## THE WEIERSTRASS CONDITION FOR MULTIPLE INTEGRAL VARIATIONAL PROBLEMS INVOLVING HIGHER DERIVATIVES<sup>1</sup>

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1. **Introduction.** We consider the problem of minimizing a multiple integral

$$I = \int_{a} f(x, z, Dz) dx = \int \cdot \cdot \cdot \int f(x, z, Dz) dx_{1} \cdot \cdot \cdot dx_{n},$$

where  $x = (x_1, \dots, x_n)$ ,  $z = (z_1, \dots, z_q)$ , z is a function of x, and  $Dz_k$  denotes the various partial derivatives of  $z_k$  with respect to the  $x_j$  up to order  $v_k$ . When it is necessary to be more explicit, we shall let i denote an n-dimensional vector with nonnegative integer coordinates, and write

$$D^{i} = \prod_{j=1}^{n} D_{x_{j}}^{i_{j}}.$$

We set  $|i| = \sum_{i} i_{i}$ , and if  $|i| = \nu_{k}$ , denote  $D^{i}z_{k}$  by  $p_{k}^{i}$ . These are the derivatives of  $z_{k}$  of the highest order that appear.

It is supposed that each  $z_k$  and its derivatives up to order  $\nu_k - 1$  are continuous on a fixed domain G and take prescribed boundary values on the boundary  $G^*$  of G, and that the derivatives of  $z_k$  of order  $\nu_k$  are piecewise continuous. We assume that the integrand f is continuous and has continuous partial derivatives with respect to the arguments  $p_k^t$ , for points (x, z, Dz) interior to a domain T. In the Weierstrass &-function, only the arguments  $p_k^t$  are varied. Hence we shall define Dz + P by the formula

$$(Dz + P)_k^i = D^i z_k$$
 for  $|i| < \nu_k$   
=  $D^i z_k + P_k^i$  for  $|i| = \nu_k$ ,

and assume for simplicity that the domain T is such that (x, z, Dz + P) is in T whenever (x, z, Dz) is in T. Then we define

$$\mathcal{E}(x, z, Dz, Dz + P) = f(x, z, Dz + P) - f(x, z, Dz) - \sum_{i,k} P_k^i f_{P_k^i}(x, z, Dz),$$

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where the summation index k runs from 1 to q, and i varies over the set  $|i| = \nu_k$ .

We shall show that if I is a minimum then

$$\mathcal{E}(x, z, Dz, Dz + P) \geq 0$$

whenever P has the form

$$(1) P_k^i = C_k \prod_{j=1}^n (\alpha_j)^{ij},$$

where  $C_k$  and  $\alpha_i$  are arbitrary.

We may restrict attention to a point x of G near which all derivatives of z which appear are continuous, and consider only variations  $\zeta$  of z which vanish outside a neighborhood of x. Then if we put

$$\bar{f}(x,\zeta,D\zeta) = f(x,z+\zeta,Dz+D\zeta) - f(x,z,Dz),$$

$$\bar{I}(\zeta) = \int \bar{f}dx,$$

we see that in  $(x, \zeta)$ -space, the minimizing manifold is  $\zeta = 0$ , and  $\bar{f}(x, 0, 0) = 0$ . By a translation we may also suppose that the point x under consideration is the origin. We replace  $\zeta$  by z and  $\bar{f}$  by f, and understand in the proofs that any argument of f or its partial derivatives which is not written is zero. In §2 we give the proof for the case q = 2,  $\nu_1 = 1$ ,  $\nu_2 = 2$ , and in §3 treat the general case. The method of proof is an extension of that given by the author for the case when only first derivatives appear.<sup>2</sup>

