

A DEFORMATION THEOREM FOR THE KOBAYASHI METRIC¹

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ABSTRACT. Let M_0 be a compact hyperbolic complex manifold. It is shown that the infinitesimal Kobayashi metric is upper semicontinuous in a C^∞ deformation parameter $t \in U \subseteq \mathbf{R}^k$. This is accomplished by proving deformation theorems for holomorphic maps.

Introduction and statement of results. In this paper we examine the behavior of compact hyperbolic complex manifolds under small perturbations of the complex structure. In particular we prove a semicontinuity theorem for Royden's infinitesimal version of the Kobayashi metric. M. Wright [9] had obtained these results a year prior to our work. His paper was not submitted for publication until our work was completed, and our work is independent of his. Brody [1] has recently shown that the property of being compact hyperbolic is preserved under small perturbations of the complex structure—thereby answering, in the affirmative, a question of Griffiths [4].

We will use the following notation throughout: $D_r = \{z \in \mathbf{C} \mid |z| < r\}$, if we write D we mean D_1 . $D^k = \{z \in \mathbf{C}^k \mid |z^i| < 1\}$. The holomorphic tangent bundle of a complex manifold X will be denoted by $\mathfrak{T}X$ and the holomorphic sphere bundle to a complex manifold X (once a hermitian metric is fixed) will be denoted by $\mathfrak{S}X$. If the complex structure of a manifold M , depends on a parameter t , varying over some open set $U \subseteq \mathbf{R}^k$, then M_t will denote the C^∞ manifold in the t -complex structure.

If M is a complex manifold then $d_M(p, q)$ is the Kobayashi pseudo-distance between p and q . If $(x, \xi) \in \mathfrak{T}M$, $F_M(x, \xi)$ will denote Royden's infinitesimal version of the Kobayashi metric.

From the definition of the Kobayashi metric it is clear that what is needed is a result on deformation of holomorphic maps of the unit disc in \mathbf{C} into the manifold in question. This is accomplished using Kohn's solutions of the $\bar{\partial}$ -Neumann problem [3] and Royden's extension lemma for regular holomorphic maps [7].

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THEOREM 1. Suppose M_0 is a complex manifold and $f_0: D \rightarrow M_0$ is a holomorphic map. Suppose $\{M_t\}_{t \in U}$ is a deformation of the complex structure on M_0 . Then given $r < 1 \exists U' \subset U$ and maps $f_t: D_r \rightarrow M_t$ so that

- (1) f_t is holomorphic,
- (2) $f_t|_{t=0} = f_0|_{D_r}$,
- (3) f_t depends smoothly on t ,
- (4) $f_t(0) = f_0(0)$,
- (5) $df_t/dz|_{z=0} = P_t(df_0/dz|_{z=0})$. $P_t(v)$ is the projection of v on $\mathfrak{T}M_t$.

Here we have made no assumptions on M_0 other than it being a complex manifold. If we assume M_0 is compact hyperbolic then we can get a stronger theorem, to wit:

THEOREM 2. If, in Theorem 1, we require that M_0 be compact hyperbolic, then we get that $\exists U' \subset U$ such that every $f: D \rightarrow M_0$ can be deformed to $f_t: D_r \rightarrow M_t$. Here U' is independent of f and depends only on r and the deformation.

We use Theorem 2 to prove our main result on Royden's metric:

THEOREM 3. Suppose M_0 is a compact hyperbolic complex manifold. Let $\{M_t\}_{t \in U}$ be a deformation of the complex structure on M_0 . Let $\epsilon > 0$ be arbitrary. Then $\exists U'_\epsilon \subset U$ so that if $t \in U'_\epsilon$ we have

$$F_{M_t}(x, P_t(\xi)) \leq F_{M_0}(x, \xi) + \epsilon, \text{ for } (x, \xi) \in \mathfrak{S}M_0$$

in some fixed Hermitian metric.

1. **Preliminaries.** We recall the definition of Royden's infinitesimal version of the Kobayashi metric. Let $(x, \xi) \in \mathfrak{T}M_0$; then

$$F_{M_0}(x, \xi) = \inf_R \left\{ \frac{1}{R}, \exists f: D_R \rightarrow M_0, f(0) = x, f'(0) = \xi, f \text{ holomorphic} \right\}.$$

We remark (i) Royden [6] has proven that F_{M_0} is the infinitesimal version of the Kobayashi metric in the sense that

$$d_{M_0}(p, q) = \inf_{\gamma \in \Gamma(p, q)} \int_{\gamma} F_M(x(t), \dot{x}(t)_{(1,0)}) dt$$

and $\Gamma(p, q)$ is the set of all piecewise smooth curves $\gamma: [0, 1] \rightarrow M, \gamma(0)' = p, \gamma(1) = q$ [6].

