COHOMOGENEITY ONE ACTIONS
ON NONCOMPACT SYMMETRIC SPACES
OF RANK ONE

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Abstract. We classify, up to orbit equivalence, all cohomogeneity one actions on
the hyperbolic planes over the complex, quaternionic and Cayley numbers, and on
the complex hyperbolic spaces $\mathbb{C}H^n$, $n \geq 3$. For the quaternionic
hyperbolic spaces $\mathbb{H}H^n$, $n \geq 3$, we reduce the classification problem to a
problem in quaternionic linear algebra and obtain partial results. For real
hyperbolic spaces, this classification problem was essentially solved by Élie
Cartan.

1. Introduction

An isometric action on a Riemannian manifold is of cohomogeneity one if its
orbit space is one-dimensional. Cohomogeneity one actions are of current interest
for the construction of geometrical structures on manifolds, e.g., Einstein metrics
and metrics with special holonomies. The reason is that a cohomogeneity one
action can be used to reduce the system of partial differential equations describing
such a geometrical structure to a nonlinear ordinary differential equation for which
one might be able to find explicit solutions. Given a Riemannian manifold $M$, it
is natural to find all cohomogeneity one actions on it, perhaps just up to orbit
equivalence. Two cohomogeneity one actions on $M$ are orbit equivalent if there
exists an isometry of $M$ that maps the orbits of one action onto the orbits of
the other action. It is worthwhile to mention that the classification problem of
cohomogeneity one actions up to orbit equivalence is equivalent to the classification
problem of homogeneous hypersurfaces up to isometric congruence. The latter is a
classical problem in submanifold theory.

The cohomogeneity one actions on spheres, equipped with their standard metric
of constant curvature, have been classified by Hsiang and Lawson [14]. Remarkably,
any such action is orbit equivalent to the isotropy representation of a Riemannian
symmetric space of rank two. For the other compact symmetric spaces of rank
one the classifications were obtained by Takagi [21] for the complex projective
spaces and by Iwata [15], [16] for the quaternionic projective spaces and the Cayley

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projective plane. For simply connected irreducible Riemannian symmetric spaces of higher rank the classification was established by Kollros [17].

The methods employed by the above authors do not work for the noncompact dual symmetric spaces. The noncompactness of the isometry group turns out to be a subtle point. There can be uncountably many families of nonisomorphic subgroups of the isometry group that act orbit equivalently by cohomogeneity one. By using the classification of isoparametric hypersurfaces on the Euclidean space $\mathbb{R}^n$ and the real hyperbolic space $\mathbb{R}H^n$ by Levi-Civita [18], Segre [20] and Cartan [10], one can obtain all cohomogeneity one actions on these spaces up to orbit equivalence. In both cases the orbit structure is either a Riemannian foliation, or a totally geodesic subspace together with the distance tubes around it. It is a general fact that a cohomogeneity one action on a symmetric space of noncompact type, or more generally on a Hadamard manifold, induces either a Riemannian foliation, or has exactly one singular orbit and the generic orbits are the distance tubes around it (see [3] for details and references).

In [4] we obtained the classification, up to orbit equivalence, of all cohomogeneity one actions on irreducible symmetric spaces of noncompact type that induce a Riemannian foliation, that is, have no singular orbit. A surprising consequence of this result is that the moduli space of all such actions just depends on the rank of the symmetric space and possible duality or triality principles on the space. In particular, on each noncompact symmetric space of rank one this moduli space consists of just two elements. The corresponding foliations are the horosphere foliation and a foliation with exactly one minimal leaf whose geometry has been investigated in [2].

The classification of all cohomogeneity one actions on irreducible symmetric spaces of noncompact type that have a totally geodesic singular orbit has been achieved in [5]. It thus remains to investigate the case of a non-totally-geodesic singular orbit. As mentioned above, in the case of $\mathbb{R}^n$ and $\mathbb{R}H^n$ a singular orbit is necessarily totally geodesic. It is remarkable that this is no longer true for the other noncompact symmetric spaces of rank one: the complex hyperbolic spaces $\mathbb{C}H^n$ ($n \geq 2$), the quaternionic hyperbolic spaces $\mathbb{H}H^n$ ($n \geq 2$), and the Cayley hyperbolic plane $\mathbb{O}H^2$. The first author and Brück constructed in [3] many examples of cohomogeneity one actions on these hyperbolic spaces (except for $\mathbb{C}H^2$) with a non-totally-geodesic singular orbit. The main result of this paper says that, up to orbit equivalence, there are no further cohomogeneity one actions on $\mathbb{C}H^n$ ($n \geq 3$), $\mathbb{H}H^2$ and $\mathbb{O}H^2$. We also show that every singular orbit of a cohomogeneity one action on $\mathbb{C}H^2$ is totally geodesic. For the quaternionic hyperbolic space $\mathbb{H}H^n$, $n \geq 3$, we prove that the set of orbit equivalence classes of cohomogeneity one actions with a singular orbit of codimension 2 is parametrized by the closed interval $[0, \pi/2]$.

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2. Preliminaries

Let $M$ be a noncompact symmetric space of rank one. Then $M$ is either a real hyperbolic space $\mathbb{R}H^n$, a complex hyperbolic space $\mathbb{C}H^n$, a quaternionic hyperbolic space $\mathbb{H}H^n$, or a Cayley hyperbolic plane $\mathbb{O}H^2$, where $n \geq 2$. We denote by $F$ one of
the real division algebras $\mathbb{R}$, $\mathbb{C}$, $\mathbb{H}$ or $\mathbb{O}$, and by $\mathbb{F}H^n$ the corresponding hyperbolic space, where we assume $n = 2$ if $\mathbb{F} = \mathbb{O}$. Let $G$ be the identity component of the full isometry group of $M$; that is, $G = SO^+(n, 1), SU(n, 1), Sp(n, 1), F_{4}^{-20}$ for $\mathbb{F} = \mathbb{R}, \mathbb{C}, \mathbb{H}, \mathbb{O}$, respectively. We fix a point $o \in M$ and denote by $K$ the isotropy subgroup of $G$ at $o$; that is, $K = SO(n), S(U(n)U(1)), Sp(n)Sp(1), Spin(9)$. Then, as a homogeneous space, $M$ is isomorphic to $G/K$. We denote by $\mathfrak{g}$ and $\mathfrak{k}$ the Lie algebras of $G$ and $K$. Let $B$ be the Killing form of $\mathfrak{g}$ and $\theta$ the Cartan involution of $\mathfrak{g}$ with respect to $\mathfrak{k}$. Then $(X, Y) = -B(X, \theta Y)$ is a positive definite inner product on $\mathfrak{g}$. Let $\mathfrak{g} = \mathfrak{k} + \mathfrak{p}$ be the Cartan decomposition of $\mathfrak{g}$ induced by $\theta$. The restriction of $(\cdot, \cdot)$ to $\mathfrak{p}$ induces a Riemannian metric on $G/K$ turning it into a Riemannian symmetric space of rank one. We normalize the Riemannian metric on $M$ so that it becomes isometric to $G/K$ with the induced metric we just described.

