

NON-SINGULAR SOLUTIONS OF TWO-POINT PROBLEMS, WITH MULTIPLE CHANGES OF SIGN IN THE NONLINEARITY

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ABSTRACT. We prove that positive solutions of the two-point boundary value problem

$$u''(x) + \lambda f(u(x)) = 0, \quad \text{for } -1 < x < 1, \quad u(-1) = u(1) = 0,$$

satisfying $\max u = u(0) > \gamma$, are non-singular, provided that $f(u)$ is predominantly negative for $u \in (0, \gamma]$, and superlinear for $u > \gamma$. This result adds a solution curve without turns to whatever is known about the solution set for $u(0) \in (0, \gamma)$. In particular, we combine it with the well-known cases of parabola-like, or S -shaped solution curves.

1. INTRODUCTION

We study global solution curves, and the exact multiplicity of positive solutions of the Dirichlet problem

$$(1.1) \quad u''(x) + \lambda f(u(x)) = 0, \quad \text{for } -1 < x < 1, \quad u(-1) = u(1) = 0,$$

where λ is a positive parameter. Since positive solutions are symmetric with respect to the midpoint of the interval, it is convenient to pose the problem on the interval $(-1, 1)$. Our problem is autonomous, and so this does not restrict the generality. Any positive solution $u(x)$ is an even function, and $u'(x) < 0$ for $x \in (0, 1)$, so that $u'(0) = 0$, and $u(0) = \max_{[-1, 1]} u(x)$. This follows immediately by observing that any solution is symmetric with respect to any of its critical points (of course, the theorem of B. Gidas, W.-M. Ni, and L. Nirenberg [1] is also applicable here). We shall need the corresponding linearized problem

$$(1.2) \quad w'' + \lambda f'(u(x))w = 0, \quad \text{for } -1 < x < 1, \quad w(-1) = w(1) = 0.$$

The following lemma is known; see, e.g., P. Korman [3] or [4]. We include its proof for completeness.

Lemma 1.1. *Assume $f(u) \in C^1(\bar{R}_+)$. Let $u(x)$ be a positive solution of (1.1), with*

$$(1.3) \quad u'(1) < 0.$$

If the problem (1.2) admits a non-trivial solution, then this solution does not change sign, i.e., we may assume that $w(x) > 0$ on $(-1, 1)$.

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Proof. The function $u'(x)$ also satisfies the linear differential equation in (1.2). By the condition (1.3), $u'(x)$ is not a constant multiple of $w(x)$. Hence, by Sturm's comparison theorem, the roots of $u'(x)$ are interlaced with those of $w(x)$. If $w(x)$ had a root ξ inside the right half-interval $(0, 1)$, then $u'(x)$ would have to vanish on $(\xi, 1)$, which is impossible. \square

We remark that the condition (1.3) holds automatically if $f(0) \geq 0$, as follows by Hopf's boundary lemma.

There are some standard conditions for solutions of (1.1) to be *non-singular*, which means that the problem (1.2) has only the trivial solution. (Non-singular solutions of (1.1) can be continued in λ , in view of the implicit function theorem.) Namely, if $f(0) \geq 0$, and

$$f'(u) > \frac{f(u)}{u} \quad (\text{or if } f'(u) < \frac{f(u)}{u}), \quad \text{for all } u > 0,$$

then the problem (1.2) has only the trivial solution. Indeed, writing the equation (1.1) in the form $u'' + \frac{f(u)}{u}u = 0$, we conclude by Sturm's comparison theorem that there is a root of $w(x) \not\equiv 0$ between the roots ± 1 of $u(x)$, which is impossible, since $w(x)$ is positive. In [3] we proved the following result (a similar result was previously given by R. Schaaf [8]).

Theorem 1.1. *Assume that $f(u) \in C^1(\bar{R}_+)$, $f(u) < 0$ on $(0, \gamma)$, while $f(u) > 0$ on (γ, ∞) , for some $\gamma > 0$. Assume also that*

$$f'(u) > \frac{f(u)}{u}, \quad \text{for all } u > \gamma.$$

Then any positive solution of (1.1), satisfying (1.3), is non-singular, i.e., the problem (1.2) admits only the trivial solution.

