

EFFECTIVITY OF DYNATOMIC CYCLES FOR MORPHISMS OF PROJECTIVE VARIETIES USING DEFORMATION THEORY

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ABSTRACT. Given an endomorphism of a projective variety, by intersecting the graph and the diagonal varieties we can determine the set of periodic points. In an effort to determine the periodic points of a given minimal period, we follow a construction similar to cyclotomic polynomials. The resulting zero-cycle is called a dynatomic cycle, and the points in its support are called formal periodic points. This article gives a proof of the effectivity of dynatomic cycles for morphisms of projective varieties using methods from deformation theory.

1. INTRODUCTION

Consider an analytic function $\phi : \mathbb{C}^N \rightarrow \mathbb{C}^N$ given by

$$[z_1, \dots, z_N] \mapsto [\phi_1(z_1, \dots, z_N), \dots, \phi_N(z_1, \dots, z_N)].$$

We can iterate the function ϕ to create a (discrete) dynamical system and denote the n^{th} iterate as $\phi^n = \phi(\phi^{n-1})$. The *periodic points* of ϕ are the points $P \in \mathbb{C}^N$ such that $\phi^n(P) = P$ for some integer n . We call n the *period* of P and the least such n the *minimal period* of P . Denote the coordinate functions of the n^{th} iterate as $\phi^n = [\phi_1^n, \dots, \phi_N^n]$. The set of periodic points of period n , but not necessarily minimal period n , for ϕ is the set of solutions to the system of equations

$$\phi_i^n(z_1, \dots, z_N) = z_i \quad \text{for } 1 \leq i \leq N.$$

To find the points of minimal period n , we could attempt to remove the points of period strictly less than n from this set. In the case of $\phi(z) \in \mathbb{C}[z]$, we can do this through division, as with cyclotomic polynomials. Consider the zeros of

$$(1) \quad \prod_{d|n} (\phi^d(z) - z)^{\mu(\frac{n}{d})}$$

where μ is the Möbius function defined as $\mu(1) = 1$ and

$$\mu(n) = \begin{cases} (-1)^\omega, & n \text{ is square-free with } \omega \text{ distinct prime factors,} \\ 0, & n \text{ is not square-free.} \end{cases}$$

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Two fundamental questions come to mind. First, are the zeros of the resulting function exactly the set of periodic points of minimal period n ? Unfortunately, the answer is no. For example for $\phi(z) = z^2 - \frac{3}{4}$ and $n = 2$ we have

$$\frac{\phi^2(z) - z}{\phi(z) - z} = \left(z + \frac{1}{2}\right)^2$$

but that $-\frac{1}{2}$ is a fixed point. However, it is true that all of the points of minimal period n are among the zeros, demonstrated for single variables polynomials in [8, Theorem 2.4] and for morphisms of projective varieties by the author in [5, Proposition 4.1]. Secondly, does the resulting function have poles as well as zeros? Fortunately, the answer is no, demonstrated in the single variable polynomial case in [8, Theorem 2.5], for automorphisms of curves and automorphisms of \mathbb{P}^N in [9], and for morphisms of projective varieties by the author in [5]. The purpose of this article is to give a new proof of the nonexistence of poles. The deformation argument used here leads to a simplified proof compared to [5] but lacks the detailed multiplicity information that allowed for the additional results presented there.

We now state the problem precisely. Let K be an algebraically closed field and X/K a projective variety of dimension b . Let $\phi : X/K \rightarrow X/K$ be a morphism defined over K . We can iterate the morphism ϕ and consider the resulting dynamical system. As we will require tools from both dynamical systems and algebraic geometry in which the word *cycle* has two different meanings, we adopt the terminology *periodic cycle* to be the points in the orbit of a periodic point and *algebraic zero-cycle* as a formal sum of points with integer multiplicities (only finitely many non-zero). If all of the multiplicities of an algebraic zero-cycle are nonnegative, we call it *effective*. For example, for $\phi \in K[z]$, if the algebraic zero-cycle of periodic points of period n is effective, then the function $\phi^n(z) - z$ has no poles. To generalize construction (1) we follow [9] and consider the graph of ϕ^n in the product variety $X \times X$ defined as