Let $\mathfrak{a}$ be a maximal abelian subspace of $\mathfrak{p}$, which is just a one-dimensional linear subspace since the rank of $M$ is one, and let

$$\mathfrak{g} = \mathfrak{g}_{-2\alpha} + \mathfrak{g}_\alpha + \mathfrak{g}_0 + \mathfrak{g}_\alpha + \mathfrak{g}_{2\alpha}$$

be the corresponding restricted root space decomposition of $\mathfrak{g}$. Note that $\mathfrak{g}_{-2\alpha}$ and $\mathfrak{g}_{2\alpha}$ are trivial if $\mathbb{F} = \mathbb{R}$. Then

$$\mathfrak{g} = \mathfrak{k} + \mathfrak{a} + \mathfrak{n} \quad \text{with} \quad \mathfrak{n} = \mathfrak{g}_\alpha + \mathfrak{g}_{2\alpha}$$

is an Iwasawa decomposition of $\mathfrak{g}$. The subalgebra $\mathfrak{n}$ of $\mathfrak{g}$ is abelian if $\mathbb{F} = \mathbb{R}$ and two-step nilpotent otherwise. In fact, $\mathfrak{n}$ is isomorphic to the $(2n - 1)$-dimensional Heisenberg algebra if $\mathbb{F} = \mathbb{C}$, and to a certain generalized Heisenberg algebra if $\mathbb{F} \in \{\mathbb{H}, \mathbb{O}\}$ (see [8] for more details on this). Moreover, $\mathfrak{z} = \mathfrak{g}_{2\alpha}$ is the center of $\mathfrak{n}$ and equal to the derived subalgebra $[\mathfrak{n}, \mathfrak{n}]$ of $\mathfrak{n}$. The dimension of $\mathfrak{z}$ is equal to 1, 3, 7 for $\mathbb{F} = \mathbb{C}, \mathbb{H}, \mathbb{O}$, respectively. The subalgebra $\mathfrak{a} + \mathfrak{n}$ of $\mathfrak{g}$ is solvable and $\mathfrak{n}$ is the derived subalgebra of $\mathfrak{a} + \mathfrak{n}$.

We denote by $\mathcal{A}$ resp. $\mathcal{N}$ the connected closed subgroup of $G$ with Lie algebra $\mathfrak{a}$ resp. $\mathfrak{n}$. Then $G = \mathcal{KAN}$ is an Iwasawa decomposition of $G$ and, since $\mathcal{K}$ is the isotropy subgroup of $G$ at $o$, the solvable subgroup $\mathcal{AN}$ of $G$ acts simply transitively on $M$. Thus $M$ is isometric to the solvable Lie group $\mathcal{AN}$ equipped with a suitable left-invariant Riemannian metric.

We define $\mathfrak{v} = \mathfrak{g}_\alpha$. Then we can identify $\mathfrak{v}$ with $\mathbb{R}^{n-1}, \mathbb{C}^{n-1}, \mathbb{H}^{n-1}, \mathbb{O}$ for $\mathbb{F} = \mathbb{R}, \mathbb{C}, \mathbb{H}, \mathbb{O}$, respectively. More precisely, if $\mathbb{F} = \mathbb{R}$, then $\mathfrak{v}$ is isomorphic to $\mathbb{R}^{n-1}$ as a real vector space. If $\mathbb{F} = \mathbb{C}$, the Kähler structure on $\mathbb{C}H^n$ induces a complex vector space structure on $\mathfrak{v}$ so that it becomes isomorphic to $\mathbb{C}^{n-1}$, and if $\mathbb{F} = \mathbb{H}$, the quaternionic Kähler structure on $\mathbb{H}H^n$ induces a (right) quaternionic vector space structure on $\mathfrak{v}$ so that it becomes isomorphic to the (right) quaternionic vector space $\mathbb{H}^{n-1}$. For $\mathbb{F} = \mathbb{O}$ we simply identify $\mathbb{O}$ with $\mathbb{R}^8$, and $\mathfrak{v}$ becomes isomorphic to $\mathbb{O}$ as a real vector space.

3. THE REDUCTION

In this section we reduce our classification problem to the problem of classifying certain subalgebras of $\mathfrak{a} + \mathfrak{n}$. We start with a general result about cohomogeneity one actions on Hadamard manifolds, i.e., connected, simply connected, complete Riemannian manifolds of nonpositive curvature. Every symmetric space of noncompact type is a Hadamard manifold. We recall that Cartan’s Fixed Point Theorem states that the action of any compact subgroup of the isometry group of a Hadamard
manifold has a fixed point. We refer to [12] for more details on Hadamard manifolds and Cartan’s Fixed Point Theorem.

**Proposition 3.1.** Let \( M \) be a Hadamard manifold and \( H \) a connected subgroup of the isometry group of \( M \) that acts with cohomogeneity one on \( M \) and has a singular orbit \( F \). Then there exists a connected solvable subgroup of \( H \) that acts transitively on \( F \).

**Proof.** We choose a Levi-Malcev decomposition

\[
h = h_{ss} + h_{solv}
\]

of the Lie algebra \( h \) of \( H \) into the semidirect sum of a semisimple subalgebra \( h_{ss} \) and a solvable ideal \( h_{solv} \). For the semisimple subalgebra \( h_{ss} \), we choose an Iwasawa decomposition

\[
h_{ss} = h_{ss}^{pcpt} + h_{ss}^{solv}
\]

of \( h_{ss} \) into the vector space direct sum of a compact subalgebra \( h_{ss}^{pcpt} \) and a solvable subalgebra \( h_{ss}^{solv} \). Then

\[
h = h_{ss}^{pcpt} + (h_{ss}^{solv} + h_{solv})
\]

where \( h_{ss}^{solv} + h_{solv} \) is a semidirect sum of the two solvable subalgebras so that \( h_{solv} \) is the ideal in it. Note that the semidirect sum of two solvable Lie algebras is solvable as well. We denote by \( H_{ss}^{pcpt} \) and \( H_{solv} \) the connected subgroups of \( H \) with Lie algebra \( h_{ss}^{pcpt} \) and \( h_{ss}^{solv} + h_{solv} \), respectively.

By Cartan’s Fixed Point Theorem, there exists a point \( p \in M \) that is fixed under the action of the compact group \( H_{ss}^{pcpt} \). If \( p \in F \), then clearly the solvable group \( H_{solv} \) acts transitively on \( F \). If \( p \notin F \), then \( p \) is on a principal orbit of the \( H \)-action on \( M \), and it follows that the solvable group \( H_{solv} \) acts transitively on this principal orbit. Since the action of \( H \) on \( M \) is of cohomogeneity one, we easily see that \( H_{solv} \) acts transitively on each orbit of the \( H \)-action and, in particular, also transitively on the singular orbit \( F \). This finishes the proof of Proposition 3.1. \( \square \)

We denote by \( M(\infty) \) the ideal boundary of \( M \) whose points are given by the equivalence classes of asymptotic geodesics in \( M \), and equip \( M = M \cup M(\infty) \) with the cone topology. The action of \( H \) on \( M \) extends canonically to an action of \( H \) on \( M \).

