

A NOTE ON ERGODIC THEORY

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The purpose of this paper is to present solutions to certain problems in ergodic theory suggested by Einar Hille in his book *Functional analysis and semi-groups* [1].¹

Let $T(\xi)$ ($\xi > 0$) be a semi-group of linear bounded transformations on a complex Banach space \mathfrak{X} to itself. Following Hille, we say that $T(\xi)$ is ergodic at infinity (or at 0) if it has a generalized limit of some sort when $\xi \rightarrow \infty$ (or $0+$). We define the Abel mean

$$(1) \quad L[\lambda, T(\cdot)x] = \lambda \int_0^\infty \exp(-\lambda\xi) T(\xi)x d\xi$$

and the Cesaro- α ($C-\alpha$) mean

$$(2) \quad a[\xi, T(\cdot)x, \alpha] = \alpha\xi^{-\alpha} \int_0^\xi (\xi - \tau)^{\alpha-1} T(\tau)x d\tau.$$

In order that the integrals involved shall have a sense, we impose the following restrictions on $T(\xi)$:

- (i) $T(\xi)$ is strongly measurable for $\xi > 0$,
- (ii)_{*} $\int_0^\infty \exp(-\lambda\xi) \|T(\xi)x\| d\xi$ exists for $\lambda > 0$ and all $x \in \mathfrak{X}$

or

- (ii)_u $\int_0^\infty \exp(-\lambda\xi) \|T(\xi)\| d\xi$ exists for $\lambda > 0$.

In theorems referring to limiting processes at infinity we shall also impose the restriction

- (iii) $\lim_{\eta \rightarrow 0+} \eta^{-1} \int_0^\eta T(\xi)x d\xi = x$ for all $x \in \mathfrak{X}$.

Condition (i) alone implies that $T(\xi)$ is strongly continuous for $\xi > 0$ (see [1, Theorem 9.2.1] and [2]); whereas (ii)_{*} implies the existence of the Abel mean for $\lambda > 0$. If (ii)_u is satisfied, the infinitesimal generator A of the semi-group operator will be a closed linear trans-

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¹ Numbers in brackets refer to the references cited at the end of the paper.

formation. If conditions (i), (ii_s), and (iii) are all satisfied, then the resolvent theory (see [1, sec. 11.8]) is valid; in particular the linear bounded operator

$$(3) \quad R(\lambda; A)x = \int_0^\infty \exp(-\lambda\xi)T(\xi)x d\xi$$

exists for $\operatorname{Re}(\lambda) > 0$, satisfies the first resolvent equation, and

$$(4) \quad \begin{aligned} (\lambda I - A)R(\lambda; A)x &= x && \text{for } x \in \mathfrak{X}, \\ R(\lambda; A)(\lambda I - A)x &= x && \text{for } x \in \mathfrak{D}[A], \end{aligned}$$

where $\mathfrak{D}[A]$, the domain of A , is now dense in \mathfrak{X} . It will be shown in Example 2 that conditions (i), (ii_w), and (iii) do not imply the boundedness of $\|T(\xi)\|$ in a neighborhood of the origin. Finally, if U is a linear operator on \mathfrak{X} to itself, we denote by $\mathfrak{R}[U]$ the range of U and by $\mathfrak{Z}[U]$ the zeros of U .

Our principal result is the proof of the following theorem conjectured by Hille [1, p. 301].

THEOREM 1. *If the semi-group operator $T(\xi)$ satisfies conditions (i), (ii_w), (iii); and if in addition $\mathfrak{R}[A^2]$ is closed and $\lim_{\lambda \rightarrow 0+} \lambda^2 R(\lambda; A)x = \theta$ for all $x \in \mathfrak{X}$, then $T(\xi)$ is Abel ergodic at infinity in the uniform topology.*

