

1011-19-180

**Dan Edidin\*** ([edidin@math.missouri.edu](mailto:edidin@math.missouri.edu)), Department of Mathematics, University of Missouri, Columbia, MO 65211. *Non-abelian localization in equivariant K-theory.*

The localization theorem for actions diagonalizable groups is a fundamental result in equivariant  $K$ -theory. The theorem can be stated as follows: If  $T$  is a diagonalizable group acting on a space  $X$  and  $h \in T$  has fixed locus  $X^h$  then the direct image in equivariant  $K$ -theory  $i_*: G(X^h, T) \rightarrow G(X, T)$  is an isomorphism after localizing at certain prime ideal in the representation ring  $R(T)$ . When  $X$  is smooth the localization isomorphism has an explicit inverse which is extremely useful for computation.

In this talk, I will explain how to obtain an explicit "localization" (which actually involves completion) formula for actions of arbitrary algebraic groups on smooth algebraic spaces defined over  $\mathbb{C}$ . Applications include a Riemann-Roch formula for geometric quotients as well as a method to represent elements of equivariant  $K$ -theory by cycles.

Much of the talk is based on a joint paper with William Graham, [math.AG/0411213](https://arxiv.org/abs/math/0411213), to appear in *Advances in Math.* (Received August 25, 2005)