, for $r = k_1 + \cdots + k_n$,

$$
|\Delta_{h_1,e_1}^k \cdots \Delta_{h_n,e_n}^k f(x)| \leq 2^{-k_1} |\Delta_{h_1,e_1}^k \Delta_{h_2,e_2}^k \cdots \Delta_{h_n,e_n}^k f(x + v h_1 e_1)|
$$

$$
+ \frac{1}{2} k_1 \sum_{p=0}^{k_1-1} w_p(1) |\Delta_{h_1,e_1}^{k_1+1} \Delta_{h_2,e_2}^k \cdots \Delta_{h_n,e_n}^k f(x + v h_1 e_1)|
$$

$$
\leq \cdots \leq 2^{-r} |\Delta_{2h_1,e_1}^k \cdots \Delta_{2h_n,e_n}^k f(x)|
$$

$$
+ \sum_{j=1}^n \frac{1}{2} k_j \sum_{p=0}^{k_j-1} w_p(j) \left( \prod_{i=1}^{j-1} 2^{-k_i} \Delta_{2h_i,e_i}^k \right) \left( \prod_{i=j+1}^n \Delta_{2h_i,e_i}^k \right) |\Delta_{h_i,e_i}^{k_j+1} f(x + v h_i e_i)|.
$$

where $w_p(j) \geq 0$ and $\sum_{p=0}^{k_j-1} w_p(j) = 1$ since

$$
\sum_{p=0}^{k_j-1} \sum_{\mu=p+1}^{k_j-1} \left( \begin{array}{c} k_j \\ \mu \end{array} \right) = k_j 2^{k_j-1}.
$$

Continuing the above process by starting from $\prod_{j=1}^n \Delta_{2h_i,e_i}^k f(x)$ and later from $\prod_{j=1}^n \Delta_{2h_i,e_i}^k f(x)$, we have

$$
(3.3) \quad |\Delta_{h_1,e_1}^k \cdots \Delta_{h_n,e_n}^k f(x)| \leq \sum_{j=0}^{p-N} 2^{-r} \left( \prod_{i=1}^{j-1} 2^{-k_i} \Delta_{2h_i,e_i}^k \right) \left( \prod_{i=j+1}^n \Delta_{2h_i,e_i}^k \right) |\Delta_{h_i,e_i}^{k_j+1} f(x + v 2 h_i e_i)|
$$

$$
+ 2^{-(p-N)r} 2^{||(f)}|.
$$

We need to choose $N$ such that $f(x)$ is defined for

$$
x + \{(k_j + 1) + (k_j - 1)\} 2^j h_j e_j
$$

or

$$
2 k_j 2^{p-N} h_j < a_j,
$$

but in order to continue our estimate, we choose $2 k_j 2^{p-N} h_j < 2 r 2^{p-N} h_j < a_j / L + 1$ where $L = n(r - 2) + 1$ and therefore $2^{-(p-N)r} 2^r \leq C(h_j / a_j)^r$ where $C$ does not
depend on \( f, a_j \) or \( h_j \). We have completed the first step in our proof that has \( L \) similar steps where \( L = n(r - 2) + 1 \). In fact, for the case \( r = 2 \) we can deduce our theorem from (3.3) since for \( k_j \neq 0, k_j + 1 = 2 \) and we have

\[
|\Delta_{2\alpha h,e_i} \Delta_{h,e}^2 f(x)| \leq 2A(\cdot, \ldots, \cdot)|\Delta_{h,e}^2 f(x)|.
\]

We observe that in (3.3) we expressed mixed differences by sums of mixed differences of higher order by 1. The induction hypothesis is that after \( K \) steps we have the estimate

\[
\begin{align*}
(3.4) \quad |\Delta_{h, e_1}^{k_1} \cdots \Delta_{h, e_n}^{k_n} f(x)| & \leq C_K \sum_{k_i \neq 0} \left( \frac{a_i}{h_i} \right)^r A(a_1, \ldots, a_n) |f(x)| \\
+ & C_K \sum_{l=0}^{p-N} 2^{-l} \sum_{\xi \in D(K)} A_s(M^2 h_1 e_1, \ldots, M^2 h_n e_n) \left| \prod_{i=1}^n \Delta_{h, e_i}^{k_i} f(x) \right| \\
+ & C_K \sum_{l=0}^{p-N} 2^{-l} \sum_{k_i \neq 0} A_s(M^2 h_1 e_1, \ldots, M^2 h_n e_n) \left| \Delta_{h, e_i}^{k_i} f(x) \right|
\end{align*}
\]

\[
\equiv I(1) + I(2) + I(3),
\]