From now on we assume that \( M = FH^n \) and that the singular orbit \( F \) of the cohomogeneity one action by \( H \) on \( M \) is not totally geodesic. Then none of the \( H \)-orbits on \( M \) is totally geodesic, and a result by Alekseevsky and Di Scala [1] implies that there exists a unique point \( x \in M(\infty) \) that is fixed under the \( H \)-action on \( M(\infty) \). We fix a point \( o \in F \) and consider the Iwasawa decomposition

\[
g = \mathfrak{t} + \mathfrak{a} + \mathfrak{n}
\]

that is determined by \( o \) and \( x \). Since \( H \cdot x = x \), we have

\[
h \subset \mathfrak{t}_x + \mathfrak{a} + \mathfrak{n},
\]

where \( \mathfrak{t}_x \) is the centralizer of \( \mathfrak{a} \) in \( \mathfrak{t} \). We denote by \( K_x \) the connected subgroup of \( K \) with Lie algebra \( \mathfrak{t}_x \). Then we have

\[
K_x = SO(n - 1), S(U(n - 1)U(1)), Sp(n - 1)Sp(1), Spin(7)
\]

for \( F = R, C, H, O \), respectively, and \( H \subset K_x AN \).

By Proposition 3.1 there exists a solvable subgroup \( S \) of \( H \) that acts transitively on the singular orbit \( F \). We denote by \( \mathfrak{s} \) the subalgebra of \( \mathfrak{h} \) corresponding to \( S \subset H \).
We recall that we may write the nilpotent subalgebra \( \mathfrak{n} \) in the form \( \mathfrak{n} = \mathfrak{g}_\alpha + \mathfrak{g}_{2\alpha} \) with some suitable root spaces \( \mathfrak{g}_\alpha \) and \( \mathfrak{g}_{2\alpha} \). Since \( \mathfrak{e}_x \) centralizes \( \mathfrak{a} \), it normalizes each root space and hence \( \mathfrak{n} \), which implies that \( \mathfrak{a} + \mathfrak{n} \) is an ideal in \( \mathfrak{e}_x + \mathfrak{a} + \mathfrak{n} \). Thus the canonical projection
\[
\pi : \mathfrak{e}_x + \mathfrak{a} + \mathfrak{n} \to \mathfrak{e}_x
\]
is a Lie algebra homomorphism, and it follows that
\[
\mathfrak{s}_c = \pi(\mathfrak{s})
\]
is a solvable subalgebra of \( \mathfrak{e}_x \). Since every solvable subalgebra of a compact Lie algebra is abelian, we conclude that
\[
(3.1) \quad \mathfrak{s}_c \text{ is an abelian subalgebra of } \mathfrak{e}_x.
\]
Let
\[
\tau : \mathfrak{e}_x + \mathfrak{a} + \mathfrak{n} \to \mathfrak{a} + \mathfrak{n}
\]
be the canonical projection and define
\[
\mathfrak{s}_n = \tau(\mathfrak{s}) .
\]
It is clear that
\[
(3.2) \quad \dim \mathfrak{s}_n = \dim F .
\]
Our aim is to show that \( \mathfrak{s}_n \) is a subalgebra of \( \mathfrak{a} + \mathfrak{n} \) and that the orbit through \( o \) of the action of the corresponding subgroup \( S_n \) of \( AN \) is just the singular orbit \( F \). For each \( k \in K_x \) the differential \( d_o k \) of \( k \) at \( o \) is given by \( d_o k = \text{Ad}(k)(\mathfrak{a} + \mathfrak{n}) \), where we identify \( T_o M \) with \( \mathfrak{a} + \mathfrak{n} \) by means of \( M = G/K = AN \). Since the isotropy subgroup \( H_o \) of \( H \) at \( o \) acts transitively on the unit sphere in the normal space \( \nu_o F \) of \( F \) at \( o \), and as \( \mathfrak{e}_x \) centralizes \( \mathfrak{a} \), we necessarily have
\[
(3.3) \quad \nu_o F \subset \mathfrak{n}
\]
and hence
\[
(3.4) \quad \mathfrak{a} \subset \mathfrak{s}_n .
\]
We shall now prove that
\[
(3.5) \quad [\mathfrak{s}, \mathfrak{s}] = \mathfrak{s}_n \cap \mathfrak{n} .
\]
Since \( \mathfrak{s} \subset \mathfrak{s}_c + \mathfrak{s}_n \), we have
\[
[\mathfrak{s}, \mathfrak{s}] \subset [\mathfrak{s}_c, \mathfrak{s}_c] + [\mathfrak{s}_c, \mathfrak{s}_n] + [\mathfrak{s}_n, \mathfrak{s}_n] .
\]
The subalgebra \([\mathfrak{s}_c, \mathfrak{s}_c]\) is trivial since \( \mathfrak{s}_c \) is abelian according to \( (3.1) \). Since \( \mathfrak{s}_c \subset \mathfrak{e}_x \), \( \mathfrak{s}_n \subset \mathfrak{a} + \mathfrak{n} \) and \( \mathfrak{e}_x \) centralizes \( \mathfrak{a} \) and normalizes \( \mathfrak{n} \), we have \([\mathfrak{s}_c, \mathfrak{s}_n] \subset [\mathfrak{e}_x, \mathfrak{a} + \mathfrak{n}] \subset \mathfrak{n} \). Finally, since \( \mathfrak{s}_n \subset \mathfrak{a} + \mathfrak{n} \) and \( \mathfrak{n} \) is the derived subalgebra of \( \mathfrak{a} + \mathfrak{n} \), we see that \([\mathfrak{s}_n, \mathfrak{s}_n] \subset \mathfrak{n} \). Altogether this implies \([\mathfrak{s}, \mathfrak{s}] \subset \mathfrak{n} \), which readily yields \([\mathfrak{s}, \mathfrak{s}] \subset \mathfrak{s}_n \cap \mathfrak{n} \).
For the converse, we fix the element \( B \in \mathfrak{a} \) for which \([B, V] = V \) and \([B, Z] = 2Z \) holds for all \( V \in \mathfrak{v} = \mathfrak{g}_\alpha \) and \( Z \in \mathfrak{z} = \mathfrak{g}_{2\alpha} \). Because of \( (3.1) \) there exists an element \( \tilde{B} \in \mathfrak{s}_c \) so that \( \tilde{B} + B \in \mathfrak{s} \). Let \( X = V + Z \in \mathfrak{v} + \mathfrak{z} \) be an arbitrary element in the orthogonal complement of \([\mathfrak{s}, \mathfrak{s}]\) in \( \mathfrak{s}_n \cap \mathfrak{n} \). Then there exists a vector \( \tilde{X} \in \mathfrak{s}_c \) so that \( \tilde{X} + X \in \mathfrak{s} \), and we have
\[
0 = \langle X, [\tilde{B} + B, \tilde{X} + X] \rangle = \langle X, [\tilde{B}, \tilde{X}] + [\tilde{B}, X] + [B, \tilde{X}] + [B, X] \rangle .
\]
Since $s_c$ is abelian we have $[\hat{B}, \hat{X}] = 0$. Since $\text{ad}(\hat{B})$ is a skew-symmetric transformation we have $\langle X, [\hat{B}, X] \rangle = 0$, and since $s_c \subset \frak{t}_x$ and $\frak{t}_x$ centralizes $a$ we have $[B, \hat{X}] = 0$. This implies

$$0 = \langle X, [B, X] \rangle = (V + Z, V + 2Z) = \langle V, V \rangle + 2\langle Z, Z \rangle,$$

and hence $V = 0 = Z$. Thus $X = 0$, which implies that the orthogonal complement of $[s, s]$ in $s_n \cap \frak{n}$ is trivial. This establishes the proof of (3.5).

