

THE ENDS OF PRODUCT MANIFOLDS

DENNIS C. HASS

ABSTRACT. In this paper we provide simple point set properties which characterize the m -spheres S^m , open m -cells E^m , closed cells I^m , and annuli $A^m = [0, 1) \times S^{m-1}$. It is important to notice that the Poincaré conjecture is not used in dimension 3 or 4.

In this paper we provide simple point set properties which characterize m -spheres S^m and open m -cells E^m among m -manifolds. Accepting these two main theorems, we establish corollaries which characterize closed cells I^m and annuli $A^m = [0, 1) \times S^{m-1}$. Then we prove the two main theorems. It is important to note that the Poincaré conjecture is not used in dimension 3 or 4.

In the following M will mean an m -manifold, for $m \geq 2$, and P is a point in M . We will always be asking for geometric consequences of supposing that a certain subset of M (such as $M - P$) is a product $A \times B$ of topological spaces where neither A nor B is a single point. Recall that such factors A, B are necessarily generalized manifolds in the sense of Wilder ([1], [2]). We will repeatedly use the fact that A or B is therefore a manifold if its dimension is ≤ 2 [1].

1. The proofs of the first two theorems are deferred until the next section.

THEOREM 1. $M = E^m$ is the only connected noncompact m -manifold such that $M - P$ is a product space.

THEOREM 2. $M = S^m$ is the only connected compact m -manifold such that $M - P$ is a product space.

COROLLARY 3. It is not necessary in Theorem 2 to assume that M is connected.

PROOF. Let N be the component of M with P in N . By Theorem 2, $N = S^m$. Now let $M - P = X \times Y$ and X_0, Y_0 be the components of X and Y

Received by the editors August 22, 1971.

AMS 1970 subject classifications. Primary 54F65, 55A40, 57A15, 57B99; Secondary 54E45, 57A05, 57A10, 57C99, 57D99.

Key words and phrases. Topological manifold, generalized manifold, spheres, cells, annulus, product space, ends, Poincaré theorem, residual set.

© American Mathematical Society 1972

for which $N - P = X_0 \times Y_0$. Then X_0 and Y_0 are contractible (hence noncompact). If X_1 is another component of X , then $X_1 \times Y_0$ is a noncompact component of M . This contradiction means X is connected. Similarly Y , and hence M , is connected. Thus $M = N = S^m$.

Without the connectivity, Theorem 1 fails, even for $m=2$. There are two distinct 2-manifolds M and M_1 such that $M - P = M_1 - P_1 = (E^1 \cup S^1) \times E^1$ is a product of E^1 by a disjoint union.

We now turn our attention to manifolds M with boundary bM and interior $\text{Int}(M)$. P will always be a point in the interior of M and Q a point in bM .

THEOREM 4. *These conditions are equivalent for a connected m -manifold with $bM = S^{m-1}$:*

- (a) $M = I^m$.
- (b) $\text{Int } M$ is a product space and M is compact.
- (c) M is a compact product space.
- (d) $\text{Int } M - P$ is a product space.
- (e) $M - Q$ is a product space and M is compact.

PROOF. (a) clearly implies the rest of the list. Each of (e) and (c) implies (b). We will show (b) implies (a). Let $N = M/bM$ be the quotient space. Then $N - (bM/bM)$ is $\text{Int } M$, which is a product space. Since N is compact, $N = S^m$ by Theorem 2. Now $\text{Int } M = E^m$ which implies (a) by Schoenflies [3]. That (d) implies (a) follows from Theorem 1.

In condition (d) compactness is a consequence rather than a hypothesis. According to Theorem 7, below, this is often true of condition (e) as well.

THEOREM 5. *These conditions are equivalent for a connected m -manifold M with $bM = S^{m-1}$:*

- (a) $M = [0, 1) \times S^{m-1} = A^m$.
- (b) $\text{Int } M$ is a product space and M is not compact.
- (c) M is a noncompact product space.

PROOF. Clearly (a) implies (c) and (c) implies (b). We shall show that (b) implies (a) by forming the manifold $N = M/bM$. Since $N - (bM/bM) = \text{Int } M$ is a product space, $N = E^m$ by Theorem 1. The theorem follows.

