ON THE GENERALIZED STEPANOV THEOREM

MACIEJ KOCAN AND XU-JIA WANG

(Communicated by J. Marshall Ash)

ABSTRACT. The generalized Stepanov theorem is derived from the Alexandrov theorem on the twice differentiability of convex functions. A parabolic version of the generalized Stepanov theorem is also proved.

In the first part of this note we provide a new proof of the generalized Stepanov theorem. This classical result is due to Calderón and Zygmund [3] (see also Oliver [12]), but is usually associated with Stepanov's name because it generalizes the Stepanov theorem (see e.g. [6]). The result we prove below (Theorem 1) constitutes a special case of a general theorem in [3]. Recently this particular version found applications in proving the twice differentiability a.e. of viscosity solutions of elliptic partial differential equations, see [11], [14] and [2]. The only complete proof of the generalized Stepanov theorem the authors are aware of is contained in [3], where Whitney's extension theorem is used. In this note the generalized Stepanov theorem will be proved by means of the Aleksandrov theorem on the twice differentiability of convex functions [1]; see also [5], [9], [10] or the appendix in [4] for more modern treatments.

In the second part of this note we show how to modify our proof to obtain a parabolic version of the generalized Stepanov theorem (Theorem 3). A result of this type is needed to prove the differentiability a.e. twice in x and once in t of viscosity solutions of parabolic equations. To the best of the authors' knowledge this result is original, though some relevant arguments appear in [16].

 $|\cdot|$ and $\langle\cdot,\cdot\rangle$ will stand for the Euclidean norm and inner-product in \mathbb{R}^n , and $B_r(x)$ will denote the open ball in \mathbb{R}^n of radius r centered at x. Given a measurable set A in an Euclidean space, |A| will denote its Lebesgue measure.

Recall some notation from [3] (see also [17]). Let $u: \Omega \to \mathbb{R}$, $\Omega \subset \mathbb{R}^n$, be bounded and $x \in \Omega$. We say that $u \in T^2_{\infty}(x)$ ($u \in t^2_{\infty}(x)$, resp.) if there exists an affine function P_x (a quadratic function Q_x) such that

$$\sup_{y \in B_r(x) \cap \Omega} |u(y) - P_x(y)| \le O(r^2)$$

$$\left(\sup_{y\in B_r(x)\cap\Omega}|u(y)-Q_x(y)|\leq o(r^2)\text{ as }r\downarrow 0,\text{ resp.}\right).$$

Observe that $u \in t^2_{\infty}(x)$ if and only if u possesses a second order Taylor series expansion at x whose remainder behaves like $o(r^2)$. If this is the case we will say

Received by the editors February 21, 1996.

¹⁹⁹¹ Mathematics Subject Classification. Primary 26B05.

This work was supported by the Australian Research Council.

that u is twice differentiable at x. On the other hand, $u \in T^2_\infty(x)$ is equivalent to saying that u can be enclosed between two paraboloids meeting at x. In particular, if $\Omega \subset \mathbb{R}^n$ is open and $u \in T^2_\infty(x)$, then u is differentiable at x and $P_x(y) = u(x) + \langle Du(x), y - x \rangle$.

Theorem 1 (Calderón-Zygmund [3]). Let $\Omega \subset \mathbb{R}^n$ be open and bounded and suppose that $u \colon \overline{\Omega} \to \mathbb{R}$ is bounded. If $u \in T^2_{\infty}(x)$ for a.e. $x \in \Omega$ then $u \in t^2_{\infty}(x)$ for a.e. $x \in \Omega$.

Proof. By the assumption for a.e. $x \in \Omega$ there are $p_x \in \mathbb{R}^n$ and $M_x \geq 0$ such that

$$|u(y) - u(x) - \langle p_x, y - x \rangle| \le M_x |y - x|^2$$
 for all $y \in \Omega$;

note that p_x is uniquely determined and we can assume that M_x is the smallest with this property. It follows that M_x is well defined and finite a.e., moreover, the mapping $x \mapsto M_x$ is measurable. For $M = 1, 2, \ldots$ put

$$\Omega_M = \{ x \in \Omega \colon M_x \leq M \};$$

then every Ω_M is measurable and $\bigcup_{M=1}^{\infty} \Omega_M$ is of full measure in Ω . Therefore it is enough to show that for every M

$$u \in t^2_{\infty}(x)$$
 for a.e. $x \in \Omega_M$.

