

## UNIQUE SOLUTIONS FOR A CLASS OF DISCONTINUOUS DIFFERENTIAL EQUATIONS

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ABSTRACT. This paper is concerned with the Cauchy Problem

$$\dot{x}(t) = f(t, x(t)), \quad x(t_0) = x_0 \in \mathbb{R}^n,$$

where the vector field  $f$  may be discontinuous with respect to both variables  $t, x$ . If the total variation of  $f$  along certain directions is locally finite, we prove the existence of a unique solution, depending continuously on the initial data.

**1. Introduction.** Let  $f$  be a vector field on  $\mathbb{R}^n$ . By definition, a Carathéodory solution of the Cauchy Problem

$$(1.1) \quad \dot{x}(t) = f(t, x(t)), \quad x(t_0) = x_0 \in \mathbb{R}^n,$$

is an absolutely continuous function  $t \rightarrow x(t)$  which takes the value  $x_0$  at  $t = t_0$  and satisfies the differential equation in (1.1) at almost every  $t$ . If  $f$  is not continuous, Peano's theorem does not apply and (1.1) may not have any solution. Some authors have thus introduced new definitions of generalized or relaxed solutions for (1.1), for which a satisfactory existence theorem could then be proven [5, 6, 9]. An alternative approach to discontinuous O.D.E.'s, pursued in [4, 7, 8], relies on the study of certain conditions on  $f$  which are weaker than continuity, yet sufficient to guarantee the existence of Carathéodory solutions. This led to the investigation of directional continuity. For a fixed  $M > 0$ , consider the cone

$$(1.2) \quad \Gamma^M = \{(t, x) \in \mathbb{R}^{n+1}; \|x\| \leq Mt\}.$$

We say that a map  $f: \mathbb{R}^{n+1} \rightarrow \mathbb{R}^n$  is  $\Gamma^M$ -continuous if, for every  $(t_0, x_0) \in \mathbb{R}^{n+1}$  and  $\varepsilon > 0$ , there exists  $\delta > 0$  such that

$$t_0 \leq t < t_0 + \delta, \quad \|x - x_0\| \leq M(t - t_0) \Rightarrow \|f(t, x) - f(t_0, x_0)\| < \varepsilon.$$

Assuming that  $\|f(t, x)\| \leq L < M$  for all  $t, x$ , solutions of O.D.E.'s with  $\Gamma^M$ -continuous right-hand sides were obtained in [7] as limits of polygonal approximations, in [2] through an application of Schauder's fixed point theorem, and in [3] by means of an upper semicontinuous, convex-valued regularization. These results acquire additional interest in connection with the theory of multivalued differential equations. Indeed, the existence of directionally continuous selections for lower semicontinuous multifunctions now provides a very effective tool for the study of differential inclusions [2, 3].

The present paper is concerned with the problem of uniqueness and continuous dependence. In the classical theory, the uniqueness of solutions of (1.1) is proved assuming that  $f$  is locally Lipschitz continuous. Here we consider a much weaker

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condition, which does not imply the continuity of  $f$ . Let  $<$  be the partial ordering on  $\mathbb{R}^{n+1}$  induced by the cone  $\Gamma^M$ :

$$(1.3) \quad (t, x) < (t', x') \quad \text{iff} \quad \|x' - x\| \leq M(t' - t).$$

Using this ordering, one can define a class of vector fields with bounded “directional variation”.

**DEFINITION 1.** A vector field  $f: \mathbb{R}^{n+1} \rightarrow \mathbb{R}^n$  has bounded  $\Gamma^M$ -variation if there exists a constant  $C$  such that

$$\sum_{i=1}^N \|f(t_i, x_i) - f(t_{i-1}, x_{i-1})\| \leq C$$

for every finite sequence  $(t_i, x_i), i = 0, 1, \dots, N$ , with  $(t_0, x_0) < (t_1, x_1) < \dots < (t_N, x_N)$ .