$$\Gamma_n = \{(x, \phi^n(x)) : x \in X\}$$

and the diagonal in $X \times X$ defined as

$$\Delta = \{(x, x) : x \in X\}.$$

Their intersection is precisely the periodic points of period n , and we can determine the multiplicity of points as the multiplicity of the intersection. Denote the intersection multiplicity of Γ_n and Δ at a point $(P, P) \in X \times X$ to be $a_P(n)$ and, when the intersection is proper, the algebraic zero-cycle of periodic points of period n as

$$\Phi_n(\phi) = \sum_{P \in X} a_P(n)(P).$$

Following construction (1), define

$$a_P^*(n) = \sum_{d|n} \mu\left(\frac{n}{d}\right) a_P(d)$$

and

$$\Phi_n^*(\phi) = \sum_{d|n} \mu\left(\frac{n}{d}\right) \Phi_d(\phi) = \sum_{P \in X} a_P^*(n)(P),$$

where μ is the Möbius function defined above.

Definition 1. We call $\Phi_n^*(\phi)$ the n^{th} *dynatomic cycle*¹ and $a_P^*(n)$ the *multiplicity* of P in $\Phi_n^*(\phi)$. If $a_P^*(n) > 0$, then we call P a periodic point of *formal period* n .

Remark. In the one variable polynomial case, Φ_n^* is called a *dynatomic polynomial* and has been studied extensively such as in [7, 8, 11]. For a more complete background and additional references in this area, see [12].

Definition 2. For $n \geq 1$, we say that ϕ^n is *nondegenerate* if Δ and Γ_n intersect properly, in other words, if $\Delta \cap \Gamma_n$ is a finite set of points.

Remark. If ϕ^n is nondegenerate, then ϕ^d is nondegenerate for all $d \mid n$ since $\Delta \cap \Gamma_d \subseteq \Delta \cap \Gamma_n$. Conversely, ϕ may be nondegenerate with ϕ^n degenerate, such as when ϕ is a nontrivial automorphism of a curve with finite order.

We prove the following theorem.

Theorem 3. Let $X \subset \mathbb{P}_K^N$ be a nonsingular, irreducible, projective variety defined over an algebraically closed field K and let $\phi : X \rightarrow X$ be a morphism defined over K . Let P be a point in $X(K)$. For all $n \geq 1$ such that ϕ^n is nondegenerate, $a_P^*(n) \geq 0$.

Recall that we have defined K to be an algebraically closed field, X/K a projective variety of dimension b , and $\phi : X \rightarrow X$ a morphism defined over K . Let $P \in X(K)$ and let R_P be the local ring of $X \times X$ at (P, P) , and let $I_\Delta, I_{\Gamma_n} \subset R_P$ be the ideals of the diagonal Δ and the graph of ϕ^n Γ_n , respectively. We use Serre's definition of intersection multiplicity [4, Appendix A],

$$a_P(n) = i(\Delta, \Gamma_n; P) = \sum_{i=0}^{b-1} (-1)^i \dim_K(\text{Tor}_i(R_P/I_\Delta, R_P/I_{\Gamma_n})).$$

In [5] we first showed that $\text{Tor}_i(R_P/I_\Delta, R_P/I_{\Gamma_n}) = 0$ for $i \geq 1$ and then performed a detailed analysis of $\dim_K(\text{Tor}_0(R_P/I_\Delta, R_P/I_{\Gamma_n}))$ which is the codimension of the ideal

$$\dim_K(\text{Tor}_0(R_P/I_\Delta, R_P/I_{\Gamma_n})) \cong \dim_K(R_P/I_\Delta \otimes R_P/I_{\Gamma_n}) \cong \dim_K(R_P/(I_\Delta + I_{\Gamma_n})).$$