We first show that $\mathfrak{D}[A^2]$ is dense in \mathfrak{X} . In fact, for any $x \in \mathfrak{X}$, set

$$(5) \quad \begin{aligned} y(\tau) &= \frac{6}{\tau^3} \int_0^\tau (\tau - \xi)\xi T(\xi)x d\xi \\ &= \frac{6}{\tau^3} \int_0^\tau (2s - \tau)s \left(s^{-1} \int_0^s T(\xi)x d\xi \right) ds. \end{aligned}$$

It follows from (iii) that $y(\tau) \rightarrow x$ as $\tau \rightarrow 0+$. Hence it will be sufficient to show that $y(\tau) \in \mathfrak{D}[A^2]$. However a straightforward calculation (compare with [1, Theorem 11.5.1]) shows that $Ay(\tau) = (6/\tau^3) \int_0^\tau (\tau - 2\xi)T(\xi)x d\xi$ and $A^2y(\tau) = (6/\tau^3) [2 \int_0^\tau T(\xi)x d\xi - \tau T(\tau)x - \tau x]$. Next, if $x \in \mathfrak{D}[A^2]$, we deduce from (4) that

$$(6) \quad \lambda^2 R(\lambda; A)x - \lambda x - Ax = R(\lambda; A)A^2x = A^2R(\lambda; A)x.$$

By hypotheses, $\lim_{\lambda \rightarrow 0+} \lambda^2 R(\lambda; A)x = \theta$, so that $\lim_{\lambda \rightarrow 0+} A^2R(\lambda; A)x = -Ax$. Thus if $x \in \mathfrak{D}[A^2]$, then $Ax \in \mathfrak{R}[A^2]$ (closed by hypothesis). In other words $\mathfrak{R}[A^2] \supset \mathfrak{D}[A] \cap \mathfrak{R}[A]$, from which it follows that $\mathfrak{D}[A] \cap \mathfrak{R}[A] = \mathfrak{D}[A] \cap \mathfrak{R}[A^2]$. Further, A is one-to-one on $\mathfrak{D}[A] \cap \mathfrak{R}[A^2]$. For, if $x \in \mathfrak{D}[A] \cap \mathfrak{R}[A]$ and $Ax = \theta$, then there exists a $y \in \mathfrak{D}[A^2]$ such that $x = Ay$ and by (6)

$$(7) \quad x = Ay = \lim_{\lambda \rightarrow 0+} R(\lambda; A)A^2y = \theta.$$

We define A_1 to be the contraction of A on $\mathfrak{R}[A^2]$. Then A_1 is closed, one-to-one, and $\mathfrak{R}[A_1] = \mathfrak{R}[A^2]$. It follows that A_1^{-1} is a linear bounded operator [1, Theorem 2.13.9] on $\mathfrak{R}[A^2]$ to itself. For $y \in \mathfrak{R}[A^2]$, set $x = A_1^{-1}y$. Then $x \in \mathfrak{D}[A_1]$ and by (4)

$$R(\lambda; A)y = -x + \lambda R(\lambda; A)x.$$

Since $\lambda^2 R(\lambda; A)x \rightarrow \theta$ as $\lambda \rightarrow 0+$ by hypothesis, $\lim_{\lambda \rightarrow 0+} \lambda R(\lambda; A)y = \theta$ for all $y \in \mathfrak{R}[A^2]$. By a generalized version of the Banach-Steinhaus theorem [1, Theorem 2.12.2] there exists a constant M such that $\|\lambda R(\lambda; A)y\| \leq M\|y\|$ for $0 < \lambda \leq 1$ and all $y \in \mathfrak{R}[A^2]$. Hence

$$(8) \quad \|\lambda R(\lambda; A)y\| \leq \lambda \|A_1^{-1}\| \|1 + M\| \|y\|$$

for all $y \in \mathfrak{R}[A^2]$ and $0 < \lambda \leq 1$.

