

1011-53-71

**Irina A Kogan\*** ([iakogan@ncsu.edu](mailto:iakogan@ncsu.edu)), Department of Mathematics, North Carolina State University, Raleigh, NC 27695, and **Ian Anderson** ([anderson@math.usu.edu](mailto:anderson@math.usu.edu)), Department of Mathematics and Statistics, Utah State University, 3900 Old Main Hill, Logan, UT 84322.  
*Variational Calculus in Moving Frames.*

Many interesting systems of differential equations and variational problems arising in geometry and physics admit a group of symmetries. As it was first recognized by S. Lie, these problems can be rewritten in terms of groups invariant objects: differential invariants, invariant differential forms, and invariant differential operators. It is desirable from both computational and theoretical points of view to use a group-invariant basis of differential operators and differential forms to perform further computations with symmetric systems. This provides a motivation for performing differential and variational calculus on a jet bundle relative to a non-standard moving frame. Complexity of the structure equations for a non-standard coframe and non-commutativity of differential operators present, however, both theoretical and computational challenge. We present new symbolic algorithms for computing prolongation of vector fields, integration by parts, Euler-Lagrange and Helmholtz operators, and Noether correspondence relative to a non-standard basis of differential operators and differential forms. (Received August 11, 2005)