Recall that the solution set of (1.1) can be faithfully represented by curves in the $(\lambda, u(0))$ plane, with $u(0)$ being the maximum value of the solution $u(x)$; see e.g., [3], or [4]. The above theorem implies that there are no turns on the solution curves, once $u(0) > \gamma$. What is remarkable here is that no additional assumptions are imposed on $f(u)$ on the interval where it is negative. In this note we present a much stronger result, replacing the condition $f(u) < 0$ on $(0, \gamma)$ by an integral condition. The new result adds a solution curve without turns to whatever is known about the solution set for $u(0) \in (0, \gamma)$, thus providing exact multiplicity results in cases where there are exactly three or exactly four solutions; see the bifurcation diagrams for Theorems 3.2, 3.3, and 3.4. Such exact multiplicity results are rare.

2. THE MAIN RESULT

As usual, we denote $F(u) = \int_0^u f(t) dt$.

Theorem 2.1. *Assume that $f(u) \in C^1(\bar{R}_+)$, and for some $\gamma > 0$, it satisfies*

$$(2.1) \quad f(\gamma) = 0, \quad \text{and } f(u) > 0 \text{ on } (\gamma, \infty),$$

$$(2.2) \quad f'(u) > \frac{f(u)}{u}, \quad \text{for } u > \gamma,$$

$$(2.3) \quad F(\gamma) - F(u) = \int_u^\gamma f(t) dt < 0, \quad \text{for } u \in (0, \gamma).$$

Then any positive solution of (1.1), satisfying

$$(2.4) \quad u(0) > \gamma, \text{ and } u'(1) < 0,$$

is non-singular, which means that the problem (1.2) admits only the trivial solution.

Proof. Assume, on the contrary, that the problem (1.2) admits a non-trivial solution $w(x) > 0$. Let $x_0 \in (0, 1)$ denote the point where $u(x_0) = \gamma$, so that the condition (2.2) holds for $0 \leq x < x_0$. From the equations (1.1) and (1.2), we get

$$(w'u - wu')' = - \left[f'(u) - \frac{f(u)}{u} \right] uw < 0, \text{ for } 0 \leq x < x_0.$$

Integrating this over $(0, x_0)$,

$$(2.5) \quad w'(x_0)u(x_0) - w(x_0)u'(x_0) < 0.$$

We claim that

$$(2.6) \quad (x_0 - 1)u'(x_0) - u(x_0) > 0.$$

Indeed, denoting $q(x) \equiv (x - 1)u'(x) - u(x)$, we see that $q(1) = 0$, while

$$q'(x) = (x - 1)u''(x) = (x - 1)[u'(x) - u'(x_0)]'.$$

We integrate this formula over $(x_0, 1)$, and perform integration by parts

$$-q(x_0) = \int_{x_0}^1 (x - 1)[u'(x) - u'(x_0)]' dx = - \int_{x_0}^1 [u'(x) - u'(x_0)] dx,$$

so that

$$q(x_0) = \int_{x_0}^1 [u'(x) - u'(x_0)] dx > 0,$$

which is the same as the desired inequality (2.6), provided we can prove that

$$(2.7) \quad u'(x) - u'(x_0) > 0, \text{ for } x \in (x_0, 1).$$

The "energy" $E(x) = \frac{1}{2}u'^2(x) + F(u(x))$ is easily seen to be constant, so that $E(x) = E(x_0)$, or

$$\frac{1}{2}u'^2(x) + F(u(x)) = \frac{1}{2}u'^2(x_0) + F(\gamma).$$

By the assumption (2.3),

$$\frac{1}{2} [u'^2(x) - u'^2(x_0)] = F(\gamma) - F(u(x)) < 0, \text{ for } x \in (x_0, 1).$$

It follows that $u'^2(x) < u'^2(x_0)$, justifying (2.7), and then giving (2.6).

Next, we observe that the function $u''(x)w(x) - u'(x)w'(x)$ is constant over $[0, 1]$. (Just differentiate this function, and use the corresponding equations.) Evaluating this function at $x = x_0$, and at $x = 1$, and observing that $u''(x_0) = -f(u(x_0)) = -f(\gamma) = 0$, we have

$$(2.8) \quad -u'(x_0)w'(x_0) = -u'(1)w'(1),$$

which implies, in particular, that

$$(2.9) \quad w'(x_0) < 0.$$

Using the assumption (2.4), we also have

$$(2.10) \quad u'(x)w'(x) - u''(x)w(x) = u'(1)w'(1) > 0, \text{ for all } x \in (0, 1).$$