The next theorem fully describes closed cells and annuli entirely in point set terms.

THEOREM 6. *Let M be a connected m -manifold with compact boundary bM . If each of M and $bM - Q$ is a product space, then M is either I^m or $[0, 1) \times S^{m-1}$.*

PROOF. By Corollary 3, bM is S^{m-1} . If M is compact, $M = I^m$ by Theorem 4(c). If not, then $M = A^m$ by Theorem 5(c).

For most m , we have two other characterizations of I^m . Whenever X is a generalized manifold, let bX denote its boundary.

- THEOREM 7. *If $M-Q = X \times Y$ is a product space with $bX = \emptyset$, then*
- the double $2M$ is S^m , so M is compact;*
 - bM is a homotopy $(m-1)$ -sphere;*
 - $\text{Int } M = E^m$;*
 - $M = I^m$, unless $m=4$ or 5 ; and*
 - $M-Q = (bM-Q) \times [0, 1)$.*

PROOF. $2M-Q = 2(X \times Y) = X \times 2Y$, because $bX = \emptyset$ and because Q is in bM . Thus, either $2M = S^m$ by Theorem 2, or $2M = E^m$ by Theorem 1. In the latter case we use the proof of Theorem 1 to conclude further that X is a compact (generalized) homotopy $(m-1)$ -sphere and that $2Y = E^1$. Now, $Y = [0, 1)$ and $M-Q = X \times [0, 1)$. Since $bM-Q = X$ and since X is compact and $bM-Q$ is not, we have reached a contradiction. Thus, $2M = S^m$ as stated.

If $\dim Y > 1$, then $bM-Q = b(M-Q) = b(X \times Y) = X \times bY$ is a product. By Theorem 2, $bM = S^{m-1}$. By Theorem 4(b), M is I^m , completing the theorem.

Thus, we let $\dim Y = 1$. Since $E^m = S^m - Q = 2M - Q = X \times 2Y$, we have $2Y = E^1$ and $Y = [0, 1)$ and X is contractible. Further, $bM-Q = b(M-Q) = X$. This means bM is a homotopy sphere. Unless $m=4$ or 5 , $bM = S^{m-1}$ and $M = I^m$ by Theorem 4(b). Finally, $E^m = S^m - Q = 2M - Q = X \times 2Y = X \times E^1 = \text{Int } M$, completing the theorem.

THEOREM 8. *If bM is compact and $\text{Int } M-P = X \times Y$ is a product space, then*

- $\text{Int } M = E^m$, so M is compact;*
- bM is a homotopy sphere;*
- $2M = S^m$; and*
- $M = I^m$, unless $m=4$ or 5 .*

PROOF. (a) follows from Theorem 1 and implies (b). (c) holds because $2M$ is the union of two m -cells. (d) follows from the Poincaré conjecture in the correct dimension.

2. In order to prove the two main theorems, we begin by studying the ends of open generalized manifolds. See Siebenmann [4] for a discussion of ends and Wilder [1, Chapter 8] for a definition of generalized manifolds.

Let M be a j -connected generalized manifold and let M have an isolated end E which is k -connected (i.e. E has small k -connected neighborhoods). Although generally no relationship exists between j and k , it is instructive to examine the following class of doughnut-like manifolds.

Let $N = S^{m+1} \times I^{n+2}$. Now, $\text{Int } N = S^{m+1} \times E^{n+2}$ is m -connected and has one isolated end whose groups are those of $bN = S^{m+1} \times S^{n+1}$. Thus, $j = m$, and $k = \min\{m, n\}$. It follows from Corollary 11 below that, just as in this example, it is always true that $j \geq k$ for such products. Proofs of the next three propositions appear in the author's dissertation [5]. Let $M = A \times B$ be an open generalized m -manifold.

LEMMA 9. *If neither A nor B is compact, then M has exactly one end.*

Let $M = A \times B$ have at least one isolated end E .

LEMMA 10. *If E has a k -connected neighborhood and if A is not compact, then B is k -connected, even if B is not compact.*

The import here is that B is a retract of every such neighborhood.