Our next aim is to prove that

$$(3.6) \quad \nu_o F \subset \frak{v} = \frak{g}_o.$$

From (3.3) we already know that $\nu_o F \subset \frak{n}$. If $\nu_o F \cap \frak{v} \neq 0$, we readily get $\nu_o F \subset \frak{v}$, because $\text{Ad}(H_n)$ acts transitively on the unit sphere in $\nu_o F$ and preserves $\frak{v}$. Now assume that $\nu_o F \cap \frak{v} = 0$. Then (3.3) implies that the canonical projection $[s, s] \subset \frak{v} + \frak{z}$ onto $\frak{v}$ is the entire space $\frak{v}$. Thus, for each $V \in \frak{v}$ there exists an element $V' \in \frak{z}$ so that $V + V' \in [s, s]$. Since $[s, s]$ is a subalgebra, we get

$$\langle V, W \rangle = \langle V + V', W + W' \rangle \in [s, s]$$

for all $V, W \in \frak{v}$. But since $[\frak{v}, \frak{v}] = [\frak{g}_o, \frak{g}_o] = \frak{g}_{2\alpha} = \frak{z}$, this implies $\frak{z} \subset [s, s]$ and hence $\nu_o F \subset \frak{v}$. This establishes the proof of (3.6).

From (3.6) we see that there exists a linear subspace $\frak{v}_o$ of $\frak{v}$ so that $s_n = \frak{a} + \frak{v}_o + \frak{z}$. Using the Lie algebra structure of $\frak{a} + \frak{n}$, we get:

$$(3.7) \quad s_{n} \text{ is a subalgebra of } \frak{a} + \frak{n}.$$

Let $S_n$ be the connected subgroup of $AN$ with Lie algebra $s_n$. Our next aim is to show that the orbit $S_n \cdot o$ of $S_n$ through $o$ coincides with the singular orbit $F$. For this purpose we define

$$t = \frak{t}_x \cap \frak{s} \subset \frak{s}_c \quad \text{and} \quad s' = \mathbb{R}(\hat{B} + B) + [s, s],$$

where $B \in \frak{a}$ and $\hat{B} \in \frak{s}_c$ are defined as above. Since $t \subset \frak{s}_c$, $\hat{B} \in \frak{s}_c$ and $\frak{s}_c$ is abelian we have $[t, \hat{B}] = 0$, and since $t \subset \frak{t}_x$ and $\frak{t}_x$ centralizes $a$ we have $[t, B] = 0$. Clearly, we also have $[t, [s, s]] \subset [s, s] \subset s'$ since $t \subset s$ and $[s, s] \subset s$. Altogether this implies $[t, s'] \subset s'$. Moreover, since $s' \subset s$, we have $[s', s'] \subset [s, s] \subset s'$, which shows that $s'$ is a subalgebra of $s$. It follows that $s'$ is an ideal in $s$ and $s = t + s'$ (semidirect sum). Let $S'$ be the connected subgroup of $S$ with Lie algebra $s'$. Since $t \subset \frak{h}_o$ we see that $S'$ acts transitively on $F$, i.e., $S' \cdot o = F$. For all $V + Z \in [s, s] \subset \frak{n} = \frak{v} + \frak{z}$ we have

$$(3.8) \quad [\hat{B}, V + Z] + V + 2Z = [\hat{B}, V + Z] + [B, V + Z] = [\hat{B} + B, V + Z] \in s',$$

since $s'$ is a subalgebra. But $A$ and $V + Z$ are in $s_n$ according to (3.3) and (3.5), and since $s_n$ is a subalgebra by (3.7), we have $V + 2Z = [B, V + Z] \in s_n \cap \frak{n} = [s, s] \subset s'$ by (3.5). By (3.8) this implies $[\hat{B}, V + Z] \in s'$. But $\hat{B} \in \frak{s}_c \subset \frak{t}_x$ and thus $\text{ad}(\hat{B})$ leaves $\frak{v}$ and $\frak{z}$ invariant, which implies that $[\hat{B}, V + Z] \in s' \cap \frak{n} \subset [s, s] \subset s_n$. We thus have proved that $s_n$ is normalized by $\hat{B}$, i.e., $[\hat{B}, s_n] \subset s_n$. Let $\text{Exp}$ be the Lie exponential map of $\frak{g}$. We now get

$$F = S' \cdot o \subset \text{Exp}(\mathbb{R} \hat{B})s_n \cdot o = s_n \text{Exp}(\mathbb{R} \hat{B}) \cdot o = s_n \cdot o$$

since $\text{Exp}(\mathbb{R} \hat{B})$ normalizes $s_n$ and $\text{Exp}(\mathbb{R} \hat{B}) \cdot o \subset H_o \cdot o = o$. Finally, by (3.2) the
dimensions of $F$ and $S_n$ coincide, and since both $F$ and $S_n \cdot o$ are complete, we must have $F = S_n \cdot o$. We thus have proved:

**Theorem 3.2.** Let $H$ be a connected subgroup of $G = \mathcal{I}^\circ(FH^n)$ that acts on $FH^n$ with cohomogeneity one and with a non-totally-geodesic singular orbit $F$. Then there exists a unique point $x \in M(\infty)$ that is fixed under the induced action of $H$ on $M(\infty)$. Let $o \in F, K$ the isotropy group of $G$ at $o$, and $g = \mathfrak{k} + \mathfrak{a} + \mathfrak{n}$ the Iwasawa decomposition of $g$ that is induced by $o$ and $x$. Then there exists a subalgebra $\mathfrak{s}$ of $\mathfrak{a} + \mathfrak{n}$ of the form $\mathfrak{s} = \mathfrak{a} + \mathfrak{v}_o + z$ with some linear subspace $\mathfrak{v}_o$ of $\mathfrak{v}$, so that $F$ is the orbit of the connected subgroup $S$ of $AN$ with Lie algebra $\mathfrak{s}$.

4. **The classification**

In this section we discuss the classification of cohomogeneity one actions on noncompact symmetric spaces of rank one up to orbit equivalence. Recall that such an action has either no singular orbit or exactly one singular orbit.