## 2. A special case. We consider here an integrand

$$f(x, z_1, z_2, Dz_1, Dz_2, D^2z_2),$$

where  $D^2z_2$  stands for all the second derivatives  $D_{x_j}D_{x_m}z_2$ , and no derivatives appear which are of higher order than those indicated. Let

$$L_0 = \sum_{j=1}^n \alpha_j x_j,$$

where for convenience  $\alpha$  is chosen as a unit vector, and for a small b>0 and  $|x| \leq b$  let

$$\phi = \left[1 + L_0^2 - \left|x\right|^2\right]^{1/2} - \left[1 - b^2\right]^{1/2},$$

where |x| denotes the Euclidean length of the vector x. (Note that

<sup>&</sup>lt;sup>2</sup> See Duke Math. J. vol. 5 (1939) pp. 656-660.

|i| was defined differently.) Then  $\phi$  has bounded partial derivatives of all orders, and  $\phi$  and its first partial derivatives approach zero uniformly with b. Let  $1 = \epsilon_0 > \epsilon_1 > \epsilon_2 > \epsilon_3 = 0$ , and set

$$L_1 = L_0 + (\epsilon_1 - 1)\phi,$$
  
 $L_2 = L_0 + (\epsilon_2 - 1)\phi,$   
 $L_3 = L_0 - \phi.$ 

Then the loci  $L_{\beta}=0$ ,  $(\beta=0, 1, 2, 3)$ , bound three adjacent domains  $R_0$ ,  $R_1$ ,  $R_2$  in x-space, defined by

(2) 
$$R_{\beta} = [x \mid L_{\beta+1} < 0 < L_{\beta}].$$

If V = V(b) denotes the volume of  $R = R_0 + R_1 + R_2$ , then the volume of  $R_{\beta}$  is  $V_{\beta} = (\epsilon_{\beta} - \epsilon_{\beta+1}) V$ , as is readily verified by considering the special case  $\alpha_1 = 1$ ,  $\alpha_j = 0$  for j > 1. Also V tends to zero with b.

The variations of the minimizing manifold z=0 are constructed as follows. Let  $A_{10}$ ,  $A_{20}$  be arbitrary constants, and let  $A_{11}$ ,  $A_{21}$ ,  $A_{22}$  denote functions of  $\epsilon_1$ ,  $\epsilon_2$ , to be determined. Set

$$z_{1} = A_{10}L_{0} \qquad \text{on } R_{0},$$

$$= A_{10}L_{0} + A_{11}L_{1} \qquad \text{on } R_{1} + R_{2},$$

$$z_{2} = A_{20}L_{0}^{2} \qquad \text{on } R_{0},$$

$$= A_{20}L_{0}^{2} + A_{21}L_{1}^{2} \qquad \text{on } R_{1},$$

$$= A_{20}L_{0}^{2} + A_{21}L_{1}^{2} + A_{22}L_{2}^{2} \qquad \text{on } R_{2},$$

$$z_{1} = z_{2} = 0 \text{ outside } R.$$

Then  $z_1$  is continuous except possibly along  $L_3 = 0$ , and  $z_2$  and its first partial derivatives are continuous except possibly along  $L_3 = 0$ . Sufficient conditions for the required continuity along  $L_3 = 0$  are

(3) 
$$A_{10} + \epsilon_1 A_{11} = 0,$$

$$A_{20} + \epsilon_1^2 A_{21} + \epsilon_2^2 A_{22} = 0,$$

$$A_{20} + \epsilon_1 A_{21} + \epsilon_2 A_{22} = 0,$$

since  $L_0 = \phi$ ,  $L_1 = \epsilon_1 \phi$ ,  $L_2 = \epsilon_2 \phi$  on  $L_3 = 0$ .

