

POSITIVE SOLUTIONS OF NONLINEAR ELLIPTIC EQUATIONS IN THE EUCLIDEAN PLANE

U. UFUKTEPE AND Z. ZHAO

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ABSTRACT. In the present paper, we study the existence of solutions to the problem

$$\begin{cases} \Delta u + f(x, u) = 0 & \text{in } D \\ u > 0 & \text{in } D \\ u = 0 & \text{on } \partial D \end{cases}$$

where D is an unbounded domain in \mathbb{R}^2 with a compact nonempty boundary ∂D consisting of finitely many Jordan curves. The goal is to prove an existence theorem for the above problem in a general setting by using Brownian path integration and potential theory.

1. INTRODUCTION

In the present paper, we study the existence of solutions to the problem

$$(1.1) \quad \begin{cases} \Delta u + f(x, u) = 0 & \text{in } D \\ u > 0 & \text{in } D \\ u = 0 & \text{on } \partial D \end{cases}$$

where D is an unbounded domain in \mathbb{R}^2 with a compact nonempty boundary ∂D consisting of finitely many Jordan curves. The goal is to prove an existence theorem for problem (1.1) in a general setting by using Brownian path integration and potential theory.

For $D \subset \mathbb{R}^n$, $n \geq 3$, D unbounded and with a compact Lipschitz boundary, Z. Zhao [13] proved the following problem:

$$(1.2) \quad \begin{cases} \Delta u + K(x)f(u) = 0 & \text{in } D \\ u > 0 & \text{in } D \\ u = 0 & \text{on } \partial D \end{cases}$$

if K is a Borel measurable function in D satisfying that the family $\left\{ \frac{K(\cdot)}{|\cdot - x|^{d-2}} \right\}$ is uniformly integrable over D with a parameter $x \in D$, and f is a continuous function in $(0, b)$ for some $0 < b \leq \infty$ satisfying that:

$$\lim_{w \rightarrow 0^+} \frac{f(w)}{w} = 0.$$

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Then the problem (1.2) has infinitely many bounded solutions. More precisely, there exists $b_0 \in (0, b]$ such that for each $c \in (0, b_0]$ there exists a solution u of (1.2) satisfying

$$\lim_{|x| \rightarrow \infty} u(x) = c.$$

A similar nonlinear problem for the second order ordinary differential equations is studied in [14]. We state our main result as

Theorem 1.1 (The Main Theorem). *Let D be an unbounded domain in \mathbb{R}^2 with a compact nonempty boundary ∂D consisting of finitely many Jordan curves. Suppose that $f(x, s)$ is a Borel measurable function in $\mathbb{R}^2 \times \mathbb{R}^+$ and $f(x, \cdot)$ is a continuous function in \mathbb{R}^+ for each fixed $x \in \mathbb{R}^2$. If there exists a positive, convex and continuously differentiable function $F(x, s)$ in $\mathbb{R}^2 \times \mathbb{R}^+$ satisfying the conditions*

$$(1.3) \quad |f(x, s)| \leq F(x, s), \quad (x, s) \in \mathbb{R}^2 \times \mathbb{R}^+,$$

$$(1.4) \quad F(x, 0) = F_s(x, 0) = 0,$$

and

$$(1.5) \quad F_s(x, \ln(|x| + 1)) \in K_2^\infty,$$

then the problem

$$(1.6) \quad \begin{cases} \Delta u + f(x, u) = 0 & \text{in } D \\ u > 0 & \text{in } D \\ u = 0 & \text{on } \partial D \end{cases}$$

has infinitely many solutions. More precisely there exists a number $b > 0$ such that for each $c \in (0, b]$, (1.6) has a solution u satisfying

$$(1.7) \quad \lim_{|x| \rightarrow \infty} \frac{u(x)}{\ln |x|} = c.$$

Remark. A special case of the above general setting is the semilinear problem for any V in K_2 , and $p > 1$: If we take $f(x, s) = V(x)s^p$ and $F(x, s) = |V(x)|s^p$, then problem (1.1) becomes the corresponding problem for the semilinear elliptic equation

$$(1.8) \quad \begin{cases} \Delta u + V(x)u^p = 0 & \text{in } D \\ u > 0 & \text{in } D \\ u = 0 & \text{on } \partial D. \end{cases}$$

