## INDEPENDENCE OF A CERTAIN AXIOMATIC SYSTEM

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To prove the independence of the system of axioms introduced in [1] we exhibit here ten models, each of them satisfying all the axioms but one; e.g. model  $M_5$  fails to satisfy  $P_5$  of [1].

We call model  $\Gamma$  the Euclidean 3-space with the usual vector structure, introduce a suitable order function  $\phi$  and the usual notion of orthogonality. Let  $A_i(i=1, 2, 3, 4)$  be the position vectors of four points and define:

$$\phi(A_1, A_2, A_3, A_4) = \text{sign det } | A_2 - A_1, A_3 - A_1, A_4 - A_1 |.$$

Model  $\Gamma$  shows the relative consistency of the system.

 $M_1$ —In  $\Gamma$ , take a new order function:  $\phi_1 = |\phi|$ .

 $M_2$ —In  $\Gamma$ , change the sign of  $\phi$  for exactly one nonsingular tetrad and its opposite.

 $M_3$ —Let the  $\phi$  of  $\Gamma$  be identically 0.

 $M_4$ —Adjoin one point X to  $\Gamma$  and extend  $\phi$ :  $\phi(X, A_1, A_2, A_3) = \phi(O, A_1, A_2, A_3)$  where O is the origin and  $A_i \in \Gamma$ .

 $M_5$ —Vectors of  $\Gamma$  with integral components and  $\phi$  restricted accordingly.

 $M_6$ —In the hyperbolic space  $H^3$  take any orientation function for  $\phi$  and keep the usual orthogonality notion.

 $M_{\tau}$ —Take the vectors of  $\Gamma$  with rational components and restrict  $\phi$ .

 $M_8$ —Imbed  $\Gamma$  in the projective space  $P^3$  adding the ideal plane  $\Omega$ . Let  $\gamma$  be a real conic on  $\Omega$  and define  $l \perp \pi$  (in  $\Gamma$ ) to mean  $l \cap \Omega$  and  $\pi \cap \Omega$  are pole and polar with respect to  $\gamma$ .

 $M_9$ —Same as before but  $l \perp \pi$  is defined only if  $l \cap \Omega$  is a two-tangent point with respect to  $\gamma$ .

 $M_{10}$ —Let  $\gamma$  be an elliptic correlation, not a polarity, on  $\Omega$ , and define  $l \perp \pi$  accordingly.

The proof is now complete.

## REFERENCE

1. L. Gutierrez-Novoa, Ten axioms for three-dimensional Euclidean geometry, Proc. Amer. Math. Soc. 19 (1958), 146-152.

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