where \( N \) is such that the points in \( A_i(\cdot) | \prod_{i=1}^n \Delta_{h, e_i}^{k_i} f(x) | \) satisfy \( y \in x + (K + 1)B/(n(r - 2) + 2) \), and \( D(K) \) is all \( s = (s_1, \ldots, s_n) \) such that \( s_j = 0 \) if \( k_j = 0 \), \( s_1 + \cdots + s_n = r + K \) and \( s_j < r \). We will now show that after \( K + 1 \) steps we have a similar estimate with \( K + 1 \) replacing \( K \). We have to estimate only \( I(2) \). We estimate \( \prod_{i=1, k_i \neq 0} n \Delta_{h, e_i}^{k_i} f(x) | \) in very much the same way as (3.3) was estimated where \( s_j \) replaces \( k_j \), \( r + K \) replaces \( r \), and \( 2^l h_i \) replaces \( h_i \). Instead of the above expression at \( x \) we have really an average of the expressions of this type at finitely many points which because of previous choice belong to

\[
x + (K + 1)B/(n(r - 2) + 2).
\]

We can now write

\[
\prod_{i=1, k_i \neq 0}^n \Delta_{h, e_i}^{k_i} f(x) \leq C \sum_{m=0}^{p-l-N} 2^{-m(K+r)} \sum_{j=1}^n \frac{1}{2^j} \sum_{\nu=0}^{s_j-1} w_s(j) \\
\times \left( \prod_{i=1}^{j-1} 2^{-5}s_{i,s_{i+1} h_1 e_1} \right) \left( \prod_{i=j+1}^n \Delta_{h, e_i}^{k_i} f(x) + \nu 2^{l+m} h_j e_j \right) \\
+ 2^{-(p-N-l)(r+K)||f||}.
\]
We sum the estimate above for terms of the type \( A(\cdots) \prod_{i=1}^{n} k_i \neq 0 \Delta_{2h_i}^{s_i} f(x) \) for all \( l \) in (3.4) and one particular sequence \((s_1, \ldots, s_n)\) and have, using \( K + r > r \), the choice of \( N \) and \( t = m + l \),

\[
\sum_{l=0}^{p-N} 2^{-l} A(M_2h_1, \ldots, M_2h_n) \prod_{k_i \neq 0}^{n} \Delta_{2h_i}^{s_i} f(x) \leq \sum_{l=0}^{p-N} 2^{-l(2-(p-N-l)(r+K))} A(a_1, \ldots, a_n) |f(x)| + C \sum_{i=0}^{p-N} 2^{-tr} \sum_{m=0}^{t} 2^{-mK} \sum_{j=1}^{n} A_j(M_2h_1, \ldots, M_2h_n) \\
\times \left( \prod_{i=1}^{j-1} \Delta_{2^{2i+1}h_i}^{s_i} \right) \left( \prod_{i=j+1}^{n} \Delta_{2^{2i+1}h_i}^{s_i} \right) \Delta_{2^{2r}h_r, \epsilon_r}^{s_r} f(x) \leq C_1 \left( \frac{h_j}{a_j} \right)^r A(a_1, \ldots, a_n) |f(x)| + C \sum_{i=0}^{p-N} 2^{-ir} \sum_{j=1}^{N} A_j(M_2h_1, \ldots, M_2h_n) \\
\times \left( \prod_{i=1}^{j-1} \Delta_{2^{2i+1}h_i}^{s_i} \right) \left( \prod_{i=j+1}^{n} \Delta_{2^{2i+1}h_i}^{s_i} \right) \Delta_{2^{2r}h_r, \epsilon_r}^{s_r} f(x) = J(1) + J(2).
\]

\( J(2) \) contains elements of the type \( I(2) \) of (3.4) for \( K + 1 \) (instead of \( K \)) but in the case \( s_j + 1 = r \) for some \( j \) the term in question would belong to those of type in \( I(3) \), we separate them accordingly and obtain (3.4) for \( K + 1 \).

In the step \( L = n(r - 2) + 1 \) we do not have any term left representing the analog of \( I(2) \) in (3.4), as \( \sum s_i = r + n(r - 2) + 1 = n(r - 1) + 1 \) and at least one of the \( s_i \) has to be \( r \), and therefore the term would belong anyway to \( I(3) \), and we complete our proof.

4. Directional differences in \( C(R^n) \), \( C(T^n) \) and \( C(R^n_+ \). In this section we state and prove the result in \( C(R^n) \), \( C(T^n) \) and \( C(R^n_+ ) \) as corollaries of Theorem 2.1.

