SYSTEMS OF INEQUALITIES INVOLVING CONVEX FUNCTIONS¹

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1. Let X be a vector space² over the real field, and let K be a nonempty convex set in X. As usual, a real-valued function f defined on K is said to be *convex*, if $f(\alpha_1x_1+\alpha_2x_2) \leq \alpha_1f(x_1)+\alpha_2f(x_2)$ holds for any two elements $x_1, x_2 \in K$ and for any $\alpha_1 \geq 0$, $\alpha_2 \geq 0$, $\alpha_1+\alpha_2=1$. f is said to be *concave*, if -f is convex.

Let f_i $(1 \le i \le m)$ be m convex functions defined on K. The system of inequalities

$$f_i(x) < 0 \qquad (1 \le i \le m)$$

is said to be *consistent*, if an element $x \in K$ satisfying all m inequalities (i.e. a *solution* of (1)) does exist. Otherwise (1) is said to be *inconsistent*. A system (1) is said to be *irreducibly inconsistent*, if it is inconsistent and if every proper subsystem of (1) is consistent.

The convex functions f_1, f_2, \cdots, f_m are said to be linearly independent, if no linear combination $\sum_{i=1}^m \lambda_i f_i$ with real coefficients λ_i , not all zero, can remain ≥ 0 throughout K. In the special case when K = X and when the f_i 's are linear forms on X, this definition of linear independence agrees with the usual one. Indeed, a linear form can remain ≥ 0 throughout the entire vector space X only when it is identically zero. Incidentally, we observe that there exist arbitrarily many linearly independent convex functions even on a one-dimensional convex set. For example, the m convex functions $f_i(x) = x^i - 1/(i+1)$ ($1 \leq i \leq m$) on the unit interval $0 \leq x \leq 1$ are linearly independent for any natural number m. In fact, if some m real numbers λ_i satisfy the relation $\sum_{i=1}^m \lambda_i (x^i - 1/(i+1)) \geq 0$ for $0 \leq x \leq 1$, then since we have $\int_0^1 \left[\sum_{i=1}^m \lambda_i (x^i - 1/(i+1))\right] dx = 0$, the polynomial $\sum_{i=1}^m \lambda_i (x^i - 1/(i+1))$ must vanish identically and therefore all $\lambda_i = 0$. The purpose of this note is to prove the following results concerning

The purpose of this note is to prove the following results concerning a system (1) of inequalities with convex functions f_i defined on K.

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² Notice that X is not topologized, and that the dimension of X is arbitrary, finite or infinite.

THEOREM 1. Either the system (1) is consistent, or there exist m numbers $\lambda_i \ge 0$, not all zero, such that

(2)
$$\sum_{i=1}^{m} \lambda_{i} f_{i}(x) \geq 0 \qquad \text{for all } x \in K.$$

The two alternatives exclude each other.

THEOREM 2. Let the system (1) be consistent, and let g be a concave function defined on K. Then:

(i) The inequality

$$(3) g(x) \le 0$$

is a consequence of (1) [i.e., every $x \in K$ satisfying (1) also satisfies (3)], if and only if there exist m numbers $\lambda_i \ge 0$ such that

(4)
$$g(x) \leq \sum_{i=1}^{m} \lambda_{i} f_{i}(x) \qquad \text{for all } x \in K.$$

(ii) The supremum γ of g(x), when $x \in K$ varies over all solutions of (1), is finite, if and only if there exist m numbers $\lambda_i \ge 0$ such that $g(x) - \sum_{i=1}^{m} \lambda_i f_i(x)$ is bounded above on K. When this condition is satisfied, we have

(5)
$$\gamma = \min_{\substack{\lambda_i \geq 0 \\ \lambda_i \geq 0}} \sup_{x \in K} \left\{ g(x) - \sum_{i=1}^m \lambda_i f_i(x) \right\}.$$

THEOREM 3. Let the system (1) be consistent, and let g be a concave function defined on K. If inequality (3) is a consequence of the system (1), and if (3) is not a consequence of any proper subsystem of (1), then the convex functions f_1, f_2, \dots, f_m are linearly independent.

THEOREM 4. The system (1) is irreducibly inconsistent, if and only if the following two conditions are both satisfied: (a) Any m-1 of the convex functions f_1, f_2, \dots, f_m are linearly independent; (b) there exist m positive numbers λ_i satisfying (2).

2. Before proving these theorems, we shall discuss their relationship to certain known results.

First, if X is a finite dimensional real vector space, K is the convex set formed by all vectors with positive components, and if the f_i 's are linear forms, then Theorem 1 becomes von Neumann's theorem of the alternative for matrices [6, pp. 138–143].

