

CHEEGER'S CONSTANT IN BALLS AND ISOPERIMETRIC INEQUALITY ON RIEMANNIAN MANIFOLDS

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ABSTRACT. We prove isoperimetric inequality on a Riemannian manifold, assuming that the Cheeger constant for balls satisfies a certain estimation.

1. INTRODUCTION AND THE MAIN RESULT

The isoperimetric property of a ball, which maximizes the volume for a given surface area, was well known to the ancient Greeks. Nowadays, isoperimetric inequalities have also become a part of Analysis, due to seminal contributions of Lord Rayleigh [12], Faber [4], Krahn [7], Pólya and Szegő [11] et al. For a recent account of isoperimetric inequalities in relation to Analysis, see Chavel [2].

Let M be a Riemannian manifold of dimension n and let $\Omega \subset M$ be an open set with smooth boundary. Denote by $V(\Omega)$ the n -dimensional Riemannian volume of Ω , and by $A(\partial\Omega)$ the $(n-1)$ -dimensional Riemannian area of $\partial\Omega$. Let $\rho(p, q)$ be a distance on M , and let $\rho_p(q)$ be the C^2 distance function from the point $p \in M$, such that $|\nabla\rho_p| \leq 1$ for all $p \in M$.

Denote by $B_r(p)$ the open ball centered at $p \in M$ of radius $r > 0$. The Cheeger constant $\bar{h}(B)$ of a ball $B = B_r(p)$ is defined by

$$(1.1) \quad \bar{h}(B) := \inf_{\Omega \subset B} \frac{A(\partial\Omega)}{V(\Omega)},$$

where inf is taken over all open sets $\Omega \subset B$ with smooth boundaries and compact closure. We say that a function $h(r)$ on an interval $(0, r_{max})$ is a *Cheeger function* if it is positive, decreasing, and for any $p \in M$ and $r \in (0, r_{max})$,

$$(1.2) \quad \bar{h}(B_r(p)) \geq h(r).$$

Here r_{max} is either a positive number or $+\infty$. Our main result is as follows.

Theorem 1.1. *Let M be a Riemannian manifold. Assume that M admits a Cheeger function,*

$$(1.3) \quad h(r) = \frac{n}{r} - h_0(r),$$

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where $h_0(r) \geq 0$ is a continuous function on $(0, r_{max})$, such that

$$(1.4) \quad J := \int_0^{r_{max}} h_0(r) dr < \infty.$$

Then, for any open set $\Omega \subset M$ with smooth boundary and compact closure, such that $V(\Omega) \leq v_{max}$, the following inequality takes place:

$$(1.5) \quad A(\partial\Omega) \geq CV(\Omega)^{1 - \frac{1}{n}},$$

where $C = 4^{-n} \left(\frac{3}{7}\omega_n\right)^{\frac{1}{n}} \exp\left(-\frac{J}{n}\right)$ and v_{max} is given by

$$(1.6) \quad v_{max} = \frac{3}{7}\omega_n r_{max}^n \exp(-J),$$

where ω_n is the volume of the unit ball in \mathbb{R}^n .

Remark 1.2. The case when M admits a Cheeger function $h(r) = \frac{n}{r}$ was considered by Chung, Grigor'yan and Yau [3]. They proved the isoperimetric inequality (1.5) using the method of Michael and Simon [9]; our proof is based on the same approach.

2. THE PROOF

Proof. The proof is divided into three steps.

First step. Fix a open set $\Omega \subset M$ with smooth boundary and compact closure, a point $p \in M$ and define two functions

$$(2.1) \quad \begin{cases} m(r) &= V(\Omega \cap B_r), \\ s(r) &= A(\partial\Omega \cap B_r). \end{cases}$$

where $B_r = B_r(p)$.