The analysis included a detailed description of the coefficients under iteration of a system of multivariate power series. In the present article, we instead deform a local representation of the map ϕ at each point $P \in \Delta \cap \Gamma_n$ and take the limit of the resulting algebraic zero-cycles. Since effectivity is a local property, we need not consider the existence of a global deformation and are able to take quite simple deformations locally. In the case $X = \mathbb{P}^N$, we could take a similarly simple global deformation since the deformed map will still be an endomorphism of the space. The example in Section 3 is such a case.

To keep this article self-contained, before examining $\text{Tor}_0(R_P/I_\Delta, R_P/I_{\Gamma_n})$ we first repeat the proofs from [5] that $\Phi_n^*(\phi)$ is an algebraic zero-cycle, that $\text{Tor}_i(R_P/I_\Delta, R_P/I_{\Gamma_n}) = 0$ for $i \geq 1$, and that $a_P(n) \geq a_P(1)$ for all $n \in \mathbb{N}$.

2. HIGHER tor-MODULES

Since ϕ^n is nondegenerate, Δ and Γ_n intersect properly. We also know $X \times X$ has dimension $2b$, Δ has dimension b , and Γ_n has dimension b . Consequently, $\Phi_n(\phi)$ is an algebraic zero-cycle. Thus, $\Phi_n^*(\phi)$ is also an algebraic zero-cycle.

¹This term is inspired by “cyclotomic”, much like “Tribonacci” was inspired by “Fibonacci”.

Lemma 4 ([10, Corollary to Theorem V.B.4]). *Let (R, \mathfrak{m}) be a regular local ring of dimension b , and let M and N be two nonzero finitely generated R -modules such that $M \otimes N$ is of finite length. Then $\mathrm{Tor}_i(M, N) = 0$ for all $i > 0$ if and only if M and N are Cohen-Macaulay modules and $\dim M + \dim N = b$.*

Theorem 5. *Let X be a nonsingular, irreducible, projective variety defined over a field K and let $\phi : X \rightarrow X$ be a morphism defined over K such that ϕ^n is nondegenerate. Let $P \in X(K)$. Then $\mathrm{Tor}_i(R_P/I_\Delta, R_P/I_{\Gamma_n}) = 0$ for all $i > 0$.*

Proof. Let $b = \dim X$. Then we have $\dim X \times X = 2b$ and $\dim \Delta = \dim \Gamma_n = b$. The ideals I_Δ and I_{Γ_n} are each generated by b elements and Δ and Γ_n intersect properly. Therefore,

$$\dim_K(R_P/(I_\Delta + I_{\Gamma_n})) = \mathrm{length}(R_P/I_\Delta \otimes R_P/I_{\Gamma_n}) < \infty.$$

Thus, the union of the generators of I_Δ and the generators of I_{Γ_n} are a system of parameters for R_P [10, Proposition III.B.6]. Consequently, since the local ring R_P is Cohen-Macaulay, we can conclude that R_P/I_Δ is Cohen-Macaulay of dimension b [10, corollary to Theorem IV.B.2], and similarly with I_{Γ_n} , to conclude that R_P/I_{Γ_n} is Cohen-Macaulay of dimension b .

We have fulfilled the hypotheses of Lemma 4 and can conclude the result. \square

Recall that we can compute the codimension of an ideal from its leading term ideal:

$$K[[X_1, \dots, X_b]]/I \cong_K \mathrm{Span}(X^v \mid X^v \notin LT(I)).$$

Lemma 6. *Assume ϕ^n is nondegenerate. Then $a_P(n) \geq a_P(1)$ for all $n \in \mathbb{N}$.*