Next, consider a system of linear inequalities

$$\phi_i(x) > \alpha_i, \qquad (1 \le i \le m)$$

where ϕ_i are linear forms on a real vector space X, and α_i are real numbers. Applying Theorem 1 to K = X, $f_i = \alpha_i - \phi_i$, then the system (6) is consistent on X, if and only if

(7)
$$\sum_{i=1}^{m} \lambda_{i} \alpha_{i} < \sup_{x \in X} \sum_{i=1}^{m} \lambda_{i} \phi_{i}(x)$$

holds for any m numbers $\lambda_i \ge 0$ which are not all zero. But $\sum_{i=1}^m \lambda_i \phi_i$ being a linear form on X, the supremum on the right hand side of (7) is $+\infty$ except when $\sum_{i=1}^m \lambda_i \phi_i = 0$. Hence (6) is consistent on X, if and only if, for any m numbers $\lambda_i \ge 0$, not all zero, the relation $\sum_{i=1}^m \lambda_i \phi_i = 0$ implies $\sum_{i=1}^m \lambda_i \alpha_i < 0$. This is a theorem due to W. B. Carver [2, Theorem 3].

Similarly, Theorem 4 includes the following result of Carver [2, Theorem 2]: The system of linear inequalities (6) is irreducibly inconsistent on X, if and only if any m-1 of the linear forms ϕ_i are linearly independent and there exist m positive numbers λ_i such that $\sum_{i=1}^{m} \lambda_i \phi_i = 0$, $\sum_{i=1}^{m} \lambda_i \alpha_i \ge 0$.

Assume now that the system (6) is consistent on X. Let ψ be a linear form on X and β a real number. By Theorem 2, (i), the inequality $\psi(x) \ge \beta$ is a consequence of (6) on X, if and only if there exist m numbers $\lambda_i \ge 0$ such that

$$\beta - \psi(x) \leq \sum_{i=1}^{m} \lambda_i [\alpha_i - \phi_i(x)]$$
 for all $x \in X$.

Since $\psi - \sum_{i=1}^{m} \lambda_i \phi_i$ is a linear form, the truth of the last inequality for all $x \in X$ is equivalent to

$$\psi = \sum_{i=1}^m \lambda_i \phi_i$$
 and $\beta \leq \sum_{i=1}^m \lambda_i \alpha_i$.

Thus we are led to a result which is analogous to a classical theorem of J. Farkas [4, pp. 5-7] and H. Weyl [7, Satz 3] concerning a system of linear inequalities $\phi_i(x) \ge \alpha_i$ [instead of the strict inequalities (6)]. Similarly, Theorem 2, (ii) includes the following result: The infimum of $\psi(x)$, when x varies over all solutions of the consistent system (6) on X, is finite, if and only if ψ is a linear combination of the ϕ_i 's with non-negative coefficients. When this condition is satisfied, the infimum in question is equal to the maximum of $\sum_{i=1}^{m} \lambda_i \alpha_i$, when λ_i vary under the conditions $\lambda_i \ge 0$ and $\psi = \sum_{i=1}^{m} \lambda_i \phi_i$. Results analogous to this, but concerning a system of linear inequalities $\phi_i(x) \ge \alpha_i$ [instead of the strict inequalities (6)] have been given by Gale, Kuhn and Tucker [5].

3. We proceed now to prove the theorems stated above.

$$\sum_{i=1}^{m} \lambda_i \xi_i < 0 \qquad \text{for } (\xi_1, \, \xi_2, \, \cdots, \, \xi_m) \in \mathbb{N}$$

and

$$\sum_{i=1}^m \lambda_i \xi_i \geq 0 \quad \text{for } (\xi_1, \, \xi_2, \, \cdots, \, \xi_m) \in B.$$

The first relation implies $\lambda_i \ge 0$ $(1 \le i \le m)$, the second relation implies (2).

Another Proof of Theorem 1. For each $x \in K$, let

$$U(x) = \{(\xi_1, \xi_2, \dots, \xi_m) \in E^m | \xi_i > f_i(x) \text{ for } 1 \leq i \leq m \}.$$

Let $U = \bigcup_{x \in K} U(x)$. Because the f_i 's are convex, the open set U is convex. Assume that (1) is inconsistent. Then U does not contain the origin $0 = (0, 0, \dots, 0)$. Therefore, again by the separation theorem of convex sets, there exist m numbers λ_i , not all zero, such that $\sum_{i=1}^{m} \lambda_i \xi_i > 0$ for all $(\xi_1, \xi_2, \dots, \xi_m) \in U$. This implies (2) and $\lambda_i \ge 0$ $(1 \le i \le m)$. In fact, for any point $(\xi_1, \xi_2, \dots, \xi_m) \in U$ and for any $\eta > 0$, the point $(\xi_1, \dots, \xi_{i-1}, \xi_i + \eta, \xi_{i+1}, \dots, \xi_m)$ remains in U. If $\lambda_i < 0$, then by taking $\eta > 0$ sufficiently large, we would have $\lambda_i(\xi_i + \eta) + \sum_{j \ne i} \lambda_j \xi_j < 0$.

PROOF OF THEOREM 2. (i) We need only prove the "only if" part. Assume that (3) is a consequence of (1). Then the system obtained by adjoining the inequality -g(x) < 0 to (1) is inconsistent. Application of Theorem 1 to this inconsistent system yields the desired condition.