Set $\Omega_r = \Omega \cap B_r$ and observe that

$$(2.2) \quad \partial\Omega_r = (\Omega \cap \partial B_r) \cup (\partial\Omega \cap B_r).$$

Since $\Omega_r \subset B_r$, we have by definition of a Cheeger function,

$$(2.3) \quad h(r)V(\Omega_r) \leq A(\partial\Omega_r).$$

Clearly,

$$(2.4) \quad \begin{aligned} A(\partial\Omega_r) &\leq A(\Omega \cap \partial B_r) + A(\partial\Omega \cap B_r) \\ &= m'(r) + s(r), \end{aligned}$$

where $m'(r)$ is the derivative with respect to r . From (2.3) and (2.4) we obtain

$$(2.5) \quad h(r)m(r) \leq s(r) + m'(r)$$

or

$$(2.6) \quad -(m'(r) - h(r)m(r)) \leq s(r).$$

Fix some $a \in (0, r_{max})$ and set

$$(2.7) \quad H(r) := \int_a^r h(t)dt.$$

Note that the function $H(r)$ is a differentiable and increasing function defined on $[0, r_{max}]$ onto $[H_{min}, H_{max}]$, where

$$-\infty \leq H(0) =: H_{min} < H(a) = 0 < H(r_{max}) =: H_{max} \leq \infty.$$

We prove this as follows: we already know that $h(r)$ is a continuous function, so that $H'(r) = h(r) \neq 0$ for all $r \in (0, r_{max})$, and therefore by the Inverse

Function Theorem there exists an inverse function denoted by $H^{-1}(s)$ where $s \in [H_{min}, H_{max}]$. Moreover $H^{-1}(s)$ is a differentiable function in (H_{min}, H_{max}) , with derivative given by

$$(H^{-1})'(s) = \frac{1}{H'(H^{-1}(s))} = \frac{1}{h(H^{-1}(s))} > 0;$$

therefore $H^{-1}(s)$ is also an increasing function.

Multiplying by the factor $F(r) := \exp(-H(r))$ gives the differential inequality

$$(2.8) \quad -\frac{d}{dr}(F(r)m(r)) \leq F(r)s(r).$$

Second step. In the sequel we will use the following lemma, which was proved in [3].

Lemma 2.1. *Let $f(r)$ be an absolutely continuous positive function on $(0, \infty)$. Suppose that for some $r_0 \in (0, \infty)$ and all $r \in (0, r_0)$ the inequality is satisfied:*

$$(2.9) \quad -\frac{d}{dr}f(r) < \frac{1}{r_0}f(4r).$$

Then

$$(2.10) \quad \sup_{(0, r_0)} f < \frac{7}{3} \sup_{(r_0, 4r_0)} f.$$

Assuming that $V(\Omega) < v_{max}$, we obtain

$$(2.11) \quad \ln\left(\frac{7}{3}V(\Omega)\omega^{-1}\right) < H_{max} := H(r_{max}),$$

where $\omega := a^n \omega_n \exp(-\int_0^a h_0(r)dr)$. Indeed we have

$$(2.12) \quad H_{max} := \int_a^{r_{max}} h(r)dr = n \ln\left(\frac{r_{max}}{a}\right) - \int_a^{r_{max}} h_0(r)dr,$$

whence

$$(2.13) \quad \omega \exp(H_{max}) = \omega_n r_{max}^n \exp(-J) = \frac{7}{3}v_{max}.$$

Therefore $V(\Omega) < v_{max}$ implies

$$(2.14) \quad V(\Omega) < \frac{3}{7}\omega \exp(H_{max});$$

hence (2.11) follows. Therefore $\frac{7}{3}V(\Omega)\omega^{-1} \in [H_{min}, H_{max}]$, and we can set

$$(2.15) \quad r_0 := H^{-1}\left(\ln\left(\frac{7}{3}V(\Omega)\omega^{-1}\right)\right).$$

