

THE DEGREE OF COCONVEX POLYNOMIAL APPROXIMATION

K. KOPOTUN, D. LEVIATAN, AND I. A. SHEVCHUK

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ABSTRACT. Let $f \in C[-1, 1]$ change its convexity finitely many times in the interval, say s times, at $Y_s : -1 < y_1 < \cdots < y_s < 1$. We estimate the degree of approximation of f by polynomials of degree n , which change convexity exactly at the points Y_s . We show that provided n is sufficiently large, depending on the location of the points Y_s , the rate of approximation is estimated by the third Ditzian–Totik modulus of smoothness of f multiplied by a constant $C(s)$, which depends only on s .

1. INTRODUCTION AND MAIN RESULTS

Let $f \in C[-1, 1]$ change its convexity finitely many times, say s , at the points $Y_s : -1 < y_1 < \cdots < y_s < 1$ in $[-1, 1]$. For later reference set $y_0 := -1$ and $y_{s+1} := 1$. Note that if $f \in C^2[-1, 1]$, then the above is equivalent to $f''(x) \prod_{i=1}^s (x - y_i) \geq 0$, in $[-1, 1]$. We wish to approximate f by means of polynomials which are coconvex with f , that is, which change convexity exactly at the points Y_s .

Questions of this nature first appeared in the work of D. J. Newman and his students (see [NPR], [PR], [PRR]). They dealt not with a function f , changing convexity, but rather with f that changes monotonicity finitely many times in $[-1, 1]$ and they were able to obtain weaker Jackson type estimates on the degree of approximation of that function by polynomials which were truly comonotone with it as well as some proper Jackson estimates when the polynomials were comonotone with f except near the points where a change of monotonicity of f occurred. Later Newman [N] obtained the proper Jackson estimate involving the modulus of continuity of f for the approximation by polynomials that were truly comonotone with f (see also Iliev [I] for some relevant work). Then Leviatan and Beatson [BL] obtained the desired estimates under the assumption that f possesses a continuous derivative in $[-1, 1]$, applying a flipping technique and induction assumption on the number of monotonicity changes of f . We will apply their technique in this paper.

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The first Jackson estimate involving the Ditzian–Totik moduli of smoothness (defined below) is due to Leviatan [L] whose estimates were later improved by Kopotun [K]. As was pointed out to us by the referee, the degree of coconvex polynomial approximation apparently was first discussed in the Ph.D. dissertation of Diane C. Myers [M] where she obtained the Jackson estimate $\omega(f, 1/n)$ for “nearly” coconvex approximation. For proper coconvex approximation there have been no results except for a short remark in [BL] that the technique employed there would give an estimate for the approximation of twice continuously differentiable functions with a single change of convexity.

The first estimates on the degree of coconvex approximation for a twice continuously differentiable function with an arbitrary finite number of convexity changes have recently been obtained by Kopotun [K1] and the purpose of this note is to improve those results in that we do not assume the existence everywhere, and continuity of even the first derivative. We are going to make use of some special polynomials related to the function f which were constructed in that article [K1] based upon the polynomials introduced by Shevchuk [S]. We remark that in the above mentioned paper, Kopotun was able to obtain estimates on the simultaneous approximation of the function and its derivatives by the polynomials and their derivatives, thus obtaining, simultaneously, coconvex approximation to f and comonotone approximation to its derivative. In order to state our main result we recall the definition of the m th order Ditzian–Totik moduli of smoothness $\omega_m^\varphi(f, t)$. For $f \in C[-1, 1]$, we set

$$\omega_m^\varphi(f, t) = \sup_{0 < h \leq t} \|\Delta_{h\varphi(\cdot)}^m f(\cdot)\|,$$

where the norm is the max-norm, $\varphi(x) := \sqrt{1 - x^2}$, and

$$\Delta_\eta^m f(x) := \begin{cases} \sum_{i=0}^m \binom{m}{i} (-1)^{m-i} f(x - \frac{m}{2}\eta + i\eta), & \text{if } x \pm \frac{m}{2}\eta \in [-1, 1], \\ 0, & \text{otherwise.} \end{cases}$$

is the symmetric m th difference.

Our main result is the following.