COROLLARY 11. *If M is k -connected at E , and if A is not compact, then B is k -connected. Thus, if neither A nor B is compact, then each of M , A and B is k -connected. That is, $j \geq k$.*

LEMMA 12. *If $K \subset E^1 \times B$ is compact, then there is another copy of K in $E^1 \times B$ disjoint from K .*

PROOF. Since K is compact, there is an r in E^1 such that $K \subset (-r, r) \times B$. The homomorphism h given by $h(x, b) = (x + 3r, b)$ is a translation which moves K disjoint from itself.

THEOREM 13. *If M is an m -manifold with P in $\text{Int } M$, and if $M - P = A \times B$ is a product space, then M is $(m-2)$ -connected. Moreover, if B is compact, then $M - P = E^1 \times B$.*

PROOF. By general position (in a coordinate chart about P), the homotopy groups of M and $M - P$ agree up to dimension $m-2$. If neither A nor B is compact, then we are done by Corollary 11. Let B be compact. Using Poincaré duality on B , $H_i B = Z_2$ for $i = \dim B$. From Corollary 11, B is $(m-2)$ -connected; that is, $H_n B = 0$ for $n \leq m-2$. Thus $\dim B = m-1$ and $\dim A = 1$. This means $A = E^1$ and $M - P = E^1 \times B$. Now, $M - P$ is $(m-2)$ -connected, because B is.

Now we are equipped to prove the two main theorems. Let P be in M .

PROOF OF THEOREM 1. By Lemma 9, if neither A nor B is compact, then $M - P$ has just one end. Since this makes M compact, we may instead assume that B is compact.

By Theorem 13, $M - P = E^1 \times B$. This makes M the open cone CB on B . Thus $M = E^m$ by Brown's open star theorem [6].

PROOF OF THEOREM 2. By Theorem 13, M is $(m-2)$ -connected. Using the Poincaré theorem, we find $M = S^m$ for $m \geq 5$. Thus, let $m \leq 4$. From

Theorem 13, we find that if B is compact, $M-P=E^1 \times B$ has two ends. Since this denies that M is compact, we may assume that neither A nor B is compact. It follows that each of $M-P$, A , and B is contractible. If $m=2$, $A=B=E^1$ so $M=S^2$. If $m=3$, $A=E^1$, $B=E^2$ or vice-versa, so $M=S^3$. Let $m=4$. If $\dim B=2$, then $A=B=E^2$, so $m=S^4$. We have left only the case $m=4$ and $\dim B=3$. In this case $A=E^1$ and $M-P=E^1 \times B$. We decompose $M=e^4 \cup K$ as a disjoint union of an open 4-cell e^4 and a compact residual set K with P not in K . Using Lemma 12 to translate K in $E^1 \times B$, we find that M is a union of two open cells, and, hence, $M=S^4$; see [7].

ACKNOWLEDGEMENT. The author wishes to thank Dr. Patrick H. Doyle for his help and Michigan State University for its support during research on this topic.

BIBLIOGRAPHY

1. R. L. Wilder, *Topology of manifolds*, Amer. Math. Soc. Colloq. Publ., vol. 32, Amer. Math. Soc., Providence, R.I., 1949. MR 10, 614.
2. F. Raymond, *Separation and union theorems for generalized manifolds with boundary*, Michigan Math. J. 7 (1960), 7-21. MR 22 #11388.
3. M. Brown, *A proof of the generalized Schoenflies theorem*, Bull. Amer. Math. Soc. 66 (1960), 74-76. MR 22 #8470b.
4. L. C. Siebenmann, *The obstruction to finding a boundary for an open manifold of dimension greater than five*, Thesis, Princeton University, Princeton, N.J., 1965.
5. D. C. Hass, *The ends of a product manifold*, Thesis, Michigan State University, East Lansing, Mich., 1970.
6. B. Mazur, *The method of infinite repetition in pure topology*. I, Ann. of Math (2) 80 (1964), 201-226. MR 29 #6477.
7. P. H. Doyle and J. G. Hocking, *A decomposition theorem for n -dimensional manifolds*, Proc. Amer. Math. Soc. 13 (1962), 469-471. MR 25 #4514.

DEPARTMENT OF MATHEMATICS, RANDOLPH-MACON WOMAN'S COLLEGE, LYNCHBURG, VIRGINIA 24504