**Theorem 4.1.** Let \( e \) be any direction in \( R^n \) or \( T^n \) and \( e_1, \ldots, e_n \) any \( n \) independent vectors that belong to \( S_{n-1} \). Then for \( f \in L_\infty(R^n) \) or \( f \in L_\infty(T^n) \), we have

\[
(4.1) \quad \omega_t(f, t, e) \leq C t^\nu ||f|| + C \sum_{i=1}^{n} t' \int_{t}^{t'} \omega_t(f, u, e_i) \frac{du}{u^{t' + 1}}
\]

and \( C \) does not depend on \( f \).

We observe that the condition in the theorem is \( f \in L_\infty(R^n) \) not \( f \in C(R^n) \) but for \( \omega_t(f, u, e_i) = o(1), u \to 0 + \), more than just \( f \in C(R^n) \) is implied.

The situation on \( L_\infty(R^n_+ ) \) is somewhat more complicated; we define \( \omega_t(f, t, e) \equiv \operatorname{Sup}_{0 < h \leq \epsilon, \epsilon < x + rh \in R^n_+ } |\Delta_{2h}^r f(x)| \) and can state
Theorem 4.2. Let \( e \in S_{n-1} \) and \( e_1, \ldots, e_n \) any \( n \) independent vectors that belong to \( S_{n-1} \cap R^n_+ \), then

\[
\omega_c(f, t, e) \leq C \left( t^r \|f\| + \sum_{i=1}^n t^r \int_0^1 \omega_c(f, \bar{h}, e_i) \frac{du}{u^{r+1}} \right) \equiv I(t).
\]

Moreover,

\[
\text{Sup}_0 < h, \leq t \text{ Sup}_x \left| \prod_{i=1}^n \Delta^k_{h_i, e_i} f(x) \right| \leq I(t) \quad \text{where} \quad \sum k_i = r
\]

and \( C \) does not depend on \( f \) or \( x \) (but does depend on \( r, n \) and for (4.2) also on \( e_1 \cdot \cdot \cdot e_n \)).

Remark 4.3. We prove Theorems 4.1 and 4.2 directly rather than use the result for \( C(D) \), because this simpler situation is easier to generalize to other spaces, and the result is on \( R^n \) or \( R^n_+ \) rather than on \( D \subset D \).

Proof of Theorems 4.1 and 4.2. Conditions of our theorems would imply that, for all \( x \) in the domain, \( x + 2 \alpha e_i \) is also in the domain for \( \alpha > 0 \) (the domain being \( R^n, T^n \) or \( R^n_+ \)). We choose \( \alpha = 1 \) and proceed recalling

\[
A(M^{2h_1}_1, \ldots, M^{2h_n}_n) |\Delta^2_{h_i, e_i} f(x)| \leq \omega_c(f, 2^i h_i, e_i)
\]

and using monotonicity of \( \omega_c(f, u, e_i) \) and of \( u \) to deduce

\[
\sum_{i=0}^{p-N} 2^{-i} A(M^{2h_1}_1, \ldots, M^{2h_n}_n) |\Delta^2_{h_i, e_i} f(x)| \leq \sum_{i=0}^{p-N} 2^{-i} \omega_c(f, 2^i h_i, e_i)
\]

\[
= h_i \sum_{i=0}^{p-N} \omega_c(f, 2^i h_i, e_i) \frac{2^i h_i}{(2^i h_i)^{r+1}} 2^i h_i = h_i \int_{h_i}^{2^i h_i} \omega_c(f, u, e_i) \frac{du}{u^{r+1}}.
\]

Therefore (2.6) implies (4.3) for \( L \infty(R^n), L \infty(T^n) \) and \( L \infty(R^n_+) \). To prove (4.1) we write \( e = \sum \alpha_i e_i \) and recall \( E(y)f(x) = f(x + y) \).

\[
\Delta_{h e} f(x) = (E(h(\alpha_1 e_1 + \alpha_2 e_2 + \cdots + \alpha_n e_n)) - I)^{\tau} f(x)
\]

\[
= \left\{ E(h(\alpha_1 e_1) - 1) + E(h(\alpha_2 e_2) - 1) \right. \cdots + \left. E(h(\alpha_n e_n) - 1) \right\}^{\tau} f(x)
\]

which is a finite sum of elements of the type \( E(y) \prod_i \Delta_{\alpha_i e_i} \), where \( \Sigma k_i = r \) and \( y - x = \sum \beta_i e_i \) with \( \beta_i \) between zero and \( \alpha_i h_i \), which concludes the proof of Theorem 4.1.

