

UNIFORM SUBELLIPTIC ESTIMATES ON SCALED CONVEX DOMAINS OF FINITE TYPE

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ABSTRACT. We show that a uniform subelliptic estimate for the $\bar{\partial}$ -Neumann problem holds on a certain family of convex domains of finite type.

Let Ω be a smoothly bounded convex domain and let $p \in b\Omega$ be a point of finite type. In this note we show that a uniform subelliptic estimate for the $\bar{\partial}$ -Neumann problem on $(0, 1)$ -forms holds on the family of rescaled domains associated to Ω as defined in [Mc1]. Uniformity here means that the constituents of the subelliptic estimate (the constant on the right hand side, the Sobolev index, the size of the neighborhood) can be chosen so that the estimate holds, with these constituents, on every domain in the rescaled family.

This result was earlier stated in [Mc1] as Proposition 4.1. While the argument given there is substantially correct, the proof of Proposition 4.1 used a plurisubharmonic constructed in Proposition 3.1 of [Mc1] and there is a gap in the proof of Proposition 3.1. This error was kindly pointed out to the author by Yves Dupain. The essential function in that proposition, ϕ , is correctly constructed; the gap occurs when the support of ϕ is cut-down to the polydisc $P_\epsilon(q)$ by using the isotropic support functions borrowed from [FoSi]. As we will indicate below, one way to repair the proof of Proposition 3.1 is to substitute the recently obtained non-isotropic support functions in [DiFo] for the isotropic support functions; the remainder of the proof of Proposition 3.1 is then as given in [Mc1].

However, the compactly supported plurisubharmonic functions of Proposition 3.1 in [Mc1] are not necessary for demonstrating that a uniform subelliptic estimate holds on the rescaled domains nor are they required for the proof of the main results in [Mc1], i.e. the estimates on the Bergman kernel, associated to Ω , and its derivatives. Once a uniform subelliptic is known to hold, all the results in [Mc1] are valid as one may simply replace the functions of Proposition 3.1 by the function ϕ mentioned above in all proofs.

Because of the confusion our error has caused and because several authors have used our Bergman kernel estimates for other applications, e.g. [Cum1], [Cum2], [KrLi], [McSt], it seems important to clarify the situation and directly establish the foundational inequality. We take this opportunity to give two separate arguments which show that a uniform subelliptic estimate holds on the rescaled domains.

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PRELIMINARIES

We fix notation and recall some results from [Mc1]. Throughout, $\Omega \subset \subset \mathbb{C}^n$ is a smoothly bounded, convex domain of finite type M defined by a real-valued function r with convex infralevel sets. We recall the definition of finite type. If g is a sufficiently smooth function defined in a neighborhood of a point $p \in \mathbb{C}^n$, we denote the order of g at p by $\nu_p(g)$; usually p will be understood in context and we will drop the subscript. For a mapping $G : \mathbb{C}^n \rightarrow \mathbb{C}^m$ defined near p , $\nu(G)$ will denote the minimum order of vanishing of the components of G . The D'Angelo 1-type of $p \in b\Omega$ is defined as

$$(1) \quad \Delta_1(p) = \sup \left\{ \frac{\nu_p(r \circ \gamma)}{\nu_0(\gamma)} : \gamma : \mathbb{C} \rightarrow \mathbb{C}^n, \gamma(0) = p, \gamma \text{ complex analytic} \right\}.$$

The notion of finite type simplifies in the convex case. Let L be an arbitrary complex line through the origin in \mathbb{C}^n . If λ is a vector such that $s \rightarrow s\lambda$ parameterizes L , we define the order of contact of L with $b\Omega$ at p to be the least positive integer M such that for some a, b with $a + b = M$,

$$(2) \quad |D_s^a D_{\bar{s}}^b r(p + s\lambda)|_{s=0} \neq 0.$$

Denote this order of contact by $\nu_p(r \circ L)$. If we normalize the length of the vectors by, say, requiring that $|\lambda| = 1$, the definition is independent of the choice of λ . In [Mc2], it is shown that $\Delta_1(p) = \sup_L \nu_p(r \circ L)$ on convex domains.

