

DYNAMIC STABILITY OF EQUILIBRIUM STATES OF THE EXTENSIBLE BEAM¹

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ABSTRACT. In this paper an equation describing the dynamic behavior of a nonlinear beam with viscous damping is treated. In particular it is shown that when the trivial solution is the only equilibrium solution then all solutions, regardless of initial data, decay exponentially to the trivial solution. In those cases where nontrivial equilibrium solutions in addition to the trivial solution are possible it is shown that the nontrivial solution corresponding to the 'lowest buckled mode' is locally stable, i.e. dynamic solutions with initial data 'close' to the lowest buckled mode decay to this equilibrium solution. Estimates are obtained for the various decay rates.

1. Introduction. The purpose of this paper is to discuss the asymptotic stability of equilibrium solutions of the equation

$$(1.1) \quad w_{tt} + \alpha w_t + w_{xxxx} - \left[(-1 + \varepsilon) + \frac{2}{\pi} \int_0^\pi w_x^2 dx \right] w_{xx} = 0 \quad (\alpha > 0)$$

which satisfy initial data

$$(1.2a) \quad w(x, 0) = f(x),$$

$$(1.2b) \quad w_t(x, 0) = g(x)$$

and boundary conditions

$$(1.3a) \quad w(0, t) = w(\pi, t) = 0,$$

$$(1.3b) \quad w_{xx}(0, t) = w_{xx}(\pi, t) = 0.$$

Solutions of (1.1) describe the damped vibrations of an extensible beam (cf. [1]).

The existence of solutions to equation (1.1) with $\alpha=0$ has been treated in [2] and [3] and there is no difficulty in extending these arguments to prove the existence of solutions to (1.1) with $\alpha>0$ for all $t \geq 0$. In this paper it will be assumed that the initial data (1.2) is sufficiently differentiable

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to guarantee that solutions of (1.1) are classical solutions. In this case it is quite easily shown following the development in [2] that the solution can be written in the form

$$(1.4) \quad w(x, t) = \sum_{j=1}^{\infty} T_j(t) \sin jx$$

where the functions $T_j(t)$ exist for all $t \geq 0$ and satisfy the infinite system of ordinary differential equations

$$(1.5) \quad \ddot{T}_j + \alpha \dot{T}_j + j^4 T_j + j^2 \left[(-1 + \varepsilon) + \sum_{l=1}^{\infty} l^2 T_l^2 \right] T_j = 0$$

($\dot{} = d/dt$) and the initial conditions

$$(1.6a) \quad -T_j(0) = \alpha_j = \frac{2}{\pi} \int_0^{\pi} f(x) \sin jx \, dx,$$

$$(1.6b) \quad \dot{T}_j(0) = \beta_j = \frac{2}{\pi} \int_0^{\pi} g(x) \sin jx \, dx.$$

If $\varepsilon \geq 0$ the 'static' problem corresponding to (1.1), i.e.

$$(1.7) \quad W_{xxxx} - \left[(-1 + \varepsilon) + \frac{2}{\pi} \int_0^{\pi} W_x^2 \, dx \right] W_{xx} = 0$$

has only the trivial solution satisfying the boundary conditions (1.3). In this case (cf. §2) it will be shown that $w \equiv 0$ is globally stable, i.e. every solution $w(x, t)$ of (1.1) has the property that $w(x, t) \rightarrow 0$ as $t \rightarrow \infty$. If $\varepsilon < 0$ equation (1.7) has, in addition to the trivial solution, solutions of the form

$$(1.8) \quad W_j^{\pm}(x) = \pm \frac{1}{j} \sqrt{1 - \varepsilon - j^2} \sin jx, \quad j = 1, 2, \dots, N,$$

where N is the largest integer such that $N^2 < 1 - \varepsilon$. In §3 conditions on the initial data are given which guarantee that if $\varepsilon < 0$ then $w(x, t) \rightarrow 0$ as $t \rightarrow \infty$. This result is actually sufficient to guarantee that $w(x, t)$ converges to one of the buckled states $W_j^{\pm}(x)$ (cf. [4]). Finally, in §4 it is shown that if the initial data is sufficiently 'close' to $W_1^+(x)$ ($W_1^-(x)$), then $w(x, t) \rightarrow W_1^+(x)$ ($w(x, t) \rightarrow W_1^-(x)$) as $t \rightarrow \infty$, i.e. if $\varepsilon < 0$ then the lowest buckled mode is 'locally' stable. The above results were obtained formally, using two time asymptotic expansions, by Reiss and Matkowsky [6].