In the proof of Theorem 4.2 we have already shown that (4.3) follows Theorem 2.1 and the argument above, but for the estimate (4.2) we have to be more careful as the above procedure may take us out of \( R^n_+ \). (That could not happen if \( R^n_+ \) is formed by \( \Sigma \alpha_i e_i \) for \( \alpha_i \geq 2 \).) Let us, therefore, rearrange \( e \), so that in \( \Sigma \alpha_i e_i = e \), \( \alpha_i > 0 \) for \( i < j \), and \( \alpha_i < 0 \) for \( i > j \). Then \( y = x + kh \sum_{i=1}^j \alpha_i e_i + \sum_{i=j+1}^n h_i \alpha_i e_i \) for \( l_i < k \) is in \( R^n_+ \) since \( x + khe \in R^n_+ \) and

\[
y = x + khe - \sum_{i=j+1}^n (k - l_i) \alpha_i he_i = x + khe + \sum_{i=j+1}^n \beta_i he_i, \quad \beta_i > 0.
\]
We now set

\[(E(he) - I)' = \left( \left[ E(he) - E(e^*_e) \right] + \left[ E(e^*_e) - I \right] \right)\]

where \(e^*_e = \sum_{i=1}^{\infty} \alpha_i e_i\) and

\[(E(he) - I)' = \sum_{k=0}^{r} \binom{r}{k} \left[ E(e^*_e) - I \right]^{k-r} \left[ E(he) - I \right] E(he^*_e).

On each of the terms \((E(e^*_e) - I)^{k-r}\) and \((E(h\sum_{i=j+1}^{n} \alpha_i e_i) - I)E(khe^*_e)\), we follow the earlier procedure, but since \(x\) and \(x + khe\) belong to \(R^n_+\), so does \(x + khe^* + h\sum_{i=j+1}^{n} \alpha_i l_i e_i\) for \(l_i < k\).

Remark 4.4. One could have used integrals in a similar way to that of [3 or 4], as will be explained in §7, to overcome the above minor combinatorial difficulty. This would be more standard but somewhat more complicated. If \(e_i\) are those forming \(R^n_+\), that difficulty would not have arisen. In §7 we use the present technique where we cannot use Stekelov-type integrals and vice versa.

5. Moduli of continuity in other spaces and for semigroups. The theorem of the last section can be extended to multivariate semigroups of contractions on a Banach space. \(T(t)\) is a semigroup of contractions on a Banach space \(B\) if \(T(t)f\) and \(f\) belong to \(B\) for \(t \in R^n_+\), \(t \in R^n\) or \(t \in T^n\), \(T(t_1 + t_2)f = T(t_1)T(t_2)f\), and \(\|T(t)f\| \leq \|f\|\). (From the last mentioned it follows that if \(t \in R^n\) or \(t \in T^n\), we have a group of isometries.)

We define the \(r\) directional modulus of continuity for \(e \in R^n_+ \cap S_{n-1}\) (or in case of a group of isometries no restriction on \(e\)) by

\[(5.1) \omega_r(T(\cdot)f, u, e, B) = \sup_t \sup_{0 \leq v \leq u} \|T(ve) - I\| T(t)f\|_B.

For \(t\) and \(t + rhe\) in \(R^n_+\), and \((T(he) - I)'T(t)\) defined by

\[(5.2) (T(he) - I)'T(t) = \sum_{k=0}^{r} (-1)^{r-k} \binom{r}{k} T(t + khe),

the definition of a semigroup implies the right-hand side exists. (We could have defined it using an argument similar to that used in proving (4.2). This would have been equivalent but (5.2) is somewhat easier to handle.)

We can now state our theorem.

Theorem 5.1. Let \(T(t)\) be a multivariate semigroup of contractions on a Banach space \(B\), \(t \in R^n_+\), \(t \in R^n\) or \(t \in T^n\), then for \(f \in B\) and both \(t_0\) and \(t_0 + rhe\) belonging to \(R^n_+\) (for a group on \(R^n\) or \(T^n\) the last condition is dropped), we have

\[(5.3) \|T(he) - I\| T(t_0)f\|_B \leq C\left( h' \|f\| + h' \sum_{i=1}^{n} \int h_i \omega_r(Tf, u, e_i, B) du \right),

where \((T(he) - I)'T(t_0)\) is defined by (5.2), \(e_1 \cdots e_n\) are independent vectors in \(S_{n-1} \cap R^n_+\), or in \(S_{n-1}\) in case of a group on \(R^n\) or \(T^n\), and \(C\) depends only on \(r, n\) and \(e_i\). (If \(e = \sum_{i=1}^{n} \alpha_i e_i\) and \(M = \max_i |\alpha_i|\), \(C\) depends only on \(r, n\) and \(M\).)
For a Banach space $B$ of functions, measures or generalized functions on $\mathbb{R}^n$, for which translation is a contraction, we can write

$$\omega_r(f, u, e, B) = \sup_{0 \leq h \leq u} \sup_{x_0} \| \Delta_{he} f(\cdot + x_0) \|_B,$$

and in case $\mathbb{R}^n$ or $T^n$ replace $\mathbb{R}^n$ we have,

$$\omega_r(f, u, e, B) = \sup_{0 \leq h \leq u} \| \Delta_{he} f(\cdot) \|_B.$$

The above formulae will yield the result moduli of continuity for $L_p(\mathbb{R}^n)$ or $L_p(\mathbb{R}^n)$, $1 \leq p \leq \infty$.