Let $p \in b\Omega$ be temporarily fixed and let U be a small neighborhood of p . If $q \in U \cap \overline{\Omega}$ and $\epsilon > 0$, the coordinate construction in [Mc1] gives coordinates $(z_1^{q,\epsilon}, \dots, z_n^{q,\epsilon})$ centered at q , which are an affine transformation of the standard coordinates on \mathbb{C}^n , in which all the computations simplify. Call these coordinates the (q, ϵ) -extremal coordinates. Associated to these coordinates are positive real numbers $\tau_1(q, \epsilon), \dots, \tau_n(q, \epsilon)$ defined as follows. Let $\tau_1(q, \epsilon) = \epsilon$. Write $(z_1, \dots, z_n) = (z_1^{q,\epsilon}, \dots, z_n^{q,\epsilon})$ and set, for each $2 \leq l \leq M$ and $2 \leq j \leq n$,

$$(3) \quad A_l^j(q) = \max \left\{ \left| \frac{\partial^l}{\partial z_j^a \partial \bar{z}_j^b} r(q) \right| : a + b = l \right\}.$$

Then for $2 \leq j \leq n$,

$$(4) \quad \tau_j(q, \epsilon) = \min \{ (\epsilon / A_l^j(q))^{1/l} : 2 \leq l \leq M \}.$$

The polydisc determined by the numbers $\tau_j(q, \epsilon)$ is denoted

$$P_\epsilon(q) = \{ z : |z_i^{q,\epsilon}| < \tau_i(q, \epsilon), \quad \forall i \}.$$

If λ is a vector in \mathbb{C}^n , we set

$$(5) \quad \sigma(q, \lambda, \epsilon) = \sup \{ D : r(q + s\lambda) - r(q) \leq \epsilon, |s| \leq D \}.$$

The main properties of the quantities above are summarized in the following proposition. The proofs are contained in [Mc1] (see also [McSt] for elaboration). Here, and in the remainder of the note, we use the notation $A \lesssim B$, $A \gtrsim B$, and $A \approx B$ in the same way as [Mc1].

Proposition 1. (i) *If u_1, \dots, u_n are the unit vectors determined by the axes $z_1^{q,\epsilon}, \dots, z_n^{q,\epsilon}$ respectively, and $\lambda = \sum a_i u_i$, $a_i \in \mathbb{C}$, then*

$$\sigma(q, \lambda, \epsilon) \approx \left(\sum_{i=1}^n \frac{|a_i|}{\tau_i(q, \epsilon)} \right)^{-1}.$$

(ii) *There exists a constant $C > 0$, independent of $q^1, q^2 \in U \cap \overline{\Omega}$ and ϵ , so that if $P_\epsilon(q^1) \cap P_\epsilon(q^2) \neq \emptyset$,*

$$P_\epsilon(q^1) \subset C P_\epsilon(q^2).$$

(iii) *For any $d > 0$, there exists a constant $C(d)$, independent of q and ϵ , such that*

$$P_{d\epsilon}(q) \subset C(d) P_\epsilon(q).$$

(iv) *If $q^2 \in P_\epsilon(q^1)$ and λ is arbitrary,*

$$\sigma(q^1, \lambda, \epsilon) \approx \sigma(q^2, \lambda, \epsilon).$$

(v) *For $q^1, q^2 \in U \cap \overline{\Omega}$, define*

$$\mathcal{M}(q^1, q^2) = \inf\{\epsilon : q^2 \in P_\epsilon(q^1)\}.$$

Then \mathcal{M} is a pseudometric, i.e.

$$\begin{aligned} \mathcal{M}(q^1, q^2) &\approx \mathcal{M}(q^2, q^1), \\ \mathcal{M}(q^1, q^2) &\lesssim \mathcal{M}(q^1, q^3) + \mathcal{M}(q^3, q^2). \end{aligned}$$

(vi) *For all j , if $1 > c > 0$,*

$$c^{1/2} \tau_j(q, \epsilon) \leq \tau_j(q, c\epsilon) \leq c^{1/M} \tau_j(q, \epsilon).$$