Then f and F satisfy (1.3) and (1.4) obviously. Condition (1.5) on F is equivalent to

$$\int_{|x| \geq 1} |V(x)|[\ln(1 + |x|)]^p dx < \infty.$$

2. GREEN FUNCTIONS AND h -CONDITIONAL BROWNIAN MOTION

In this section we collect the results on Green functions in \mathbb{R}^2 and h -conditional Brownian motion.

The Kato class K_2 is defined to be the set of all Borel measurable functions on \mathbb{R}^2 satisfying

$$(2.1) \quad \lim_{\alpha \downarrow 0} \left[\sup_{x \in \mathbb{R}^2} \int_{|y-x| < \alpha} \ln \frac{1}{|y-x|} |q(y)| dy \right] = 0$$

where $q : \mathbb{R}^2 \rightarrow \mathbb{R}$ is measurable. K_2 is an important class of the potential functions for the Schrödinger operator. Another potential class K_2^∞ which was introduced in [5] is as follows:

$$(2.2) \quad K_2^\infty = \left\{ q \in K_2 : \int_{|y| > 1} \ln |y| |q(y)| dy < \infty \right\}.$$

Let $\{X_t\}$ be 2-dimensional Brownian motion (see [2]). For any open or closed set A in \mathbb{R}^2 , let

$$T_A(\omega) = \inf\{t > 0 : X_t(\omega) \in A\}.$$

This is called the hitting time of A . The hitting time of A^c is called the exit time from A and denoted by τ_A . We shall use P^x to denote the probability measure on the Brownian continuous paths starting at x . E^x is the expectation on P^x . Let $G_D(x, y)$ be the Green function for D . We list some known results.

For any Borel function φ in D the Green operator is defined as

$$\begin{aligned} G_D \varphi(x) &= E^x \left[\int_0^{\tau_D} \varphi(X_t) dt \right] \\ &= \int_D G_D(x, y) \varphi(y) dy, \end{aligned}$$

and

$$(2.3) \quad \Delta(G_D \varphi) = -2\varphi.$$

Proposition 2.1. *Let D be an unbounded domain in \mathbb{R}^2 with a compact nonempty boundary ∂D consisting of finitely many Jordan curves. Then there exists a harmonic function $h > 0$ in D such that*

$$(2.4) \quad \lim_{D \ni x \rightarrow z} h(x) = 0 \quad \forall z \in \partial D,$$

and

$$(2.5) \quad \lim_{|x| \rightarrow \infty} \frac{h(x)}{\ln |x|} = 1.$$

Proof. Pick a point $a \in \mathbb{R}^2 \setminus \bar{D}$ and $r > 0$ (small enough) such that $\bar{B}(a, r) \subset \mathbb{R}^2 \setminus \bar{D}$. Let $x^* = a + r^2 \frac{(x-a)}{|x-a|^2}$ be the Kelvin inversion from $D \cup \{\infty\}$ onto D^* , where $D^* = \{x^* \in B(a, r) : x \in D \cup \{\infty\}\}$. Since the Kelvin inversion preserves harmonic functions and D^* is bounded Jordan domain, we have

$$G_D(x, y) = G_{D^*}(x^*, y^*), \quad \forall x, y \text{ in } D.$$

Let

$$h(x) = \pi G_{D^*}(x^*, a).$$

Thus, we have

$$(2.6) \quad \lim_{y \rightarrow \infty} \pi G_D(x, y) = \lim_{y^* \rightarrow a} \pi G_{D^*}(x^*, y^*) = \pi G_{D^*}(x^*, a).$$

