

## A PROBLEM OF PRESCRIBING GAUSSIAN CURVATURE ON $S^2$

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ABSTRACT. A class of functions  $K(x) = K(x_1, x_2, x_3)$  and the corresponding solutions of

$$\Delta u + K(x)e^{2u} = 1$$

are obtained as a special case of the solutions of

$$\Delta^m u + K(x)e^{au} = f(x), \quad x = (x_1, x_2, \dots, x_n),$$

where  $\Delta^m$  is defined as  $\Delta(\Delta^{m-1})$ .

On the two-sphere  $S^2 = \{x \in R^3 | x_1^2 + x_2^2 + x_3^2 = 1\}$  with metric  $ds_0^2 = dx_1^2 + dx_2^2 + dx_3^2$ , if the metric is conformally changed to  $ds^2 = e^{2u} ds_0^2$ , then the Gaussian curvature  $K(x)$  of the new metric is determined by the equation

$$(1) \quad \Delta u + K(x)e^{2u} = 1, \quad x \in S^2,$$

where  $\Delta$  denotes the Laplacian relative to the metric  $ds_0^2$ .

The question raised by L. Nirenberg is: Which functions  $K(x)$  can be prescribed so that (1) has a solution  $u$ ?

Integrating (1) over the whole sphere, we get

$$\int_{S^2} K e^{2u} d\mu = 4\pi,$$

where  $d\mu$  denotes the surface measure on  $S^2$ . Thus, an obvious necessary condition is that  $K$  must be positive somewhere. Another necessary condition was found by Kazdan and Warner [3] via integration by parts. Moser [4] proved that if  $K$  is an even function on  $S^2$ , then (1) has a solution. In [1], Cheng and Smoller considered the case of rotationally symmetric functions  $K$ .

The purpose of this note is to show that a class of functions  $K$  and the corresponding solutions can be produced by means of elementary arguments. We first prove the following result:

**Theorem 1.** *If  $a > 0$  is an arbitrary constant and the functions  $K(x)$  and  $f(x)$  are positive and such that*

$$(2) \quad \Delta^m \ln \left( \frac{K(x)}{f(x)} \right) = 0, \quad x = (x_1, x_2, \dots, x_n),$$

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then the solution of

$$(3) \quad \Delta^m u + K(x)e^{au} = f(x)$$

is given by

$$(4) \quad u = \frac{1}{a} \ln \left( \frac{f(x)}{K(x)} \right).$$

*Proof.* We divide (3) by  $f(x)$  and write it as

$$(5) \quad \frac{1}{f(x)} \Delta^m u + e^{au + \ln \left( \frac{K(x)}{f(x)} \right)} = 1.$$

Now by the change of variables

$$(6) \quad au + \ln \left( \frac{K(x)}{f(x)} \right) = \nu$$

and with the help of (2), we obtain

$$(7) \quad \Delta^m u = \frac{1}{a} \Delta^m \nu.$$

Thus the equation (5) reduces to

$$(8) \quad \frac{1}{af(x)} \Delta^m \nu + e^\nu = 1.$$

Clearly,  $\nu = 0$  is a solution of (8). We then get from (6)

$$u = \frac{1}{a} \ln \left( \frac{f(x)}{K(x)} \right).$$

This completes the proof.  $\square$

If in Theorem 1 we choose  $m = 1$ ,  $a = 2$ ,  $n = 3$  and  $f(x) = 1$ , then we have

**Theorem 2.** *If the function  $K(x) = K(x_1, x_2, x_3)$  is positive and  $\ln(K(x))$  is harmonic, then  $u = \frac{1}{2} \ln \left( \frac{1}{K(x)} \right)$  is a solution of (1).*

*Remark.* Evidently  $u = \frac{1}{a} \ln \left( \frac{f(x)}{K(x)} \right)$  is also a solution of the nonlinear Dirichlet problem  $\Delta u + K(x)e^{au} = f(x)$  in  $D$  and  $u = 0$  on  $\partial D$  as long as  $f(x) = K(x)$  on  $\partial D$  and  $\ln \left( \frac{K(x)}{f(x)} \right)$  is harmonic in  $D$ .

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