$\mathfrak{Z}[A]$ can be characterized as the set of all x such that $T(\xi)x \equiv x$. In fact, if $x \in \mathfrak{Z}[A]$,

$$T(\xi)x - x = \int_0^\xi \frac{dT(\tau)x}{d\tau} d\tau = \int_0^\xi T(\tau)Ax d\tau = \theta;$$

the converse is obvious. It follows that $\mathfrak{Z}[A]$ is a closed linear subspace and that $\lambda R(\lambda; A)x \equiv x$ for each $x \in \mathfrak{Z}[A]$. Thus $\mathfrak{Z}[A] \cap \mathfrak{R}[A^2] = \phi$. On the other hand $(\mathfrak{Z}[A] \oplus \mathfrak{R}[A^2])^- = \mathfrak{X}$.² For if $x \in \mathfrak{D}[A^2]$, then $A^2x = z \in \mathfrak{R}[A^2]$. Let $x_1 = A_1^{-2}z$; then $x_1 \in \mathfrak{D}[A^2] \cap \mathfrak{R}[A^2]$. Hence $A^2(x - x_1) = 0$. Applying (7) (with $y = x - x_1$), we see that $x_2 = x - x_1 \in \mathfrak{Z}[A]$. In other words $x = x_1 + x_2 \in \mathfrak{R}[A^2] \oplus \mathfrak{Z}[A]$. The conclusion then follows from the fact that $(\mathfrak{D}[A^2])^- = \mathfrak{X}$. We can, however, prove much more; in fact, $\mathfrak{X} = \mathfrak{R}[A^2] \oplus \mathfrak{Z}[A]$. Given $x \in \mathfrak{X}$, as we have just shown, there exists a sequence $x_n = y_n + z_n$ such that $x_n \rightarrow x$, $y_n \in \mathfrak{R}[A^2]$, and $z_n \in \mathfrak{Z}[A]$. Now

$$[T(\xi) - I]x_n = [T(\xi) - I]y_n = [T(\xi) - I]A^2w_n = A^2[T(\xi) - I]w_n$$

where $w_n \in \mathfrak{D}[A^2]$. Hence $[T(\xi) - I]x \in \mathfrak{R}[A^2]$ for all $\xi > 0$. Since $\mathfrak{R}[A^2]$ is closed and linear

$$\frac{6}{\tau^3} \int_0^\tau (\tau - \xi)\xi(T(\xi) - I)x d\xi \in \mathfrak{R}[A^2].$$

However, as we have seen in (5), $y(\tau) \in \mathfrak{D}[A^2]$ and as above $\mathfrak{D}[A^2]$

² $(\mathfrak{M})^-$ denotes the closure of the set \mathfrak{M} .

$\mathfrak{C}\mathfrak{R}[A^2] \oplus \mathfrak{Z}[A]$. Therefore

$$x = \frac{6}{\tau^3} \int_0^\tau (\tau - \xi)\xi T(\xi)x d\xi - \frac{6}{\tau^3} \int_0^\tau (\tau - \xi)\xi [T(\xi) - I]x d\xi$$

belongs to $\mathfrak{R}[A^2] \oplus \mathfrak{Z}[A]$. Thus for each $x \in \mathfrak{X}$ there exists a unique decomposition $x = y + z$ where $y \in \mathfrak{R}[A^2]$ and $z \in \mathfrak{Z}[A]$. We define the projection operator $Px = z$. Since both $\mathfrak{R}[A^2]$ and $\mathfrak{Z}[A]$ are closed, P will be closed and since it is defined for all $x \in \mathfrak{X}$ it will be bounded [1, Theorem 2.13.9]. Now $Px \in \mathfrak{Z}[A]$, so that $\lambda R(\lambda; A)Px = Px$. Hence by (8)

$$\|\lambda R(\lambda; A)x - Px\| = \|\lambda R(\lambda; A)(1 - P)x\| \leq \lambda K\|x\|$$

and $T(\xi)$ is therefore uniformly ergodic at infinity to the projection operator P .

We remark that the converse of Theorem 1 follows directly from [1, Theorem 14.8.3 and 14.8.4].