The rest of the proof is just the properties of the Green function in the bounded domain. □

Now we can develop the notion of conditional Brownian motion introduced by Doob for a general theory. Let $h > 0$ be a harmonic function in D . We define

$$p_h^D(t; x, y) = h(x)^{-1} p^D(t; x, y) h(y), \quad t > 0, \quad x, y \in D,$$

where p^D is the transition density of the killed Brownian motion. $p_h^D(t; x, y)$ satisfies the conditions for a transition density. Let P_h^x and E_h^x denote respectively the probability and expectation determined by the h -conditional Brownian motion starting at x . Then we have for all $f \in \mathcal{B}^+(D)$:

$$E_h^x[t < \tau_D; f(X_t)] = h(x)^{-1} E^x[t < \tau_D; f(X_t)h(X_t)], \quad x \in D.$$

Theorem 2.2 (3-G). *Let $D \subset \mathbb{R}^2$ be as in Proposition 2.1. Then there exists a constant $\mathbf{C} > 0$ depending on D only such that $\forall x, y$, and $z \in D$:*

$$(2.7) \quad \frac{G_D(x, y)G_D(y, z)}{G_D(x, z)} \leq \mathbf{C}[G_D(x, y) + G_D(y, z) + 1].$$

Proof. We used Kelvin transformation to reduce to the bounded Jordan domain case (see [2]). For $n \geq 3$, the 3-G theorem for the unbounded Lipschitz domain was proved by Herbst and Zhao [6] based on [4]. □

Proposition 2.3. *If $q \in K_2^\infty$, then $q \in L^1(\mathbb{R}^2)$.*

Proof. Let $q \in K_2^\infty$. Then by definition of K_2^∞ , $q \in K_2$. So there exists $\alpha_1 > 0$ such that

$$(2.8) \quad \sup_{x \in \mathbb{R}^2} \int_{|y-x| \leq \alpha_1} \ln \frac{1}{|x-y|} |q(y)| dy < 1$$

and

$$(2.9) \quad \int_{|y| \geq e} \ln |y| |q(y)| dy < \infty.$$

Let $\alpha = \min(\alpha_1, e^{-1})$. For the compact set $\bar{B} = \bar{B}(0, e)$, there exists finite points $x_i, i = 1, \dots, L$, such that $\bar{B} \subseteq \bigcup_{i=1}^L B(x_i, \alpha)$ and $\forall i = 1, \dots, L, y \in B(x_i, \alpha)$ we have $\ln \frac{1}{|x_i - y|} \geq \ln \frac{1}{e^{-1}} = 1$. Then by (2.8)

$$(2.10) \quad \begin{aligned} \int_{|y| \leq e} |q(y)| dy &\leq \sum_{i=1}^L \int_{B(x_i, \alpha)} |q(y)| dy \\ &\leq \sum_{i=1}^L \int_{B(x_i, \alpha)} \ln \frac{1}{|x_i - y|} |q(y)| dy \\ &\leq L. \end{aligned}$$

Since $q \in K_2^\infty$, we have

$$(2.11) \quad \int_{|y|>e} |q(y)|dy \leq \int_{|y|>e} \ln |y||q(y)|dy < \infty.$$

Thus, by (2.10) and (2.11)

$$\int_{\mathbb{R}^2} |q(y)|dy \leq \int_{|y|>e} |q(y)|dy + L < \infty.$$

□

3. UNIFORMLY INTEGRABLE FUNCTIONS

This is the main technical section in which we investigate uniform integrability of the family of the functions $\{G_D(x, \cdot)|q(\cdot)|\}$ and $\{\frac{1}{h(x)}G_D(x, \cdot)h(\cdot)|q(\cdot)|\}$.