**No singular orbit.** In [4] it was shown that there exist only two such actions without a singular orbit. The first one is given by the action of the nilpotent group $N$ in an Iwasawa decomposition $G = KAN$ of $G = \mathcal{I}^\circ(FH^n)$, and the orbits form a horosphere foliation. The second one is given by the subgroup $S$ of $AN$ with Lie algebra $\mathfrak{s} = \mathfrak{a} + \mathfrak{v}_o + z$, where $\mathfrak{v}_o$ is a linear subspace of $\mathfrak{a}$ with codimension one. The corresponding foliation has exactly one minimal leaf and has been investigated in detail in [2]. In the case of $FH^n$ the minimal leaf is a totally geodesic $\mathbb{R}H^{n-1} \subset \mathbb{R}H^n$.

**Totally geodesic singular orbit.** The cohomogeneity one actions on $FH^n$ with a totally geodesic singular orbit $F$ are given by:

- $M = \mathbb{R}H^n : F \in \{\text{pt}, \mathbb{R}H^1, \ldots, \mathbb{R}H^{n-2}\}$;
- $M = \mathbb{C}H^n : F \in \{\text{pt}, \mathbb{C}H^1, \ldots, \mathbb{C}H^{n-1}, \mathbb{C}H^n\}$;
- $M = \mathbb{H}H^n : F \in \{\text{pt}, \mathbb{H}H^1, \ldots, \mathbb{H}H^{n-1}, \mathbb{H}H^n\}$;
- $M = \mathbb{O}H^2 : F \in \{\text{pt}, \mathbb{O}H^1, \mathbb{O}H^2\}$.

Here, pt is a point in $FH^n$, and the corresponding cohomogeneity one action is just the action of the isotropy group of $\mathcal{I}^\circ(FH^n)$ at that point. More details about this can be found in [3].

**Non-totally-geodesic singular orbit.** We now come to the classification of cohomogeneity one actions with a non-totally-geodesic singular orbit $F$. We will use the same notation as in the previous section. Let $H$ be the connected component of the group of isometries of $M$ that leave $F$ invariant. By Theorem 3.2 there exists a unique point $x \in M(\infty)$ that is fixed under the induced action of $H$ on $M(\infty)$. Let $o \in F, K$ the isotropy group of $G$ at $o$, and $g = \mathfrak{k} + \mathfrak{a} + \mathfrak{n}$ the Iwasawa decomposition of $g$ that is induced by $o$ and $x$. Using again Theorem 3.2 there exists a subalgebra $\mathfrak{s}$ of $\mathfrak{a} + \mathfrak{n}$ of the form $\mathfrak{s} = \mathfrak{a} + \mathfrak{v}_o + z$ with some linear subspace $\mathfrak{v}_o$ of $\mathfrak{v}$, so that $F$ is the orbit of the connected subgroup $S$ of $AN$ with Lie algebra $\mathfrak{s}$. From the construction it is clear that the identity component of $H_o$ coincides with the identity component $N^\circ_K(\mathfrak{s})$ of the normalizer $N_K(\mathfrak{s})$ of $\mathfrak{s}$ in $K$. In order that $H$ acts with cohomogeneity one it is therefore necessary and sufficient that the action of $N^\circ_K(\mathfrak{s})$ on the normal space $\mathfrak{v}_o F$ is transitive on the unit sphere in $\mathfrak{v}_o F$. Note that $N^\circ_K(\mathfrak{s}) \subset K_s$. Since all Iwasawa decompositions of $g$ are conjugate to each other under an inner automorphism of $g$, it therefore remains to classify all subalgebras...
s of $a + n$ of the form $s = a + v_o + j$ with some linear subspace $v_o$ of $v$ such that $N_K^o(s)$ acts transitively on the unit sphere in $v_o^\perp$, the orthogonal complement of $v_o$ in $v$. This proves the first part of the following theorem:

**Theorem 4.1.** Let $g = \mathfrak{p} + a + n$ be the Iwasawa decomposition induced by $o \in M$ and $x \in M(\infty)$.

(i) Let $v_o$ be a linear subspace of $v$ so that $\dim v_o^\perp \geq 2$ and $N_K^o(v_o)$ acts transitively on the unit sphere in $v_o^\perp$. Then the connected subgroup of $G$ with Lie algebra $N^K_o(v_o) + a + v_o + j$ acts on $M$ with cohomogeneity one so that the orbit through $o$ is singular. Furthermore, every cohomogeneity one action on $M$ with a non-totally-geodesic singular orbit can be obtained in this way up to orbit equivalence.

(ii) Let $v_o$ and $v'_o$ be linear subspaces of $v$ as in (i), and assume that the corresponding cohomogeneity one actions have non-totally-geodesic singular orbits. Then, these actions are orbit equivalent if and only if there exists an isometry $k \in K_x$ so that $\text{Ad}(k)v_o = v'_o$.

**Proof.** It remains to prove part (ii). The “if”-part of the statement is obvious. Conversely, assume that the two cohomogeneity one actions are orbit equivalent. Then the corresponding singular orbits, say $S$ and $S'$, are congruent under an isometry $k$ of $M$. We may assume that $k$ fixes $o$. By construction, the normalizers $N_G(S)$ and $N_G(S')$ fix $x$, the point at infinity that determines our Iwasawa decomposition. Then $k$ must fix $x$ as well, since $kN_G(S)k^{-1} = N_G(S')$ and $x$ is the unique fixed point in $M(\infty)$ of $N_G(S)$ and of $N_G(S')$. Therefore we conclude that $\text{Ad}(k)v_o = v'_o$. \hfill \Box

We now discuss the four different hyperbolic spaces individually.

$M = \mathbb{R}H^n$ It follows from the classification of isoparametric hypersurfaces in $\mathbb{R}H^n$ by Cartan [10] that there exist no such actions. Since a singular orbit of a cohomogeneity one action is necessarily minimal, one can also apply a result by Di Scala and Olmos [11] stating that every minimal homogeneous submanifold of $\mathbb{R}H^n$ is totally geodesic.

The classification also follows easily from Theorem [11]. Assume there is a cohomogeneity one action on $\mathbb{R}H^n$ with a non-totally-geodesic singular orbit $F$. Theorem [11] implies that the action is orbit equivalent to the $H$-action induced from $\mathfrak{h} = N^K_o(v_o) + a + v_o$ for some suitable subspace $v_o$ of $v$. But for such an $H$-action the orbit $F = H \cdot o$ is totally geodesic, which is a contradiction.