(ii) F_{M_0} is homogeneous of degree 1 in the ξ -variable so that F_M can be thought of as defined on $\mathfrak{S}M_0$.

We will assume that M_0 is compact hyperbolic and list two relevant properties that hyperbolicity implies. In both cases the proofs are straightforward.

(a) Let $H(D, M_0)$ denote the space of holomorphic mappings of D into M_0 equipped with the compact-open topology. Then $H(D, M_0)$ is compact.

(b) Let $(x, \xi) \in \mathfrak{T}M_0$; then

$$\exists f_{(x,\xi)}: D_{F_{M_0}(x,\xi)}^{-1} \rightarrow M_0 \quad \text{with } f(0) = x, f'(0) = \xi.$$

(b) follows easily from (a), and (a) follows from the distance decreasing property of the Kobayashi metric and the Arzelà-Ascoli Theorem.

We will be interested in a deformation of the complex structure on M_0 . We will deal locally in the deformation space, so we will assume, using the Newlander-Nirenberg Theorem, that the deformation is given by a holomorphic vector field valued $(0, 1)$ form on the original manifold satisfying an integrability condition. More precisely suppose we are given a family of operators $\bar{\partial}_t$ on M considered as a C^∞ manifold $\bar{\partial}_t: C^\infty(M) \rightarrow \Lambda^1(M)$ with the following properties:

1. In local holomorphic coordinates $z = (z^1, \dots, z^n)$ on M_0

$$\bar{\partial}_t = \sum_i \left(\frac{\partial}{\partial \bar{z}^i} + \sum_k \varphi_i^k(t) \frac{\partial}{\partial z^k} \right) d\bar{z}^i;$$

2. $\varphi_i^k(0) \equiv 0$;

3. φ_i^k is C^∞ in both the t and z parameter;

4. $\bar{\partial}_t$ extends naturally to an operator $\bar{\partial}_t: \Lambda^k(M) \rightarrow \Lambda^{k+1}(M)$.

The integrability condition is then that $\{\bar{\partial}_t\}$ should define a complex i.e. $\bar{\partial}_t^2 = 0$.

The Cauchy-Riemann operator for the deformed structure M_t is then given by $\bar{\partial}_t$. It is clear that $\bar{\partial}_t$ acts on sections of vector bundles E_t which are holomorphic over M_t , since $\bar{\partial}_t$ annihilates the transition matrices.

We will use the following proposition which tells us that holomorphic functions can be chosen to depend smoothly on the deformation parameter, if the original manifold is a strongly pseudo-convex domain with C^∞ boundary in a complex manifold. $\mathcal{O}(\Omega)$ will denote the space of holomorphic functions on a complex manifold Ω .

PROPOSITION 1.1. *Let Ω_0 be a strongly pseudo-convex domain with smooth boundary. Let $\zeta_0 \in \mathcal{O}(\Omega_0) \cap C^\infty(\bar{\Omega}_0)$. Then if Ω_t is a deformation of the complex structure on Ω_0 smooth on $\partial\Omega_0$, we can find ζ_t for t sufficiently small satisfying*

1. $\zeta_t \in (\Omega_t) \cap C^\infty(\bar{\Omega}_t)$,

2. $\zeta_0 = \zeta_t|_{t=0}$,

3. $\|\zeta_t - \zeta_0\|_s \leq C(s, \zeta_0)\|\varphi(t)\|_s$, where $\|\cdot\|_s$ is the Sobolev norm in some Hermitian metric.

PROOF. We are looking for a solution of $\bar{\partial}_t \zeta_t = 0$. Let $\mu_t = \bar{\partial}_t \zeta_0$. Now since Ω_0 is strongly pseudo-convex so is Ω_t for t small. We now use Kohn's solution of the $\bar{\partial}$ -Neumann problem to solve $\bar{\partial}_t u_t = \mu_t$ to get a solution u_t such that $\|u\|_s \leq C\|\mu(t)\|_s$.

Now consider

$$\zeta_t = \zeta_0 - u_t, \quad \bar{\partial}_t \zeta_t = \bar{\partial}_t(\zeta_0 - u_t) = 0,$$

and

$$\|\xi_t - \xi_0\|_s = \|u_t\|_s \leq C_1 \|\mu(t)\|_s \leq C_2 \|\xi_0\|_{s+1} \|\varphi(t)\|_s.$$

REMARKS. 1. In Proposition 1.1 ξ_0 need not be a function but can be a holomorphic vector field. What one does in this case is first project ξ_0 to the holomorphic tangent bundle of Ω_t , and then proceed as in the proof above.