Since $D \supset B_r^* = \mathbb{R}^2 \setminus \overline{B(a, r)}$, using the explicit formula of $G_{B_r^*}(\cdot, \cdot)$ and the definition of K_2^∞ , we can prove:

Proposition 3.1. *For $q \in K_2^\infty$, the family of functions $\{G_D(x, \cdot)|q(\cdot)|\}$ with parameter $x \in D$ is uniformly integrable over D .*

We define

$$(3.1) \quad \|q\|_D = \sup_{x \in D} \int_D G(x, y)|q(y)|dy,$$

and

$$(3.2) \quad \|q\|_1 = \int_D |q(y)|dy.$$

Proposition 3.2. *Let D and h be as in Proposition 2.1. Then for any $q \in K_2^\infty$, we have*

- (a) $\{\frac{1}{h(x)}G_D(x, \cdot)h(\cdot)|q(\cdot)| : x \in D\}$ is uniformly integrable.
- (b) There exists a constant c_D such that $\forall x \in D$:

$$(3.3) \quad \frac{1}{h(x)} \int_D G_D(x, y)h(y)|q(y)|dy \leq c_D(\|q\|_D + \|q\|_1).$$

Proof. By Theorem (3-G), there exists $\mathbf{C} > 0$ such that

$$(3.4) \quad \frac{G_D(x, y)G_D(y, z)|q(y)|}{G_D(x, z)} \leq \mathbf{C}(G_D(x, y) + G_D(y, z) + 1)|q(y)|.$$

Recalling $h(x) = \lim_{z \rightarrow \infty} \pi G_D(x, z)$, and using Proposition 3.1 and the fact $q \in L^1(D)$, we can obtain that $\{\frac{1}{h(x)}G_D(x, \cdot)h(\cdot)|q(\cdot)| : x \in D\}$ is uniformly integrable. Thus, (a) follows.

By taking the integral of (3.4) with respect to y , we have

$$\begin{aligned}
 & \frac{1}{G_D(x, z)} \int_D G_D(x, y) G_D(y, z) |q(y)| dy \\
 (3.5) \quad & \leq \mathbf{C} \left(\int_D G_D(x, y) |q(y)| dy + \int_D G_D(y, z) |q(y)| dy + \int_D |q(y)| dy \right) \\
 & \leq c_D (\|q\|_D + \|q\|_1),
 \end{aligned}$$

where $c_D = 2\mathbf{C}$. By taking the limit of (3.5) as $z \rightarrow \infty$, we have by Fatou’s lemma:

$$\frac{1}{h(x)} \int_D G_D(x, y) h(y) |q(y)| dy \leq c_D (\|q\|_D + \|q\|_1).$$

□

Proposition 3.3. *Let D and h be as in Proposition 2.1. Let $q \in K_2^\infty$. If*

$$(3.6) \quad \sup_{x \in D} E_h^x \left[\int_0^{\tau_D} |q(X_t)| dt \right] \leq \frac{1}{2},$$

then the function

$$(3.7) \quad w(x) = h(x) E_h^x \left[e^{\int_0^{\tau_D} q(X_s) ds} \right], \quad \forall x \in D,$$

is well defined in D and satisfies that $\forall x \in D$

$$(3.8) \quad e^{-\frac{1}{2}} h(x) \leq w(x) \leq 2h(x),$$

and

$$(3.9) \quad w(x) = h(x) + \int_D G_D(x, y) q(y) w(y) dy.$$

Proof. By Khas’minskii’s lemma, we have by (3.6),

$$(3.10) \quad E_h^x \left[e^{\int_0^{\tau_D} q(X_s) ds} \right] \leq 2.$$

By Jensen’s inequality and (3.6), we have

$$(3.11) \quad e^{-\frac{1}{2}} \leq E_h^x \left[e^{\int_0^{\tau_D} q(X_s) ds} \right].$$

