

# A NOTE ON THE REPRESENTATION OF A SOLUTION OF AN ELLIPTIC DIFFERENTIAL EQUATION NEAR AN ISOLATED SINGULARITY<sup>1</sup>

DAVID G. SCHAEFFER<sup>2</sup>

There are a number of results known which state that a solution  $u$  of an elliptic differential equation

$$(1) \quad Au = 0$$

which has an isolated singularity at a point  $p \in \mathbf{R}^n$  may be expressed as the sum of a derivative of the fundamental solution of  $A$  and a solution of (1) regular at  $p$ , providing that  $u$  satisfies one of various conditions limiting its growth near  $p$  (see for example F. John [2] or R. Seeley [7]). The main conclusion of this note is a representation of any solution of (1) with an isolated singularity at  $p$  which makes no assumption on the behavior of  $u$  near the singularity; the representation is in terms of a (real) analytic functional supported on  $\{p\}$  applied to the fundamental solution. This result is in the spirit of the work of J. L. Lions and E. Magenes [3] on elliptic boundary value problems with analytic functionals as data.

Actually with our method it involves no additional difficulty to obtain the representation when  $u$  is singular on a compact set  $K \subset \mathbf{R}^n$ —that is, when  $u$  is a solution of (1) on  $\Omega \sim K$ , where  $\Omega$  is some open connected neighborhood of  $K$  in  $\mathbf{R}^n$ . We may suppose without loss of generality that  $\partial\Omega$  is smooth and that  $u$  is  $\mathcal{C}^\infty$  on  $\bar{\Omega} \sim K$ , because any neighborhood of  $K$  contains a smaller neighborhood for which this will be true. We assume that  $A$  is a properly elliptic differential operator (as defined by M. Schechter in [6]) of order  $2m$  whose coefficients are analytic on  $\bar{\Omega}$ . Let  $\gamma$  be a two-sided fundamental solution for  $A$  on  $\Omega$ ; more explicitly, if  $\Gamma: \mathcal{D}(\Omega) \rightarrow \mathcal{E}(\Omega)$  is defined by

$$\Gamma\phi(x) = \int_{\Omega} dx' \gamma(x, x')\phi(x'),$$

---

Received by the editors March 3, 1969.

<sup>1</sup> This research was conducted as part of the author's doctoral dissertation at the Massachusetts Institute of Technology. It is a pleasure to express my appreciation to Professor T. Kotake, my thesis supervisor, for his advice on this problem.

<sup>2</sup> The author acknowledges with gratitude the support he received from the National Science Foundation through a graduate fellowship and through NSF GP6761.

then

$$(2) \quad \Gamma A\phi = A\Gamma\phi = \phi$$

for all  $\phi \in \mathfrak{D}(\Omega)$ . The existence of such a fundamental solution was proved by B. Malgrange in [4].

To specify the notation we review in this paragraph the terminology of analytic functionals (see A. Martineau [5] for details). We define the space of functions  $\mathfrak{A}(V)$  analytic on an open set  $V$  in  $\mathbb{R}^n$  as the inductive limit as  $\epsilon \rightarrow 0$  of the space of functions on  $V$  whose power series about any point converges in a ball of radius  $\epsilon$ . That is, if  $\epsilon > 0$ , let

$$\|\psi\|_\epsilon = \sup_{x \in V} \sup_{\alpha} (\alpha!)^{-1} \epsilon^{|\alpha|} |D^\alpha \psi(x)|,$$

where  $\alpha$  is a multi-index exponent for the differentiation operator  $D$ ; let

$$\mathfrak{A}(V; \epsilon) = \{ \psi \in \mathfrak{E}(V) \mid \|\psi\|_\epsilon < \infty \}$$

and give it the norm topology; and finally let

$$\mathfrak{A}(V) = \text{ind} \lim_{\epsilon \rightarrow 0} \mathfrak{A}(V; \epsilon).$$

In the usual way, the space of functions  $\mathfrak{A}(K)$  analytic on a closed set  $K$  is defined as the inductive limit of the space of functions analytic on some neighborhood  $V$  of  $K$  as  $V$  decreases to  $K$ . A (real) analytic functional supported on  $K$  is a continuous linear functional on  $\mathfrak{A}(K)$ , an element of the dual space  $\mathfrak{A}'(K)$ .