From now on let M be fixed. Note that for every $x \in \Omega_M$

$$u(y) - \langle p_x, y \rangle \le u(x) - \langle p_x, x \rangle + M|y - x|^2$$
 for all $y \in \Omega$,

or

$$\tilde{u}(y) < \tilde{u}(x) + \langle q_x, y - x \rangle$$
 for all $y \in \Omega$,

where $\tilde{u} = u - M|\cdot|^2$ and $q_x = p_x - 2Mx$. Denoting by \hat{u} the upper concave envelope of \tilde{u} on $\overline{\Omega}$, that is,

$$\hat{u}(x) = \inf\{p(x): p \text{ is affine and } p \ge \tilde{u} \text{ on } \Omega\},$$

we obtain that $\tilde{u} = \hat{u}$ on Ω_M , or using the notation in [7], $\Omega_M \subset \Gamma$, where $\Gamma = \Gamma_{\tilde{u}}^+ = \{\tilde{u} = \hat{u}\}$ is the upper contact set of \tilde{u} on Ω . From the Aleksandrov theorem \hat{u} is twice differentiable a.e., that is, there exists $F \subset \Omega$ of full measure such that $\hat{u} \in t_{\infty}^2(x)$ for every $x \in F$. Note that $D\tilde{u} = D\hat{u}$ on $\Omega_M \cap F$, which yields

(1)
$$|\tilde{u}(y) - \hat{u}(y)| \le O(|y - x|^2) \text{ for every } x \in \Omega_M \cap F.$$

We will show that (1) implies that

(2)
$$|\tilde{u}(y) - \hat{u}(y)| \le o(|y - x|^2)$$
 as $y \to x$ for a.e. $x \in \Omega_M$.

Put $v = \hat{u} - \tilde{u}$ and for $N = 1, 2, \dots$ let

$$\Omega_{M,N} = \{x \in \Omega_M : |v(y)| \le N|y - x|^2 \text{ for all } y \in \Omega\}.$$

To prove (2) it is enough to show that for every N

(3)
$$|v(y)| \le o(|y-x|^2)$$
 as $y \to x$ for a.e. $x \in \Omega_{M,N}$.

We will show that this holds for any point of density of $\Omega_{M,N}$. So let $x_0 \in \Omega_{M,N}$ be a point of density and let $1 > \epsilon > 0$. Then for all sufficiently small r, say $r < \delta$, where $B_{\delta}(x_0) \subset \Omega$,

(4)
$$\frac{|B_r(x_0) \setminus \Omega_{M,N}|}{|B_r(x_0)|} < \epsilon^n.$$

Suppose that $y \in B_{\delta(1-\epsilon)}(x_0)$ and let $r = |y - x_0|/(1-\epsilon) < \delta$. It follows that $B_{\epsilon r}(y) \subset B_r(x_0)$ and from (4) $B_{\epsilon r}(y) \cap \Omega_{M,N} \neq \emptyset$, say $x_1 \in B_{\epsilon r}(y) \cap \Omega_{M,N}$. Then

$$|v(y)| \le N|y - x_1|^2 < N\epsilon^2 r^2 = \epsilon \frac{N\epsilon}{(1 - \epsilon)^2} |y - x_0|^2,$$

and (3), and consequently (2), follows.

To finish the proof of the theorem it is enough to remark that if $\hat{u} \in t_{\infty}^2(x)$ and $|\tilde{u}(y) - \hat{u}(y)| \le o(|y - x|^2)$ as $y \to x$, then the Taylor expansion for \hat{u} works for \tilde{u} , and thus $\tilde{u} \in t_{\infty}^2(x)$, and consequently $u \in t_{\infty}^2(x)$.