We will prove that there exists $r \in (0, r_0)$ such that

$$(2.16) \quad s(r) \geq \frac{1}{r_0}m(4r)\frac{F(4r)}{F(r)}.$$

Assume on the contrary that (2.16) is false. That means for all $r \in (0, r_0)$,

$$(2.17) \quad F(r)s(r) < \frac{1}{r_0}F(4r)m(4r),$$

which implies by (2.8)

$$(2.18) \quad -\frac{d}{dr}(F(r)m(r)) < \frac{1}{r_0}F(4r)m(4r).$$

Applying Lemma 2.1 to $f(r) = F(r)m(r)$ we conclude that

$$(2.19) \quad \sup_{(0, r_0)} F(r)m(r) < \frac{7}{3} \sup_{(r_0, 4r_0)} F(r)m(r).$$

By definition of F and H , we have

$$(2.20) \quad F(r) = \left(\frac{a}{r}\right)^n \exp\left(-\int_r^a h_0(r)dr\right).$$

Noting that $m(r) \sim \omega_n r^n$ as $r \rightarrow 0$, we obtain from (2.20)

$$(2.21) \quad \lim_{r \rightarrow 0} F(r)m(r) = \omega_n a^n \exp\left(-\int_0^a h_0(r)dr\right) = \omega.$$

Hence, by (2.19) and (2.21),

$$(2.22) \quad \omega < \frac{7}{3} \sup_{(0, r_0)} F(r)m(r).$$

On the other hand, $F(r)$ is decreasing and $m(r) \leq V(\Omega)$, which implies

$$(2.23) \quad \sup_{(r_0, 4r_0)} F(r)m(r) \leq F(r_0)V(\Omega).$$

Combining the above two lines, we obtain

$$(2.24) \quad \omega < \frac{7}{3}F(r_0)V(\Omega).$$

However, by the choice of r_0 ,

$$(2.25) \quad F(r_0) = \exp(-H(r_0)) = \frac{3}{7}V(\Omega)^{-1}\omega,$$

whence $\frac{7}{3}V(\Omega)F(r_0) = \omega$, contradicting (2.24).

Third step. In the previous step we proved that there exists $r \in (0, r_0)$ such that

$$(2.26) \quad A(\partial\Omega \cap B_r) \geq \frac{1}{r_0} \left(\frac{F(4r)}{F(r)}\right) V(\Omega \cap B_{4r}).$$

Since $h(r) \leq \frac{n}{r}$ it follows that

$$(2.27) \quad \frac{F(4r)}{F(r)} = \exp\left(-\int_r^{4r} h(r)dr\right) \geq 4^{-n}.$$

Then by (2.26) and (2.27) we obtain

$$(2.28) \quad A(\partial\Omega \cap B_r) \geq \frac{1}{4^n r_0} V(\Omega \cap B_{4r}).$$

Next we will use the following lemma, proved in [5] (see also [3] and [8]).

Lemma 2.2. *Let (M, d) be a metric space with countable base. Suppose that any point x from a set $\Omega \subset M$ is assigned a metric ball $B_{r_x}(x)$ of radius $r_x \in (0, r_0)$. Then there exists an (at most countable) set $S \subset \Omega$ such that all balls $B_{r_x}(x)$, $x \in S$, are disjoint, whereas the union of the balls $B_{4r_x}(x)$, $x \in S$, covers all the set Ω .*

Let $S = \{x_i\}$ be the countable set given by Lemma 2.2, and set $r_i = r_{x_i}$. We have by (2.26):

$$\begin{aligned}
 A(\partial\Omega) &\geq \sum_i A(\partial\Omega \cap B_{r_i}) \\
 (2.29) \qquad &\geq \sum_i \frac{1}{r_0} \frac{1}{4^n} V(\Omega \cap B_{4r_i}) \\
 &\geq \frac{1}{r_0} \frac{1}{4^n} V(\Omega).
 \end{aligned}$$

To conclude the proof of the theorem, we need to prove that

$$(2.30) \qquad r_0 \leq KV(\Omega)^{\frac{1}{n}},$$

where $K = \left(\frac{7}{3}\right)^{\frac{1}{n}} \omega_n^{-\frac{1}{n}} \exp\left(\frac{J}{n}\right)$.