Thus, it follows by (3.7), (3.10), and (3.11) that

$$h(x) e^{-\frac{1}{2}} \leq w(x) \leq 2h(x).$$

The equality (3.9) will be obtained by calculation on the conditional Brownian paths:

$$\begin{aligned} w(x) - h(x) &= h(x)E_h^x \left[e^{\int_0^{\tau_D} q(X_s)ds} - 1 \right] \\ &= h(x)E_h^x \left[\int_0^{\tau_D} q(X_t)e^{\int_t^{\tau_D} q(X_s)ds} dt \right] \\ &= h(x) \int_0^\infty E_h^x \left[t < \tau_D : q(X_t)e^{\int_t^{\tau_D} q(X_s)ds} \right] dt \\ &= h(x) \int_0^\infty E_h^x \left[t < \tau_D : q(X_t)E_h^{X_t} \left[e^{\int_0^{\tau_D} q(X_s)ds} \right] \right] dt \end{aligned}$$

(by the Markov property for the conditional Brownian motion)

$$\begin{aligned} &= \int_0^\infty E^x \left[t < \tau_D; q(X_t)h(X_t)E_h^{X_t} \left[e^{\int_0^{\tau_D} q(X_s)ds} \right] \right] dt \\ &= \int_0^\infty E^x [t < \tau_D; q(X_t)w(X_t)] dt \\ &= E^x \left[\int_0^{\tau_D} q(X_t)w(X_t) dt \right] \\ &= \int_D G_D(x, y)q(y)w(y)dy. \end{aligned}$$

□

4. PROOF OF THE MAIN THEOREM

Let $D^\infty = \bar{D} \cup \{\infty\}$ be the compactification of D . Let

$$(4.1) \quad \mathcal{P}(D) = \{ \psi \in C(D) : \lim_{x \rightarrow z \in \partial D} \psi(x) \text{ and } \lim_{|x| \rightarrow \infty} \psi(x) \text{ exist and are finite} \}.$$

Obviously $\mathcal{P}(D)$ is isometric to $C(D^\infty)$. $\mathcal{P}(D)$ is a Banach space, with the norm

$$\| \psi \| = \sup_{x \in D} | \psi(x) |.$$

Let q_0 be a positive function belonging to K_2^∞ , and let

$$(4.2) \quad Q_0 = \{ q \in K_2^\infty : |q(x)| \leq q_0(x), \forall x \in D \}.$$

Proposition 4.1. *For a fixed $q_0 > 0$ and $q_0 \in K_2^\infty$, and the harmonic function h as defined in Proposition 2.1, the family of the functions*

$$G_D^h[Q_0] = \left\{ \frac{1}{h(\cdot)} \int_D G_D(\cdot, y)h(y)q(y)dy : q \in Q_0 \right\}$$

is uniformly bounded and equicontinuous in D , and consequently it is relatively compact in $\mathcal{P}(D)$.

Remark. In order to imply the relative compactness of the family in the supremum norm, the equicontinuity of the family in $\mathcal{P}(D)$ should include that the two limits in (4.1) converge uniformly for all functions in the family. This is a modification of the classical Ascoli-Arzelà theorem.

Proof. The uniform integrability of $\left\{ \frac{1}{h(x)}G(x, \cdot)h(\cdot)|q(\cdot)| : x \in D \right\}$, by Proposition 3.2, justifies the interchange of the limit and integration, hence we obtain that the function

$$L_q(x) \equiv \frac{1}{h(x)} \int_D G_D(x, y)h(y)q(y)dy$$

is continuous. $\lim_{|x| \rightarrow \infty} L_q(x)$ and $\lim_{x \rightarrow z \in \partial D} L_q(x)$ exist and are finite. Thus, L_q belongs to $\mathcal{P}(D)$. For any $q \in Q_0$, by (4.2) and 3.2 we have

$$\begin{aligned} \sup_{x \in \bar{D}} \int_D \frac{G_D(x, y)}{h(x)}h(y)|q(y)|dy &\leq \sup_{x \in D} \int_D \frac{G_D(x, y)}{h(x)}h(y)q_0(y)dy \\ &\leq c_D(\|q_0\|_D + \|q_0\|_1). \end{aligned}$$