We have the following corollary of Theorem 5.1.

**Corollary 5.2.** Let $B$ be a Banach space of functions, measures or generalized functions on $\mathbb{R}^n$ (or $\mathbb{R}^n$ or $T^n$) for which translation is a contraction (or an isometry). Then for n independent, $e_i \in S_{n-1} \cap R^+ (e_i \in S_{n-1})$ and a unit vector $e$, we have

$$\omega_r(f, h, e, B) \leq C \left( r \| f \| + r \sum_{i=1}^{n} \int_{h}^{1} \omega_r(f, u, e_i, B) \frac{du}{u^{r+1}} \right)$$

where $C$ depends only on $r$, $n$ and $e_1 \cdots e_n$.

**Proof of Theorem 5.1.** We choose $g \in B^*$, $\|g\|_{B^*} = 1$, and obtain $\langle T(t) f, g \rangle = F(t)$, and $F(t)$ is a function on $\mathbb{R}^n$ (or $\mathbb{R}^n$ or $T^n$) which is bounded by $\|f\|_B \cdot \|g\|_{B^*} = \|f\|_B$. Therefore, $F(t)$ satisfies the conditions of Theorems 4.1 and 4.2,

$$\omega_r(F(t), h, e) \leq Ch^r \|F\| + C \sum_{i=1}^{n} h^r \int_{h}^{1} \omega_r(F, u, e_i) \frac{du}{u^{r+1}}$$

$$\leq Ch^r \|f\| + C \sum_{i=1}^{n} h^r \int_{0}^{1} \omega_r(T(t) f, u, e_i, B) \frac{du}{u^{r+1}}$$

since

$$\omega_r(F, u, e_i) = \sup_{\eta \leq u} \| \Delta_{he_i} F(t) \| = \sup_{\eta \leq u} \| (T(\eta e_i) - I)^r T(t) f \|_B.$$ 

We choose $t_0$ and $\eta \leq h$ such that $t_0, t_0 + \eta e \in R^+$ and $\| \Delta_{\eta e} T(t_0) f \| \geq \omega_r(T(t_0), h, e) - \epsilon$. We choose $g \in B^*$, $\|g\| = 1$ such that

$$\| \Delta_{\eta e} F(t_0) \| \geq \| \Delta_{\eta e} T(t_0) f \|_B - \epsilon \geq \omega_r(T(t_0), h, e) - 2\epsilon$$

but $\| \Delta_{\eta e} F(t_0) \| \leq \omega_r(F(t), h, e)$ and $\epsilon$ can be arbitrarily small, which completes the proof.

**Remark 5.3.** (a) In the case of function spaces we have $T(t)f(x) = f(x + t)$ and $\langle T(t)f, g \rangle = \int f(x + t)g(x) dx$ as was done in [1].

(b) We did not require $T(t)$ to be strongly continuous.

**6. The case $\alpha = r$.** In an earlier section it was proved that in $\mathbb{R}^n$ (and, in fact, for other domains), $\omega_r(f, h, e_i) \leq Mh^r$ for $n$ independent $e_i$, and $\alpha < r$ implies that $\omega_r(f, h, e_i) \leq Kh^r$ for any direction $e$. In the case $\alpha = r$ the result proved implied
\[ \omega(f, h, e) \leq Kh' \log(1/h). \] In the following example it will be shown that this estimate is sharp.

**Example 6.1.** Let \( \psi(x, y) \in C_0^\infty \); that is, \( \psi \) has compact support and all derivatives, and let \( \psi(x, y) = 1 \) for \( x^2 + y^2 \leq 1 \). We define

\[ f(x, y) = \psi(x, y)xy \log(x^2 + y^2) \quad \text{and} \quad f(0, 0) = 0. \]

It is not hard to see that \( |\Delta_{he}^2 f(x, y)| \leq Mh^2 \) for \( e_1 = (1, 0) \) and \( e_2 = (0, 1) \), while \( \sup |\Delta_{he}^2 f(x, y)| \sim Kh^2 \log(1/h) \) in other directions. Also the mixed difference \( \sup |\Delta_{he} \Delta_{he}^2 f(x, y)| \sim Kh^2 \log(1/h) \).