**DEFINITION 2.** A vector field  $f: \mathbb{R}^{n+1} \rightarrow \mathbb{R}^n$  has locally bounded  $\Gamma^M$ -variation if, for every  $(t_0, x_0) \in \mathbb{R}^{n+1}$ , there exist  $\delta > 0$  and a constant  $C$  such that

$$(1.4) \quad \sum_{i=1}^N \|f(t_i, x_i) - f(t_{i-1}, x_{i-1})\| \leq C$$

for every finite sequence  $(t_i, x_i), i = 1, \dots, N$ , satisfying

$$(1.5) \quad (t_0, x_0) < (t_1, x_1) < \dots < (t_N, x_N), \quad t_N < t_0 + \delta.$$

Our main result shows that if  $f$  has locally bounded directional variation, then the solution of (1.1) is unique:

**THEOREM 1.** *Let  $f: \mathbb{R}^{n+1} \rightarrow \mathbb{R}^n$  be a vector field with locally bounded  $\Gamma^M$ -variation. If  $\|f(t, x)\| \leq L < M$  for all  $t, x$ , then the Cauchy Problem (1.1) has a unique forward solution  $x(\cdot)$ , which is defined on  $[t_0, \infty)$ . Moreover, the restriction of  $x(\cdot)$  to any bounded interval  $[t_0, T]$  depends continuously on the initial value  $x_0$ .*

In §2 we establish an intermediate result. The proof of Theorem 1 is then completed in §3; it relies on the construction of a directionally continuous version of  $f$  and on a proper use of the classical Contraction Mapping Principle.

**2. An auxiliary theorem.** The following uniqueness result for solutions of the Cauchy Problem

$$(2.1) \quad \dot{x}(t) = f(t, x(t)), \quad x(0) = 0 \in \mathbb{R}^n,$$

will be instrumental for the proof of Theorem 1.

**THEOREM 2.** *Assume that there exist constants  $L, M, \delta > 0$  and a function  $\phi: \Gamma^M \rightarrow \mathbb{R}$  such that*

- (i)  $\|f(t, x)\| \leq L < M$ ,
- (ii)  $\lim_{t \rightarrow 0^+, \|x\| \leq Mt} \phi(t, x) = \phi(0, 0) = 0$ ,
- (iii)  $\|f(t, x) - f(s, y)\| \leq \phi(t, x) - \phi(s, y)$  whenever  $(t, x), (s, y) \in \Gamma^M, 0 \leq s \leq t < \delta, \|x - y\| \leq M(t - s)$ .

*Then (2.1) has a unique forward solution, defined on some positive interval  $[0, T]$ .*

**PROOF.** Using (ii), choose  $T \in (0, \delta/2)$  such that

$$(2.2) \quad \phi(t, x) \leq (M - L)/4$$

whenever  $0 \leq t \leq 2T$ ,  $\|x\| \leq Mt$ . Consider the set  $\mathbf{K}$  of all continuous mappings  $y: [0, T] \rightarrow \mathbb{R}^n$  with  $y(0) = 0$  and with Lipschitz constant  $L$ . Define the Picard operator  $P: K \rightarrow K$  by setting

$$(2.3) \quad P(y)(t) = \int_0^t f(s, y(s)) ds.$$

For any  $y \in \mathbf{K}$ , (iii) and (2.2) imply that the map  $s \rightarrow f(s, y(s))$  has bounded variation, hence the integral in (2.3) is well defined. Clearly  $P(y) \in K$  because of (i). We claim that  $P$  is a strict contraction. For any  $y_1, y_2 \in K$ , set

$$(2.4) \quad \sigma = \|y_1 - y_2\|_{\mathcal{C}^0} = \max_{t \in [0, T]} \|y_1(t) - y_2(t)\| \leq 2LT.$$

Call  $\xi = \sigma/2M$  and define the auxiliary map

$$(2.5) \quad z(t) = [y_1(t - \xi) + y_2(t - \xi)]/2, \quad t \in [\xi, T + \xi].$$