Thus, $G_D^h[Q_0]$ is uniformly bounded. By using the uniform integrability of $\left\{ \frac{1}{h(x)}G_D(x, \cdot)h(\cdot)q_0(\cdot) \right\}$, we have

i) $\forall q \in Q_0, \forall z \in \bar{D}$, as $x, x' \rightarrow z$:

$$\begin{aligned} &\left| \int_D \frac{G_D(x, y)}{h(x)}h(y)q(y)dy - \int_D \frac{G_D(x', y)}{h(x')}h(y)q(y)dy \right| \\ (4.3) \quad &\leq \int_D \left| \frac{G_D(x, y)}{h(x)} - \frac{G_D(x', y)}{h(x')} \right| h(y)|q(y)|dy \\ &\leq \int_D \left| \frac{G_D(x, y)}{h(x)} - \frac{G_D(x', y)}{h(x')} \right| h(y)q_0(y)dy \rightarrow 0, \end{aligned}$$

since $x - x' \rightarrow 0$.

ii) $\forall q \in Q_0$,

$$\int_D \frac{G_D(x, y)}{h(x)}h(y)|q(y)|dy \leq \int_D \frac{G_D(x, y)}{h(x)}h(y)q_0(y)dy \rightarrow 0$$

as $|x| \rightarrow \infty$.

Thus, $G_D^h[Q_0]$ is equicontinuous in $\mathcal{P}(D)$, and the limits in (4.1) converge uniformly for all functions in $G_D^h[Q_0]$. Then by the Ascoli-Arzelà theorem $G_D^h[Q_0]$ is relatively compact in $\mathcal{P}(D)$. \square

Proof of the Main Theorem. Let $b > 0$ be the real number determined later and, for $c \in (0, b]$, let

$$(4.4) \quad \Lambda = \left\{ v \in \mathcal{P}(D) : ce^{-\frac{1}{2}} \leq v(x) \leq 2c, \quad \forall x \in D \right\}.$$

For each $v \in \Lambda$ define

$$(4.5) \quad Tv(x) = cE_h^x \left[e^{\int_0^{\tau_D} q_v(X_t)dt} \right], \quad \forall x \in D,$$

where

$$(4.6) \quad q_v(x) = \frac{f(x, v(x)h(x))}{2v(x)h(x)}.$$

For each $x \in D$, by using condition (1.3), (1.4) and the mean value theorem we showed that

$$(4.7) \quad \left| \frac{f(x, v(x)h(x))}{2v(x)h(x)} \right| \leq F_s(x, 2c\eta \ln(|x| + 1)).$$

We now have

$$\begin{aligned} E_h^x \left[\int_0^{\tau_D} |q_v(X_t)| dt \right] &= \frac{1}{h(x)} E^x \left[\int_0^{\tau_D} \frac{h(X_t) |f(X_t, v(X_t)h(X_t))|}{2v(X_t)h(X_t)} dt \right] \\ &= \frac{1}{h(x)} \int_D \frac{G_D(x, y) h(y) |f(y, v(y)h(y))|}{2v(y)h(y)} dy \end{aligned}$$

(by (4.7) and the 3-G Theorem)

$$(4.8) \quad \leq \mathbf{C} \int_D (G_D(x, y) + h(y) + 1) F_s(y, 2c\eta \ln(|y| + 1)) dy.$$

Since $F_s(y, \ln(|y| + 1)) \in K_2^\infty \subseteq K_2$, there exists $\alpha \in (0, 1)$ such that

$$(4.9) \quad \sup_{x \in D} \frac{1}{\pi} \int_{|y-x| < \alpha} \ln \frac{1}{|y-x|} F_s(y, \ln(|y| + 1)) dy < \frac{1}{4\mathbf{C}}.$$