THEOREM 2. *If the semi-group operator $T(\xi)$ satisfies conditions (i) and (ii_s), if $T(\xi)$ is strongly Abel ergodic at 0, and if $\|a(\xi, T(\cdot)x, \alpha)\| \leq M\|x\|$ for $0 < \xi < 1$, then $T(\xi)$ is strongly (C- α) ergodic at 0.*

Condition (ii_s) can be replaced by the weaker condition $\int_0^1 \|T(\xi)x\| d\xi < \infty$ for all $x \in \mathfrak{X}$. It is interesting to note that Theorem 2 does not have its counterpart in the infinite limit. In the latter case, Hille [1, Theorem 14.7.2] has proved a much weaker theorem and this with the help of a Tauberian theorem, whereas the following proof is of an elementary nature.

By assumption, $\lim_{\lambda \rightarrow \infty} L[\lambda, T(\cdot)x] = Jx$ for all $x \in \mathfrak{X}$. As Hille has shown [1, Theorem 14.6.2], J is a bounded projection operator, $X = \mathfrak{R}[J] \oplus \mathfrak{Z}[J]$, $\mathfrak{Z}[J] = \cap_{\xi} \mathfrak{Z}[T(\xi)]$, and $\mathfrak{R}[J] = (\mathfrak{D}[A])^-$. Hence for any $x \in \mathfrak{X}$, $x = Jx + (I - J)x = y + z$. Since $y \in \mathfrak{R}[J] = (\mathfrak{D}[A])^-$, there exists a sequence $y_n \in \mathfrak{D}[A]$ such that $y_n \rightarrow y$. For $y_n \in \mathfrak{D}[A]$, $\lim_{\xi \rightarrow 0+} T(\xi)y_n = y_n$; whereas for $z \in \mathfrak{Z}[J]$, $T(\xi)z \equiv 0$. Hence

$$\lim_{\xi \rightarrow 0+} a[\xi, T(\cdot)(y_n + z), \alpha] = y_n.$$

By hypothesis $a[\xi, T(\cdot)x, \alpha]$ is a family of linear continuous operators, uniformly bounded for $\xi \in (0, 1)$. Hence the iterated limits exist and their order may be interchanged; that is,

$$\begin{aligned} \lim_{\xi \rightarrow 0+} a[\xi, T(\cdot)x, \alpha] &= \lim_{\xi \rightarrow 0+} \lim_n a[\xi, T(\cdot)(y_n + z), \alpha] \\ &= \lim_n y_n = y = J(x). \end{aligned}$$

For purposes of the following theorem, we define $\mathfrak{X}_1 = (\mathfrak{R}[A] \oplus \mathfrak{B}[A])^-$, A_1 to be the retraction of A on \mathfrak{X}_1 , and A_2 to be the retraction of A on $(\mathfrak{R}[A])^-$. We then have the following theorem.

THEOREM 3. *If the semi-group operator $T(\xi)$ satisfies conditions (i), (ii_s), (iii), and if $\|\lambda R(\lambda; A)\| \leq M$ for $0 < \lambda < 1$, then $\lim_{\lambda \rightarrow 0+} \lambda R(\lambda, A)x$ exists for all $x \in \mathfrak{X}_1$, $T(\xi)\mathfrak{X}_1 \subset \mathfrak{X}_1$, and $(\mathfrak{R}[A])^- = (\mathfrak{R}[A_1])^- = (\mathfrak{R}[A_2])^-$.*