The domain Ω is rescaled using the coordinates $z^{q,\epsilon}$ and the weights $\tau(q, \epsilon)$. Let q and ϵ be temporarily fixed (for simplicity write (z_1, \dots, z_n) for the (q, ϵ) -extremal coordinates), and define the mapping

$$(z_1, \dots, z_n) = \Phi^{q,\epsilon}(w_1, \dots, w_n) = (\tau_1(q, \epsilon)w_1, \dots, \tau_n(q, \epsilon)w_n).$$

Note that $\Phi^{q,\epsilon}(0) = 0 = (z_1(q), \dots, z_n(q))$. If V is a neighborhood of 0, we define

$$\Omega^{q,\epsilon} \cap V = \{w \in V : \rho_\epsilon(w) < 0\},$$

where

$$(6) \quad \rho_\epsilon(w) = \frac{1}{\epsilon} r \circ \Phi^{q,\epsilon}(w).$$

Finally, we recall the estimate referred to in the title. If U is a neighborhood of $p \in b\Omega$, let $\mathcal{D}^{0,1}(U)$ denote the smooth $(0, 1)$ -forms, supported in U , which satisfy

$$\sum_{j=1}^n \frac{\partial r}{\partial z_j} u_j = 0 \quad \text{on } b\Omega,$$

where $u = \sum u_j d\bar{z}_j$. A subelliptic estimate, of order κ , for the $\bar{\partial}$ -Neumann problem on $(0, 1)$ -forms holds in U if there exists a constant C such that

$$(7) \quad \|u\|_\kappa^2 \leq C(\|\bar{\partial}u\|^2 + \|\vartheta u\|^2 + \|u\|^2), \quad u \in \mathcal{D}^{0,1}(U).$$

Here $\|\cdot\|$ denotes the Euclidean L^2 norm and $\|\cdot\|_\kappa$ denotes the tangential Sobolev norm of order κ .

UNIFORMITY OF TYPE UNDER RESCALING

First, we introduce a measurement related to (3). Let $\lambda \in \mathbb{C}^n$ be a vector and consider the parameterized complex line $s \rightarrow s\lambda$, $s \in \mathbb{C}$. Let $D_s^a = \partial^a / \partial s^a$, $D_{\bar{s}}^b = \partial^b / \partial \bar{s}^b$, and set

$$c_{ab}^\lambda(q) = D_s^a D_{\bar{s}}^b r(q + s\lambda)|_{s=0}.$$

Also define, for $1 \leq l \leq M$,

$$(8) \quad A(q, l, \lambda) = \max \{ |c_{ab}^\lambda(q)| : a + b = l \},$$

and, for $\epsilon > 0$,

$$(9) \quad \theta(q, \lambda, \epsilon) = \min \left\{ \left(\frac{\epsilon}{A(q, l, \lambda)} \right)^{1/l} : 1 \leq l \leq M \right\}.$$

We shall show that $\theta(q, \lambda, \epsilon)$ is comparable to $\sigma(q, \lambda, \epsilon)$ on a convex domain of finite type. First, we recall the following result from [B-N-W]; see also [B-C-D].

Lemma 2. *Let $N \in \mathbb{N}$. There exists a constant $C = C(N)$ such that*

- (a) *If P is a polynomial of degree $\leq N$ which is convex on $[-1, 1]$, $P(x) = \sum_{j=1}^N c_j x^j$, then*

$$\max \{ |P(-x)|, |P(x)| \} \geq C \sum_{j=1}^N |c_j| |x|^j, \quad -1 \leq x \leq 1.$$

- (b) *If P is a polynomial on \mathbb{C} of degree $\leq N$ which is convex on $|z| \leq 1$, $P(z) = \sum_{1 \leq a+b \leq d} c_{ab} z^a \bar{z}^b$, then*

$$\sup_{|z|=h} |P(z)| \geq C \sum_{1 \leq a+b \leq d} |c_{ab}| h^{a+b}, \quad 0 \leq h \leq 1.$$

Proof. The result follows from Lemma 2.1 in [B-N-W]. However, the result there is not written exactly as above and we mention the small modifications which give the stated version.