Theorem. *Let $f \in C[-1, 1]$ have s changes of convexity at $Y_s : -1 < y_1 < \dots < y_s < 1$, and denote $d(Y_s) := \min\{1 + y_1, y_2 - y_1, \dots, y_s - y_{s-1}, 1 - y_s\}$. Then there exists a constant $A = A(s)$ which depends only on the number of convexity changes $-s$, such that, for $n > \frac{A(s)}{d(Y_s)}$, there is a polynomial p_n of degree not exceeding n , which is coconvex with f and satisfies*

$$(1) \quad \|f - p_n\| \leq C(s)\omega_3^\varphi(f, n^{-1}),$$

whence,

$$(1') \quad \|f - p_n\| \leq C(s)\omega_3(f, 1/n).$$

The constant $C(s)$ is independent of f and n and of the location of the convexity changes.

Remark. Estimate (1) is best possible in that one cannot replace $\omega_3^\varphi(f, n^{-1})$ by any higher modulus of smoothness, even not with the larger ordinary modulus of smoothness. This is due to Shvedov [Sv] in case f is convex and to Zhou [Z] in case f has convexity changes.

While it is obvious that the constants $C(s)$ and $A(s)$ depend on s , we have no estimate as to how fast they grow with it. For instance, one readily observes that

the proof below yields exponential growth of $C(s)$ as a function of s (due to the induction process), but we do not know that this is actually the case.

Even the following immediate consequences of the theorem are new:

Corollary. *Let f be as in the theorem and let $n > \frac{A(s)}{d(Y_s)}$. If in addition $f^{(r-1)} \in AC[-1, 1]$, and $f^{(r)} \in L_\infty$, $r = 1, 2, 3$, then the same polynomial p_n satisfies*

$$(1'') \quad \|f - p_n\| \leq \frac{C(s)}{n^r} \|f^{(r)}\|_\infty,$$

where the norm on the right is the L_∞ -norm. (The case $r = 3$ follows from [K1].)

In the sequel we will denote by C an absolute constant which may vary from one occurrence to another even in the same line. Similarly $C(\cdot)$ will denote a constant which depends on a specific parameter but may change from one occurrence to another.

2. PROOF OF THE THEOREM

If f has no change of convexity in $[-1, 1]$, i.e., $s = 0$ and f is convex in $[-1, 1]$, then the theorem is valid and it was proved by Kopotun [K]; thus we will assume that $s \geq 1$. We first need to construct a smoother function at y_1 . The function f is either concave or convex in $[-1, y_1]$, and each case will need a separate though similar construction. We will detail the construction for the case where f is concave in $[-1, y_1]$. For the sake of simplicity in notation in the sequel we write $\alpha := y_1$. Now let $x_j := x_{j,n} := \cos \frac{j\pi}{n}$, $j = 0, \dots, n$, be the Chebyshev nodes; and denote $I_j := [x_j, x_{j-1}]$, $h_j := h_{j,n} := x_{j-1} - x_j$ and

$$(2) \quad \psi_j(x) := \psi_{j,n}(x) := \frac{h_j}{|x - x_j| + h_j}.$$

It is well known that $h_{j\pm 1} < 3h_j$ and that for $x \in I_j$ $\Delta_n(x) \leq h_j < 5\Delta_n(x)$, where, as always, $\Delta_n(x) := \frac{\sqrt{1-x^2}}{n} + \frac{1}{n^2}$. We assume that $\alpha \in [x_{j_0}, x_{j_0-1}]$. Then, if $n > N_\alpha := \max\{\frac{50}{y_2-\alpha}, \frac{50}{1+\alpha}\}$, we are assured that $x_{j_0+3} \geq -1$ and that $x_{j_0-4} \leq y_2$. Set $h := c\Delta_n(\alpha) < \frac{1}{6}h_{j_0}$, where c is chosen sufficiently small to guarantee the right inequality. Note that this implies $x_{j_0+1} < \alpha - 2h < \alpha + 2h < x_{j_0-2}$.

We are going to replace f on the interval $[\alpha - h, \alpha + h]$ in a way that will keep us near the original function and at the same time the new function (see \hat{g} below) will be smoother at α . As was mentioned above, we will apply a flipping technique and induction on the number of convexity changes of f . The case $s = 0$ is known and serves as the beginning of the induction process; it has been proved by Kopotun [K]. When $s = 0$, then (1) holds for all $n \geq 2$. Thus, we proceed by induction.