As in Theorem 1, $\mathfrak{B}[A]$ is closed and $\lambda R(\lambda; A)x \equiv x$ if $x \in \mathfrak{B}[A]$. If $x \in \mathfrak{R}[A]$, then $x = Ay$ and by (4), $\lambda R(\lambda; A)x = \lambda^2 R(\lambda; A)y - \lambda y$ so that $\lambda R(\lambda; A)x \rightarrow \theta$ as $\lambda \rightarrow 0+$. Thus this limit exists for all $x \in \mathfrak{R}[A] \oplus \mathfrak{B}[A]$ and since $\|\lambda R(\lambda; A)\| \leq M$ for $\lambda \in (0, 1)$, it will exist for all $x \in \mathfrak{X}_1$. Now if $x = y + z$ where $y \in \mathfrak{R}[A]$ and $z \in \mathfrak{B}[A]$, then $T(\xi)z \equiv z$ and $T(\xi)y = T(\xi)Aw = AT(\xi)w$ for some $w \in \mathfrak{D}[A]$. Hence $T(\xi)x = z + AT(\xi)w$ belongs to \mathfrak{X}_1 , and since $T(\xi)$ is continuous the same applies to all $x \in \mathfrak{X}_1$. Therefore relative to \mathfrak{X}_1 , $T(\xi)$ is strongly Abel ergodic at infinity. As Hille [1, Theorem 14.6.1] has shown, there exists a bounded projection operator P_1 on \mathfrak{X}_1 such that $\lim_{\lambda \rightarrow 0+} L[\lambda, T(\cdot)x] = P_1x$ for all $x \in \mathfrak{X}_1$, $\mathfrak{B}[P_1] = (\mathfrak{R}[A_1])^-$, $\mathfrak{R}[P_1] = \mathfrak{B}[A_1]$, and $\mathfrak{X}_1 = (\mathfrak{R}[A_1])^- \oplus \mathfrak{B}[A_1]$. Now by the definition of \mathfrak{X}_1 , it follows that $\mathfrak{B}[A] = \mathfrak{B}[A_1]$. Clearly $(\mathfrak{R}[A])^- \supset (\mathfrak{R}[A_1])^-$. The converse is likewise true. For if $x \in \mathfrak{R}[A]$, then as above $\lambda R(\lambda; A)x \rightarrow \theta$. The same is true of $x \in (\mathfrak{R}[A])^-$ since $\|\lambda R(\lambda; A)\| \leq M$ for $0 < \lambda < 1$. Hence if $x \in (\mathfrak{R}[A])^-$, then $x \in \mathfrak{B}[P_1] = (\mathfrak{R}[A_1])^-$. Finally if $y \in \mathfrak{R}[A_1]$, then there exists an $x \in \mathfrak{D}[A_1]$ such that $y = A_1x$. By the above decomposition, $P_1x \in \mathfrak{B}[A_1]$; hence $w = (I - P_1)x \in \mathfrak{D}[A_1] \cap (\mathfrak{R}[A_1])^-$ and $A_1w = y$. In other words $\mathfrak{R}[A_2] = \mathfrak{R}[A_1]$.

COROLLARY 1. *If $T(\xi)$ satisfies the hypothesis of Theorem 3 and if $\mathfrak{X} = (\mathfrak{R}[A] \oplus \mathfrak{B}[A])^-$, then $T(\xi)$ is strongly Abel ergodic at infinity.*

This result is slightly stronger than that obtained by Hille [1, Theorem 14.7.1 (2)].

COROLLARY 2. *If $T(\xi)$ satisfies the hypothesis of Theorem 3, then $\lambda = 0$ is either in the resolvent set or in the continuous spectrum of A_2 .*

Clearly $(\mathfrak{R}[A])^- = (\mathfrak{R}[A_2])^-$ rules out the residual spectrum and $\mathfrak{B}[A] \cap (\mathfrak{R}[A])^- = \phi$ rules out the point spectrum.

Hille has conjectured [1, p. 295] that a semi-group operator satisfying the hypothesis of Theorem 3 and such that $\lambda = 0$ does not belong to the residual spectrum of either A or A_2 would necessarily be strongly Abel ergodic at infinity. It is clear from Corollary 2 that the condition imposed on A_2 is already implied by the other restrictions. Thus in order to construct a counter-example to this conjecture it

will be sufficient to produce a non-Abel-ergodic semi-group satisfying the hypothesis of Theorem 3 and having $\lambda = 0$ in the point spectrum of A . This we do in the following example.