For (a), let $\mathcal{P}_x^N = \{ P(x) = \sum_{j=1}^N c_j x^j \}$ be the set of all polynomials, of $x \in \mathbb{R}$, of degree $\leq N$ which vanish at 0. Let $C\mathcal{P}_x^N$ be the subset of \mathcal{P}_x^N consisting of elements which are convex on $[-1, 1]$. Consider the following two functionals:

$$\|P\|_1 = \max \{ |P(1)|, |P(-1)| \},$$

$$\|P\|_2 = \sum_{j=1}^N |c_j|.$$

$\|\cdot\|_2$ is obviously a norm on \mathcal{P}_x^N . However, $\|\cdot\|_1$ is a norm on $C\mathcal{P}_x^N$, since $\|P\|_1 = 0$ implies that $P(1) = P(-1) = P(0) = 0$, and convexity then forces $P \equiv 0$. Since \mathcal{P}_x^N is finite dimensional, there exists a constant $C > 0$ such that

$$(10) \quad \|P\|_1 \geq C \|P\|_2, \quad P \in C\mathcal{P}_x^N.$$

If $x \in [-1, 1]$, apply (10) to the polynomial $Q(t) = P(t|x|)$ to obtain (a).

The proof of (b) is basically the same. Let $\mathcal{P}_z^N = \{ P(z) = \sum_{1 \leq a+b \leq N} c_{ab} z^a \bar{z}^b \}$ be the set of all polynomials, of $z \in \mathbb{C}$, of degree $\leq N$ which vanish at 0. Let $C\mathcal{P}_z^N$ be the subset of \mathcal{P}_z^N consisting of elements which are convex on $|z| \leq 1$. The

relevant functionals are: $\|P\|_3 = \sup\{|P(z)| : |z| = 1\}$ and $\|P\|_4 = \sum_{1 \leq a+b \leq d}^N |c_{ab}|$. As before, convexity shows that $\|\cdot\|_3$ is non-degenerate on $C\mathcal{P}_z^N \setminus 0$. The finite dimensionality of \mathcal{P}_z^N and scaling then give (b). \square

Proposition 3. *Let $p \in b\Omega$ and let U be a neighborhood of p such that $\Delta_1(\tilde{p}) \leq M$ for all $\tilde{p} \in U \cap b\Omega$. For all $\epsilon > 0$ sufficiently small and $|\lambda| = 1$, there exist constants such that*

$$\theta(q, \lambda, \epsilon) \approx \sigma(q, \lambda, \epsilon), \quad q \in U.$$

Proof. Restrict r to the line $s \rightarrow s\lambda$, $s \in \mathbb{C}$; for $N \geq 2$ Taylor's theorem gives

$$r(q + s\lambda) - r(q) = \sum_{2 \leq a+b \leq N} c_{ab}^\lambda(q) s^a \bar{s}^b + \mathcal{O}(|s|^{N+1}).$$

Let $N = M$. If $|s| \leq \theta(q, \lambda, \epsilon)$, it follows from (9) and the fact that $\theta(q, \lambda, \epsilon) \lesssim \epsilon^{1/M}$ that $|r(q + s\lambda) - r(q)| \lesssim \epsilon$. Thus, definition (5) implies $\sigma(q, \lambda, \epsilon) \gtrsim \theta(q, \lambda, \epsilon)$.

For the reverse inclusion, let $e = \min\{l : \theta(q, \lambda, \epsilon) = (\frac{\epsilon}{A(q, l, \lambda)})^{1/l}\}$. Letting $h = \theta(q, \lambda, \epsilon)$, Lemma 2 implies

$$\begin{aligned} \sup_{s=r} |r(q + s\lambda) - r(q)| &\gtrsim \sum_{1 \leq a+b \leq M} |c_{ab}^\lambda(q)| \theta(q, \lambda, \epsilon)^{a+b} + \mathcal{O}(\theta(q, \lambda, \epsilon)^{M+1}) \\ &\geq A(q, e, \lambda) \theta(q, \lambda, \epsilon)^e \\ &\geq \epsilon. \end{aligned}$$

Thus, $\sigma(q, \lambda, \epsilon) \lesssim \theta(q, \lambda, \epsilon)$. \square

We mention a simple

Corollary 4. *Let $p \in U \cap b\Omega$ and suppose that there exists a constant C so that for any $\lambda \in \mathbb{C}^n$, $|\lambda| = 1$,*

$$(11) \quad \sigma(p, \lambda, \delta) \leq C\delta^{1/K},$$

for all small $\delta > 0$. Then $\Delta_1(p) \leq K$.