Observe that  $\xi \leq T$  and that  $z$  has Lipschitz constant  $L$ . Moreover

$$(2.6) \quad \|z(t + \xi) - y_i(t)\| \leq \sigma/2 = M[(t + \xi) - t],$$

therefore we can apply (iii) and deduce

$$(2.7) \quad \|f(t + \xi, z(t + \xi)) - f(t, y_i(t))\| \leq \phi(t + \xi, z(t + \xi)) - \phi(t, y_i(t))$$

for all  $t \in [0, T]$ ,  $i = 1, 2$ . Observe that (iii) trivially implies

$$(2.8) \quad \|x - y\| \leq M(t - s) \Rightarrow \phi(s, y) \leq \phi(t, x).$$

In particular, the maps  $t \rightarrow \phi(t, y_i(t))$  and  $t \rightarrow \phi(t + \xi, z(t + \xi))$  are nondecreasing. For  $0 \leq r \leq (M - L)/4$ ,  $i = 1, 2$ , define

$$\begin{aligned} \tau_i(r) &= \inf\{t \in [0, T]; \phi(t, y_i(t)) \geq r\} \wedge T, \\ \tau_z(r) &= \inf\{t \in [0, T]; \phi(t + \xi, z(t + \xi)) \geq r\} \wedge T. \end{aligned}$$

We claim that

$$(2.9) \quad 0 \leq \tau_i(r) - \tau_z(r) \leq \sigma/(M - L).$$

Indeed, the first inequality follows from (2.6), (2.8) which imply

$$\phi(t, y_i(t)) \leq \phi(t + \xi, z(t + \xi)) \quad \forall t \in [0, T].$$

To prove the second inequality, set  $\tau = \tau_z(r)$ . If  $\tau = T$ , the conclusion is obvious. Otherwise, for any  $\tau' \in (\tau, T]$ , the choice of  $\xi$  implies

$$\begin{aligned} & \left\| z(\tau' + \xi) - y_i \left( \tau' + \frac{\sigma}{M - L} \right) \right\| \\ & \leq \|z(\tau' + \xi) - y_i(\tau')\| + \left\| y_i(\tau') - y_i \left( \tau' + \frac{\sigma}{M - L} \right) \right\| \\ & \leq \frac{\sigma}{2} + \frac{\sigma}{M - L} \cdot L = M \left( \frac{\sigma}{M - L} - \xi \right). \end{aligned}$$

Therefore (2.8) yields

$$r \leq \phi(\tau' + \xi, z(\tau' + \xi)) \leq \phi \left( \tau' + \frac{\sigma}{M - L}, y_i \left( \tau' + \frac{\sigma}{M - L} \right) \right),$$

hence  $\tau_i(r) \leq \tau' + \sigma/(M - L)$  for all  $\tau' > \tau$ , completing the proof of (2.9). Relying on (2.2) and (2.9) we now obtain our basic estimate, through a change in the order of integration:

$$\begin{aligned} & \int_0^T \|f(t + \xi, z(t + \xi)) - f(t, y_i(t))\| dt \\ & \leq \int_0^T [\phi(t + \xi, z(t + \xi)) - \phi(t, y_i(t))] dt = \int_0^T \int_{\phi(t, y_i(t))}^{\phi(t + \xi, z(t + \xi))} dr dt \\ & = \int_0^{(M-L)/4} [\tau_i(r) - \tau_z(r)] dr \leq \frac{M - L}{4} \cdot \frac{\sigma}{M - L} = \frac{\sigma}{4}. \end{aligned}$$

From (2.10) it follows that

$$\int_0^T \|f(t, y_1(t)) - f(t, y_2(t))\| dt \leq \frac{\sigma}{2} = \frac{\|y_1 - y_2\|}{2}.$$

Therefore the Picard operator  $P$  is a strict contraction on  $K$  and has a unique fixed point  $x(\cdot)$ , which yields the unique Carathéodory solution of (2.1) on  $[0, T]$ .