Proof. If P is not a fixed point of ϕ , then the statement is trivial, so assume that $\phi(P) = P$. It is clear that

$$\Delta \cap \Gamma_1 \subseteq \Delta \cap \Gamma_n$$

and we have a local representation of $\phi = [\phi_1, \dots, \phi_b]$ at the fixed point P . Iterating this representation involves taking combinations of the ϕ_i , and hence these combinations are all elements of the original ideal I_{Γ_1} . Hence, we have

$$I_{\Gamma_n} + I_\Delta \subseteq I_{\Gamma_1} + I_\Delta.$$

Therefore,

$$LT(I_{\Gamma_n} + I_\Delta) \subseteq LT(I_{\Gamma_1} + I_\Delta),$$

which implies $a_P(n) \geq a_P(1)$. \square

3. PROOF OF THEOREM 3

The method is to deform the local intersection at P into a flat family of algebraic zero-cycles whose generic member is a transverse intersection. Then we take the limit of these algebraic zero-cycles to conclude the theorem. The main references are flat families [2, §6], families of algebraic cycles [3, §§10–11], and basic analytic geometry in several complex variables [1, §1.4].

Effectivity is a local property, so consider a point $P \in X(K)$. In what follows, we work over the completion $\widehat{R}_P \cong K[[x_1, \dots, x_b, y_1, \dots, y_b]] = K[[\mathbf{x}, \mathbf{y}]]$ so that we may consider our problem over a local power series ring. Locally at P we may write $\phi(\mathbf{x})$ as a system of power series denoted $[\phi_1(\mathbf{x}), \dots, \phi_b(\mathbf{x})]$. We wish to deform an algebraic zero-cycle, so we consider $Z_{n,P}$ to be the algebraic zero-cycle obtained by intersecting the local equations for the diagonal $(x_1 - y_1, \dots, x_b - y_b)$ and the

graph $(y_1 - \phi_1^n(\mathbf{x}), \dots, y_b - \phi_b^n(\mathbf{x}))$ as analytic varieties. We have now reduced the problem to a multiplicity question on an analytic variety $Z_{n,P}$ and we can deform in this situation without concern for the global structure on X . We deform $Z_{n,P}$ by considering the iterates of

$$\phi(\mathbf{x}, t) = [\phi_1(\mathbf{x}) + t, \dots, \phi_b(\mathbf{x}) + t]$$

for a parameter $t \in \mathbb{A}_K^1$ and their graphs denoted $\Gamma_n(t)$. Note that $\phi^n(\mathbf{x}, 0) = \phi^n(\mathbf{x})$. We denote the deformed family as $Z_{n,P}(t)$. Notice that we are deforming and then iterating so that $Z_{n,P}(t)$ is associated to $(\phi(\mathbf{x}, t))^n$. It is important that P be a fixed point so that a local representation of ϕ^n at P is given by the iterate of the local representation of ϕ at P . Before beginning the proof, we illustrate the method with the one-dimensional polynomial example mentioned in the introduction.

Example. Consider $\phi(x) = x^2 - 3/4$. The fixed points are determined as

$$\phi(x) - x = (x + 1/2)(x - 3/2) = 0$$

and are both of multiplicity one: $a_{-1/2}(1) = a_{3/2}(1) = 1$. After deforming, the fixed points as functions of t are determined as

$$\phi(x, t) - x = x^2 - x - 3/4 + t = 0$$

with two distinct multiplicity one solutions, unless $t = 1$:

$$P_1(t) = \frac{1}{2}(1 + 2\sqrt{1-t}) \quad \text{and} \quad P_2(t) = \frac{1}{2}(1 - 2\sqrt{1-t}).$$