2. If Ω is biholomorphically equivalent to a domain in \mathbb{C}^n , we can take the vector field ξ_t at a given point, 0, to be $p_t(\xi_0)(0)$ the projection of ξ_0 on the holomorphic tangent bundle to Ω_t by simply subtracting from u_t the constant solution $u_t(0)$.

2. **Deformations of hyperbolic structure.** In this section we will prove the theorems stated in the introduction. Essential to our treatment will be the following theorem of Royden.

PROPOSITION 2.1 [7]. *Let f be a holomorphic embedding of D into a complex manifold M . Then given $r < 1$ there is a holomorphic embedding $F: D_r \times D^{n-1} \rightarrow M$ such that*

$$F|_{D_{D_r \times \{0\}}} = f|_{D_r}.$$

REMARK. Royden's theorem is actually for embeddings of the unit polydisk D^k into M , and has been extended by C. Seabury [8] to embeddings with trivial normal bundle of a Stein manifold into a complex manifold. We, however, only need the case of D .

PROOF OF THEOREM 1. We consider the case of an embedding. Let F_0 be the extension of f_0 to $D_{r'} \times D^{n-1}$, $r' > r$, given by Royden's theorem. So we have $F_0: D_{r'} \times D^{n-1} \rightarrow M_0$. Since F_0 is an embedding we can choose a strongly pseudo-convex domain with C^∞ boundary, Ω_0 , so that

$$F_0(D_{r'} \times D^{n-1}) \supset \Omega_0 \supset F_0(D_r \times D^{n-1}).$$

On Ω_0 we consider the holomorphic vector field

$$L_0 = F_{0*}(\partial/\partial z^1).$$

Clearly L_0 is an extension of $f_{0*}(d/dz)$ from $f_0(D_r)$ to Ω_0 . By Proposition 1.1 and the remarks following it \exists a vector field L_t , holomorphic with respect to the t -structure for small t , so that

$$L_t(f_0(0)) = P_t(df_0/dz|_{z=0}), \quad L_t|_{t=0} = L_0, \quad \|L_t - L_0\|_s \leq C\|\varphi(t)\|_s.$$

We now consider the system of ordinary differential equations on D

$$f_{t*}(d/dz) = L_t(f_t(z)), \quad f_t(0) = f_0(0).$$

Since L_t is close to L_0 by standard theory of ordinary differential equations [2] a holomorphic solution of this system exists if t is sufficiently small.

If f is not an embedding consider the graph map

$$g_{f_0} : D \rightarrow D \times M_0, \quad z \rightarrow (z, f_0(z)).$$

Then g_{f_0} is an embedding and we apply what we have just done to g_{f_0} and the deformation, $D \times M_t$ of $D \times M_0$ which is 0 in the first factor and the given deformation in the second, to get a map $(g_f)_t : D_r \rightarrow D \times M_t$.

To complete the proof we just project $(g_f)_t$ onto M_t .

We now turn to Theorem 2. In order to prove this theorem we need to examine Royden's extension of a map f and see how it can be chosen to depend continuously on $f \in H(D, M)$. What we do is state, without proof, Royden's main lemma and then use this to discuss the continuity of the extension.

LEMMA 2.2 [7]. *Suppose $f: D \rightarrow M$ is an embedding and $0 < r < 1$. Then $\exists S_f^r \subset M$ a Stein manifold open in M , so that $f(\bar{D}_r) \subset S_f^r$.*

LEMMA 2.3. *Let $f: D \rightarrow S$ be an embedding into a Stein manifold S . Then $\exists F: D \times D^{n-1} \rightarrow S$ an embedding so that $F|_{D \times \{0\}} = f$ and F can be chosen to depend continuously on f .*

PROOF. Embed S as a closed submanifold of \mathbb{C}^N for some N . $\varphi: S \rightarrow \mathbb{C}^N$. Consider $D \xrightarrow{f} S \xrightarrow{\varphi} \mathbb{C}^N$. We will explicitly construct an extension for $\varphi \circ f$.