**Example 6.2.** For \( R^n \) and the standard basis \( e_i \) and a given \( r \), we have

\[ f(x_1, \ldots, x_n) = \psi(x_1, \ldots, x_n) \left( \prod_{i=1}^n x_i^{s_i} \right) \log \left( \sum_{i=1}^n x_i^2 \right)^{-1} \]

and \( f(0, 0, \ldots, 0) = 0 \) where \( \psi(x_1, \ldots, x_n) \in C_0^\infty \) and \( \psi(x_1, \ldots, x_n) = 1 \) for \( |(x_1, \ldots, x_n)| \leq 1 \) and \( \sum k_i = r \). If at least two \( k_i \) are different from \( 0 \), then all \( \omega_r(f, h, e_i) = O(h^r) \) in the \( C(R^n) \) norm but for the vector \( e = (1/\sqrt{n})(1, 1, \ldots, 1) \), for example, \( \omega_r(f, h, e) = O(h^r \log(1/h)) \) in \( C(R^n) \).

The above situation does not hold in \( L_p, 1 < p < \infty \). In fact, one can deduce from known results the following

**Theorem 6.3.** If \( f \) has compact support, \( f \in L_p(R^n) \) for \( 1 < p < \infty \) and \( \omega_r(f, h, e, L_p) = O(h^r) \) for \( n \) independent \( e_i \), then \( \omega_r(f, h, e, L_p) = O(h^r) \) for any direction \( e \). (Also all mixed differences of order \( r \) can be estimated by \( O(h^r) \)).

**Proof.** For \( f \in L_p(R^n), 1 < p < \infty \), and \( \omega_r(f, h, e_i, L_p) = O(h^r) \), we actually have \( f, \delta f/\delta x_i, \ldots, (\delta^r f/\delta x_i^r)f \) in \( L_p \) and \( \int (\delta^r f/\delta x_i^r)f \, dx_i = (\delta^r f/\delta x_i^r)^{-1}f \) for \( j \leq r \) (where the derivatives are the strong \( L_p \) derivatives) and \( ||(\delta^r f/\delta x_i^r)f||_p \leq \sup_h h^{-r} \omega_r(f, h, e_i, L_p) \). This is a classical result in essence. However, appropriate minor modification of the results of Hardy-Littlewood and of Berens-Butzer to adjust to \( R^n \) and the present situation are much more cumbersome than the following proof.

Our condition that \( h^{-r} \Delta_{he} f \) is in a ball in \( L_p \), and therefore so is \( h^{-r} \Delta_{he}^j f \) for \( j \leq r \) which implies \( h^{-r} \Delta_{he} f \) for \( j \leq r \), has a weak* accumulation point which we call \( \phi_j \).

For \( 1 < p < \infty \) the weak* closure is in \( L_p \) and \( ||\phi_j|| \leq \sup ||h^{-r} \Delta_{he}^j f||_{L_p} \). For \( \psi \in C_0^\infty \) (\( C^\infty \) functions with compact support)

\[ \langle h^{-r} \Delta_{he} f, \psi \rangle = \langle f, h^{-r} \Delta_{he} \psi \rangle \rightarrow (-1)^j \left\langle f, \left( \frac{\partial}{\partial x_i} \right)^j \psi \right\rangle = \langle \phi_j, \psi \rangle \]

or, in other words, since \( C_0^\infty \) is dense in \( L_q, q^{-1} + p^{-1} = 1 \), \( \phi_j = (\partial/\partial x_i)f \) where the derivative is taken in the distributional sense (and therefore \( \phi_j \) is unique as an
accumulation point). Define $(g(x))_h = h^{-1} \int_0^h g(x + ue_j) \, du$ and recall that for $g \in L_p$, $\lim_{h \to 0^+} \frac{g(x)}{h} = g(x)$ in $L_p$ and a.e. For $1 \leq j \leq r$ we have

$$\langle (\phi_j)_h, \psi \rangle = \langle (\phi_j, (\psi)_h) = -\langle \phi_{j-1}, \left( \frac{\partial}{\partial x_j} \right) (\psi)_h \rangle = -\langle \phi_{j-1}, \left( \frac{\partial}{\partial x_j} \psi \right)_h \rangle$$

or $(\phi_j)_h = h^{-1} \Delta_{he_j} \phi_{j-1}$ but $(\phi_j)_h \to \phi_j$ in $L_p$ and therefore so does $h^{-1} \Delta_{he_j} \phi_{j-1}$.