(ii) γ is finite, if and only if there exists a real number β such that the inequality $g(x) - \beta \leq 0$ is a consequence of (1). Then the condition for γ to be finite follows from (i). Assume now that γ is finite. Then $g(x) - \gamma \leq 0$ is a consequence of (1). By (i), there are $\rho_i \geq 0$ such that $g(x) - \sum_{i=1}^m \rho_i f_i(x) \leq \gamma$ for all $x \in K$. On the other hand, for any $\epsilon > 0$, there is a solution $x_{\epsilon} \in K$ of (1) such that $g(x_{\epsilon}) > \gamma - \epsilon$. If $\lambda_i \geq 0$ and if α denotes the supremum of $g(x) - \sum_{i=1}^m \lambda_i f_i(x)$ over K, then $\gamma - \epsilon < g(x_{\epsilon}) \leq \alpha + \sum_{i=1}^m \lambda_i f_i(x_{\epsilon}) \leq \alpha$ for every $\epsilon > 0$. Hence $\gamma \leq \alpha$ and (5) is proved.

PROOF OF THEOREM 3. First, by Theorem 2, (i), there are m numbers $\lambda_i \ge 0$ satisfying (4). As (3) is not a consequence of any proper subsystem of (1), we have $\lambda_i > 0$ $(1 \le i \le m)$. Suppose, if possible, that μ_i are real numbers, not all zero, such that $\sum_{t=1}^m \mu_i f_i(x) \ge 0$ for all $x \in K$. Then as (1) is consistent, at least one of the μ_i 's is <0. Let $I = \{i \mid \mu_i < 0\}$ and $\nu = \max_{i \in I} \lambda_i / \mu_i < 0$. Put $\eta_i = \lambda_i - \nu \mu_i$ $(1 \le i \le m)$. Then

$$g(x) \leq \sum_{i=1}^{m} \lambda_{i} f_{i}(x) \leq \sum_{i=1}^{m} \lambda_{i} f_{i}(x) - \nu \sum_{i=1}^{m} \mu_{i} f_{i}(x) = \sum_{i=1}^{m} \eta_{i} f_{i}(x)$$

for all $x \in K$. But each $\eta_i \ge 0$ and at least one of them is 0, so by Theorem 2, (i), (3) would be a consequence of some proper subsystem of (1). This proves that the convex functions f_1, f_2, \dots, f_m are linearly independent.

PROOF OF THEOREM 4. Assume that (1) is irreducibly inconsistent. Then (b) follows from Theorem 1. The inequality $-f_m(x) \le 0$ is a consequence of the consistent system

(8)
$$f_i(x) < 0$$
 $(1 \le i \le m-1)$

without being a consequence of any proper subsystem of (8). Hence by Theorem 3, the m-1 convex functions f_1, f_2, \dots, f_{m-1} are linearly independent. This proves (a). Conversely, by Theorem 1, (a) implies that every proper subsystem of (1) is consistent, (b) implies the inconsistency of (1).

4. Instead of system (1) of strict inequalities, one may wish to consider the system

$$(9) f_i(x) \leq 0, (1 \leq i \leq m)$$

where f_i are as before convex functions defined on a convex set K. From a known result on linear inequalities (see e.g., [3, Theorem 1]), the following conjecture would seem to be reasonable: If (9) is inconsistent, then there exist m non-negative numbers λ_i such that

 $\sum_{i=1}^{m} \lambda_i f_i(x) > 0$ for all $x \in K$. This conjecture turns out to be false. Let X be the Euclidean plane, where points are denoted by $x = (\xi_1, \xi_2)$. Let K be the convex set which is the union of the open halfplane $\xi_2 > 0$ and the half-line $\xi_1 > 0$, $\xi_2 = 0$. Let f_1, f_2 be defined on K by $f_1(x) = \xi_1, f_2(x) = \xi_2$. Then the system $f_i(x) \le 0$ (i = 1, 2) is inconsistent on K, but no pair of non-negative numbers λ_1 , λ_2 can satisfy $\lambda_1 \xi_1 + \lambda_2 \xi_2 > 0$ for all $(\xi_1, \xi_2) \in K$.

5. In this final section, we indicate that Theorems 1 and 2 can be extended to a much more general situation. Let K be as before a nonempty convex set in a vector space X over the real field. Let Y be a locally convex topological real vector space. Let P be a convex cone in Y with nonempty interior. The interior of P will be denoted by Int P. A function f defined on K and taking its values in Y is said to be convex, if

$$\alpha_1 f(x_1) + \alpha_2 f(x_2) - f(\alpha_1 x_1 + \alpha_2 x_2) \in P$$

holds for any two elements x_1 , $x_2 \in K$ and for any $\alpha_1 \ge 0$, $\alpha_2 \ge 0$, $\alpha_1 + \alpha_2 = 1$. Then Theorems 1, 2 can be generalized, if we replace the system (1) of inequalities involving m real-valued convex functions by a single relation $-f(x) \in \text{Int } P$, where f is a convex function defined on K and taking its values in Y.

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