2. Stability of the trivial solution. In this section it will be shown that if $\varepsilon \geq 0$ solutions of (1.1) tend to zero as $t \rightarrow \infty$. This result is based on the fact that solutions of (1.1) satisfying the boundary conditions (1.3) must

satisfy the identities

$$(2.1) \quad \begin{aligned} \frac{dE}{dt} + 2\alpha \int_0^\pi w_t^2 dx \\ = \frac{d}{dt} \left\{ \int_0^\pi w_t^2 dx + \int_0^\pi w_{xx}^2 dx + (\varepsilon - 1) \int_0^\pi w_x^2 dx + \frac{1}{\pi} \left(\int_0^\pi w_x^2 dx \right)^2 \right\} \\ + 2\alpha \int_0^\pi w_t^2 dx = 0 \end{aligned}$$

and

$$(2.2) \quad \frac{d}{dt} \int_0^\pi w w_t dx - 2 \int_0^\pi w_t^2 dx + E + \frac{1}{\pi} \left(\int_0^\pi w_x^2 dx \right)^2 + \alpha \int_0^\pi w w_t dx = 0.$$

The identities (2.1) and (2.2) follow upon multiplying equation (1.1) first by w_t and then by w . Multiplying equation (2.2) by α and adding the result to (2.1) yields the identity³

$$(2.3) \quad \frac{d}{dt} \left\{ E + \alpha \int_0^\pi w w_t dx \right\} + \alpha \left\{ E + \alpha \int_0^\pi w w_t dx \right\} = - \frac{\alpha}{\pi} \left(\int_0^\pi w_x^2 dx \right)^2 \leq 0$$

or

$$(2.4) \quad E(t) + \alpha \int_0^\pi w w_t dx \leq \left(E(0) + \alpha \int_0^\pi f(x)g(x) dx \right) \exp(-\alpha t)$$

where

$$(2.5) \quad \begin{aligned} E(0) = \int_0^\pi g(x)^2 dx + \int_0^\pi f''(x)^2 dx \\ + (\varepsilon - 1) \int_0^\pi f'(x)^2 dx + \frac{1}{\pi} \left(\int_0^\pi f'(x)^2 dx \right)^2. \end{aligned}$$

The functions $w(x, t)$ and $w_{xx}(x, t)$ vanish at $x=0$ and $x=\pi$. Thus the minimum characterization of eigenvalues (cf. [5]) guarantees that

$$(2.6) \quad \int_0^\pi w_{xx}^2 dx / \int_0^\pi w_x^2 dx \geq 1$$

and

$$(2.7) \quad \int_0^\pi w_x^2 dx / \int_0^\pi w^2 dx \geq 1$$

since $\lambda=1$ is the smallest eigenvalue of both

$$(2.8) \quad w_{xxxx} + \lambda w_{xx} = 0,$$

$$(2.9) \quad w_{xx} + \lambda w = 0$$

³ The identity (2.3) was suggested to the author by P. R. Rabinowitz.

under the prescribed boundary conditions. We conclude that solutions of (1.1) satisfying the boundary conditions (1.3) must also satisfy the inequality

$$(2.10) \quad \int_0^\pi w^2 dx \leq \int_0^\pi w_x^2 dx \leq \int_0^\pi w_{xx}^2 dx.$$

This fact in conjunction with (2.4) implies that $w(x, t)$ must satisfy

$$(2.11) \quad \frac{\alpha}{2} \frac{d}{dt} \int_0^\pi w^2 dx + \varepsilon \int_0^\pi w^2 dx + \frac{1}{\pi} \left(\int_0^\pi w^2 dx \right)^2 \\ \leq \left(E(0) + \alpha \int_0^\pi f(x)g(x) dx \right) \exp(-\alpha t)$$

and in addition the weaker inequality

$$(2.12) \quad \frac{\alpha}{2} \frac{d}{dt} \int_0^\pi w^2 dx + \varepsilon \int_0^\pi w^2 dx \leq \left(E(0) + \alpha \int_0^\pi f(x)g(x) dx \right) \exp(-\alpha t).$$

