

1. H. J. STETTER, "Stabilizing predictors for weakly unstable correctors," *Math. Comp.*, v. 19, 1965, pp. 84–89. MR 31 #2833.
2. H. J. STETTER, "A study of strong and weak stability in discretization algorithms," *J. Soc. Indust. Appl. Math. Ser. B Numer. Anal.*, v. 2, 1965, pp. 265–280. MR 32 #4859.
3. R. L. CRANE & R. W. KLOPFENSTEIN, "A predictor-corrector algorithm with an increased range of absolute stability," *J. Assoc. Comput. Math.*, v. 12, 1965, pp. 227–241. MR 31 #6378.
4. F. T. KROGH, "Predictor-corrector methods of high order with improved stability characteristics," *J. Assoc. Comput. Mach.*, v. 13, 1966, pp. 374–385. MR 33 #5127.
5. B. A. FUCHS & V. I. LEVIN, *Functions of a Complex Variable and Some of Their Applications*, Vol. II, Pergamon Press, New York, 1961; Addison-Wesley, Reading, Mass., 1962. MR 24 #A2654.
6. E. C. TITCHMARSH, *The Theory of Functions*, Oxford Univ. Press, Oxford, 1939.
7. ANTHONY RALSTON, "Relative stability in the numerical solution of ordinary differential equations," *SIAM Rev.*, v. 7, 1965, pp. 114–125. MR 31 #2831.
8. F. T. KROGH, "A test for instability in the numerical solution of ordinary differential equations," *J. Assoc. Comput. Mach.*, v. 14, 1967, pp. 351–354. (This gives the stability diagram for the method proposed by Stetter in [1].)

Midpoint Quadrature Formulas

By Seymour Haber

A family of quadrature formulas for the interval $(0, 1)$ can be constructed in the following manner: For any positive integer n , we partition $(0, 1)$ into subintervals I_1, I_2, \dots, I_n (I_1 being the leftmost, I_2 adjacent to it, etc.) of lengths a_1, a_2, \dots, a_n , respectively. Now let x_k be the midpoint of I_k , for $k = 1, \dots, n$, and take

$$(1) \quad a_1 f(x_1) + \dots + a_n f(x_n)$$

as the approximation to $\int_0^1 f(x) dx$. The simplest of these rules is the "Euler's" or "midpoint" rule

$$\int_0^1 f(x) dx \approx f\left(\frac{1}{2}\right).$$

We will refer to the members of this family as "midpoint quadrature formulas" and determine their properties. We first find their "degrees of precision"—that is, for any formula, the highest integer p such that the formula is exact for all polynomials of degree p or lower.

THEOREM 1. *The degree of precision of a midpoint quadrature formula is 1.*

Proof. The formula is exact for constants, since necessarily $a_1 + a_2 + \dots + a_n = 1$. To check the exactness of the formula for $f(x) = x$, we first note that

$$(2) \quad x_1 = \frac{a_1}{2}, x_2 = a_1 + \frac{a_2}{2}, \dots, x_n = a_1 + \dots + a_{n-1} + \frac{a_n}{2}.$$

So for the integral $\int_0^1 x dx$, (1) gives us

$$a_1(a_1/2) + a_2(a_1 + a_2/2) + \dots + a_n(a_1 + \dots + a_{n-1} + a_n/2).$$

But this is just

$$\frac{1}{2}(a_1^2 + a_2^2 + \cdots + a_n^2 + 2a_1a_2 + 2a_1a_3 + \cdots + 2a_{n-1}a_n),$$

or $\frac{1}{2}(a_1 + \cdots + a_n)^2$, which is $\frac{1}{2}$. Thus the degree of precision is at least one. To show it is no greater, we calculate error in integrating $x^2/2$ by the rule:

$$\int_0^1 \frac{x^2}{2} dx - \sum_{i=1}^n a_i \frac{x_i^2}{2} = \frac{1}{6} - \frac{1}{2} \sum_{i=1}^n a_i \left(a_1 + a_2 + \cdots + a_{i-1} + \frac{a_i}{2} \right)^2.$$

Multiplying out and collecting terms in the last sum, we obtain:

$$\sum_i a_i x_i^2 = \frac{1}{4} \sum_i a_i^3 + \sum_{i \neq j} a_i a_j^2 + 2 \sum_{i \neq j \neq k} a_i a_j a_k,$$

where the indices of summation run from 1 to n .

Now

$$1 = (a_1 + \cdots + a_n)^3 = \sum_i a_i^3 + 3 \sum_{i \neq j} a_i a_j^2 + 6 \sum_{i \neq j \neq k} a_i a_j a_k,$$

so that

$$\frac{1}{3} - \sum_i a_i x_i^2 = \frac{1}{12} (a_1^3 + \cdots + a_n^3).$$

It follows that

$$(3) \quad \int_0^1 \frac{x^2}{2} dx - \sum_i a_i \frac{x_i^2}{2} = \frac{1}{24} (a_1^3 + \cdots + a_n^3) > 0,$$

which proves the theorem.

THEOREM 2. *The error of a midpoint quadrature formula, for an integrand with continuous second derivative, is given by*

$$(4) \quad \int_0^1 f(x) dx - \sum_i a_i f(x_i) = \frac{1}{24} (a_1^3 + \cdots + a_n^3) f''(\xi)$$

for some ξ in $(0, 1)$.

Proof. By a general remainder theorem (see, e.g., [1]) the error may be written in the form

$$(5) \quad \int_0^1 f''(t) K(t) dt$$

where

$$K(t) = \frac{(1-t)^2}{2} - \sum_{x_i > t} a_i (x_i - t).$$

To derive (4) from (5) it is sufficient to show that $K(t)$ does not change sign in $(0, 1)$; for then we may write

$$\int_0^1 f''(t) K(t) dt = f''(\xi) \int_0^1 K(t) dt,$$

and, taking $f(x) = x^2/2$, we see from (3) that

$$\int_0^1 K(t)dt = \frac{1}{24} (a_1^3 + \cdots + a_n^3).$$

We shall show that, in fact, $K(t) \geq 0$ for $t \in [0, 1]$.

For t between x_k and x_{k+1} ,

$$\begin{aligned} 2K(t) &= (1-t)^2 - 2 \sum_{i=k+1}^n a_i(x_i - t) \\ &= (1-t)^2 - 2 \sum_{i=k+1}^n a_i(1-t) + 2 \sum_{i=k+1}^n a_i(1-x_i). \end{aligned}$$

Now, in fact

$$2 \sum_{i=k+1}^n a_i(1-x_i) = (a_{k+1} + a_{k+2} + \cdots + a_n)^2.$$

To prove this by induction, we need only show that

$$2a_k(1-x_k) = a_k^2 + 2a_k(a_{k+1} + \cdots + a_n),$$

which follows directly from the fact that

$$x_k = 1 - a_n - a_{n-1} - \cdots - a_{k+1} - a_k/2.$$

Therefore, in $[x_k, x_{k+1})$,

$$2K(t) = ((1-t) - (a_{k+1} + \cdots + a_n))^2 \geq 0;$$

and it can similarly be shown that K is nonnegative in $[0, x_1]$ and $[x_n, 1]$.

It is easy to see that, given n , the coefficient $(a_1^3 + \cdots + a_n^3)/24$ in (4) is least when $a_1 = a_2 = \cdots = a_n = 1/n$, so that for any n , the "best" midpoint quadrature rule is simply the repeated Euler's rule.

National Bureau of Standards
Washington, D. C. 20234

1. V. I. KRYLOV, *Approximate Calculation of Integrals*, Macmillan, New York, 1962, p. 77.
MR 26 #2008.