The 2-periodic points are determined as

$$(2) \quad \phi^2(x) - x = (x + 1/2)^3(x - 3/2) = 0.$$

The solutions are not distinct and they are both fixed points. In particular, $a_{-1/2}(2) = 3$ and $a_{3/2}(2) = 1$. This causes $a_{-1/2}^*(2) = 2$ even though $-1/2$ is a fixed point. It is this higher multiplicity counting that makes the statement of effectivity interesting and the complication that this deformation argument seeks to circumvent. After deforming, the 2-periodic points are determined as

$$\phi^2(x, t) - x = x^4 + (2t - 3/2)x^2 - x + (t^2 - 1/2t - 3/16) = 0$$

with four distinct multiplicity one solutions, unless $t = 1$ or $t = 0$:

$$\begin{aligned} P_1(t) &= \frac{1}{2}(1 + 2\sqrt{1-t}), & P_2(t) &= \frac{1}{2}(1 - 2\sqrt{1-t}), \\ P_3(t) &= -\frac{1}{2}(1 - 2\sqrt{-t}), & P_4(t) &= -\frac{1}{2}(1 + 2\sqrt{-t}). \end{aligned}$$

There are two main facts to notice about these four points. First, as $t \rightarrow 0$, the points correspond in multiplicity to the undeformed system (2):

$$P_1(0) = \frac{3}{2}, \quad P_2(0) = P_3(0) = P_4(0) = -\frac{1}{2}.$$

Secondly, $P_1(t)$ and $P_2(t)$ are fixed points, while $P_3(t)$ and $P_4(t)$ are periodic points with minimal period 2 and all four occur with multiplicity one. Examining the dynatomic multiplicities we have

$$\begin{aligned} a_{P_1(t)}^*(2) &= a_{P_2(t)}^*(2) = 0, \\ a_{P_3(t)}^*(2) &= a_{P_4(t)}^*(2) = 1 \end{aligned}$$

for a total of

$$a_{-1/2}^*(2) = a_{P_2(t)}^*(2) + a_{P_3(t)}^*(2) + a_{P_4(t)}^*(2) = 2$$

as computed directly above.

We start by showing that $Z_{n,P}(t)$ is a flat family using the following local criteria for flatness.

Lemma 7 ([2, Corollary 6.9]). *Suppose that (R, \mathfrak{m}) is a local Noetherian ring. Let $x \in R$ be a nonzero divisor on R and let M be a finitely generated R -module. If x is a nonzero divisor on M , then M is flat over R if and only if M/xM is flat over $R/(x)$.*

Proposition 8. *Let $n \in \mathbb{N}$ be such that ϕ^n is nondegenerate and let $P \in X(K)$. The family $Z_{n,P}(t)$ is flat over $K[[t]]$.*

Proof. Recall that $Z_{n,P} = a_P(n)(P)$ with $a_P(n) = \dim_K \widehat{R}_P / (I_{\Gamma_n} + I_\Delta)$. Thus, to show flatness for $Z_{n,P}(t)$, we need to show flatness for $\widehat{R}_P[[t]] / (I_{\Gamma_n(t)} + I_\Delta)$.

We apply Lemma 7 with $M = \widehat{R}_P[[t]] / (I_{\Gamma_n(t)} + I_\Delta)$, $R = K[[t]]$, and $x = t$.

We see that $M/tM \cong \widehat{R}_P / (I_{\Gamma_n} + I_\Delta)$ from our choice of deformation and $K[[t]]/(t) \cong K$. Thus, M/tM is a flat K -module since it is a finite dimensional K -vector space by the nondegeneracy of ϕ^n . Now, we just need to show that t is not a zero divisor on M .

Assume that t is a zero divisor. Then there exists an $m \in M$ with $m \neq 0$ such that $tm = 0$. In particular there exist $a_i \in K[[t]]$ such that

$$tm = \sum_{i=1}^{2b} a_i m_i,$$

where the m_i are the generators of $(I_{\Gamma_n(t)} + I_\Delta)$. Specializing to $t = 0$, we must have

$$\left(\sum_{i=1}^{2b} a_i m_i \right)_{t=0} = 0,$$

with $(m_i)_{t=0} \neq 0$ for all i . Assume that $(a_i)_{t=0} = 0$ for all i . Then we have

$$\sum_{i=1}^{2b} \frac{a_i}{t} m_i = m$$

with $\frac{a_i}{t} \in K[[t]]$. This contradicts $m \notin (I_{\Gamma_n(t)} + I_\Delta)$. So we have at least one $(a_i)_{t=0} \neq 0$ and, hence, there is a relation among the $(m_i)_{t=0}$, which contradicts the assumption that ϕ^n is nondegenerate. \square