The function $z(x) \equiv xu'(x)$ is easily seen to satisfy

$$z'' + f'(u)z = -2f.$$

Combining this equation with (1.2), we express

$$(z'w - w'z)' = -2fw = -2[F(u(x)) - F(\gamma)]' \frac{w(x)}{u'(x)}.$$

Integrating this over $(x_0, 1)$, we get (observe that $z' = u' + xu''$, $z'(x_0) = u'(x_0)$)

$$\begin{aligned} M &\equiv -u'(1)w'(1) - u'(x_0)w(x_0) + x_0u'(x_0)w'(x_0) \\ &= -2 \int_{x_0}^1 [F(u(x)) - F(\gamma)]' \frac{w(x)}{u'(x)} dx \\ &= 2 \int_{x_0}^1 [F(u(x)) - F(\gamma)] \frac{w'(x)u'(x) - w(x)u''(x)}{u'^2(x)} dx > 0, \end{aligned}$$

in view of (2.3) and (2.10).

On the other hand, using (2.8) and (2.5), and then (2.6) and (2.9), we have

$$\begin{aligned} (2.11) \quad M &< -u'(x_0)w'(x_0) - w'(x_0)u(x_0) + x_0u'(x_0)w'(x_0) \\ &= w'(x_0) [(x_0 - 1)u'(x_0) - u(x_0)] < 0, \end{aligned}$$

a contradiction. □

Observe that we only needed $\int_u^\gamma f(t) dt \leq 0$ for $u \in (0, \gamma)$, with the inequality being strict on a set of positive measure.

3. APPLICATIONS

Our condition (2.3) implies that $F(\gamma) \leq 0$. Let $\gamma_1 \geq \gamma$ be defined by

$$F(\gamma_1) = 0.$$

(In case $F(\gamma) = 0$, we have $\gamma_1 = \gamma$.) Our condition (2.2) implies that $\frac{f(u)}{u}$ is increasing for $u > \gamma$, and so the limit $L = \lim_{u \rightarrow \infty} \frac{f(u)}{u} \leq \infty$ exists.

We consider positive solutions of the problem

$$(3.1) \quad u''(x) + \lambda f(u(x)) = 0, \text{ for } -1 < x < 1, \quad u(-1) = u(1) = 0,$$

where λ is a positive parameter. Recall that $u(0)$ gives the maximum value of any solution. Moreover, the value of $u(0)$ gives the global parameter on the solution curves, uniquely identifying the solution pair $(\lambda, u(x))$; see e.g., [3]. Hence, the set of positive solutions of (3.1) can be represented by curves in the $(\lambda, u(0))$ plane, giving us the *solution curves*.

Theorem 3.1. *Assume that $f(u) \in C^1(\bar{R}_+)$; satisfies the conditions (2.1), (2.2) and (2.3). Then all positive solutions of (3.1), satisfying $u(0) > \gamma$, lie on a unique solution curve joining (δ, ∞) to (δ_1, γ_1) in the $(\lambda, u(0))$ plane, with some $0 \leq \delta < \delta_1 \leq \infty$. If $L = \infty$, then $\delta = 0$, and in case $L < \infty$, we have $\delta > 0$. If $F(u) < 0$ for all $u \in (0, \gamma)$, then $\delta_1 = \frac{1}{2} \left(\int_0^{\gamma_1} \frac{du}{\sqrt{-F(u)}} \right)^2 < \infty$, and $\delta_1 = \infty$ in case $\max_{u \in (0, \gamma)} F(u) \geq 0$.*

Proof. We begin by showing the existence of positive solutions, with $u(0) > \gamma$. We use “shooting”, considering for $x > 0$ the solutions of

$$(3.2) \quad u''(x) + f(u(x)) = 0, \quad u(0) = u_0, \quad u'(0) = 0.$$

The “energy” $\frac{1}{2}u'^2(x) + F(u(x))$ is constant, and so

$$(3.3) \quad \frac{1}{2}u'^2(x) + F(u(x)) = F(u_0), \quad \text{for all } x.$$

Let $u_0 > \gamma$ be such that $F(u_0) > F(u)$ for all $u \in (0, u_0)$. Then the solution of (3.2) is decreasing, and $u'(x)$ cannot become zero, or tend to zero, by (3.3). It follows that $u(x)$ becomes zero at some x_0 , and then by rescaling we get a solution of (3.1) at some value of λ .