Using a result by Ilin [2, p. 301], we have $\|D^s f\|_p \leq C(\sum_{i=1}^n \|\partial / \partial x_i\|^p + \|f\|)$ where $\nu = (\nu_1, \ldots, \nu_r)$ and $\nu_1 + \cdots + \nu_r \leq r$. This would yield an estimate of all mixed derivatives and therefore a derivative in any direction $e$ satisfies $\|\partial / \partial x^s_{j} f\|_p \leq K(\sum_{i=1}^n \|\partial / \partial x_i\|^p + \|f\|_p)$ and hence $\omega(f, h, e, L_p) = O(h^r)$. One should note that when $r$ is even a more accessible source for the above is Stein’s text [5, p. 114] as $\Sigma(\partial / \partial x^s_{j})^r = P(D)$ is elliptic and $\|P(D)f\|_p \leq \Sigma_{i=1}^n \|\partial / \partial x_i\|^p$.

**Remark 6.4.** It is not known to me whether for $L_1(R^n)$ we have the sharp estimate by $O(h^r \log(1/h))$. (We cannot hope for an analog to Theorem 6.3.)

7. The result for $C(D)$, $L_p(D)$ and other spaces. We define for a domain $D$, $D \subset R^n$, the constant $a$, and $n$ independent vectors $e_1,\ldots,e_n$, the domain $D_a(e_1,\ldots,e_n)$ by

$$D_a(e_1,\ldots,e_n) = \{x; x + a_i(e_1,\ldots,e_n) \subset D \text{ for some vector of}$$

(7.1) integers $(i_1,\ldots,i_n)$ where

$$B_a(i_1,\ldots,i_n) = [0,(-1)^{i_n}a] \times \cdots \times [0,(-1)^{i_1}a].$$

We always have $D_a \subset D$. If $D$ is a box with sides parallel to $e_i$, and $a$ small enough then, $D_a = D$ and the same is true if $D = \{\sum \xi_i e_i, \xi_i > 0\}$ but in most cases $D_a$ is strictly smaller than $D$.

We will observe a few properties common to many Banach spaces that will be needed in the theorem below.

**Definition 7.1.** A Banach space will satisfy condition A if

(a) $f(x) \in B$ implies $f(x + h) \in B$, $x, h \in R^n$,

(b) $f \in B$ and $E$ measurable implies $\chi(E)f(x) \in B$,

(c) $|f| \leq |g|$ (and $f, g \in B$) implies $\|f\| \leq \|g\|$.

**Definition 7.2.** A Banach space will satisfy condition B if it satisfies condition A, its elements are locally Lebesgue integrable and $\|f(\cdot + h) - f(\cdot)\|_B = o(1)$, $|h| \to 0$, $h \in R^n$. (And therefore $\|1/h\|_B^h f(\cdot + he_j) \, du - f(\cdot)\|_B = o(1)$ as $h \to 0$, $h \in R$.)

It is clear that $C(R^n)$ does not satisfy condition A but $L_p(R^n)$, $1 \leq p < \infty$, does and so many other spaces. The following results will apply to $C(R^n)$ or $C(D)$ through $L_{\infty}(R^n)$ or $L_{\infty}(D)$. ($L_{\infty}(R^n)$ does not satisfy condition B while $L_p$ for $1 \leq p < \infty$ does.) We also define

$$D(he) = \bigcap_{0 \leq \eta \leq h} \{ -he + D \}.$$
Definition 7.3. The $r$ directional modulus of continuity is given by

\[(7.3) \quad \omega_r(f, h, e, B(D)) = \sup_{\eta \in h} \|x(D(\eta e))\Delta_{\eta e} f\|_B.\]

We are now able to state and prove our theorem.

Theorem 7.1. For a Banach space $B$ satisfying condition A, $n$ independent unit vectors $e_1, \ldots, e_n$, and integers $k_i$ satisfying $k_1 + \cdots + k_n = r$, we have

\[(7.4) \quad \|x(D_a)\Delta_{\epsilon e_1} \cdots \Delta_{\epsilon e_n} f\|_B \leq C \left( \|x(D)\|_{B:h^r} + \sum_{i=1}^n \int_h^a \frac{\omega_r(f, u, e_i, B(D))}{u^{r+1}} du \right) \]

where $C$ depends only on $r$, $n$ and $a$ (and not on $Bh, f, D$ and $e$). For $e = \sum \alpha_i e_i$, $|\alpha_i| \leq M, |e| = 1$ we have

\[(7.5) \quad \|x(D_{r,Mh})\Delta_{\epsilon e} f\|_B \leq C \left( \|x(D)\|_{B:h^r} + \sum_{i=1}^n \int_h^a \frac{\omega_r(f, u, e_i, B(D))}{u^{r+1}} du \right) \]

where $D_{r,Mh} = \{ x; x + B_{r,Mh} \subset D_a \}$ where

\[B_{r,Mh} = \{ y; e = \sum \beta_i e_i \text{ and } |\beta_i| \leq rMh \} \]

and $C$ depends only on $M, a$ and $r$.