Remark 2. Under the assumptions of Theorem 1 we proved that for a.e. $x_0 \in \Omega$ there exist $p(x_0) \in \mathbb{R}^n$ and a symmetric $n \times n$ matrix $A(x_0)$ such that

(5)
$$u(y) = u(x_0) + \langle p(x_0), y - x_0 \rangle + \frac{1}{2} \langle A(x_0)(y - x_0), y - x_0 \rangle + o(|y - x_0|^2) \text{ as } y \to x_0.$$

Clearly u is then differentiable at every such point x_0 with $Du(x_0) = p(x_0)$. A natural question arises whether A(x) is the derivative of Du(x). Denoting $F_1 = \{x \in \Omega \colon Du(x) \text{ exists}\}$ and $F_2 = \{x \in \Omega \colon u \in t^2_\infty(x)\} \subset F_1$, we would like to find out whether for a.e. $x_0 \in F_2$

(6)
$$Du(y) = Du(x_0) + \langle A(x_0), y - x_0 \rangle + o(|y - x_0|) \text{ as } F_1 \ni y \to x_0.$$

By the C^2 version of the Aleksandrov theorem (see e.g. [10] or [4]) convex functions have this property, and therefore the proof of Theorem 1 shows that (6) holds in the approximate sense for a.e. $x_0 \in \Omega$. That is, there exists $F_3 \subset F_2 \subset \Omega$ of full measure such that for every $x_0 \in F_3$ and $\epsilon > 0$ the set

$$\{y \in F_1: |Du(y) - Du(x_0) - \langle A(x_0), y - x_0 \rangle| < \epsilon |y - x_0| \}$$

has density 1 at x_0 . In general, to claim (6) stronger assumptions on u are required; see e.g. Theorem 3.5.7 in [17].

We would like to emphasize that this paper is concerned with pointwise derivatives and in general in our setting one doesn't expect the existence of generalized derivatives. However, if $u \in t^2_{\infty}(x)$ for all $x \in \Omega$ with p and A as in (5) belonging to $L^p(\Omega)$, $1 \le p < \infty$, then $u \in W^{2,p}(\Omega)$; see Theorem 3.9.5 in [17].

A modification of our approach leads to a proof of a parabolic version of the generalized Stepanov theorem. We are concerned with real-valued functions on \mathbb{R}^{n+1} . We will write points in \mathbb{R}^{n+1} as (x,t), where $x \in \mathbb{R}^n$ and $t \in \mathbb{R}$. Given $(y,s),(x,t) \in \mathbb{R}^{n+1}$, define their parabolic distance d according to

$$d((y,s),(x,t)) = \sqrt{|x-y|^2 + |t-s|}$$

and their one-sided parabolic distance d_{∞} by

$$d_{\infty}((y,s),(x,t)) = \begin{cases} d((y,s),(x,t)) \text{ if } s \leq t, \\ +\infty \text{ otherwise.} \end{cases}$$

Let $u: Q \to \mathbb{R}$, $Q \subset \mathbb{R}^{n+1}$, be bounded and $(x_0, t_0) \in Q$. We say that $u \in T^{2,1}_{\infty}(x_0, t_0)$ ($u \in t^{2,1}_{\infty}(x_0, t_0)$, resp.) if there exists an affine function P_{x_0,t_0} of variable

x (a quadratic in x and affine in t function Q_{x_0,t_0}) such that

$$|u(y,s) - P_{x_0,t_0}(y,s)| \le O\left(d_{\infty}^2((y,s),(x_0,t_0))\right) \text{ for } (y,s) \in Q$$

$$\left(|u(y,s) - Q_{x_0,t_0}(y,s)| \le O\left(d^2((y,s),(x_0,t_0))\right) \text{ as } Q \ni (y,s) \to (x_0,t_0), \text{ resp.}\right).$$

Note that in the definition of $t_{\infty}^{2,1}(x_0,t_0)$ an appropriate inequality holds for s both larger and smaller than t_0 , while in the definition of $T_{\infty}^{2,1}(x_0,t_0)$ only the values $s \leq t_0$ matter. $u \in t_{\infty}^{2,1}(x_0,t_0)$ roughly corresponds to the differentiability of u at (x_0,t_0) , twice in x, once in t.

Theorem 3. Let $\Omega \subset \mathbb{R}^n$ be open and bounded, T > 0 and suppose that $u \colon \overline{Q} \to \mathbb{R}$ is bounded, where $Q = \Omega \times (0,T)$. If $u \in T^{2,1}_{\infty}(x,t)$ for a.e. $(x,t) \in Q$ then $u \in t^{2,1}_{\infty}(x,t)$ for a.e. $(x,t) \in Q$.