Now when b tends to zero, so do  $\phi$ , each  $L_{\beta}$ ,  $z_1$ ,  $z_2$ , and each  $D_{x_j}\phi$ , and hence

$$D_{x_j}L_{eta} o D_{x_j}L_0 = \alpha_j,$$
 $D_{x_i}L_{eta}^2 o 0,$ 

$$egin{aligned} D_{x_j}D_{x_m}L_{eta}^2 &
ightarrow 2lpha_jlpha_m, \ D_{x_j}z_1 &
ightarrow A_{10}lpha_j & ext{on } R_0, \ &
ightarrow (A_{10}+A_{11})lpha_j & ext{on } R_1+R_2, \ D_{x_j}z_2 &
ightarrow 0, \ D_{x_j}D_{x_m}z_2 &
ightarrow 2A_{20}lpha_jlpha_m & ext{on } R_0, \ &
ightarrow 2(A_{20}+A_{21})lpha_jlpha_m & ext{on } R_1, \ &
ightarrow 2(A_{20}+A_{21}+A_{22})lpha_jlpha_m & ext{on } R_2, \end{aligned}$$

Since

$$\frac{I}{V} = \frac{1-\epsilon_1}{V_0} \int_{R_0} f dx + \frac{\epsilon_1-\epsilon_2}{V_1} \int_{R_1} f dx + \frac{\epsilon_2}{V_2} \int_{R_2} f dx,$$

we find from  $I(0) = 0 = \min \text{minimum of } I(b) \text{ that}$ 

$$0 \leq (1 - \epsilon_{1}) f(A_{10}\alpha_{j}, 2A_{20}\alpha_{j}\alpha_{m})$$

$$+ (\epsilon_{1} - \epsilon_{2}) f[(A_{10} + A_{11})\alpha_{j}, 2(A_{20} + A_{21})\alpha_{j}\alpha_{m}]$$

$$+ \epsilon_{2} f[(A_{10} + A_{11})\alpha_{j}, 2(A_{20} + A_{21} + A_{22})\alpha_{j}\alpha_{m}].^{3}$$

This inequality may be regarded as a generalized form of the Weierstrass condition, in which no partial derivatives of the integrand f appear. We obtain the ordinary form of the condition by dividing by  $(1-\epsilon_1)$  and letting  $\epsilon_1$  tend to one. In order to evaluate this limit we need the derivatives  $A'_{11}$ ,  $A'_{21}$  and  $A'_{22}$  of  $A_{11}$ ,  $A_{21}$  and  $A_{22}$  with respect to  $\epsilon_1$  at  $\epsilon_1=1$ . Let  $M_{\beta}$  be the cofactor of  $s_{\beta}$  in the determinant

$$\begin{vmatrix} s_0 & s_1 & s_2 \\ 1 & \epsilon_1 & \epsilon_2 \\ 1 & \epsilon_1^2 & \epsilon_2^2 \end{vmatrix}.$$

Then from the equations (3),

$$A_{21} = A_{20}M_1/M_0, \qquad A_{22} = A_{20}M_2/M_0.$$

Also at  $\epsilon_1 = 1$ ,  $M_1 = -M_0$ ,  $M_2 = 0$ , and

$$\frac{\partial}{\partial \epsilon_1} \frac{M_1}{M_0} = \frac{M'_0}{M_0}, \quad \frac{\partial}{\partial \epsilon_1} \frac{M_2}{M_0} = \frac{M'_2}{M_0},$$

$$A'_{21} = A_{20}M'_0/M_0, \quad A'_{22} = A_{20}M'_2/M_0, \quad A'_{11} = A_{10},$$

$$A_{10} + A_{11} = 0 \quad A_{20} + A_{21} = 0, \quad A_{20} + A_{21} + A_{22} = 0.$$

<sup>&</sup>lt;sup>3</sup> Here the arguments x,  $z_1$ ,  $z_2$ ,  $Dz_2$  of f, which are all zero, have been omitted.

