

VARIATIONS OF GEOMETRIC INVARIANT QUOTIENTS FOR PAIRS, A COMPUTATIONAL APPROACH

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ABSTRACT. We study GIT compactifications of pairs formed by a hypersurface and a hyperplane. We provide a general setting to characterize all polarizations which give rise to different GIT quotients. Furthermore, we describe a finite set of one-parameter subgroups sufficient to determine the stability of any GIT quotient. We characterize all maximal orbits of non-stable and strictly semistable pairs, as well as minimal closed orbits of strictly semistable pairs. Our construction gives natural compactifications of the space of log smooth pairs for Fano and Calabi-Yau hypersurfaces.

1. INTRODUCTION

The construction and study of moduli spaces is a central subject in algebraic geometry, and Geometric Invariant Theory (GIT) is one of its foundational tools. It has been applied to study hypersurfaces [1, 4, 9], and it is a first step towards constructing the moduli space of del Pezzo surfaces admitting a Kähler–Einstein metric [12]. A GIT quotient depends on a choice of a line bundle in a parameter space, and any two compactifications, with the exceptions of some limit cases, are related by birational transformations (see [14], [3]).

In this article, we consider the GIT quotients parameterizing pairs (X, H) where $X \subset \mathbb{P}^{n+1}$ is a hypersurface of degree d and $H \subset \mathbb{P}^{n+1}$ is a hyperplane. This is a natural setting to consider pairs (X, D) where $D = X \cap H$ is a hyperplane section. Our work generalizes to higher dimensions R. Laza’s work on curves [8]. Our setting can be automatized to perform computations for any dimension n and degree d . Indeed, in the companion to this article [5] we provide algorithms, already fully implemented in software [7], to compute all the invariants and functions in this article. In [6], we apply the current setting and a specific analysis of singularities to describe *geometrically* all GIT compactifications of pairs (S, C) where S is a cubic surface and $C \in |-K_S|$ is an anticanonical divisor.

Let $\mathcal{R}_{n,d}$ be the parameter space of pairs (X, H) . There is a one-dimensional space of stability conditions parametrized by $t \in [0, t_{n,d}]$ corresponding to polarizations of $\mathcal{R}_{n,d}$ (see Section 2). There is a finite number of values $t_i \in \mathbb{Q}_{\geq 0}$ known as *GIT walls* where $0 = t_0 < t_1 < \dots < t_{n,d}$ and segments (t_i, t_{i+1}) known as *GIT chambers*. Two GIT quotients are isomorphic if and only if their linearizations belong to either the same GIT chamber or wall. In particular, there is a finite number

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of non-isomorphic GIT quotients $\overline{M}_{n,d,t}^{GIT}$ corresponding to values $t = t_i$ and to any $t \in (t_i, t_{i+1})$.

Theorem 1.1. *Let $S_{n,d}$ be the set of one-parameter subgroups in Definition 3.1. All GIT walls $\{t_0, \dots, t_{n,d}\}$ correspond to a subset of the finite set*

$$(1) \quad \left\{ -\frac{\langle m, \lambda \rangle}{\langle x_i, \lambda \rangle} \mid m \text{ is a monomial of degree } d, 0 \leq i \leq n + 1, \lambda \in S_{n,d} \right\},$$

and they are contained in the interval $[0, t_{n,d}]$ where $t_{n,d} = \frac{d}{n+1}$. Every pair (X, H) has an interval of stability $[a, b]$ with $a, b \in \{t_0, \dots, t_{n,d}\}$. Namely, (X, H) is t -semistable if and only if $t \in [t_i, t_j]$ for some walls t_i, t_j . If (X, H) is t -stable for some t , then (X, H) is t -stable if and only if $t \in (t_i, t_j)$.

Corollary 1.2. *Assume that the ground field is algebraically closed with characteristic 0 and that the locus of stable points is not empty and $d \geq 3$. Then*

$$\dim \overline{M}_{n,d,t}^{GIT} = \binom{n+d+1}{d} - n^2 - 3n - 3.$$

Each $\overline{M}_{n,d,t}^{GIT}$ is a compactification of the space of log smooth pairs $(X, X \cap H)$ described above.

When X is Fano or Calabi-Yau the pairs (X, H) are realized as log pairs:

Theorem 1.3. *Every point in the GIT quotient $\overline{M}_{n,d,t}^{GIT}$ parametrizes a closed orbit associated to a pair (X, D) with $D = X \cap H$ in the cases where X is a Calabi-Yau or a Fano hypersurface of degree $d > 1$. Furthermore, if X is Fano $t \leq t_{n,d}$ and (X, D) is t -semistable, then X does not contain a hyperplane in its support, unless $t = t_{n,d}$, in which case (X, D) is strictly $t_{n,d}$ -semistable.*

Once a set of coordinates is fixed, any pair (X, H) can be determined by homogeneous polynomials F and F' of degrees d and 1, respectively, which define a pair of sets of monomials, namely those which appear with non-zero coefficients in F and F' . Suppose (X, H) is not t -stable. We find sets of monomials $N_t^\oplus(\lambda_k, x_i)$ such that in some coordinate system the equations of F and F' are given by monomials in $N_t^\oplus(\lambda_k, x_i)$. A similar procedure follows for t -unstable pairs, where the relevant sets of monomials are $N_t^+(\lambda_k, x_i)$.