Proof. Let L be an arbitrary complex line parameterized by $s \rightarrow s\lambda$. Proposition 3 and (11) imply that $\theta(p, \lambda, \delta) \lesssim \delta^{1/K}$, for an independent constant. It follows from (9) that $A(p, K, \lambda) \gtrsim 1$, and this implies that the order of contact of L with $b\Omega$ at p is $\leq K$. \square

We now show that the type is not increased by scaling with respect to the τ -structure.

Proposition 5. *There exists a constant $C > 0$ such that: if $q \in U \cap \Omega$, $\epsilon > 0$, and L is a complex line through $0 = \Phi_{q, \epsilon}(q)$, then*

$$|D^\alpha(\rho_\epsilon \circ L)(0)| \geq C$$

for some α , $|\alpha| \leq M$. Thus $0 \in b\Omega_{q, \epsilon}$ is of finite type at most M , independent of q and ϵ .

Proof. It is convenient to extend the definitions of $\sigma(q, \lambda, \epsilon)$ and $\theta(q, \lambda, \epsilon)$ to functions other than r . If f is defined in a neighborhood of $q \in \mathbb{C}^n$, $\lambda \in \mathbb{C}^n$, and $\epsilon > 0$, define

$$(12) \quad \sigma(f; q, \lambda, \epsilon) = \sup\{D : |f(q + s\lambda) - f(q)| \leq \epsilon, |s| \leq D\}.$$

If f is C^∞ near q and $M \in \mathbb{N}$ is given, set

$$A(f; q, l, \lambda) = \max \left\{ |D_s^a D_{\bar{s}}^b f(q + s\lambda)|_{s=0} : 1 \leq l \leq M \right\},$$

and define

$$(13) \quad \theta(f; q, \lambda, \epsilon) = \min \left\{ \left(\frac{\epsilon}{A(f; q, l, \lambda)} \right)^{1/l} : 1 \leq l \leq M \right\}.$$

We shall use the coordinates $(z_1^{q, \epsilon}, \dots, z_n^{q, \epsilon})$ associated to q and ϵ to express all vectors. Let $\lambda = (\lambda_1, \dots, \lambda_n)$ be a vector in \mathbb{C}^n such that $s \rightarrow s\lambda$ parameterizes L and let $\tilde{\lambda} = (\tau_1(q, \epsilon)\lambda_1, \dots, \tau_n(q, \epsilon)\lambda_n)$. For $\delta > 0$, it follows directly from (6) and (12) that

$$\sigma(\rho_\epsilon; q, \lambda, \delta) = \sigma(r; q, \tilde{\lambda}, \delta\epsilon).$$

However (i) and (vi) in Proposition 1 imply

$$\sigma(r; q, \tilde{\lambda}, \delta\epsilon) \approx \left(\sum_{l=1}^n \frac{\tau_l(q, \epsilon)|\lambda_l|}{\tau_l(q, \delta\epsilon)} \right)^{-1} \leq \delta^{1/M}.$$

The result now follows from Corollary 4. \square

A careful examination of the proofs of Theorems 9.1 and 9.2 in [Cat] show that the family of weight constructed in those theorems may be constructed (locally) on each of the domains $\Omega_{q, \epsilon}$ and, because of Proposition 5, the constants involved are independent of q and ϵ . The main result in [Cat] then implies that (7) holds, for a uniform U , C , and κ , on each of the domains $\Omega_{q, \epsilon}$. We point out that the value of κ given by Catlin's construction is rather small; see the introduction in [Cat] for an estimate of its size.