In this way we obtain from (4) the inequality

$$0 \leq f(A_{10}\alpha_{j}, 2A_{20}\alpha_{j}\alpha_{m})$$

$$+ (\epsilon_{2} - 1) \left[ \sum_{j} f_{p_{1j}} A_{10}\alpha_{j} + \sum_{j,m} f_{p_{2jm}} 2A_{20} M'_{0}\alpha_{j}\alpha_{m} / M_{0} \right]$$

$$- \epsilon_{2} \left[ \sum_{j} f_{p_{1j}} A_{10}\alpha_{j} + \sum_{j,m} f_{p_{2jm}} 2A_{20} (M'_{0} + M'_{2}) \alpha_{j}\alpha_{m} / M_{0} \right].$$

Now at  $\epsilon_1 = 1$ ,  $(1 - \epsilon_2)M_0' + \epsilon_2(M_0' + M_2') = M_0$ , so this becomes

$$0 \le f(A_{10}\alpha_j, 2A_{20}\alpha_j\alpha_m) - \sum_j f_{p_{1j}} A_{10}\alpha_j - \sum_{j,m} f_{p_{2jm}} 2A_{20}\alpha_j\alpha_m$$

or

$$0 \leq f(p_1, p_2) - \sum_{i} p_{1i} f_{p_{1i}} - \sum_{i,m} p_{2im} f_{p_{2im}},$$

where  $p_{1j} = A_{10}\alpha_j$ ,  $p_{2jm} = 2A_{20}\alpha_j\alpha_m$ , and the arguments of the partial derivatives of f are those along the minimizing manifold  $z_1 = z_2 = 0$ .

3. The general case. We let  $\mu$  denote the maximum  $\nu_k$ , and select  $\epsilon_{\theta}$  satisfying

$$1 = \epsilon_0 > \epsilon_1 > \cdots > \epsilon_u > \epsilon_{u+1} = 0.$$

With  $L_0$  and  $\phi$  chosen as in §2, we set

$$L_{\beta} = L_0 + (\epsilon_{\beta} - 1)\phi.$$

There are now  $\mu+1$  domains  $R_{\beta}$  defined by (2), and the domain R which is their union is defined by the inequality  $0 < L_0 < \phi$ . On  $R_{\beta}$  we set

$$z_k = \sum_{\sigma=0}^{\lambda} A_{k\sigma} L_{\sigma}^{\nu_k},$$

where  $\lambda$  is the lesser of  $\beta$  and  $\nu_k$ ,  $A_{k0}$  is arbitrary, and the remaining  $A_{k\sigma}$  are to be determined as multiples of  $A_{k0}$ . Outside of R we set  $z_k = 0$ . The functions  $z_k$  and their partial derivatives up to order  $\nu_k - 1$  are obviously continuous along the manifolds  $L_{\beta} = 0$  for  $\beta = 0$ ,  $1, \dots, \mu$ . To assure the required continuity along the manifold  $L_{\mu+1} = 0$ , it is sufficient to require that the  $A_{k\sigma}$  satisfy the equations

$$\sum_{n=0}^{\nu_k} A_{k\sigma} \epsilon_{\sigma}^{\rho} = 0, \qquad \rho = 1, \cdots, \nu_k,$$

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as may be verified by observing that when  $L_{\mu+1}=0$ ,  $L_{\sigma}=\epsilon_{\sigma}\phi$ ,  $DL_{0}=\alpha$ ,  $DL_{\sigma}=DL_{0}+(\epsilon_{\sigma}-1)D\phi$ ,  $D^{2}L_{\sigma}=(\epsilon_{\sigma}-1)D^{2}\phi$ , etc. Hence we take

$$A_{k\sigma} = A_{k0} M_{k\sigma} / M_{k0},$$

where  $M_{k\sigma}$  is the cofactor of  $s_{\sigma}$  in the determinant

$$\Delta = \begin{vmatrix} s_0 & s_1 & s_2 & \cdots & s_{r_k} \\ 1 & \epsilon_1 & \epsilon_2 & \cdots & \epsilon_{r_k} \\ 1 & \epsilon_1 & \epsilon_2 & \cdots & \cdots \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \epsilon_1 & \epsilon_1 & \cdots & \epsilon_n \end{vmatrix}.$$

When b tends to zero, each  $z_k$ , with its derivatives up to order  $\nu_k - 1$ , tends to zero, and for  $|i| = \nu_k$ ,  $D^i z_k$  tends to  $p_k^i \rho$  on  $R_{\rho}$ , where