If $\varepsilon > 0$ the inequality (2.12) implies that either

$$(2.13) \quad \int_0^\pi w^2 dx \leq C_1 \exp(-\alpha t) + C_2 \exp(-2\varepsilon t/\alpha)$$

if $\alpha^2 \neq 2\varepsilon$ or

$$(2.14) \quad \int_0^\pi w^2 dx \leq (C_3 + C_4 t) \exp(-\alpha t)$$

if $\alpha^2 = 2\varepsilon$. The constants C_1, C_2, C_3 and C_4 depend only on the initial data. In either case (2.12) and (2.13) imply that $w(x, t) \rightarrow 0$ as $t \rightarrow \infty$ if $\varepsilon > 0$. If $\varepsilon = 0$ it is easily shown, using (2.11), that

$$(2.15) \quad \frac{d}{dt} \left(\int_0^\pi w^2 dx \right)^2 \leq C_5$$

and

$$(2.16) \quad \int_0^t \left(\int_0^\pi w^2 dx \right)^2 d\tau \leq C_6$$

where C_5 and C_6 depend on the initial data. It is an immediate consequence of (2.15) and (2.16) that, even in the case $\varepsilon = 0$, $w(x, t) \rightarrow 0$ as $t \rightarrow \infty$. We summarize these results in the following theorem:

THEOREM (2.1). *If $\varepsilon \geq 0$ every solution $w(x, t)$ of (1.1) satisfying the boundary conditions (1.3) has the property that $w(x, t) \rightarrow 0$ as $t \rightarrow \infty$.*

3. Conditions for which $w(x, t) \rightarrow 0$ as $t \rightarrow \infty$. If $\varepsilon < 0$ it is possible to specify initial data such that $E(0) < 0$. For example, if

$$w(x, 0) = W_1^\pm(x) = \pm \sqrt{-\varepsilon} \sin x$$

and $w_t(x, 0) = 0$ it is easily seen that $E(0) = -\pi\varepsilon^2/4$. In this section it will be shown that:

THEOREM (3.1). *Every solution $w(x, t)$ of (1.1) satisfying the boundary conditions (1.3) and the condition $E(0) < 0$ has the property and $w(x, t) \rightarrow 0$ as $t \rightarrow \infty$.*

PROOF. If $E(0) < 0$ ($\Rightarrow \varepsilon < 0$) the identity (2.1) implies that

$$(3.1) \quad E(t) \leq E(0) < 0$$

for all $t \geq 0$. In view of (2.10) the inequality (3.1) yields

$$(3.2) \quad \varepsilon\pi \int_0^\pi w_x^2 dx + \left(\int_0^\pi w_x^2 dx \right)^2 - \pi E(0) \leq 0$$

or equivalently

$$(3.3) \quad 0 < M_- \leq \int_0^\pi w_x^2 dx \leq M_+$$

where

$$(3.4) \quad M_\pm = \frac{\pi}{2} \{ -\varepsilon \pm (\varepsilon^2 + 4E(0)/\pi)^{1/2} \}.$$

(Note that (3.3) and (3.4) imply that $E(0) \geq -\pi\varepsilon^2/4$, i.e. the minimum energy is attained when $w(x, t) = W_1^\pm(x)$.) It is an immediate consequence of (3.1) and (3.3) that there exists a positive constant M such that

$$(3.5) \quad \int_0^\pi w_{xx}^2 dx \leq M$$

for all $t \geq 0$. In addition the inequality (3.3) suffices to guarantee that $w_x(x, t) \rightarrow 0$ as $t \rightarrow \infty$. It remains to show that $w(x, t) \rightarrow 0$ as $t \rightarrow \infty$. However, this follows from the fact that

$$(3.6) \quad \int_0^\pi w_x^2 dx = - \int_0^\pi w w_{xx} dx \leq \left(\int_0^\pi w^2 dx \int_0^\pi w_{xx}^2 dx \right)^{1/2}.$$

The inequalities (3.3), (3.5), and (3.6) imply that

$$(3.7) \quad \int_0^\pi w^2 dx \geq \frac{M_-^2}{M} > 0.$$

Thus, $w(x, t) \rightarrow 0$ as $t \rightarrow \infty$. Q.E.D.