By using $F_s(y, \ln(|y| + 1)) \in K_2^\infty$ again, we have by Proposition 2.3

$$\left\{ h(y) + 1 + \frac{1}{\pi} \left[C_r + \ln \frac{1}{\alpha} + 2 \ln |y - a| \right] \right\} F_s(y, \ln(|y| + 1)) \in L^1(D).$$

Thus, using the monotone convergence theorem and noting that $F_s(y, 0) = 0$ and that $F_s(y, \cdot)$ is a nondecreasing function, there exists $\gamma \in (0, 1)$ such that

$$(4.10) \quad \int_D \left[h(y) + 1 + \frac{1}{\pi} \left(C_r + \ln \frac{1}{\alpha} + 2 \ln |y - a| \right) \right] F_s(y, \gamma \ln(|y| + 1)) dy < \frac{1}{4\mathbf{C}}.$$

Now, we determine b by letting

$$(4.11) \quad b = \frac{\gamma}{2\eta}.$$

Thus, $\forall x \in D$, for $c \in (0, b]$, $2\eta c \leq \gamma < 1$, we have

$$(4.12) \quad \begin{aligned} \int_D G_D(x, y) F_s(y, 2\eta c \ln(|y| + 1)) dy &\leq \int_D G_{B_r^+(a)}(x, y) F_s(y, \gamma \ln(|y| + 1)) dy \\ &\leq \frac{1}{\pi} \int_D (C_r + 2 \ln |y - a| + \ln |x - y|^{-1}) F_s(y, \gamma \ln(|y| + 1)) dy \end{aligned}$$

by (4.9)

$$\leq \frac{1}{4\mathbf{C}} + \frac{1}{\pi} \int_D \left(C_r + 2 \ln |y - a| + \ln \frac{1}{\alpha} \right) F_s(y, \gamma \ln(|y| + 1)) dy.$$

It follows from (4.8), (4.10), and (4.12) that

$$(4.13) \quad \sup_{x \in D} E_h^x \left[\int_0^{\tau_D} |q_v(X_t)| dt \right] \leq \frac{1}{2}.$$

Similarly,

$$(4.14) \quad \sup_{x \in D} E_h^x \left[\int_0^{\tau_D} F_s(X_t, 2c\eta \ln(|x_t| + 1)) \right] \leq \frac{1}{2}.$$

Thus by (4.5), (4.13) and Proposition 3.3 we have

$$(4.15) \quad ce^{-\frac{1}{2}} \leq Tv(x) \leq 2c,$$

and

$$(4.16) \quad Tv(x) = c + \frac{1}{h(x)} \int_D G_D(x, y) h(y) q_v(y) Tv(y) dy.$$

By (4.15) and the uniform integrability of $\left\{ \frac{1}{h(x)} G_D(x, \cdot) h(\cdot) q(\cdot) : x \in D \right\}$, we see that $\lim_{x \rightarrow z \in \partial D} Tv(x)$ and $\lim_{|x| \rightarrow \infty} Tv(x)$ exist and are finite. Tv is continuous in D . Thus, $Tv \in \mathcal{P}(D)$ and $Tv \in \Lambda$, so

$$(4.17) \quad T\Lambda \subseteq \Lambda.$$

For any $v \in \Lambda$, by (4.7):

$$|q_v(y)Tv(y)| \leq 2cF_s(y, \ln(|y| + 1)).$$

Let $q_0(y) = 2cF_s(y, \ln(|y| + 1))$ and let Q_0 be given as in (4.1). It follows that

$$(4.18) \quad q_v(\cdot)Tv(\cdot) \in Q_0,$$

and

$$\left\{ \frac{1}{h(\cdot)} \int_D G_D(\cdot, y) h(y) q_v(y) Tv(y) dy : v \in \Lambda \right\} \subseteq G_D^h[Q_0].$$