To this end we note that either $\Delta_h^2 f(\alpha) \geq 0$, or $\Delta_h^2 f(\alpha) < 0$.

In the first case, let $L_1(x)$ denote the linear function interpolating f at $\alpha - h$ and α . Then the function $g := f - L_1$ satisfies

$$g(\alpha - h) = g(\alpha) = 0, \quad g(\alpha + h) \geq 0, \quad \text{and} \quad g(x) \leq 0, \quad -1 \leq x < \alpha - h.$$

Hence, for $J_0 := [x_{j_0+1}, x_{j_0-2}]$, we have,

$$\begin{aligned} 0 \leq g(\alpha + h) &\leq g(\alpha + h) - g(\alpha - 2h) \\ &= g(\alpha + h) - 3g(\alpha) + 3g(\alpha + h) - g(\alpha - 2h) \\ &\leq \omega_3(g, h; J_0) = \omega_3(f, h; J_0). \end{aligned}$$

Similarly, in the latter case, let $L_1(x)$ denote the linear function interpolating f at α and $\alpha + h$. Then the function $g := f - L_1$ satisfies

$$g(\alpha + h) = g(\alpha) = 0, \quad g(\alpha - h) < 0, \quad \text{and} \quad g(x) \geq 0, \quad \alpha + h \leq x < y_2.$$

Hence,

$$\begin{aligned} 0 < -g(\alpha - h) &\leq g(\alpha + 2h) - g(\alpha - h) \\ &= g(\alpha + 2h) - 3g(\alpha + h) + 3g(\alpha) - g(\alpha - h) \\ &\leq \omega_3(g, h; J_0) = \omega_3(f, h; J_0). \end{aligned}$$

Thus, in both cases we have,

$$\max\{|g(\alpha - h)|, |g(\alpha)|, |g(\alpha + h)|\} \leq C\omega_3(f, h; J_0),$$

which in turn implies that the quadratic polynomial $L_2(x)$, interpolating g at $\alpha - h$, α and $\alpha + h$, is bounded by the same on $[\alpha - h, \alpha + h]$. Thus

$$(3) \quad |L_2(x)| \leq C \left(\frac{|x - \alpha| + h_{j_0}}{h_{j_0}} \right)^2 \omega_3(f, h; J_0), \quad x \in [-1, 1].$$

At the same time applying Whitney's Theorem we conclude that

$$|g(x) - L_2(x)| \leq C\omega_3(f, h; J_0), \quad x \in [\alpha - h, \alpha + h].$$

Now it follows by Lemma 4.2 of [S1] that

$$(4) \quad |g(x) - L_2(x)| \leq C \left(\frac{|x - \alpha| + h_{j_0}}{h_{j_0}} \right)^3 \omega_3(f, h; J_0), \quad x \in [-1, 1].$$

Observing that

$$\omega_3(f, h; J_0) \leq C\omega_3^\varphi(f, n^{-1}),$$

we obtain by (3) and (4),

$$(5) \quad |g(x)| \leq C\psi_{j_0}^{-3} \omega_3^\varphi(f, n^{-1}), \quad x \in [-1, 1].$$

Now let

$$\tilde{g}(x) = \begin{cases} -g(x), & x \in [-1, \alpha], \\ g(x), & \text{otherwise,} \end{cases}$$

and finally,

$$\hat{g}(x) = \begin{cases} \tilde{g}(x), & x \notin [\alpha - h, \alpha + h], \\ \max\{\tilde{g}(x), 0\}, & x \in [\alpha - h, \alpha + h]. \end{cases}$$

By virtue of (5) we immediately have

$$(6) \quad \|\tilde{g} - \hat{g}\| \leq C\omega_3^\varphi(f, n^{-1}).$$

Also

$$(7) \quad \begin{aligned} \omega_3^\varphi(\hat{g}, n^{-1}) &\leq \omega_3^\varphi(\tilde{g}, n^{-1}) + C\omega_3^\varphi(f, n^{-1}) \\ &\leq C\omega_3^\varphi(f, n^{-1}), \end{aligned}$$

where the first inequality follows from (6), while the second is due to the fact that for $x \notin J_0$,

$$|\Delta_{\varphi(x)/n}^2 \tilde{g}(x)| = |\Delta_{\varphi(x)/n}^2 g(x)| = |\Delta_{\varphi(x)/n}^2 f(x)|,$$

and for $x \in J_0$ we apply (5).