4. Local stability of the lowest buckled mode. The equilibrium solutions $W_1^\pm(x)$ of (1.1) are not globally stable even though $\varepsilon < 0$. Indeed when $\varepsilon < 0$ there exist solutions of (1.1) which tend asymptotically to each of the

possible equilibrium solutions (cf. [6]). What is true and will be shown in this section is that solutions which 'start' sufficiently close to $W_1^\pm(x)$ decay to $W_1^\pm(x)$ as $t \rightarrow \infty$.

In order to show that $W_1^+(x)$ is locally stable when $\varepsilon < 0$ it is convenient to adopt the Fourier series representation of the solution (cf. (1.4)). In this case the identity (2.3) becomes

$$(4.1) \quad \frac{d}{dt} \left\{ E(T_j) + \alpha \sum_{j=1}^{\infty} T_j \dot{T}_j \right\} + \alpha \left\{ E(T_j) + \alpha \sum_{j=1}^{\infty} T_j \dot{T}_j + \frac{1}{2} \left(\sum_{j=1}^{\infty} j^2 T_j^2 \right)^2 \right\} = 0$$

where

$$(4.2) \quad E(T_j) = \sum_{j=1}^{\infty} \dot{T}_j^2 + \sum_{j=1}^{\infty} j^4 T_j^2 + (\varepsilon - 1) \sum_{j=1}^{\infty} j^2 T_j^2 + \frac{1}{2} \left(\sum_{j=1}^{\infty} j^2 T_j^2 \right)^2.$$

In order to show that $w(x, t) \rightarrow W_1^+(x)$ it suffices to show that $T_1(t) \rightarrow \sqrt{-\varepsilon}$ and $T_j(t) \rightarrow 0$ for $j=2, 3, \dots$ as $t \rightarrow \infty$. For this purpose define new variables

$$(4.3a) \quad S_1 = T_1 - \sqrt{-\varepsilon},$$

$$(4.3b) \quad S_j = T_j, \quad j = 2, 3, \dots$$

The function S_1 satisfies the differential equation

$$(4.4) \quad \ddot{S}_1 + \alpha \dot{S}_1 - 2\varepsilon S_1 + S_1^2(S_1 + 3\sqrt{-\varepsilon}) + (S_1 + \sqrt{-\varepsilon}) \sum_{j=2}^{\infty} j^2 S_j^2 = 0.$$

The object is to determine conditions on the initial data which guarantee that $S_j(t) \rightarrow 0$ as $t \rightarrow \infty$. The identity (4.1) can be rewritten in terms of the functions S_j and in fact after some elementary manipulations (4.1) becomes

$$(4.5) \quad \frac{d}{dt} \left\{ E(S_j) + \alpha \sum_{j=1}^{\infty} S_j \dot{S}_j + \alpha \sqrt{-\varepsilon} \dot{S}_1 \right. \\ \left. + S_1^2(2\sqrt{-\varepsilon} S_1 - 3\varepsilon) + (2\sqrt{-\varepsilon} S_1 - \varepsilon) \sum_{j=2}^{\infty} j^2 S_j^2 \right\} \\ + \alpha \left\{ E(S_j) + \alpha \sum_{j=1}^{\infty} S_j \dot{S}_j + \frac{1}{2} \left(\sum_{j=1}^{\infty} j^2 S_j^2 \right)^2 + \alpha \sqrt{-\varepsilon} \dot{S}_1 - 2\varepsilon \sqrt{-\varepsilon} S_1 \right. \\ \left. + S_1^2(4\sqrt{-\varepsilon} S_1 - 6\varepsilon) + (4\sqrt{-\varepsilon} S_1 - 2\varepsilon) \sum_{j=2}^{\infty} j^2 S_j^2 \right\} = 0$$

or equivalently (cf. (4.4))