We thus have by Proposition 4.1 that $T\Lambda$ is a relatively compact set in $\mathcal{P}(D)$. We shall prove the continuity of T in Λ in the supremum norm. Let $v_n \rightarrow v$ in Λ as $n \rightarrow \infty$. Since $\tau < \infty$ for P^x -almost Brownian paths, we have by the continuity of function f and the bounded convergence theorem that for almost every Brownian path:

$$(4.19) \quad \int_0^{\tau_D} \frac{f(X_t, v_n(X_t)h(X_t))}{2v_n(X_t)h(X_t)} dt \rightarrow \int_0^{\tau_D} \frac{f(X_t, v(X_t)h(X_t))}{2v(X_t)h(X_t)} dt.$$

Since $\{v_n\} \subset \Lambda$, each term of the sequence in (4.19) is bounded by

$$\int_0^{\tau_D} F_s(X_t, 2\eta c \ln(|X_t| + 1)) dt.$$

By (4.14) and Khas'minskii's lemma

$$(4.20) \quad E_h^x \left[e^{\int_0^{\tau_D} F_s(X_t, 2\eta c \ln(|X_t| + 1)) dt} \right] \leq 2 < \infty,$$

and hence it follows from (4.19), (4.20), and the dominated convergence theorem that $\forall x \in D$

$$E_h^x \left[e^{\int_0^{\tau_D} q_{v_n}(X_t) dt} \right] \rightarrow E_h^x \left[e^{\int_0^{\tau_D} q_v(X_t) dt} \right].$$

Thus by (4.5)

$$(4.21) \quad Tv_n(x) \rightarrow Tv(x)$$

as $n \rightarrow \infty$. We have proved that $T\Lambda$ is a relatively compact family, therefore the pointwise convergence in (4.21) implies the uniform convergence, namely, $\|Tv_n - Tv\| \rightarrow 0$ as $n \rightarrow \infty$. Thus, we proved that T is a compact and continuous mapping from Λ to itself. By the definition of Λ , Λ is obviously a nonempty, closed, bounded, and convex set in $\mathcal{P}(D)$. Hence by the Schauder fixed-point theorem, there exists a function $v \in \Lambda$ such that

$$(4.22) \quad Tv = v.$$

It follows from (4.16) and (4.22) that

$$(4.23) \quad v(x) = c + \frac{1}{h(x)} \int_D G_D(x, y)h(y)q_v(y)v(y)dy.$$

Now let

$$(4.24) \quad u(x) = h(x)v(x).$$

Since $v \geq ce^{-\frac{1}{2}}$ and $h > 0$ in D , $u > 0$ in D . By (4.6), (4.23), and (4.24), we have

$$(4.25) \quad u(x) = ch(x) + \frac{1}{2} \int_D G_D(x, y)f(y, u(y))dy.$$

Since h is harmonic in D , applying Δ to both sides of (4.25) and using $\Delta(G_D f) = -2f$, we have

$$(4.26) \quad \begin{aligned} \Delta u(x) &= \frac{1}{2} \Delta \left[\int_D G_D(x, y)f(y, u(y))dy \right] \\ &= -f(x, u(x)). \end{aligned}$$

By the property of h and the boundedness of v , we have

$$(4.27) \quad \lim_{x \rightarrow \partial D} u(x) = 0$$

and

$$(4.28) \quad \lim_{|x| \rightarrow \infty} \frac{u(x)}{\ln|x|} = \lim_{|x| \rightarrow \infty} \frac{v(x)h(x)}{\ln|x|} = c.$$

We thus complete the proof. □

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DEPARTMENT OF MATHEMATICS, UNIVERSITY OF MISSOURI, COLUMBIA, MISSOURI 65211

Current address, U. Ufuktepe: Akdeniz Universitesi, Fen-Edebiyat Fakultesi, Matematik Bolumu, 07058 Antalya, Turkey

E-mail address: uunal@pascal.sci.akdeniz.edu.tr

E-mail address: mathzz@mizzou1.missouri.edu