Now $\varphi \circ f = (f_1(z), \dots, f_N(z))$ and let $D \times D^{n-1} = (z, w^1, \dots, w^{n-1})$. The map

$$\tilde{F}(z, w^1, \dots, w^{n-1}) = (f_1, \dots, f_N) + \sum_{i=1}^{n-1} (0, \dots, -f'_N, \dots, f'_i)w^i$$

is the required map. Here $-f'_N$ is inserted in the i th component. \tilde{F} depends continuously on f and is an embedding of $D \times \{|w^i| < \epsilon_i\}$. Now for $|w^i|$ sufficiently small, $F(D \times D^{n-1})$ can be made to lie in an arbitrarily prescribed neighborhood of $\varphi(S)$ in \mathbb{C}^N .

By the holomorphic retraction theorem [5] we can retract this neighborhood onto S by a map ρ . We take $F = \rho \circ \tilde{F}$ and since ρ has maximal rank we can solve $w^i = w^i(z, w^j)$, $j \geq n$, by the implicit function theorem. Now we just make a change of scale in the w -variable to complete the proof.

LEMMA 2.4. *Let $0 < r < 1$ and let M_0 be compact hyperbolic. Then $\exists k < \infty$ and $S_i^r, i = 1, \dots, k, S_i^r \subset D \times M_0$, Stein submanifolds open in $D \times M_0$ such that for every $f \in H(D, M_0)$ its graph restricted to D_r lies in some S_i^r .*

PROOF. The space $G(H(D, M_0)) \subset H(D, D \times M_0)$ of graphs of elements in $H(D, M_0)$ is naturally homeomorphic to $H(D, M)$ and, hence, is compact. By Lemma 2.2 $g|_{D_r} \subset S_g^r$. We take an open set in $G(H(D, M_0))$, U_g , consisting of all mappings whose restrictions to \bar{D}_r have graphs lying in S_g^r . Then $\{U_g\}_{g \in G(H(D, M_0))}$ form an open cover. We get the result by taking a finite subcover.

PROOF OF THEOREM 2. Without loss of generality we may assume the deformation space is $0 \leq t \leq 1$. Fix $1 > r' > r$ and apply Lemma 2.4 to get $S_i^{r'}, 1, \dots, k$.

We define

$$t'_i(f_0) = \sup\{0 < t \leq 1: f \text{ can be deformed to } f_i: D_r \rightarrow M$$

if we take the extension F_0 , of g_{f_0} , into $S_i^{r'}$ \}.

It is clear from Lemma 2.3 and the method of proof of Theorem 1 that if we consider our mappings being extended into a fixed $S_i^{r'}$ then $t'_i(f_0)$ is a continuous function on those mappings whose graphs lie in $S_i^{r'}$. Call this class of mappings $\mathcal{S}_i^{r'}$.

We define the function $t': H(D, M_0) \rightarrow (0, 1]$ by

$$t'(f_0) = \min_i t'_i(f_0), \quad f \in \mathcal{S}_i^{r'}.$$

t' is not continuous on $H(D, M_0)$ for suppose we have a sequence $f_j \in \bigcap_{i=1}^k \mathcal{S}_i^{r'}$ and in $H(D, M_0)$, $f_j \rightarrow f \in \bigcap_{i=1}^{k+1} \mathcal{S}_i^{r'}$. Then possibly $t'(f) < \lim_j t'(f_j)$.

However this semicontinuity is sufficient to conclude that $t'(f_0) \geq C > 0$, for suppose $t'(f_0) \rightarrow 0$ for some sequence $f_0 \in H(D, M_0)$. By compactness we may assume $f_0 \rightarrow f$. But then $t'(f) = 0$, a contradiction to Theorem 1.

PROOF OF THEOREM 3. Since M_0 is compact hyperbolic, F_{M_0} is continuous on $\mathcal{S}M_0$ [6]. The sphere bundle being compact we get $0 < C_1 < F_{M_0}(x, \xi) < C_2 < \infty$. Let $(x, \xi) \in \mathcal{S}M_0$.

By Remark (b) in §1 let

$$f_0: D_{F_{M_0}(x, \xi)^{-1}} \rightarrow M_0$$

be so that $f_0(0) = x, f'_0(0) = \xi$.

We now deform f_0 . We can, by Theorem 2, take t sufficiently small so that all $f_0: D \rightarrow M_0$ can be deformed to $f_i: D_{1-\epsilon k} \rightarrow M_t$ where k is to be determined. Then by change of scale all $f_0: D_R \rightarrow M_0$ can be deformed to $f_t: D_{R-\epsilon k R} \rightarrow M_t$.

To prove the result we need $1/(R - \epsilon k R) < 1/R + \epsilon$ or $k < R/(\epsilon R + 1)$. So take $k = (1/C_2)(C_1/(C_1 + \epsilon))$ and we are done.

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