$$(4.6) \quad \frac{d}{dt} \left\{ E(S_j) + \alpha \sum_{j=1}^{\infty} S_j \dot{S}_j + S_1^2(2\sqrt{-\varepsilon} S_1 - 3\varepsilon) + (2\sqrt{-\varepsilon} S_1 - \varepsilon) \sum_{j=2}^{\infty} j^2 S_j^2 \right\} \\ + \alpha \left\{ E(S_j) + \alpha \sum_{j=1}^{\infty} S_j \dot{S}_j + \frac{1}{2} \left(\sum_{j=1}^{\infty} j^2 S_j^2 \right)^2 + S_1^2(3\sqrt{-\varepsilon} S_1 - 3\varepsilon) \right. \\ \left. + (3\sqrt{-\varepsilon} S_1 - \varepsilon) \sum_{j=2}^{\infty} j^2 S_j^2 \right\} = 0.$$

Noting that

$$(4.7) \quad \frac{1}{2} \sum_{j=1}^{\infty} \dot{S}_j^2 + \alpha \sum_{j=1}^{\infty} S_j \dot{S}_j = \frac{1}{2} \sum_{j=1}^{\infty} (\dot{S}_j + \alpha S_j)^2 - \frac{\alpha^2}{2} \sum_{j=1}^{\infty} S_j^2$$

the identity (4.6) can be rewritten

$$(4.8) \quad \frac{d}{dt} P + \alpha Q = -\frac{1}{2} \left(\sum_{j=1}^{\infty} j^2 S_j^2 \right) \leq 0$$

where

$$(4.9a) \quad P = \frac{1}{2} \sum_{j=1}^{\infty} \dot{S}_j^2 + \frac{1}{2} \sum_{j=1}^{\infty} (\dot{S}_j + \alpha S_j)^2 + \sum_{j=1}^{\infty} j^4 S_j^2 + (\varepsilon - 1) \sum_{j=1}^{\infty} j^2 S_j^2 \\ + \frac{1}{2} \left(\sum_{j=1}^{\infty} j^2 S_j^2 \right)^2 + S_1^2 (2\sqrt{-\varepsilon} S_1 - 3\varepsilon) + (2\sqrt{-\varepsilon} S_1 - \varepsilon) \sum_{j=2}^{\infty} j^2 S_j^2,$$

$$(4.9b) \quad Q = \sum_{j=1}^{\infty} \dot{S}_j^2 + \sum_{j=1}^{\infty} j^4 S_j^2 + (\varepsilon - 1) \sum_{j=1}^{\infty} j^2 S_j^2 + \frac{1}{2} \left(\sum_{j=1}^{\infty} j^2 S_j^2 \right)^2 \\ + S_1^2 (3\sqrt{-\varepsilon} S_1 - 3\varepsilon) + (3\sqrt{-\varepsilon} S_1 - \varepsilon) \sum_{j=2}^{\infty} j^2 S_j^2.$$

Both P and Q are nonnegative if $|S_1|$ is sufficiently small. In order to see this, simply note that

$$(4.10a) \quad P = \frac{1}{2} \sum_{j=1}^{\infty} \dot{S}_j^2 + \frac{1}{2} \sum_{j=1}^{\infty} (\dot{S}_j + \alpha S_j)^2 + \frac{1}{2} \left(\sum_{j=1}^{\infty} j^2 S_j^2 \right)^2 \\ + S_1^2 (2\sqrt{-\varepsilon} S_1 - 2\varepsilon) + \sum_{j=2}^{\infty} (2\sqrt{-\varepsilon} S_1 + j^2 - 1) j^2 S_j^2,$$

$$(4.10b) \quad Q = \sum_{j=1}^{\infty} \dot{S}_j^2 + \frac{1}{2} \left(\sum_{j=1}^{\infty} j^2 S_j^2 \right)^2 \\ + S_1^2 (3\sqrt{-\varepsilon} S_1 - 2\varepsilon) + \sum_{j=2}^{\infty} (3\sqrt{-\varepsilon} S_1 + j^2 - 1) j^2 S_j^2$$

and thus both P and Q are nonnegative if

$$(4.11) \quad |S_1| \leq \min(2\sqrt{-\varepsilon}/3, 1/\sqrt{-\varepsilon}) = \gamma.$$