It is readily seen that $\hat{g} \in C[-1, 1]$, that it is convex in $[-1, y_2]$ and that it changes convexity at $Y'_{s-1} := Y_s \setminus \{y_1\}$. If, on the other hand, f was convex in $[-1, y_1]$, then \hat{g} would be concave in $[-1, y_2]$ and change convexity at Y'_{s-1} . Thus in any case \hat{g} has fewer convexity changes, so by induction, we may assume that for $n > \frac{A(s-1)}{d(Y'_{s-1})}$, there exists an n th degree polynomial q_n which is coconvex with \hat{g} , and which satisfies the analogue of (1). Namely (by (7)),

$$(8) \quad \|\hat{g} - q_n\| \leq C(s-1)\omega_3^\varphi(\hat{g}, n^{-1}) \leq C(s)\omega_3^\varphi(f, n^{-1}).$$

Thus, fixing $n > \max\{\frac{A(s-1)}{d(Y'_{s-1})}, N_\alpha\}$ readily leads to the definition of $A(s)$. Note that since $\hat{g}(\alpha) = 0$, we may assume that $q_n(\alpha) = 0$ doubling the constant in (8).

Kopotun [K1] has constructed for α and q_n for each n as above, two polynomials V_n and W_n of degrees at most $20n(s+1) =: 4n\mu$, with the properties that for all $x \in [-1, 1]$,

$$V_n(x)\operatorname{sgn}(x - \alpha) \geq 0,$$

$$V'_n(x)q''_n(x)(q'_n(x) - q'_n(\alpha))\operatorname{sgn}(x - \alpha) \geq 0,$$

$$(9) \quad |V_n(x) - \operatorname{sgn}(x - \alpha)| \leq C(s)\psi_{j_0}^\mu,$$

$$(10) \quad |W_n(x) - \operatorname{sgn}(x - \alpha)| \leq C(s)\psi_{j_0}^\mu;$$

$$(11) \quad |V'_n(x)| \leq C(s)\psi_{j_0}^\mu h_{j_0}^{-1};$$

and finally,

$$W'_n(x)\operatorname{sgn} q'_n(\alpha) \leq 0, \quad x \in [y_{2j}, y_{2j+1}], \quad j = 0, \dots, [s/2],$$

and

$$W'_n(x)\operatorname{sgn} q'_n(\alpha) \geq 0, \quad x \in [y_{2j+1}, y_{2j+2}], \quad j = 0, \dots, [(s-1)/2].$$

We are ready to define the polynomial

$$p_n(x) := \int_\alpha^x [(q'_n(u) - q'_n(\alpha))V_n(u) + q'_n(\alpha)W_n(u)] du,$$

of degree at most $5n\mu$, which evidently is coconvex with f . Note that $P_n(x) := L_1(x) + p_n(x)$ is of the same degree and it too is coconvex with f . Hence, we conclude the induction step by proving (1) for P_n .

We begin with

$$\begin{aligned} |f(x) - P_n(x)| &= |g(x) - p_n(x)| = |\tilde{g}(x)\operatorname{sgn}(x - \alpha) - p_n(x)| \\ &\leq \|\tilde{g} - \hat{g}\| + |\hat{g}(x)\operatorname{sgn}(x - \alpha) - p_n(x)| \\ &\leq C\omega_3^\varphi(f, n^{-1}) + |(\hat{g}(x) - q_n(x))\operatorname{sgn}(x - \alpha)| + |q_n(x)\operatorname{sgn}(x - \alpha) \\ &\quad - \int_\alpha^x q'_n(u)V_n(u) du| + |q'_n(\alpha) \int_\alpha^x (V_n(u) - W_n(u)) du| \\ &=: E_1 + E_2 + E_3 + E_4, \text{ say.} \end{aligned}$$