This solution is non-singular by Theorem 2.1. We now continue this solution in λ , using the implicit function theorem. For decreasing λ , the solution curve goes to infinity, as described in the statement of the theorem, by standard results; see e.g., [3]. For increasing λ , the solution curve either continues for all λ , or at some $\lambda = \delta_1$, and the corresponding $u = \bar{u}(x)$, we have $\bar{u}'(1) = 0$, and the solutions become sign-changing for $\lambda > \delta_1$. Then

$$(3.4) \quad \frac{1}{2}\bar{u}'^2(x) + \delta_1 F(\bar{u}(x)) = 0.$$

It follows that $F(\bar{u}(0)) = 0$, and so $\bar{u}(0) = \gamma_1$, and $F(u) < 0$ for $u \in (0, \gamma_1)$. We conclude that in case $\max_{u \in (0, \gamma)} F(u) \geq 0$, the solution $\bar{u}(x)$ with $\bar{u}'(1) = 0$ is not possible, and therefore the curve of positive solutions continues for all λ . In case $F(u) < 0$ for all $u \in (0, \gamma)$, the existence of $\bar{u}(x)$ follows by shooting and scaling, as above (with $u_0 = \gamma_1$), and the value of δ_1 is computed by integration of (3.4). \square

This result can be used in many situations. It adds a solution curve, which has no turns, to whatever is known about the solution set for $u(0) \in (0, \gamma)$. In particular, it can be used with the well-known cases of parabola-like (see P. Korman, Y. Li, and T. Ouyang [7], or S.-H. Wang [10]), or *S*-shaped solution curves (see P. Korman and Y. Li [5], or S.-H. Wang [11]), giving the following results.

Theorem 3.2. *Assume that the function $f(u) \in C^2(\bar{R}_+)$ has three positive roots $0 < a < b < \gamma$, and*

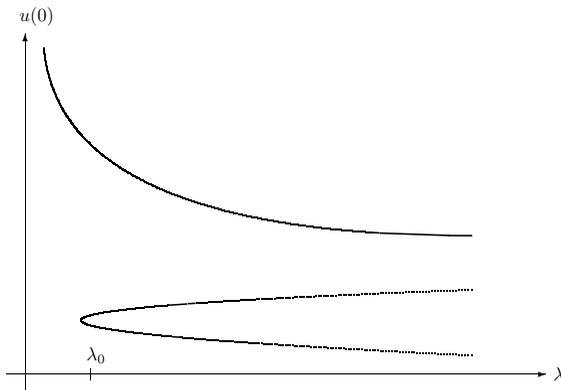
$$f(0) = 0, \quad f(u) < 0 \text{ on } (0, a) \cup (b, \gamma), \quad f(u) > 0 \text{ on } (a, b) \cup (\gamma, \infty),$$

$$F(b) = \int_0^b f(u) du > 0.$$

Assume that there is an $\alpha \in (a, b)$, so that

$$f''(u) > 0 \text{ for } u \in (0, \alpha), \quad f''(u) < 0 \text{ for } u \in (\alpha, b).$$

Assume, finally, that $f(u)$ satisfies the conditions (2.2) and (2.3). Also, assume for definiteness that $\lim_{u \rightarrow \infty} \frac{f(u)}{u} = \infty$. Then the set of positive solutions of (3.1) consists of two solution curves. The lower curve is parabola-like, opening to the right, and the upper one is given by Theorem 3.1, with $\delta = 0$, and $\delta_1 = \infty$. In particular, there is a critical λ_0 , so that the problem (3.1) has exactly one positive solution for $\lambda \in (0, \lambda_0)$, exactly two positive solutions at $\lambda = \lambda_0$, and exactly three positive solutions for $\lambda > \lambda_0$.



Bifurcation diagram for Theorem 3.2

Theorem 3.3. Assume that the function $f(u) \in C^2(\bar{R}_+)$ has two positive roots $0 < a < \gamma$, and

$$f(u) > 0 \text{ on } [0, a) \cup (\gamma, \infty), \quad f(u) < 0 \text{ on } (a, b).$$

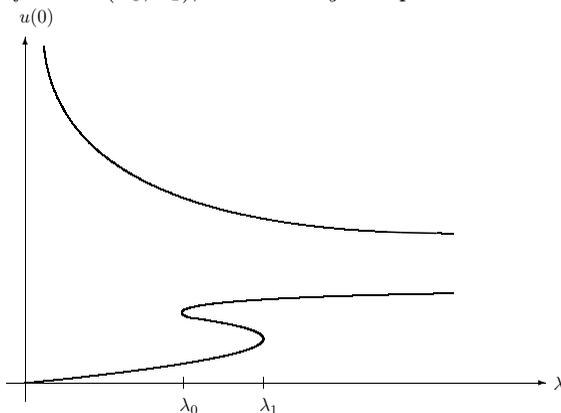
Assume that there is an $\alpha \in (0, a)$, so that

$$f''(u) > 0 \text{ for } u \in (0, \alpha), \quad f''(u) < 0 \text{ for } u \in (\alpha, a).$$