$M = \mathbb{C}H^n$ In this case the Kähler structure on $\mathbb{C}H^n$ induces a complex structure $J$ on $v$ so that $v$ is isomorphic to $\mathbb{C}^{n-1}$ as a complex vector subspace. Let $v_o$ be a linear subspace of $v$ so that $\dim v_o^\perp \geq 2$. Recall that the Kähler angle of a nonzero vector $v \in v_o^\perp \subset \mathbb{C}^{n-1}$ is defined as the angle between $Jv$ and $v_o^\perp$. In order that $N_K^o(s)$ acts transitively on the unit sphere in $v_o^\perp$ it is necessary that the Kähler angle of $v_o^\perp$ does not depend on the choice of the unit vector in $v_o^\perp$. We thus assume that for all nonzero vectors $v \in v_o^\perp$ the Kähler angle is equal to some $\varphi \in [0, \pi/2]$. In the special case that $\varphi = 0$, $v_o^\perp$ is a complex subspace of $v$, and if $\varphi = \pi/2$, then $v_o^\perp$ is a real subspace of $v$. The subspaces of complex vector spaces with constant Kähler angle have been classified in [3]. For $\varphi = 0$ we just have the complex subspaces and for $\varphi = \pi/2$ the real subspaces, and in both cases the congruence classes (under the action of $K_x = U(n-1)$ on $v = \mathbb{C}^{n-1}$) are parametrized by the complex, resp. real, dimension. For $\varphi \in (0, \pi/2)$ there exists exactly one congruence class
of subspaces with constant Kähler angle \( \varphi \) for each dimension \( 0 < 2k \leq n - 1 \). For any such subspace the resulting action on \( CH^n \) is of cohomogeneity one and \( F \) is a non-totally-geodesic singular orbit unless \( \varphi = 0 \) (then \( F \) is a totally geodesic complex submanifold). Using Theorem 4.4, we therefore conclude:

**Theorem 4.2.** The moduli space of all cohomogeneity one actions on \( CH^n \), \( n \geq 2 \), with a non-totally-geodesic singular orbit (up to orbit equivalence) is isomorphic to the disjoint union

\[
\{2, \ldots, n-1\} \cup \left( \{(0, \pi/2) \times \{2k \mid k \in \mathbb{Z}, 0 < 2k < n\}\} \right).
\]

The integer in \( \{2, \ldots, n-1\} \) indicates the codimension of the singular orbit if the normal spaces are real, and the integer in \( \{2k \mid k \in \mathbb{Z}, 0 < 2k < n\} \) indicates the codimension of the singular orbit if the normal spaces have constant Kähler angle \( \varphi \in (0, \pi/2) \).

**Corollary 4.3.** Any singular orbit of a cohomogeneity one action on \( CH^2 \) is totally geodesic.

Note that by this result we now have a complete classification of the homogeneous hypersurfaces in \( CH^n \) for all \( n \geq 2 \). In view of [3], we call a submanifold \( M \) normally homogeneous if \( M \) is homogeneous and if the slice representation at \( p \in M \) acts transitively on the unit sphere in \( \nu_pM \). A singular orbit of a cohomogeneity one action is clearly a normally homogeneous submanifold. The above shows that for each \( k \in \{2, \ldots, n-1\} \) there exists, up to holomorphic congruence, exactly one normally homogeneous submanifold \( F_k \) of \( CH^n \) with real normal bundle of rank \( k \), and for each \( k \in \{1, \ldots, [n-1/2]\} \) and each \( \varphi \in (0, \pi/2) \) there exists exactly one, up to holomorphic congruence, normally homogeneous submanifold \( F_{k,\varphi} \) of \( CH^n \) with normal bundle of rank \( 2k \) and constant Kähler angle \( \varphi \).

**Theorem 4.4.** Let \( M \) be a homogeneous hypersurface in \( CH^n \), \( n \geq 2 \). Then \( M \) is holomorphically congruent to one of the following hypersurfaces:

1. A tube of radius \( r \in \mathbb{R}_+ \) around the totally geodesic \( CH^k \subset CH^n \) for some \( k \in \{0, \ldots, n-1\} \);
2. A tube of radius \( r \in \mathbb{R}_+ \) around the totally geodesic \( RH^n \subset CH^n \);
3. A horosphere in \( CH^n \);
4. The minimal ruled real hypersurface \( S \) determined by a horocycle in a totally geodesic \( RH^2 \subset CH^n \), or an equidistant hypersurface to \( S \);
5. A tube of radius \( r \in \mathbb{R}_+ \) around the normally homogeneous submanifold \( F_k \) of \( CH^n \) with real normal bundle of rank \( k \), \( k \in \{2, \ldots, n-1\} \);
6. A tube of radius \( r \in \mathbb{R}_+ \) around the normally homogeneous submanifold \( F_{k,\varphi} \) of \( CH^n \) with normal bundle of rank \( 2k \in \{2, \ldots, 2([n-1/2])\} \) and constant Kähler angle \( \varphi \in (0, \pi/2) \).

In this case the quaternionic Kähler structure on \( HH^n \) induces a quaternionic structure \( J \) on \( \mathfrak{v} \) so that \( \mathfrak{v} \) is isomorphic to \( HH^{n-1} \) as a (right) quaternionic vector subspace. Let \( \mathfrak{v}_o \) be a linear subspace of \( \mathfrak{v} \) so that \( \dim_{\mathbb{R}} \mathfrak{v}_o^+ \geq 2 \). In [3] the first author and Brück introduced the notion of a quaternionic Kähler angle, which is defined as follows. Let \( S^2 \) be the two-sphere of all almost Hermitian structures in \( \mathfrak{J} \). For each nonzero vector \( v \in \mathfrak{v}_o^+ \) and each \( J \in S^2 \) denote by \( \varphi(v, J) \) the Kähler angle of \( JV \) and \( \mathfrak{v}_o^+ \) in the complex vector space \( \langle v, J \rangle \). Since \( S^2 \) is compact,
there exist a minimum and a maximum for these K"ahler angles. It was shown in
[3] that for each nonzero $v$ there always exists a canonical basis $J_1, J_2, J_3$ of
elements in $S^2$ (i.e., $J_1J_{1+1} = J_{2+1} = -J_{2+1}J_2$, index modulo 3) such that $\varphi(v, J_3)$
is the minimum $\varphi_1(v)$ of these K"ahler angles and $\varphi(v, J_3)$ is the maximum $\varphi_3(v)$
of these K"ahler angles. For any canonical basis with this property the K"ahler angle
$\varphi_2(v) = \varphi(v, J_2)$ attains the same value. The triple $\Phi(v) = (\varphi_1(v), \varphi_2(v), \varphi_3(v))$ of
K"ahler angles is called the quaternionic K"ahler angle of $V^+_n$ with respect to $v$. For a
cohomogeneity one action the quaternionic K"ahler angle of $V^+_n$ must be independent
of the choice of the unit vector in $V^+_n$. In [3] several examples of subspaces of $\mathbb{H}^{n-1}$
with constant quaternionic K"ahler angle were given, but a complete classification
is still missing. The examples are as follows:

(a) $\Phi = (0, 0, 0)$. The linear subspaces of $V$ with constant quaternionic K"ahler
angle $\Phi = (0, 0, 0)$ are the quaternionic subspaces. A linear subspace $V \subset V$ is
quaternionic if $JV \subset V$ holds for all $J \in \mathbb{J}$. For each integer $k$ with $0 < k < n$ there
exists exactly one (up to orbit equivalence) cohomogeneity one action on $\mathbb{H}^n$ with
a singular orbit $F$ of real codimension $4k$ with the property that the normal spaces
of $F$ have constant quaternionic K"ahler angle $\Phi = (0, 0, 0)$, and $F$ is congruent to
the totally geodesic $\mathbb{H}^{n-k} \subset \mathbb{H}^n$.