**3. Proof of Theorem 1.** For simplicity we assume  $t_0 = 0, x_0 = 0 \in \mathbb{R}^n$ , which is not restrictive. Define the auxiliary vector field  $\tilde{f}: \mathbb{R}^{n+1} \rightarrow \mathbb{R}^n$  by setting

$$(3.1) \quad \tilde{f}(t, x) = \lim_{s \rightarrow t^+} f(s, x).$$

The limit in (3.1) always exists because, for  $\varepsilon > 0$  small enough, the map  $s \rightarrow f(s, x)$  has bounded variation on  $[t, t + \varepsilon]$ . Set  $\tilde{M} = (M + L)/2$ . For all  $(t, x)$  inside the cone

$$\Gamma^{\tilde{M}} = \{(t, x); \|x\| \leq \tilde{M}t\}$$

define

$$(3.2) \quad \phi(t, x) = \sup \left\{ \sum_{i=1}^N \|\tilde{f}(t_i, x_i) - \tilde{f}(t_{i-1}, x_{i-1})\| \right\},$$

the supremum being taken over all finite sequences  $\{(t_i, x_i); i = 0, \dots, N\}$  with  $N \geq 1, (t_0, x_0) = (0, 0), (t_N, x_N) = (t, x)$  and  $\|x_i - x_{i-1}\| \leq \tilde{M}(t_i - t_{i-1})$  for all  $i$ . Some properties of  $\tilde{f}$  and  $\phi$  will be examined in the next lemmas.

**LEMMA 1.** *The vector field  $\tilde{f}$  is  $\Gamma^{\tilde{M}}$ -continuous.*

**PROOF.** Assume, on the contrary, that there exists a sequence of points  $(t_n, x_n)$  converging to  $(t, x)$ , with  $\|x_n - x\| \leq \tilde{M}(t_n - t)$  but

$$(3.3) \quad \|\tilde{f}(t_n, x_n) - \tilde{f}(t, x)\| > \eta > 0 \quad \forall n \geq 1.$$

By (3.1), we can choose  $t'_n \in (t_n, t_n + 1/n]$  suitably close to  $t_n$  and still have

$$(3.4) \quad \|f(t'_n, x_n) - \tilde{f}(t, x)\| > \eta \quad \forall n \geq 1.$$

Let  $\{s_m\}$  be a sequence strictly decreasing to  $t$ , with the property

$$(3.5) \quad \|f(s_m, x) - \tilde{f}(t, x)\| < \eta/2 \quad \forall m \geq 1.$$

Let  $\delta > 0$  be given. By induction, we now construct a sequence  $(\tau_j, y_j)$  such that, recalling (1.3),

$$(3.6) \quad 0 < \tau_j < \delta, \quad (\tau_{j+1}, y_{j+1}) < (\tau_j, y_j) \quad \forall j \geq 1,$$

$$(3.7) \quad \begin{cases} \text{if } j \text{ is even,} & (\tau_j, y_j) = (t'_{n_j}, x_{n_j}) \text{ for some } n_j, \\ \text{if } j \text{ is odd,} & (\tau_j, y_j) = (s_{m_j}, x) \text{ for some } m_j. \end{cases}$$