EXAMPLE 1. Let $\mathfrak{X} = m$, the space of bounded sequences $\{a_n\}$, with norm $\|\{a_n\}\| = \text{LUB } |a_n|$. We define $T(\xi)\{a_n\} = \{a'_n\}$ by

$$\begin{aligned} a'_0 &= a_0, \\ a'_n &= a_n \exp(-i\xi/n) \end{aligned} \quad \text{for } n \geq 1.$$

Clearly $\|T(\xi)\| = 1$, and

$$\|(T(\xi) - I)\{a_n\}\| \leq \|\{a_n\}\| \cdot |\exp(i\xi) - 1|.$$

Thus $T(\xi)$ is uniformly continuous at the origin and hence A is a linear bounded operator. In fact for $A\{a_n\} = \{a'_n\}$, we have

$$\begin{aligned} a'_0 &= 0, \\ a'_n &= ia_n/n \end{aligned} \quad \text{for } n \geq 1.$$

It is clear that $\lambda = 0$ is in the point spectrum of A . Finally if we have $\lambda R(\lambda; A)\{a_n\} = \{a'_n\}$, then

$$\begin{aligned} a'_0 &= a_0, \\ a'_n &= a_n n\lambda / (n\lambda + i) \end{aligned} \quad \text{for } n \geq 1,$$

and since $|n\lambda / (n\lambda + i)| \leq 1$ for $\lambda > 0$, it follows that $\|\lambda R(\lambda; A)\| \leq 1$ for $\lambda > 0$. Now if $T(\xi)$ were strongly ergodic at infinity to the projection operator P , then

$$\mathfrak{R}[P] = \mathfrak{B}[A] = [(b, 0, 0, 0, \dots)].$$

However this limit fails for $\{a_n \equiv 1\}$ since

$$\|(\lambda R(\lambda; A) - P)(1, 1, \dots)\| = \|(0, \dots, n\lambda / (n\lambda + i), \dots)\| = 1$$

for all $\lambda > 0$.

EXAMPLE 2. We next define a semi-group operator $T(\xi)$ satisfying conditions (i), (ii_u), (iii) and such that $\lim \sup_{\xi \rightarrow 0+} \|T(\xi)\| = \infty$. We start with a sequence of two-dimensional normed linear spaces \mathfrak{X}_n and define \mathfrak{X} to be the set of all sequences $\{x_n \in \mathfrak{X}_n\}$ such that $\sum \|x_n\| < \infty$, with norm $\|\{x_n\}\| = \sum \|x_n\|$. \mathfrak{X}_n itself is defined as the set of all complex-valued pairs $x_n = (y, z)$ with norm $\|x_n\| = (|y|^2 + n|z|^2)^{1/2}$. We now define a semigroup operator $T_n(\xi)x_n = x'_n$ on \mathfrak{X}_n to \mathfrak{X}_n such that

$$\begin{aligned} y' &= \exp[-(n + in^3)\xi](y \cos n\xi - z \sin n\xi), \\ z' &= \exp[-(n + in^3)\xi](y \sin n\xi + z \cos n\xi). \end{aligned}$$

It is clear that $\|T_n(\xi)\| \leq n^{1/2} \exp(-n\xi)$ and that $\|T_n(\pi/2n)\|$

$= n^{1/2} \exp(-\pi/2)$ [as can be seen by operating on $(1, 0)$]. The semi-group operator $T(\xi)$ is defined by $T(\xi)\{x_n\} = \{T_n(\xi)x_n\}$. It follows from the way the norm in X has been defined that $\|T(\xi)\| = \text{LUB } \|T_n(\xi)\| \leq (2e\xi)^{-1/2}$. Now $T_n(\xi)x_n$ is clearly continuous in ξ , and since the $\lim_k \sum_k \|T_n(\xi)x_n\| = 0$ uniformly in $\xi \geq \delta > 0$, $T(\xi)\{x_n\}$ will itself be strongly continuous for $\xi > 0$. In this case $\|T(\xi)\|$ is measurable and, from the above upper bound, we have

$$\int_0^\infty \exp(-\lambda\xi) \|T(\xi)\| d\xi \leq \int_0^\infty \exp(-\lambda\xi) (2e\xi)^{-1/2} d\xi < \infty \quad \text{for } \lambda > 0.$$