USING NON-ISOTROPIC SUPPORT FUNCTIONS

For $q \in b\Omega$, let N_q denote the unit normal to $b\Omega$ at q . If T_q is a unit tangent vector to $b\Omega$ at q and $s \in \mathbb{C}$, let

$$a_{kl}(q, T_q) = \frac{\partial^{k+l}}{\partial s^k \partial \bar{s}^l} r(q + sT_q)|_{s=0}$$

and set

$$A_j(q, T_q) = \sum_{k+l=j} |a_{kl}(q, T_q)|.$$

Let $B(q, R)$ denote the ball in \mathbb{C}^n centered at q of radius R .

Recently, Diederich and Fornæss proved the following

Theorem ([DiFo]). *There exist constants $C, R > 0$ so that: for every $q \in b\Omega$, there exists a holomorphic function, $S_q(z)$, on $B(q, R)$ satisfying*

- (i) $S_q(q) = 0$,
- (ii) if $z \in \bar{\Omega} \cap B(q, R)$ and $z = aN_q + bT_q$, then

$$\operatorname{Re} S_q(z) \leq -C(|\operatorname{Re} a| + |\operatorname{Im} a|^2 + \sum_{j=2}^M A_j(q, T_q)|b|^j).$$

Fix $q \in b\Omega$, let $\epsilon > 0$, and let (z_1, \dots, z_n) be the (q, ϵ) -extremal coordinates.

From the coordinate construction, $\operatorname{Re} z_1 \leq 0$ in $\overline{\Omega} \cap U$, so $\log z_1$ is well defined locally, and

$$(14) \quad \operatorname{Re}(iz_1^{1/2}) \leq -\frac{1}{2}|z_1|^{1/2}, \quad z \in \overline{\Omega} \cap U.$$

On a small neighborhood of q , contained both in U and in $B(q, R)$, define

$$C_q(z) = iz_1^{1/2} + S_q(z),$$

using the (z_1, \dots, z_n) coordinates.

Proposition 6. *If $z \in (\overline{\Omega} \setminus P_\epsilon(q)) \cap U$, then*

$$\operatorname{Re} C_q(z) \lesssim -\epsilon$$

for a constant independent of q and ϵ .

Proof. Write $z \in (\overline{\Omega} \setminus P_\epsilon(q)) \cap U$ as $z = aN_q + bT_q$, $a, b \in \mathbb{C}$, for T_q some tangent vector. If $|b| \geq c_1\sigma(q, T_q, \epsilon)$ for a small, independent constant c_1 , then

$$\begin{aligned} \operatorname{Re} C_q(z) &\leq \operatorname{Re} S_q(z) \\ &\leq -C \sum_{j=2}^M A_j(q, T_q) |b|^j \\ &\leq -Cc_1 \sum_{j=2}^M A_j(q, T_q) \sigma(q, T_q, \epsilon)^j \\ &\lesssim -\epsilon. \end{aligned}$$

The last inequality follows from (9).

However, if $|b| \leq c_1\sigma(q, T_q, \epsilon)$, then $z \notin P_\epsilon(q)$ implies that $|a| \gtrsim \epsilon$. It follows directly from (14) that

$$\operatorname{Re} C_q(z) \lesssim -\epsilon^{1/2} \ll -\epsilon.$$

This completes the proof. \square

To repair the proof of Proposition 3.1 in [Mc1], start with the function ϕ constructed in the early part of that proposition: ϕ is plurisubharmonic on Ω , $|\phi| \leq 1$ on $\Omega \cap U$, and

$$\sum_{i,j=1}^n \frac{\partial^2 \phi}{\partial z_i \partial \bar{z}_j}(z) \xi_i \bar{\xi}_j \gtrsim \sum_{i=1}^n \frac{|\xi_i|^2}{\tau_i(q, \epsilon)^2}, \quad z \in P_\epsilon(q),$$

where (z_1, \dots, z_n) are the (q, ϵ) -extremal coordinates and the constant is independent of q and ϵ . Also, $A = \phi(q)$ is independent of q and ϵ .

Proposition 6 above shows that $\omega(z) = \frac{1}{K\epsilon} C_q(z)$, for a constant K independent of q and ϵ , satisfies

- (i) $\omega(q) = 0$, and
- (ii) $\omega(z) \leq -1$ if $z \in (\overline{\Omega} \setminus P_\epsilon(q)) \cap U$.