By virtue of (8),

$$(12) \quad E_2 \leq C(s)\omega_3^\varphi(f, n^{-1}).$$

Recalling that $q_n(\alpha) = 0$, integration by parts and (11) yield

$$\begin{aligned}
 E_3 &= |q_n(x)(\operatorname{sgn}(x - \alpha) - V_n(x)) + \int_{\alpha}^x q_n(u)V_n'(u) du| \\
 (13) \quad &\leq C(s)(|q_n(x)|\psi_{j_0}^{\mu} + \int_{\alpha}^x |q_n(u)|h_{j_0}^{-1}\psi_{j_0}^{\mu}(u) du) \\
 &\leq C(s)\omega_3^{\varphi}(f, n^{-1}),
 \end{aligned}$$

where the last inequality in (13) follows from (applying (5), (6) and (7)),

$$\begin{aligned}
 |q_n(x)| &\leq |\tilde{g}(x)| + |\tilde{g}(x) - q_n(x)| \\
 &\leq |g(x)| + \|\tilde{g} - \hat{g}\| + \|\hat{g} - q_n\| \\
 &\leq C\psi_{j_0}^{-3}\omega_3^{\varphi}(f, n^{-1}),
 \end{aligned}$$

and the easy inequality

$$(14) \quad \int_{\alpha}^x \psi_{j_0}^{\nu}(u) du \leq Ch_{j_0}, \quad \nu \geq 2.$$

Finally, in order to estimate E_4 , we need an estimate on $q_n'(\alpha)$. To this end we observe that since q_n is convex in $[-1, y_2]$, then q_n' is monotone increasing there. If $q_n'(\alpha) \geq 0$, then by (5), for some $\xi \in (\alpha, \alpha + h_{j_0})$,

$$\begin{aligned}
 0 \leq q_n'(\alpha) \leq q_n'(\xi) &= \frac{q_n(\alpha + h_{j_0}) - q_n(\alpha)}{h_{j_0}} \\
 &= h_{j_0}^{-1}q_n(\alpha + h_{j_0}) \leq Ch_{j_0}^{-1}\omega_3^{\varphi}(f, n^{-1}).
 \end{aligned}$$

And if $q_n'(\alpha) < 0$, then by (5), for some $\xi \in (\alpha - h_{j_0}, \alpha)$,

$$\begin{aligned}
 0 \leq -q_n'(\alpha) \leq -q_n'(\xi) &= \frac{q_n(\alpha - h_{j_0}) - q_n(\alpha)}{h_{j_0}} \\
 &= h_{j_0}^{-1}q_n(\alpha - h_{j_0}) \leq Ch_{j_0}^{-1}\omega_3^{\varphi}(f, n^{-1}).
 \end{aligned}$$

Hence by (9), (10) and (14),

$$\begin{aligned}
 (15) \quad E_4 &\leq |q_n'(\alpha)| \int_{\alpha}^x |V_n(u) - W_n(u)| du \\
 &\leq Ch_{j_0}|q_n'(\alpha)| \leq C\omega_3^{\varphi}(f, n^{-1}).
 \end{aligned}$$

Combining (12), (13) and (15) we see that

$$\|f - P_n\| \leq C\omega_3^{\varphi}(f, n^{-1}).$$

This completes our proof.

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DEPARTMENT OF MATHEMATICAL SCIENCES, UNIVERSITY OF ALBERTA, EDMONTON, ALBERTA, CANADA T6G 2G1

Current address: Department of Mathematics, Vanderbilt University, Nashville, Tennessee 37240

E-mail address: kkopotun@math.vanderbilt.edu

SCHOOL OF MATHEMATICAL SCIENCES, SACKLER FACULTY OF EXACT SCIENCES, TEL AVIV UNIVERSITY, TEL AVIV 69978, ISRAEL AND DEPARTMENT OF MATHEMATICS, UNIVERSITY OF SOUTH CAROLINA, COLUMBIA, SOUTH CAROLINA 29208

E-mail address: leviatan@math.tau.ac.il

INSTITUTE OF MATHEMATICS, NATIONAL ACADEMY OF SCIENCES OF UKRAINE, KYIV 252601, UKRAINE

E-mail address: shevchuk@dad.imath.kiev.ua