We remark that the fundamental solution for  $A$  is analytic, because  $A$  has analytic coefficients. Thus if  $x \in \Omega \sim K$ , then  $D_x^\alpha \gamma(x, \cdot) \in \mathfrak{A}(K)$  for any multi-index  $\alpha$ , and the difference quotients for these derivatives converge in the topology of  $\mathfrak{A}(K)$ . In particular,

$$A\gamma(x, \cdot) = 0 \in \mathfrak{A}(K)$$

for  $x \in \Omega \sim K$ . If  $T \in \mathfrak{A}'(K)$ , we denote by  $T[\gamma]$  the function

$$(3) \quad v(x) = T[\gamma(x, \cdot)] \quad (x \in \Omega \sim K).$$

It is readily shown by an exchange of limits that  $Av = 0$ . We state now our main theorem.

**THEOREM 1.** *If  $u$  is a solution of (1) on  $\Omega \sim K$ , then there is an analytic functional  $T$  supported on  $K$  such that  $u - T[\gamma]$  is the restriction to  $\Omega \sim K$  of an (analytic) solution of (1) defined on  $\Omega$ .*

Before we prove the theorem we introduce a space of solutions on  $K$  of the adjoint equation and we construct from  $u$  a certain linear functional on this space which characterizes the singularity of  $u$  on  $K$ .<sup>3</sup> Let

$$\mathcal{J}(K) = \{\psi \in \mathcal{A}(K) \mid A^*\psi = 0\},$$

and give it the relative topology. If  $\phi$  is a smooth function on  $\Omega \sim K$  such that  $A\phi \in L^1(\Omega \sim K)$  and if  $\psi \in \mathcal{J}(V)$  [that is, the kernel of  $A^*$  in  $\mathcal{A}(V)$ , where  $V$  is some neighborhood of  $K$ ], let  $\rho$  be a  $C^\infty$  function supported in  $V$  that is identically one near  $K$  and define

$$(4) \quad B[\phi, \psi] = \int_{\Omega \sim K} dx \{ \phi A^*(\rho\psi) - \rho\psi A\phi \}.$$

Since  $A^*(\rho\psi)$  has compact support, the possibly troublesome first term of the integral in (4) is well defined. The integral is independent of the choice of  $\rho$  because the difference of two possible choices is a test function supported in  $\Omega \sim K$ , permitting an integration by parts. For each  $V$  the functional  $B[\phi, \cdot]$  is continuous on  $\mathcal{J}(V)$ , so  $B[\phi, \cdot] \in \mathcal{J}'(K)$  by inductive limits. The functional  $B[u, \cdot]$  specifies the boundary data of  $u$  on  $\partial K$  in the sense of equation (6) below.

Suppose  $w$  is a smooth function on  $\bar{\Omega}$  such that  $A^*w$  vanishes in a neighborhood  $V$  of  $K$ ; choose  $\rho$  as in (4) and let  $\zeta = 1 - \rho$ , so that  $\zeta$  is a  $C^\infty$  function vanishing near  $K$ . Consider the integral

$$(5) \quad \int_{\Omega \sim K} dx \{ u A^*w - w A u \} = \int_{\Omega \sim K} dx \{ u A^*(\rho w) - \rho w A u \} + \int_{\Omega \sim K} dx \{ u A^*(\zeta w) - \zeta w A u \};$$

the first term on the right in (5) is simply  $B[u, w]$ , while the second reduces to a surface integral by Green's theorem. Hence

$$(6) \quad \int_{\Omega \sim K} dx \{ u A^*w - w A u \} = B[u, w] + \sum_{j=0}^{2m-1} \int_{\partial\Omega} d\sigma \left( \frac{\partial}{\partial\nu} \right)^j u D_j w,$$

where  $\partial/\partial\nu$  denotes the exterior normal derivative and  $D_j$  is a differential operator of order  $2m - j - 1$  for which  $\partial\Omega$  is noncharacteristic.

**PROPOSITION 2.** *If  $u$  is a solution of  $Au = 0$  on  $\Omega \sim K$ , then  $u$  is the restriction to  $\Omega \sim K$  of a solution on  $\Omega$  if and only if  $B[u, \cdot] = 0$ .*

<sup>3</sup> This procedure is very suggestive of the duality considered by A. Grothendieck in [1] and by others.

PROOF. If  $u$  extends to a solution of (1) on  $\Omega$ , then an integration by parts in (4) checks that  $B[u, \cdot] = 0$ . Conversely, suppose that  $B[u, \cdot] = 0$ ; we show that an extension of  $u$  to  $\Omega$  may be obtained as a solution  $u'$  of the Dirichlet problem,  $Au' = 0$  in  $\Omega$ , whose Dirichlet data on  $\partial\Omega$  coincides with that of  $u$ . A solution  $u'$  exists, for if  $w$  is any solution of the adjoint equation  $A^*w = 0$  with homogeneous data, then by (6)

$$\sum_{j=0}^{m-1} \int_{\partial\Omega} d\sigma \left(\frac{\partial}{\partial\nu}\right)^j u D_j w = 0;$$

that is, the data is orthogonal to any solution of the adjoint equation, so a solution exists according to the Fredholm alternative.