Let χ be a convex, increasing function on \mathbb{R} with the properties $\chi(x) = 0$ if $x < A/2$ and $\chi'(x) > 0$ if $x \geq A/2$. Set $h(z) = \phi(z) + \omega(z)$ and define $F_{q,\epsilon}(z) = \chi \circ h(z)$. Inserting $F_{q,\epsilon}$ into display (3.5) in the proof of Proposition 3.1 and following the rest of the argument in that proof gives the functions claimed in the proposition.

As in Proposition 3.2 of [Mc1], the functions in Proposition 3.1 may be summed to give a certain family of bounded plurisubharmonic functions in a strip near $b\Omega$. Theorem 2.2 in [Cat] then shows that (7) holds with $\kappa = 1/M$ on a neighborhood of each $p \in b\Omega$. To establish (7), with uniform constituents, on the domains $\Omega_{q,\epsilon}$, we use the argument in Proposition 4.1. For clarity, we amplify this argument. Temporarily fix q and ϵ , let $\delta > 0$ be given, and let (z_1, \dots, z_n) be the $(q, \delta\epsilon)$ -extremal coordinates. Let $S (= S(q, \epsilon, \delta))$ be the scaling map in these coordinates with scale factors $\tau_1(q, \epsilon), \dots, \tau_n(q, \epsilon)$:

$$z = S(w) = (\tau_1(q, \epsilon)w_1, \dots, \tau_n(q, \epsilon)w_n).$$

If $F = F_{q,\delta\epsilon}$ is the function given by Proposition 3.1, it follows from (vi) in Proposition 1 that

$$\begin{aligned} \sum_{k,l=1}^n \frac{\partial^2}{\partial w_k \partial \bar{w}_l} (F \circ S)(w) \xi_k \bar{\xi}_l &\gtrsim \sum_{j=1}^n \frac{|\tau_j(q, \epsilon) \xi_j|^2}{\tau_j(q, \delta\epsilon)^2} \\ &\gtrsim \delta^{-\frac{2}{M}} \|\xi\|^2, \quad \text{if } S(w) \in P_{\delta\epsilon}(q). \end{aligned}$$

Furthermore, $F \circ S$ is supported in $\{w : S(w) \in P_{\delta\epsilon}(q)\}$. Note that $S^{-1}(P_{\delta\epsilon}(q)) = \{w : |w_j| \leq \frac{\tau_j(q, \delta\epsilon)}{\tau_j(q, \epsilon)}\}$. The properties in Proposition 1 (ii) and (iii) for the polydiscs $P_\epsilon(q)$ also hold for the sets $S^{-1}(P_{\delta\epsilon}(q))$; this follows by combining (i) and (iv) with (ii) and (iii) in Proposition 1.

Consider the strip near $b\Omega_{q,\epsilon}$ of thickness δ :

$$C_\delta = \{-\delta < \rho_\epsilon < 0\}.$$

It follows from the remarks above (see the proof of Proposition 3.2 in [Mc1]) that $C_\delta \cap V$ may be covered by a finite number of sets $S^{-1}(P_{\delta\epsilon}(q_1)), \dots, S^{-1}(P_{\delta\epsilon}(q_N))$, where $N = N(\delta)$, but where the number of the sets $S^{-1}(P_{\delta\epsilon}(q_j))$ that intersect another $S^{-1}(P_{\delta\epsilon}(q_k))$ is bounded independent of q, ϵ , and δ . Adding up the functions $F_{q_j, \delta\epsilon}$ gives a plurisubharmonic function λ_δ satisfying

- (a) $|\lambda_\delta| \lesssim 1$ on $\Omega_{q,\epsilon} \cap V$,
- (b) $\partial\bar{\partial}\lambda_\delta(z)(\xi, \bar{\xi}) \gtrsim \delta^{-\frac{2}{M}} \|\xi\|^2$, $z \in C_\delta$.

Theorem 2.2 in [Cat] then implies that (7) holds, with $\kappa = 1/M$, uniformly on the domains $\Omega_{q,\epsilon}$.

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