For $(x,t) \in \mathbb{R}^{n+1}$ and r > 0 put

$$P_r(x,t) = \{(y,s) \in \mathbb{R}^{n+1} : d((x,t),(y,s)) < r\},\$$

$$Q_r(x,t) = \{(y,s) \in \mathbb{R}^{n+1} : d_{\infty}((x,t),(y,s)) < r\}.$$

The following proposition will be used in the proof of Theorem 3. It follows in a standard way from a version of the covering theorem of Vitali, which employs Q_r 's instead of the Euclidean balls; see e.g. Remark I.3.1 in [8].

Proposition 4. Let $A \subset \mathbb{R}^{n+1}$ be measurable. Then

$$\lim_{r\downarrow 0} \frac{|Q_r(x,t)\setminus A|}{|Q_r(x,t)|} = 0 \text{ for a.e. } (x,t)\in A.$$

Proof of Theorem 3. The proof of Theorem 3 parallels that of Theorem 1. By assumption for a.e. $(x,t) \in Q$ there are $p_{x,t} \in \mathbb{R}^n$ and $M_{x,t} \geq 0$ such that

$$|u(y,s) - u(x,t) - \langle p_{x,t}, y - x \rangle| \le M_{x,t}(|y-x|^2 + t - s)$$
 for all $y \in \Omega$, $s \in [0,t]$.

As before the mapping $(x,t) \mapsto M_{x,t}$ is measurable and putting for $M = 1, 2, \dots$

$$Q_M = \{(x,t) \in Q \colon M_{x,t} \le M\}$$

gives that $\bigcup_{M=1}^{\infty} Q_M$ is of full measure in Q. Fix M and define $\tilde{u}(x,t) = u(x,t) - M(|x|^2 - t)$; it follows that for every $(x,t) \in Q_M$

(7)
$$\tilde{u}(y,s) \leq \tilde{u}(x,t) + \langle q, y - x \rangle$$
 for all $y \in \Omega$ and $s \in [0,t]$,

with an appropriate $q \in \mathbb{R}^n$. In the parabolic context the upper concave envelope \hat{u} of given function $\tilde{u}: Q \to \mathbb{R}$ is defined by (see [13] or [15])

$$\hat{u} = \inf\{v \colon v \geq \tilde{u} \text{ on } Q, v \text{ concave in } x \text{ and increasing in } t\},$$

and thus (7) shows that $\tilde{u} = \hat{u}$ on Q_M . A parabolic version of the Aleksandrov theorem (see Theorem 1, Appendix 2 in [9]) guarantees that there exists $F \subset Q$ of full measure such that $\hat{u} \in t^{2,1}_{\infty}(x,t)$ for every $(x,t) \in F$. It follows that

(8)
$$|\tilde{u}(y,s) - \hat{u}(y,s)| \le O\left(d_{\infty}^2((y,s),(x,t))\right)$$
 for every $(x,t) \in Q_M \cap F$.

We will show that (8) implies that

(9)
$$|\tilde{u}(y,s) - \hat{u}(y,s)| \le o\left(d^2((y,s),(x,t))\right)$$
 for a.e. $(x,t) \in Q_M$,

which will give the result as in the proof of Theorem 1. Put $v = \hat{u} - \tilde{u}$ and for N = 1, 2, ... let

$$Q_{M,N} = \{(x,t) \in Q_M : |v(y,s)| \le Nd_{\infty}^2((y,s),(x,t)) \text{ for every } (y,s) \in Q\},\$$

and suppose that $(x_0, t_0) \in Q_{M,N}$ is such that

$$\lim_{r\downarrow 0} \frac{|Q_r(x_0,t_0)\setminus Q_{M,N}|}{|Q_r(x_0,t_0)|} = 0;$$

by Proposition 4 a.e. $(x_0, t_0) \in Q_{M,N}$ will do. Let $0 < \epsilon < 1$. For all sufficiently small r, say $r < \delta$,