Indeed we have by definition of r_0 (equation (2.15)),

$$(2.31) \qquad \ln\left(\frac{7}{3}V(\Omega)\omega^{-1}\right) = H(r_0) = n \ln \frac{r_0}{a} - \int_a^{r_0} h_0(r)dr.$$

Therefore,

$$(2.32) \qquad r_0 \leq a \left(\frac{7}{3}V(\Omega)\omega^{-1}\right)^{\frac{1}{n}} \exp\left(\frac{1}{n} \int_a^{r_0} h_0(r)dr\right).$$

Substituting ω , we obtain

$$(2.33) \qquad r_0 \leq \left(\frac{7}{3}\right)^{\frac{1}{n}} \omega_n^{-\frac{1}{n}} \exp\left(\frac{J}{n}\right) V(\Omega)^{\frac{1}{n}},$$

which completes the proof. □

3. EXAMPLES

Example 3.1 (Hadamard-Cartan manifolds). A manifold M is called a Hadamard-Cartan (H-C) manifold, if and only if M is a geodesic complete manifold, simply connected, noncompact and with nonpositive sectional curvature.

Any H-C manifold (including \mathbb{R}^n and \mathbb{H}_κ^n) admits as a Cheeger function $h(r) = \frac{n}{r}$. We prove this as follows: let M be an H-C manifold. Grigory'an [6] and García León [5] report that if M is an H-C manifold and ρ_p denotes a C^2 distance function from the point $p \in M$ such that $|\nabla\rho_p| \leq 1$, then its Laplacian satisfies

$$(3.1) \qquad \Delta\rho_p \geq \frac{n-1}{\rho_p}.$$

Let r_p be the geodesic distance from the point $p \in M$. It is well known that $|\nabla r_p| = 1$; hence by (3.1),

$$(3.2) \qquad \Delta r_p^2 = 2\left(r_p\Delta r_p + |\nabla r_p|^2\right) \geq 2n.$$

Let $r \in (0, r_{max})$ and $\Omega \subset B_r(p)$ be an open set with smooth boundary and compact closure. Hence by (3.2) we obtain

$$(3.3) \qquad \int_\Omega \Delta r_p^2 dV \geq 2nV(\Omega).$$

On the other hand, by the Green’s formula,

$$(3.4) \quad 2r A(\partial\Omega) \geq \int_{\Omega} \Delta r_p^2 dV;$$

thus from equations (3.3) and (3.4) we obtain

$$(3.5) \quad \bar{h}(B_r(p)) \geq \frac{n}{r}.$$

Now let $r_{max} = \infty$ and $h_0(r) = 0, \forall r > 0$. Applying Theorem 1.1, we conclude that if M is an H-C manifold, then the inequality (1.5) is satisfied for all open sets Ω with smooth boundary and compact closure.

Example 3.2. If the curvature of M is allowed to be positive, one should expect a Cheeger function to be smaller than $\frac{n}{r}$. Indeed, \mathbb{S}^2 has a Cheeger function $h(r) = \cot(\frac{r}{2}), 0 < r < \pi$, which is smaller than $\frac{2}{r}$, but the function $h_0 = \frac{2}{r} - \cot(\frac{r}{2})$ is bounded and hence satisfies our condition (1.4). A similar statement is true for \mathbb{S}^n .

Example 3.3 (Surfaces with bounded mean curvature). Let M be a surface in \mathbb{R}^n , let $p, q \in M$ and let $d(p, q)$ be the extrinsic distance. We know that if ρ_p denotes the extrinsic distance function, then $\rho_p \leq r_p$, where r_p denotes the geodesic distance function from the point $p \in M$. Moreover it implies that $|\nabla \rho_p| \leq 1, \forall p \in M$.