If condition B is satisfied or our Banach space is $C(D)$ and the interval $[x, x + rh] \subset D_a$, then

\[(7.6) \quad \|x(D_a)\Delta_{\epsilon e} f\|_B \leq C \left( \|x(D)\|_{B:h^r} + \sum_{i=1}^n \int_h^a \frac{\omega_r(f, u, e_i, B(D))}{u^{r+1}} du \right) \]

where $C$ depends on $a, r$, and $e_1, \cdots e_n$ only.

Proof. Using (2.6) for $x \in D_a$ and recalling that for such $x$,

\[\|x(D_a)\Delta_{\epsilon e} f(\cdot + 2^i h_i e_1 + \cdots + 2^i h_n e_n)\| \leq \omega_r(f, u, e_i B(D))\]

and, therefore, simply using the lattice compatibility and the triangle inequality, we obtain (7.4). Actually Theorem 3.1 is proved in a way that is amenable to proving (7.4). To prove (7.5) we recall that $x \in D_{r,Mh}^*$ guarantees that the process of writing the directional difference in terms of mixed differences following Theorem 4.1 does not take $x$ out of $D_a$. In fact, in view of Theorem 4.2, we can use a somewhat less restrictive domain than $D_{r,Mh}^*$. However, for most spaces in question that would not matter as one can prove the more general (7.6) if our Banach space satisfies condition B as $L_p, 1 \leq p < \infty$, do. If sets of the type $\{ x, x + B_a(i_1, \ldots, i_n) \subset D \}$ cover $D_a$, so do $\{ x, x + B_a/2(i_1, \ldots, i_n) \subset D \}$ and in those the isolated points of $D_a$ are not isolated. We treat the domains $\{ x, x + B_a/2(i_1, \ldots, i_n) \subset D \} \cap D_a$ one at a time which we may because of lattice compatibility and which we, for convenience,
call $E = E_1 \cap D_a$. But in each we may define
\[
F_h(x) = \frac{(-r)^n}{h^n} \int_0^{h/r} \ldots 
\int_0^{h/r} \left( (-1)^n \Delta_{(u_1, \ldots, u_n)} \Delta_{(u_{r+1}, \ldots, u_{2r})} \ldots \Delta_{(u_{rn-1}, \ldots, u_{rn})} e_{u_1} - 1 \right) \cdot f(x) \, du_1 \ldots du_{rn},
\]
Obviously, $\|x(E)F_h(x) - f(x)\|$ can be estimated by $w_r(f, h, e, B(D))$. Moreover, $F_h$ being just a Stekelov-type average, its mixed derivative of order $r$ will be $h^{-r}$ times a finite combination of mixed differences of order $r$ that were already estimated in (7.4). (This is the step in which we use condition B or our Banach spaces is $C(D)$.) This yields an estimate for the $r$ derivative in the $e$ direction of $F_h$ and we complete our theorem. We have to observe that we actually use the earlier part of the theorem with $a/2$ instead of $a$ and that at least one $E_1$ contains $x$ and part of $[x, x + rhe]$ i.e., $[x, x + \delta e]$.

Sometimes for a particular domain it is useful to use a finite but bigger collection of vectors $e_j$. For instance, if we discuss the simplex $(0,0), (0,1)$ and $(1,0)$ for $D$, it is useful to have the vectors $(0,1), (1,0)$ and $(1/\sqrt{2})(1,1)$, and $D$ is the union of $D_a$ generated by two of the above 3 vectors (3 different $D_a$ with small enough $a$, say $a = \frac{1}{4}$). This and similar situations are important for actual approximation problems while not crucial for the present question. Of particular use will be a situation in which $D$ is covered by finitely many $D_a$ which are generated by subsets of $e_1 \cdots e_k$; but while for a very general $D$ (see Sharpley [4]) there exists such a collection $e_1 \cdots e_k$, our problem here is, however: given the fixed collection, on what part of $D$ is the result valid? If the result is valid on $D_1 \cdots D_h$ then it is valid on their union.

RemarK. We can choose $a$ to be small and $D_a$ will be close to $D$. Moreover, when $\omega_r(f, h, e_i, B(D)) \leq Mh^a$, $\alpha < r$, we can choose $a \leq Mh^{1-\alpha/r}$ and the constants will depend on $M$ rather than $a$.

REFERENCES


DEPARTMENT OF MATHEMATICS, UNIVERSITY OF ALBERTA, EDMONTON, ALBERTA, CANADA T6G 2G1