This can be done as follows. First choose  $m_1$  such that  $s_{m_1} < \delta$  and set  $(\tau_1, y_1) = (s_{m_1}, x)$ . If  $(\tau_j, y_j)$  has been defined for all  $j < 2k$ , select  $n_{2k}$  so large that  $\widetilde{M}t'_{n_{2k}} \leq M(\tau_{2k-1} - t'_{n_{2k}})$  and set  $(\tau_{2k}, y_{2k}) = (t'_{n_{2k}}, x_{n_{2k}})$ . Then select  $m_{2k+1}$  so large that  $\|y_{2k}\| = \|x_{n_{2k}}\| \leq M(\tau_{2k} - s_{m_{2k+1}})$  and set  $(\tau_{2k+1}, y_{2k+1}) = (s_{m_{2k+1}}, x)$ . All this is possible because the sequences  $\{t'_n\}, \{s_m\}$  converge to  $t$  and  $\|x_n - x\| < M(t'_n - t)$  for every  $n$ . The sequence  $\{(\tau_j, y_j); j \geq 1\}$  then satisfies (3.6), (3.7). From (3.4) and (3.5) it follows that

$$(3.8) \quad \sum_{j=1}^{\infty} \|f(\tau_{j+1}, y_{j+1}) - f(\tau_j, y_j)\| = \infty,$$

hence the vector field  $f$  cannot have locally bounded  $\Gamma^M$ -variation near the point  $(t, x)$ . This contradiction proves the lemma.

**LEMMA 2.** *The sets of Carathéodory solutions for the differential equations  $\dot{x}(t) = f(t, x(t))$  and  $\dot{x}(t) = \tilde{f}(t, x(t))$  coincide.*

**PROOF.** Let  $u: [a, b] \rightarrow \mathbb{R}^n$  be any continuous map with Lipschitz constant  $L$ . Define  $J$  as the set of times  $t \in [a, b]$  for which there exists some sequence  $\{t_k\}$ , strictly decreasing to  $t$ , with  $f(t_k, u(t_k))$  converging to  $f(t, u(t))$ . The measurability of the map  $t \rightarrow f(t, u(t))$  implies that  $\text{meas}(J) = b - a$  (see Lemma 2.3 in [3] for details). Since  $L < \widetilde{M}$ , the  $\Gamma^{\widetilde{M}}$ -continuity of  $\tilde{f}$  implies  $\tilde{f}(t, u(t)) = f(t, u(t))$  for all  $t \in J$ , hence almost everywhere on  $[a, b]$ . Lemma 2 is now clear, because every integral curve for the vector fields  $f$  or  $\tilde{f}$  is Lipschitz continuous with constant  $L$ .

**LEMMA 3.** *There exists  $\delta > 0$  such that  $\phi$  is bounded on the set  $\Delta = \{(t, x); \|x\| \leq \widetilde{M}t, 0 \leq t < \delta\}$ . Moreover,*

$$(3.9) \quad \|\tilde{f}(t, x) - \tilde{f}(s, y)\| \leq \phi(t, x) - \phi(s, y)$$

for all  $(t, x), (s, y) \in \Delta$  with  $\|x - y\| \leq \widetilde{M}(t - s)$ ;

$$(3.10) \quad \lim_{\substack{t \rightarrow 0^+ \\ \|x\| \leq \widetilde{M}t}} \phi(t, x) = 0.$$

**PROOF.** We begin by proving the last assertion. If (3.10) fails, then there exists a constant  $\eta > 0$  such that, for every  $\varepsilon > 0$ , one can find a finite sequence  $\{(t_i, x_i); i = 0, \dots, N\}$  satisfying

$$(3.11) \quad (t_0, x_0) = (0, 0), \quad t_N < \varepsilon, \quad \|x_i - x_{i-1}\| \leq \widetilde{M}(t_i - t_{i-1}),$$

$$(3.12) \quad \sum_{i=1}^N \|\tilde{f}(t_i, x_i) - \tilde{f}(t_{i-1}, x_{i-1})\| > \eta.$$

Choosing  $\tau_i > t_i$  suitably close to  $t_i$ , we obtain a finite sequence  $(\tau_i, x_i)$  which satisfies

$$(3.13) \quad 0 < \tau_0 < \dots < \tau_N < \varepsilon, \quad \|x_i\| \leq \widetilde{M}\tau_i, \quad \|x_i - x_{i-1}\| \leq M(\tau_i - \tau_{i-1}),$$

$$(3.14) \quad \sum_{i=1}^N \|f(\tau_i, x_i) - f(\tau_{i-1}, x_{i-1})\| > \eta.$$