Defining $h(u) = 2F(u) - uf(u)$, we assume that

$$h(\alpha) < 0.$$

Assume, finally, that $f(u)$ satisfies the conditions (2.2) and (2.3). Also, assume for definiteness that $\lim_{u \rightarrow \infty} \frac{f(u)}{u} = \infty$. Then the set of positive solutions of (3.1) consists of two solution curves. The lower curve is S-shaped, and the upper one is given by Theorem 3.1, with $\delta = 0$, and $\delta_1 = \infty$. In particular, there are two critical numbers $\lambda_0 < \lambda_1$, so that the problem (3.1) has exactly two positive solutions for $\lambda \in (0, \lambda_0)$, exactly three positive solutions at $\lambda = \lambda_0$ and $\lambda = \lambda_1$, exactly four positive solutions for $\lambda \in (\lambda_0, \lambda_1)$, and exactly two positive solutions for $\lambda > \lambda_0$.



Bifurcation diagram for Theorem 3.3

Finally, we consider the case of broken reverse S-shaped curves, considered previously by J. Shi and R. Shivaji [9], and K.-C. Hung [2]. We have the following result.

Theorem 3.4. Assume that the function $f(u) \in C^2(\bar{R}_+)$ has three positive roots $0 < a < b < \gamma$, and

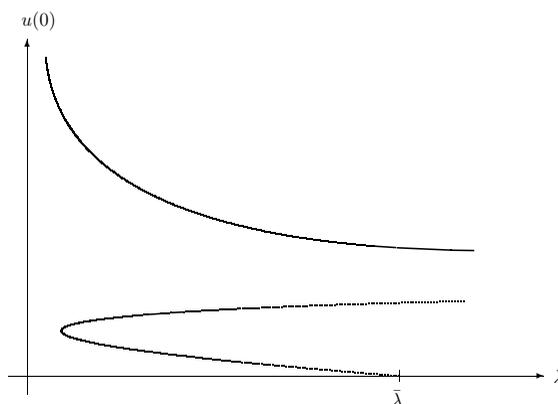
$$f(u) < 0 \text{ on } [0, a) \cup (b, \gamma), \quad f(u) > 0 \text{ on } (a, b) \cup (\gamma, \infty),$$

$$(3.5) \quad \int_0^b f(u) du > 0, \quad \int_a^\gamma f(u) du < 0.$$

Assume that

$$f''(u) < 0 \text{ for } u \in (0, b).$$

Assume, finally, that $f(u)$ satisfies the condition (2.2). Also, assume for definiteness that $\lim_{u \rightarrow \infty} \frac{f(u)}{u} = \infty$. Then the set of positive solutions of (3.1) consists of two solution curves. The lower curve is parabola-like, opening to the right, and the upper one is without any turns, and it joins $(0, \infty)$ to (∞, γ_1) in the $(\lambda, u(0))$ plane. The lower branch of the lower curve terminates at some finite $\bar{\lambda}$ (at $\bar{\lambda}$, $u'(1) = 0$, and the solutions are sign-changing for $\lambda > \bar{\lambda}$).



Bifurcation diagram for Theorem 3.4

Proof. Observe that (3.5) implies that (2.3) holds. Theorem 3.1 applies, and provides us with the upper curve. For $u(0) \in (a, b)$, only turns to the right are possible on the solution curve, see [3], and since $f(0) < 0$, arguing as above, we see that the lower branch terminates at some finite $\bar{\lambda}$. \square

Let us compare this result with Theorem 2.2 in K.-C. Hung [2]. We do not impose any concavity assumptions on $f(u)$ for $u \in (b, \infty)$, and we dropped several technical assumptions. However, we added an extra condition $\int_a^\gamma f(u) du < 0$, which K.-C. Hung [2] does not have. For the cubic $f(u) = (u - a)(u - b)(u - c)$, $0 < a < b < c$, K.-C. Hung's theorem produces the optimal result (i.e., the bifurcation diagram is the same as for Theorem 3.4), requiring only that $\int_0^b f(u) du > 0$, while our result requires that in addition, $\int_a^c f(u) du < 0$. On the other hand, our result allows many changes in convexity on (b, ∞) .

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