(b) $\Phi = (0, \pi/2, \pi/2)$. The linear subspaces of $V$ with constant quaternionic
K"ahler angle $\Phi = (0, \pi/2, \pi/2)$ are the totally complex subspaces. A linear subspace
$V \subset V$ is totally complex if there exists an almost Hermitian structure $J_1 \in \mathbb{J}$ such
that $J_1V \subset V$ and $JV \subset V^\perp$ for all $J \in \mathbb{J}$ perpendicular to $J_1$. For each integer
$k \in \{1, \ldots, n-1\}$ there exists exactly one (up to orbit equivalence) cohomogeneity one action on $\mathbb{H}^n$
with a non-totally-geodesic singular orbit $F$ of real codimension $2k$ with the property that the normal spaces
of $F$ have constant quaternionic K"ahler angle $\Phi = (0, 0, 0)$, and $F$ is congruent to
the totally geodesic $\mathbb{H}^n \subset \mathbb{H}^n$.

(c) $\Phi = (\pi/2, \pi/2, \pi/2)$. The linear subspaces of $V$ with constant quaternionic
K"ahler angle $\Phi = (\pi/2, \pi/2, \pi/2)$ are the totally real subspaces. A linear subspace
$V \subset V$ is totally real if $JV \subset V^\perp$ holds for all $J \in \mathbb{J}$. For each integer $k \in \{2, \ldots, n-1\}$ there exists exactly one (up to orbit equivalence) cohomogeneity one action on $\mathbb{H}^n$
with a non-totally-geodesic singular orbit $F$ of real codimension $k$ with the property that the normal spaces of $F$ have constant quaternionic K"ahler angle $\Phi = (0, \pi/2, \pi/2)$.

(d) $\Phi = (0, 0, \pi/2)$. The linear subspaces of $V$ with constant quaternionic K"ahler
angle $\Phi = (0, 0, \pi/2)$ are the 3-dimensional subspaces of the form $\{\text{Im} \mathbb{H} \}v$ for some
unit vector $v \in V$. There exists exactly one (up to orbit equivalence) cohomogeneity one action on $\mathbb{H}^n$
with a non-totally-geodesic singular orbit $F$ of real codimension 3 with the property that the normal spaces of $F$ have constant quaternionic K"ahler angle $\Phi = (0, 0, \pi/2)$.

(e) $\Phi = (\varphi, \pi/2, \pi/2), \varphi \in (0, \pi/2)$. The linear subspaces of $V$ with constant quaternionic K"ahler angle $\Phi = (\varphi, \pi/2, \pi/2), \varphi \in (0, \pi/2)$, are the linear subspaces
with constant K"ahler angle $\varphi$ in a totally complex subspace $V$ of $V$. Here, the
K"ahler angle in $V$ is measured with respect to the almost Hermitian structure $J_1$
as described in (b). For each integer $k \in \{1, \ldots, [n-1]/2\}$ and each $\varphi \in (0, \pi/2)$
there exists exactly one (up to orbit equivalence) cohomogeneity one action on $\mathbb{H}^n$
with a non-totally-geodesic singular orbit $F$ of real codimension $2k$ with the property that the normal spaces of $F$ have constant quaternionic K"ahler angle $\Phi = (\varphi, \pi/2, \pi/2)$. 

(f) $\Phi = (0, \varphi, \varphi), \varphi \in (0, \pi/2)$. The linear subspaces of $v$ with constant quaternionic Kähler angle $\Phi = (0, \varphi, \varphi), \varphi \in (0, \pi/2)$, are the complexifications of linear subspaces with constant Kähler angle $\varphi$ in a totally complex subspace $w$ of $v$. More precisely, let $J_2 \in J$ be an almost Hermitian structure and consider $v$ as the complexification of $w$ with respect to an almost Hermitian structure $J_1 \in J$ orthogonal to $J_2$; that is, $v = w + J_1 w$ with a $J_2$-invariant linear subspace $w \subset v$. Let $W$ be a linear subspace of the complex vector space $(w, J_2)$ with constant Kähler angle $\varphi$. Then the complexification of $W$ with respect to $J_1$ is a linear subspace of $v$ with constant quaternionic Kähler angle $\Phi = (0, \varphi, \varphi)$. For each integer $k \in \{1, \ldots, [(n-1)/2]\}$ and each $\varphi \in (0, \pi/2)$ there exists exactly one (up to orbit equivalence) cohomogeneity one action on $\mathbb{H}H^n$ with a non-totally-geodesic singular orbit $F$ of real codimension $4k$ with the property that the normal spaces of $F$ have constant quaternionic Kähler angle $\Phi = (0, \varphi, \varphi)$.

We conjecture that each cohomogeneity one action on $\mathbb{H}H^n$ with a non-totally-geodesic singular orbit is orbit equivalent to one of these examples. This is true for $n = 2$, and for the case that the singular orbit has codimension 2.

**Theorem 4.5.** The moduli space of all cohomogeneity one actions on $\mathbb{H}H^2$ with a non-totally-geodesic singular orbit (up to orbit equivalence) is isomorphic to the set $\{2, 3\}$. The number $k \in \{2, 3\}$ parametrizes the unique (up to orbit equivalence) cohomogeneity one action on $\mathbb{H}H^2$ with a non-totally-geodesic singular orbit of codimension $k$.

**Proof.** In the case of $\mathbb{H}H^2$ the quaternionic vector space $v$ has quaternionic dimension one. It is easy to see that every 2-dimensional subspace of a one-dimensional quaternionic subspace has constant quaternionic Kähler angle $\Phi = (0, \pi/2, \pi/2)$, and every 3-dimensional subspace of a one-dimensional quaternionic subspace has constant quaternionic Kähler angle $\Phi = (0, 0, \pi/2)$. The result then follows from (b) and (d) above. Note that codimension 4 occurs for quaternionic Kähler angle $\Phi = (0, 0, 0)$, which leads to a totally geodesic singular orbit. □

**Theorem 4.6.** The moduli space of all cohomogeneity one actions on $\mathbb{H}H^n$, $n > 2$, with a non-totally-geodesic singular orbit with codimension 2 (up to orbit equivalence) is isomorphic to the closed interval $[0, \pi/2]$. The number $\varphi \in [0, \pi/2]$ parametrizes the unique (up to orbit equivalence) cohomogeneity one action on $\mathbb{H}H^n$ with a non-totally-geodesic singular orbit of codimension 2 for which the normal spaces have constant quaternionic Kähler angle $\Phi = (\varphi, \pi/2, \pi/2)$.