Further, since $\|T(\pi/2n)\| \geq n^{1/2} \exp(-\pi/2)$, $\limsup_{\xi \rightarrow 0+} \|T(\xi)\| = \infty$. It remains to show that (iii) is satisfied. We define

$$S(\eta)x = \eta^{-1} \int_0^\eta T(\xi)x d\xi = \{S_n(\eta)x_n\}.$$

Here

$$S_n(\eta)x_n = \eta^{-1} \int_0^\eta T_n(\xi)x_n d\xi = x'_n = (\alpha(\eta)y - \beta(\eta)z, \beta(\eta)y + \alpha(\eta)z)$$

where

$$\alpha(\eta) = \eta^{-1} \int_0^\eta \exp[-(n + in^3)\xi] \cos n\xi d\xi,$$

$$\beta(\eta) = \eta^{-1} \int_0^\eta \exp[-(n + in^3)\xi] \sin n\xi d\xi.$$

A straightforward calculation shows that $|\alpha(\eta)| \leq 1$ and $|\beta(\eta)| \leq 2/n^2$. Hence for $|y|^2 + n|z|^2 = 1$,

$$\begin{aligned} |y'|^2 + n|z'|^2 &\leq |y|^2 + n|z|^2 + (4/n)|y||z| + (4/n^2)|y||z| \\ &\quad + (4/n^2)|y|^2 + (4/n^4)|z|^2 \\ &\leq 1 + 16/n \leq 17. \end{aligned}$$

Therefore $\|S(\eta)\| \leq \text{LUB } \|S_n(\eta)\| \leq 17$. For ultimately zero vectors, it is clear that $T(\xi)x \rightarrow x$ as $\xi \rightarrow 0+$ and hence that $S(\eta)x \rightarrow x$ as $\eta \rightarrow 0+$. Since such vectors are dense in \mathfrak{X} and since $\|S(\eta)\| \leq 17$, it follows that $S(\eta)x \rightarrow x$ as $\eta \rightarrow 0+$ for all $x \in \mathfrak{X}$.

EXAMPLE 3. We conclude with an example of a strongly continuous group operator $T(\xi)$ on $(-\infty, \infty)$ for which $\|T(\xi)\|$ is not continuous. This example settles a question raised by Hille [1, p. 184]. As in Example 2, $\mathfrak{X} = \prod \mathfrak{X}_n$ and $\|x\| = \sum \|x_n\|$. In this case, however, $\|x_n\| = |y|$

$+|z|$, and $T_n(\xi)x_n = x'_n$ is defined by

$$y' = y \cos n\xi - z \sin n\xi, \quad z' = y \sin n\xi + z \cos n\xi,$$

which is simply a rotation in \mathfrak{X}_n . Since the unit sphere in \mathfrak{X}_n is a square, the maximum expansion will be $2^{1/2}$. Hence $\|T(\xi)\| = \text{LUB } \|T_n(\xi)\| \leq 2^{1/2}$. For $\xi = k\pi$ ($k=0, \pm 1, \pm 2, \dots$), $\|T(\xi)x\| = \|x\|$ so that $\|T(k\pi)\| = 1$. For $n\xi = (nk \pm 1/4)\pi$, set $x_n = (1, 0)$ and $x_j = \theta$ for $j \neq n$. Then $x'_n = (\pm 1/2^{1/2}, \pm 1/2^{1/2})$ so that $\|T[(k \pm 1/4n)\pi]\| = 2^{1/2}$. Therefore $\|T(\xi)\|$ is discontinuous at the points $k\pi$. One can show as in Example 2 that $T(\xi)x$ is strongly continuous on $(-\infty, \infty)$.

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