(5) 
$$p_{k\beta}^{i} = \nu_{k}! \prod_{j=1}^{n} (\alpha_{j})^{i_{j}} \sum_{\sigma=0}^{\lambda} A_{k\sigma} = B_{k}^{i} \sum_{\sigma=0}^{\lambda} A_{k\sigma} = B_{k}^{i} A_{k0} \sum_{\sigma=0}^{\lambda} M_{k\sigma} / M_{k0}.$$

As in §2 we may write

$$\frac{I}{V} = \sum_{\beta=0}^{\mu} \frac{\epsilon_{\beta} - \epsilon_{\beta+1}}{V_{\beta}} \int_{R_{\alpha}} f dx,$$

and derive as before the inequality

(6) 
$$0 \leq \sum_{\beta=0}^{\mu} (\epsilon_{\beta} - \epsilon_{\beta+1}) f(p_{\beta}).$$

Then we divide (6) by  $(1-\epsilon_1)$  and let  $\epsilon_1$  tend to unity. In order to evaluate the result we observe the following relations.

If in the determinant  $\Delta$  we put  $s_0 = s_1 = 1$ ,  $s_{\sigma} = \epsilon_{\sigma}$  for  $\sigma > 1$ , we find by differentiating the expansion of  $\Delta$  on the first row that

(7) 
$$\frac{\partial \Delta}{\partial \epsilon_1} = \frac{\partial M_{k0}}{\partial \epsilon_1} + \sum_{\sigma=2}^{r_k} \epsilon_{\sigma} \frac{\partial M_{k\sigma}}{\partial \epsilon_1} .$$

By first subtracting the second row from the first and then differentiating, we find

$$\frac{\partial \Delta}{\partial \epsilon_1} = -M_{k1}.$$

At  $\epsilon_1 = 1$ , we find

(9) 
$$M_{k1} = -M_{k0}, M_{k\beta} = 0 \text{ for } \beta > 1,$$

$$\frac{\partial}{\partial \epsilon_{1}} \frac{M_{k1}}{M_{k0}} = \frac{1}{M_{k0}} \frac{\partial M_{k0}}{\partial \epsilon_{1}},$$

$$\frac{\partial}{\partial \epsilon_{1}} \frac{M_{k\beta}}{M_{k0}} = \frac{1}{M_{k0}} \frac{\partial M_{k\beta}}{\partial \epsilon_{1}} \quad \text{for } \beta > 1.$$

$$\frac{\partial}{\partial \epsilon_{1}} p_{k\beta}^{i} = B_{k}^{i} \frac{A_{k0}}{M_{k0}} \frac{\partial}{\partial \epsilon_{1}} \left[ M_{k0} + \sum_{\sigma=2}^{\lambda} M_{k\sigma} \right],$$

$$\sum_{\beta=1}^{\mu} (\epsilon_{\beta} - \epsilon_{\beta+1}) \frac{\partial}{\partial \epsilon_{1}} \left[ M_{k0} + \sum_{\sigma=2}^{\lambda} M_{k\sigma} \right]$$

$$= \frac{\partial}{\partial \epsilon_{1}} \left[ M_{k0} + \sum_{\sigma=2}^{r_{k}} \epsilon_{\sigma} M_{k\sigma} \right] = M_{k0}.$$

The last equality follows from (7), (8) and (9). So from (6) we have

$$0 \leq f(B_k^i A_{k0}) - \sum_{\beta=1}^{\mu} (\epsilon_{\beta} - \epsilon_{\beta+1}) \sum_{k,i} f_{pk}^i \frac{\partial}{\partial \epsilon_1} p_{k\beta}^i$$
$$= f(B_k^i A_{k0}) - \sum_{k,i} B_k^i A_{k0} f_{pk}^i(0),$$

with the help of (10) and (11). Since by (5)

$$B_k^i = \nu_k! \prod_{j=1}^n (\alpha_j)^{ij},$$

and since we have assumed f(0) = 0, the result has the form given in §1.

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