(10)
$$\frac{|Q_r(x_0, t_0) \setminus Q_{M,N}|}{|Q_r(x_0, t_0)|} < \epsilon^{n+2}.$$

Suppose that $(y,s) \in P_{\delta(1-\epsilon)}(x_0,t_0)$ and let $r = d((y,s),(x_0,t_0))/(1-\epsilon) < \delta$. It follows that $P_{\epsilon r}(y,s) \subset P_r(x_0,t_0)$ and from (10) $Q_{\epsilon r}(y,s) \cap Q_{M,N} \neq \emptyset$, say $(x_1,t_1) \in Q_{\epsilon r}(y,s) \cap Q_{M,N}$. In particular $t_1 \geq s$ and therefore

$$|v(y,s)| \le N(|y-x_1|^2 + t_1 - s) < N\epsilon^2 r^2 = \epsilon \frac{N\epsilon}{(1-\epsilon)^2} d^2((y,s),(x_0,t_0)).$$

Thus (9) is proved for a.e. $(x,t) \in Q_{M,N}$ for every N, and consequently for a.e. $(x,t) \in Q_M$.

References

- A. D. Aleksandrov, Almost everywhere existence of the second differential of a convex function and some properties of convex functions, Leningrad Univ. Ann. (Math. Ser.) 37 (1939), 3–35 (Russian).
- L. Caffarelli, M. G. Crandall, M. Kocan, and A. Święch, On viscosity solutions of fully nonlinear equations with measurable ingredients, Comm. Pure Appl. Math. 49 (1996), 365–397.
 CMP 96:09
- A. P. Calderón and A. Zygmund, Local properties of solutions of elliptic partial differential equations, Studia Math. 20 (1961), 171–225. MR 25:310
- M. G. Crandall, H. Ishii, and P.L. Lions, User's guide to viscosity solutions of second order partial differential equations, Bull. Amer. Math. Soc. 27 (1992), 1–67. MR 92j:35050
- L. C. Evans and R. F. Gariepy, Measure theory and fine properties of functions, CRC Press, Boca Raton, 1992. MR 93f:28001
- 6. H. Federer, Geometric measure theory, Springer-Verlag, New York, 1969. MR 41:1976
- D. Gilbarg and N. S. Trudinger, Elliptic partial differential equations of second order, 2nd ed., Springer-Verlag, New York, 1983. MR 86c:35035
- 8. M. de Guzmán, Differentiation of integrals in \mathbb{R}^n , Lecture Notes in Math., vol. 481, Springer-Verlag, New York, 1975. MR **56:**15866
- N. V. Krylov, Nonlinear elliptic and parabolic equations of the second order, Reidel Pub. Co., Dordrecht, 1987. MR 88d:35005
- F. Mignot, Contrôle optimal dans les inéqualitions variationelles ellitiques, J. Funct. Anal. 22 (1976), 130–185. MR 54:11136
- N. S. Nadirashvili, Some differentiability properties of solutions of elliptic equations with measurable coefficients, Math. USSR Izvestiya 27 (1986), 601–606.
- 12. W. H. Oliver, Differential properties of real functions, Ph.D. thesis, Univ. of Chicago, 1951.
- S. J. Reye, Fully non-linear parabolic differential equations of second order, Ph.D. thesis, Australian National Univ., 1985.
- N. S. Trudinger, On the twice differentiability of viscosity solutions of nonlinear elliptic equations, Bull. Austral. Math. Soc. 39 (1989), 443–447. MR 90f:35038

- Kaising Tso, On an Aleksandrov-Bakel'man type maximum principle for second-order parabolic equations, Comm. Part. Diff. Eq. 10 (1985), 543–553. MR 87f:35031
- 16. Lihe Wang, On the regularity of fully nonlinear parabolic equations: I, Comm. Pure Appl. Math. 45 (1992), 27–76. MR 92m:35126
- 17. W. P. Ziemer, Weakly differentiable functions, Springer-Verlag, New York, 1989. MR ${\bf 91e:}46046$

Centre for Mathematics and Its Applications, Australian National University, Canberra, ACT 0200, Australia

 $E\text{-}mail\ address: \verb|kocan@maths.anu.edu.au| } E\text{-}mail\ address: \verb|wang@maths.anu.edu.au|}$