The next step in the procedure is to estimate P in terms of Q while assuming $|S_1|$ satisfies the bound (4.11). For this purpose note that since

$$\alpha \sum_{j=1}^{\infty} S_j \dot{S}_j \leq \frac{1}{2} \sum_{j=1}^{\infty} \dot{S}_j^2 + \frac{\alpha^2}{2} \sum_{j=1}^{\infty} S_j^2,$$

P can be estimated by

$$(4.12) \quad P \leq \frac{3}{2} \sum_{j=1}^{\infty} S_j^2 + \frac{1}{2} \left(\sum_{j=1}^{\infty} j^2 S_j^2 \right)^2 + S_1^2 (2\sqrt{-\varepsilon} S_1 - 2\varepsilon + \alpha^2) + \sum_{j=2}^{\infty} (2\sqrt{-\varepsilon} S_1 + j^2 - 1 + \alpha^2/j^2) j^2 S_j^2.$$

If $|S_1| \leq \gamma - \delta \leq 2\sqrt{-\varepsilon}/3 - \delta$ ($\delta > 0$) then

$$(4.13) \quad (2\sqrt{-\varepsilon} S_1 - 2\varepsilon + \alpha^2) \leq C_1 (3\sqrt{-\varepsilon} S_1 - 2\varepsilon)$$

if

$$(4.14) \quad C_1 = (2\delta\sqrt{-\varepsilon} - 2\varepsilon/3 + \alpha^2)/(3\delta\sqrt{-\varepsilon})$$

and if $|S_1| \leq \gamma - \delta \leq 1/\sqrt{-\varepsilon} - \delta$ ($\delta > 0$) then

$$(4.15) \quad (2\sqrt{-\varepsilon} S_1 + j^2 - 1 + \alpha^2/j^2) \leq C_2 (3\sqrt{-\varepsilon} S_1 + j^2 - 1),$$

$j = 2, 3, \dots$

where

$$(4.16) \quad C_2 = \max_{j=2,3,\dots} \frac{2\delta\sqrt{-\varepsilon} + j^2 - 3 + \alpha^2/j^2}{3\delta\sqrt{-\varepsilon} + j^2 - 4}.$$

Combining this result with (4.12) yields

$$(4.17) \quad P \leq \beta Q$$

where

$$(4.18) \quad \beta = \max(3/2, C_1, C_2)$$

if $|S_1| \leq \gamma - \delta$. Thus (4.8) implies that

$$(4.19) \quad dP/dt + \alpha P/\beta \leq 0$$

or

$$(4.20) \quad P(t) \leq P(0)\exp(-\alpha t/\beta)$$

as long as $|S_1| \leq \gamma - \delta$. Assume that

$$(4.21a) \quad P(0) \leq (\gamma - \delta)^4/2$$

and

$$(4.21b) \quad |S_1(0)| < \gamma - \delta.$$

In this case $|S_1(t)| < \gamma - \delta$ in some interval. Assume there exists a value $t = t^*$ such that $|S_1(t^*)| = \gamma - \delta$. The inequality (4.20) implies that at $t = t^*$,

$$(4.22) \quad P(t^*) \leq P(0)\exp(-\alpha t^*/\beta) < P(0) \leq (\gamma - \delta)^4/2.$$

However, (4.10a) implies that

$$(4.23) \quad \frac{1}{2}S_1(t^*)^4 \leq P(t^*)$$

so that

$$(4.24) \quad |S_1(t^*)| < \gamma - \delta.$$

This contradiction shows that $|S_1(t)| < \gamma - \delta$ for all $t \geq 0$, or equivalently (4.20) holds for all $t \geq 0$. We conclude that $S_j(t) \rightarrow 0$ as $t \rightarrow \infty$. The conditions (4.21) can be rewritten as conditions on $w(x, 0)$ and $w_t(x, 0)$. However, the expressions are rather complicated and will not be included here. The preceding remarks may be summarized as:

THEOREM (4.1). *If $\varepsilon < 0$ and the initial data satisfies the conditions (4.21), then $w(x, t) \rightarrow \sqrt{-\varepsilon} \sin x$ as $t \rightarrow \infty$.*

In a manner similar to the above, it can be shown that if the initial conditions are sufficiently close to $-\sqrt{-\varepsilon} \sin x$ then $w(x, t) \rightarrow -\sqrt{-\varepsilon} \sin x$ as $t \rightarrow \infty$.

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