If we denote by H the mean curvature vector and we assume that

$$(3.6) \quad \sup |H| \leq K,$$

where the sup runs on all points of $M, 0 < K < \infty$ is a constant and $r_{max} > 0$ is an arbitrary and fixed number. Osserman [10] and Grigor’yan [6] proved that: If ρ_p is the extrinsic distance, shifting x_1, \dots, x_N coordinates in \mathbb{R}^N and taking p as the origin, then

$$(3.7) \quad \begin{aligned} \Delta \rho_p^2 &= 2 \left(\sum_{i=1}^N x_i H_i + \sum_{i=1}^N |\nabla x_i^2| \right) \\ &= 2 \left(\sum_{i=1}^N x_i H_i + n \right), \end{aligned}$$

where H_i means coordinates of the mean curvature vector, and by computation we obtain that it is true that $\sum_{i=1}^N |\nabla x_i^2| = n$. By Schwarz inequality it is obtained that

$$(3.8) \quad \sum_{i=1}^N x_i H_i \leq \rho_p |H|,$$

whence

$$(3.9) \quad \begin{aligned} \Delta \rho_p^2 &\geq 2 \left(n - \sum_{i=1}^N x_i H_i \right) \\ &\geq 2(n - \rho_p |H|). \end{aligned}$$

We already know that $|H| \leq K$, where $K > 0$ is constant. By (3.9), we obtain

$$(3.10) \quad \Delta \rho_p^2 \geq 2(n - K \rho_p).$$

Let us define $\varphi(r)$ by

$$\varphi(r) = n - K r, \quad 0 < r < r_{max},$$

where we take

$$r_{max} = \frac{n}{K} > 0.$$

We will construct a continuous function $h_0 : (0, r_{max}) \rightarrow \mathbb{R}$ such that

- $h_0(r) \geq 0, \forall r \in (0, r_{max})$, and
- $\int_0^{r_{max}} h_0(r) dr \leq J$, for all $p \in M$, where $0 < J < \infty$ is a constant.

Note that the function $\varphi(r)$ is in fact a decreasing and continuous function. Let $r \in (0, r_{max}), p \in M$ and let $\Omega \subset B_r(p)$ be an open set with smooth boundary and compact closure. Hence integrating (3.10) on Ω , and by the fact that $\varphi(r)$ is a decreasing function,

$$(3.11) \quad \int_{\Omega} \Delta \rho_p^2 dV \geq 2 \int_{\Omega} \varphi(\rho_p) dV \geq 2\varphi(r)V(\Omega).$$

On the other hand, by the Green's formula,

$$(3.12) \quad 2r A(\partial\Omega) \geq \int_{\Omega} \Delta \rho_p^2 dV.$$

Hence by (3.11) and (3.12), for all open sets with smooth boundary and compact closure, it is satisfied that

$$(3.13) \quad \frac{A(\partial\Omega)}{V(\Omega)} \geq \frac{\varphi(r)}{r}.$$

We conclude by definition of Cheeger's constant on the ball that

$$(3.14) \quad \bar{h}(B_r(p)) \geq \frac{\varphi(r)}{r} = \frac{n}{r} - K.$$

Let $h_0 : (0, r_{max}) \rightarrow \mathbb{R}$ be the constant function $h_0(r) = K \geq 0$. Thus estimating its integral on $(0, r_{max})$,

$$(3.15) \quad \int_0^{r_{max}} h_0(r) dr = K r_{max} = n =: J < \infty.$$

Now by Theorem 1.1, if $V(\Omega) < v_{max}$, then

$$(3.16) \quad A(\partial\Omega) \geq C V(\Omega)^{1 - \frac{1}{n}},$$

where

$$(3.17) \quad \begin{aligned} C &= 4^{-n} \left(\frac{3}{7}\right)^{\frac{1}{n}} e^{-1}, \\ v_{max} &= \frac{3}{7} \left(\frac{n}{e}\right)^n K^{-n}. \end{aligned}$$

Remark 3.4. On minimal manifolds we already know that $|H| = 0$, and in this case we obtain that $r_{max} = v_{max} = \infty$. Therefore if M is a minimal manifold, then M satisfies the isoperimetric property.

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