Let  $N$  denote the finite-dimensional space of solutions of (1) on  $\Omega$  with vanishing Dirichlet data. If  $f \in \mathfrak{D}(\Omega \sim K)$  is orthogonal to  $N$ , choose  $w$  so that  $A^*w = f$  and  $w$  has homogeneous data. Then again by (6)

$$\int_{\Omega \sim K} dx u' A^*w = \sum_{j=0}^{m-1} \int_{\partial\Omega} d\sigma \left(\frac{\partial}{\partial\nu}\right)^j u' D_j w = \int_{\Omega \sim K} dx u A^*w,$$

thus

$$\int dx (u - u') f = 0.$$

Hence  $(u - u')$  is orthogonal to any vector in  $N^\perp$ , so  $u$  differs from  $u'$  by an element of  $N$  which may be added to  $u'$  to obtain the desired extension.

PROOF OF THEOREM 1. Suppose  $u$  is a solution of (1) on  $\Omega \sim K$ . For  $x \in \Omega \sim K$  we define the function

$$v(x) = B[u, \gamma(x, \cdot)].$$

By the Hahn-Banach theorem  $B[u, \cdot]$  may be extended from  $\mathfrak{g}(K)$  to a linear functional  $T$  on  $\mathfrak{Q}(K)$ , so  $v$  is of the form  $T[\gamma]$ . As we remarked before Theorem 1,  $Av = 0$ ; we show below that  $B[v, \cdot] = B[u, \cdot]$ . Hence by the proposition  $u - v$  is the restriction to  $\Omega \sim K$  of a solution of (1) on  $\Omega$ .

If  $w \in \mathfrak{g}(K)$ ,

$$\begin{aligned} B[v, w] &= \int dx v(x) A^*[\rho w(x)] = \int dx T[\gamma(x, \cdot)] A^*[\rho w(x)] \\ &= T \left\{ \int dx \gamma(x, \cdot) A^*[\rho w(x)] \right\}, \end{aligned}$$

since the fact that  $A^*(\rho w)$  has compact support in  $\Omega \sim K$  implies that the integral converges in the topology of  $\mathcal{G}(K)$ . Thus

$$(7) \quad B[v, w] = T[\Gamma^* A^*(\rho w)],$$

where  $\Gamma^* \phi(x) = \int dx' \bar{\gamma}(x', x) \phi(x')$ . It is obvious from (2) that  $\Gamma^* A^* \phi = A^* \Gamma^* \phi = \phi$  for all  $\phi \in \mathcal{D}(\Omega)$ ; moreover, since  $\rho \equiv 1$  near  $K$ ,  $\Gamma^* A^*(\rho w) = w$  near  $K$ . Therefore from (7),  $B[v, w] = T[w] = B[u, w]$ , where the final equality follows from the observation that  $w \in \mathcal{G}(K)$ . This completes the proof.

We remark in closing that a similar representation for a solution of the inhomogeneous equation  $Au = f$  can be proved quite simply with our methods.

#### BIBLIOGRAPHY

1. A. Grothendieck, *Sur les espaces de solutions d'une classe générale d'équations aux dérivées partielles*, J. Analyse Math. **2** (1952/1953), 243–280.
2. F. John, *The fundamental solution of linear elliptic differential equations with analytic coefficients*, Comm. Pure Appl. Math. **3** (1950), 273–304.
3. J. L. Lions and E. Magenes, *Problèmes aux limites non homogènes*. VII, Annali di Math. (4) **63** (1963), 201–224.
4. B. Malgrange, *Existence et approximation des solutions des équations aux dérivées partielles et des équations de convolution*, Ann. Inst. Fourier (Grenoble) **6** (1955/1956), 271–355.
5. A. Martineau, *Les hyperfonctions de M. Sato*, Séminaire Bourbaki **13**, Exposé 214 (1960/1961).
6. M. Schechter, *General boundary value problems for elliptic partial differential equations*, Comm. Pure Appl. Math. **12** (1959), 457–486.
7. R. T. Seeley, *Refinement of the functional calculus of Calderon and Zygmund*, Nederl. Akad. Wetensch. Proc. Ser. A **68** (1965), 521–531.

MASSACHUSETTS INSTITUTE OF TECHNOLOGY