Let  $\delta > 0$  be given. Construct a sequence of finite sets  $S_k = \{(\tau_i^k, x_i^k); i = 0, \dots, N_k\}$ ,  $k \geq 1$ , inductively as follows. Define  $S_1$  to be any finite sequence for which (3.13) and (3.14) hold with  $\varepsilon = \delta$ . When  $S_{k-1}$  has been defined, let  $S_k$  be any finite sequence which satisfies (3.13) and (3.14) with  $\varepsilon = \tau_0^{k-1}(M + \widetilde{M})/(M - \widetilde{M})$ . Since  $\|x_0^{k-1}\| \leq \widetilde{M}\tau_0^{k-1}$ ,  $\|x_{N_k}^k\| \leq \widetilde{M}\tau_{N_k}^k$ , this choice of  $\varepsilon$  implies

$$(3.15) \quad (\tau_{N_k}^k, x_{N_k}^k) < (\tau_0^{k-1}, x_0^{k-1}) \quad \forall k > 1.$$

Because of (3.15), the set  $S = \bigcup_{k \geq 1} S_k$  is totally ordered by the relation  $<$  defined at (1.3). We can thus arrange its elements into a unique decreasing sequence, say  $S = \{(\tau_j, x_j), j \geq 0\}$ , with  $(\tau_j, x_j) < (\tau_{j-1}, x_{j-1})$  for all  $j \geq 1$ . Since every  $S_k$  satisfies (3.14), it follows that

$$(3.16) \quad \sum_{j=1}^{\infty} \|f(\tau_j, x_j) - f(\tau_{j-1}, x_{j-1})\| = \infty.$$

By (3.16),  $f$  cannot have locally bounded  $\Gamma^M$ -variation near the point  $(0, 0)$ . This contradiction proves (3.10). The existence of a set  $\Delta$  where  $\phi$  is bounded is an obvious consequence of (3.10). The ‘‘dynamic programming’’ equation (3.9) follows easily from the definition of  $\phi$  at (3.2).

It is now possible to complete the proof of Theorem 1. By Lemma 3, one can apply Theorem 2 to the vector field  $\tilde{f}$  (with  $M$  replaced by  $\widetilde{M}$ ) and obtain the existence of a unique local solution  $x(\cdot)$  for the Cauchy Problem

$$(3.17) \quad \dot{x}(t) = \tilde{f}(t, x(t)), \quad x(t_0) = x_0,$$

on some forward interval  $[t_0, T]$ . By Lemma 2,  $x(\cdot)$  is also the unique solution of (1.1) on  $[t_0, T]$ . Since  $f$  is bounded, this solution can be uniquely extended to  $[t_0, \infty)$ . To prove the continuous dependence on the initial data, consider the upper semicontinuous compact convex valued multifunction  $F$ :

$$(3.18) \quad F(t, x) = \bigcap_{\varepsilon > 0} \overline{\text{co}}\{f(s, y); |s - t| < \varepsilon, \|y - x\| < \varepsilon\},$$

where  $\overline{\text{co}}$  stands for closed convex hull. By Lemma 3.2 in [3], the Carathéodory solutions of (1.1) coincide with those of the multivalued Cauchy Problem

$$(3.19) \quad \dot{x}(t) \in F(t, x(t)), \quad x(t_0) = x_0.$$

For any fixed  $T > t_0$ , let  $\mathcal{S}(x_0) \subseteq \mathcal{E}([t_0, T]; \mathbf{R}^n)$  denote the family of solutions of (3.19). The set-valued map  $x_0 \rightarrow \mathcal{S}(x_0)$  is then upper semicontinuous [1, p. 104]. By uniqueness, in our case  $\mathcal{S}(x_0)$  reduces to a single element, therefore it depends continuously on  $x_0$ .

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