**Proof.** Every 2-dimensional subspace of $v$ has constant quaternionic Kähler angle $\Phi = (\varphi, \pi/2, \pi/2)$ for some $\varphi \in [0, \pi/2)$. The result then follows from (b), (c) and (e) above. □
The Lie group $Spin(7)$ acts on $\mathbb{R}^8$ by its irreducible 8-dimensional spin representation. This naturally induces actions of $Spin(7)$ on $G^+_4(\mathbb{R}^8)$ and $G_4(\mathbb{R}^8)$. For $k = 1$, it was proved by Borel [7] that $Spin(7)$ acts transitively on $G^+_4(\mathbb{R}^8) = S^7$ and that $S^7 = Spin(7)/G_2$. For $k = 2$ we also have a transitive action, so that $G^+_4(\mathbb{R}^8) = Spin(7)/U(3)$ (see e.g. [8]), and hence also $G^+_4(\mathbb{R}^8) = Spin(7)/U(3)$. Also for $k = 3$ the action is transitive, and we have $G^+_4(\mathbb{R}^8) = Spin(7)/SO(4)$ (see e.g. [19]), and thus also $G^+_4(\mathbb{R}^8) = Spin(7)/SO(4)$.

The action of $Spin(7)$ on $G^+_4(\mathbb{R}^8)$ is not transitive, but of cohomogeneity one (see [8] and [13] for details). One singular orbit of this action consists of the so-called Cayley 4-planes in $\mathbb{O}$ introduced by Harvey and Lawson [13]. The submanifolds of $\mathbb{O}$ all of whose tangent spaces are Cayley 4-planes in $\mathbb{O}$ and that principal orbits are the 3-spheres in $S^4$ and that $[8]$ and $[13]$ for details). One singular orbit of this action consists of the so-called Cayley 4-planes in $\mathbb{O}$ and provide a beautiful example of a calibrated geometry. This singular orbit is isomorphic to $Spin(7)/(SU(2)^3/Z_2)$, and the second singular orbit consists just of the Cayley 4-planes with opposite orientation. This can also be seen in the following way. Let $V \in G^+_4(\mathbb{R}^8)$ be an oriented 3-plane in $\mathbb{R}^8$. We know from the above that $Spin(7)$ acts transitively on $G^+_4(\mathbb{R}^8)$ and the isotropy group at $V$ is some $SO(4) \subset Spin(7)$. There is a unique unit vector $\xi$ in the orthogonal complement $V^\perp$ of $V$ in $\mathbb{R}^8$ so that the 4-plane $V \oplus \mathbb{R} \xi$ is a Cayley 4-plane. Then $V \oplus \mathbb{R}(-\xi)$ is the same 4-plane with opposite orientation. The action of $SO(4)$ on the unit sphere $S^4$ in $V^\perp$ is the standard action determined by the two fixed points $\pm \xi$. The principal orbits are the 3-spheres in $S^4$ with center $\xi$. Each such orbit parametrizes in a canonical way a set of oriented 4-planes in $\mathbb{R}^8$ containing the 3-dimensional subspace $V$. We now turn to the induced action of $Spin(7)$ on the Grassmannian $G_4(\mathbb{R}^8)$ of unoriented 4-planes in $\mathbb{R}^8$. This action is clearly of cohomogeneity one as well. The two singular orbits on $G^+_4(\mathbb{R}^8)$ become identified under the two-fold covering map $G^+_4(\mathbb{R}^8) \to G_4(\mathbb{R}^8)$ and provide one singular orbit of the action. The second singular orbit in $G^+_4(\mathbb{R}^8)$ is the projection of the principal orbit on $G^+_4(\mathbb{R}^8)$ containing 4-planes of both orientations. This orbit contains the 4-planes that are constructed from the unique totally geodesic principal orbit of the $SO(4)$-action on $S^4 \subset V^\perp$. The second singular orbit in $G_4(\mathbb{R}^8)$ is therefore a 2-fold subcovering of any principal orbit and thus has the same dimension as the principal orbits.

From Theorem 4.1 it is clear that if the action of $Spin(7)$ is transitive on $G_4(\mathbb{R}^8)$, then all cohomogeneity one actions constructed from a $k$-dimensional subspace of $\mathbf{v}$ are orbit equivalent. In the case $k = 4$, the cohomogeneity one actions induced from a 4-dimensional subspace of $\mathbf{v}$ up to orbit equivalence are in one-to-one correspondence with the orbits of the action of $Spin(7)$ on $G_4(\mathbb{R}^8)$. Altogether this now implies:

**Theorem 4.7.** The moduli space of all cohomogeneity one actions on $\mathbb{O}H^2$ with a non-totally-geodesic singular orbit (up to orbit equivalence) is isomorphic to the disjoint union

$$\{2, 3, 6, 7\} \cup \{(4) \times [0, 1]\}.$$  

The number $k \in \{2, 3, 6, 7\}$ parametrizes the unique (up to orbit equivalence) cohomogeneity one action on $\mathbb{O}H^2$ with a singular orbit of codimension $k$. The set $\{(4) \times [0, 1]\}$ parametrizes the cohomogeneity one actions on $\mathbb{O}H^2$ with a singular orbit of codimension 4 (up to orbit equivalence).

The above result says that for each $k \in \{2, 3, 6, 7\}$ there exists exactly one, up to isometric congruence, normally homogeneous submanifold $F_k$ of $\mathbb{O}H^2$ with normal
bundle of rank \(k\), and for each \(\varphi \in [0, 1]\) there exists exactly one, up to isometric congruence, normally homogeneous submanifold \(F_{k,\varphi}\) of \(\mathbb{O}H^2\) with normal bundle of rank 4. We now have a complete classification of the homogeneous hypersurfaces in the Cayley hyperbolic plane.

**Theorem 4.8.** Let \(M\) be a homogeneous hypersurface in \(\mathbb{O}H^2\). Then \(M\) is isometrically congruent to one of the following hypersurfaces:

1. A geodesic hypersphere of radius \(r \in \mathbb{R}_+\) in \(\mathbb{O}H^2\);
2. A tube of radius \(r \in \mathbb{R}_+\) around the totally geodesic \(\mathbb{O}H^2 \subset \mathbb{O}H^2\);
3. A tube of radius \(r \in \mathbb{R}_+\) around the totally geodesic \(\mathbb{H}H^2 \subset \mathbb{O}H^2\);
4. A horosphere in \(\mathbb{O}H^2\);
5. The minimal homogeneous hypersurface \(S\) in \(\mathbb{O}H^2\), or an equidistant hypersurface to \(S\);
6. A tube of radius \(r \in \mathbb{R}_+\) around the normally homogeneous submanifold \(F_k\) of \(\mathbb{O}H^2\) with normal bundle of rank \(k\), \(k \in \{2, 3, 6, 7\}\);
7. A tube of radius \(r \in \mathbb{R}_+\) around the normally homogeneous submanifold \(F_{4,\varphi}\) of \(\mathbb{O}H^2\) with normal bundle of rank 4 and \(\varphi \in [0, 1]\).

**References**


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