Recall that P is a (possibly high multiplicity) solution to the set of equations $\phi_i(\mathbf{x}) = x_i$. We have perturbed this system to obtain the set of equations $\phi_i(\mathbf{x}, t) = x_i$ for $i = 1, \dots, b$. We will use the Weierstrass Preparation Theorem to obtain distinct solutions $P_j(t)$ as power series in t for some set of $j = 1, \dots, a_P(n)$.

Proof of Theorem 3. We fix n and consider each point $P \in X(K)$. If P is not periodic of period n , then we have $a_d(P) = 0$ for all $d \mid n$ and hence $a_P^*(n) = 0$. So we may assume that P is periodic of some minimal period $m \mid n$. Replacing P with $\phi^m(P)$, ϕ with ϕ^m , and n with n/m , we may assume that P is a fixed point of

ϕ . Working locally, we consider the family of algebraic zero-cycles $Z_{n,P}(t)$ defined above. By Proposition 8 this is a flat family and, thus, by [6] we have that

$$\lim_{t \rightarrow 0} Z_{n,P}(t) = Z_{n,P}(0) = Z_{n,P}.$$

In particular, if the $P_j(t)$ are the points in the support of $Z_{n,P}(t)$ which go to P as $t \rightarrow 0$, then if we write the algebraic zero-cycle as

$$Z_{n,P}(t) = \sum_j a_{P_j(t)}(n)(P_j(t)),$$

we have that

$$a_P(n) = \sum_j a_{P_j(t)}(n) \quad \text{and} \quad a_P^*(n) = \sum_j a_{P_j(t)}^*(n).$$

Note that each $P_j(t)$ is periodic with minimal period dividing n and there are finitely many such $P_j(t)$; in fact by flatness, there are $a_P(n)$ of them counted with multiplicity. From standard results in the theory of analytic varieties in several complex variables concerning the Weierstrass Preparation Theorem and multiple roots of Weierstrass polynomials [1, §1.4], we know that the set of t values for which there is a solution $P_j(t)$ with multiplicity greater than one is a thin set. In particular, generically there are $a_P(n)$ distinct $P_j(t)$ which satisfy $P_j(0) = P$. Finally, $a_P(d) \leq a_P(n)$ for $1 \leq d \leq n$ by Lemma 6. Thus, by avoiding a thin set of t , for each $d \mid n$ each $P_j(t)$ occurs with multiplicity 1 in $Z_{d,P}(t)$ if it has minimal period dividing d and multiplicity 0 otherwise. Using properties of the Möbius function, we compute for $P_j(t)$ with minimal period $m < n$

$$a_{P_j(t)}^*(n) = \sum_{d \mid n} \mu\left(\frac{n}{d}\right) a_{P_j(t)}(d) = \sum_{d \mid \frac{n}{m}} \mu\left(\frac{n}{dm}\right) a_{P_j(t)}(d) = \sum_{d \mid \frac{n}{m}} \mu\left(\frac{n}{dm}\right) = 0.$$

For $P_j(t)$ with minimal period n we compute

$$a_{P_j(t)}^*(n) = \sum_{d \mid n} \mu\left(\frac{n}{d}\right) a_{P_j(t)}(d) = a_{P_j(t)}(n) = 1.$$

Thus, any $P_j(t)$ with minimal period strictly less than n must contribute 0 to $a_P^*(n)$ and any $P_j(t)$ with minimal period n must contribute positively. In particular, $a_P^*(n) \geq 0$. \square

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