Theorem 1.4. *Let $t \in (0, t_{n,d})$. A pair (X, H) is not t -stable (t -unstable, respectively) if and only if there exists $g \in SL(n, \mathbb{K})$ such that the set of monomials associated to $(g \cdot X, g \cdot H)$ is contained in a pair of sets $N_t^\oplus(\lambda, x_i)$ ($N_t^+(\lambda, x_i)$, respectively) defined in Lemma 5.2.*

Furthermore, the sets $N_t^\oplus(\lambda, x_i)$ and $N_t^+(\lambda, x_i)$ which are maximal with respect to the containment order of sets define families of non- t -stable pairs (t -unstable pairs, respectively) in $\mathcal{R}_{n,d}$. Any non- t -stable (respectively t -unstable) pair $(g \cdot X, g \cdot H)$ belongs to one of these families for some group element g .

These results allow us to identify non- t -stable pairs, and these are either strictly t -semistable or t -unstable.

The Centroid Criterion gives a polyhedral interpretation of stability. Indeed, a pair (X, H) determines a convex polytope $\text{Conv}_t(X, H)$, and the parameter t determines a point \mathcal{O}_t in affine space (for details see Section 4).

Lemma 1.5 (Centroid Criterion). *Let $t \in \mathbb{Q}_{\geq 0}$. A pair (X, H) is t -semistable (respectively t -stable) if and only if $\mathcal{O}_t \in \overline{\text{Conv}}_t(X, H)$ ($\mathcal{O}_t \in \text{Int}(\text{Conv}_t(X, H))$), respectively).*

The boundary of $\overline{M}_{n,d,t}^{GIT}$ is of special interest for GIT problems. Each of its points has a one-to-one correspondence to a strictly t -semistable closed orbit.

Theorem 1.6. *Assume $t \in (0, t_{n,d})$ and ground field of characteristic 0. If a pair (X, H) belongs to a closed strictly t -semistable orbit, then there are $g \in \text{SL}_{n+2}$, $\lambda \in S_{n,d}$, and x_i such that the set of monomials associated to $(g \cdot \mathcal{X}, g \cdot \mathcal{H})$ corresponds to those in a pair of sets $(V_t^0(\lambda, x_i), B^0(\lambda, x_i))$ defined such that $(v, b) \in V_t^0(\lambda, x_i) \times B^0(\lambda, x_i)$ if and only if $\mu_t(v, b) = 0$ and $(v, b) \in N_t^\oplus(\lambda, x_i)$.*

1.1. Conventions and notation. We work over an algebraically closed field \mathbb{K} . Let $G = \text{SL}(n+2, \mathbb{K})$ and $T \subset G$ be a fixed maximal torus. The torus $T \cong (\mathbb{K}^*)^{n+2}$ induces lattices of characters $M = \text{Hom}_{\mathbb{Z}}(T, \mathbb{G}_m) \cong \mathbb{Z}^{n+2}$ and of one-parameter subgroups $N = \text{Hom}_{\mathbb{Z}}(\mathbb{G}_m, T) \cong \mathbb{Z}^{n+2}$, with a natural pairing:

$$\langle -, - \rangle : M \times N \longrightarrow \text{Hom}_{\mathbb{Z}}(\mathbb{G}_m, \mathbb{G}_m) \cong \mathbb{Z}.$$

We choose projective coordinates $(x_0 : \dots : x_{n+1})$ in \mathbb{P}^{n+1} such that T is diagonal. Given a one-parameter subgroup $\lambda : \mathbb{G}_m \cong \mathbb{K}^* \rightarrow T \subset G$ in M , we say it is *normalized* ([10, §7.2(b)]) if

$$\lambda(s) = \text{Diag}(s^{r_0}, \dots, s^{r_{n+1}}) := \begin{pmatrix} s^{r_0} & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & s^{r_{n+1}} \end{pmatrix},$$

such that $r_0 \geq \dots \geq r_{n+1}$, $\sum r_i = 0$, and not all $r_i = 0$. In particular $r_0 > 0$ and $r_{n+1} < 0$. Denote by Ξ_k the set of all monomials of degree k in variables x_0, \dots, x_{n+1} . Since each monomial in Ξ_k can be identified with a character $\mathcal{X}^a \in M$ of weight k , we can see the pairing $\langle -, - \rangle$ of one-parameter subgroups with monomials as

$$\langle x_0^{d_0} \dots x_{n+1}^{d_{n+1}}, \text{Diag}(s^{r_0}, \dots, s^{r_{n+1}}) \rangle = \langle \mathcal{X}^a, \lambda \rangle = \sum d_i \cdot r_i \in \mathbb{Z},$$

where $a = (d_0, \dots, d_{n+1}) \in (\mathbb{Z}_{\geq 0})^{n+2}$, $\sum d_i = k$.

Let X be a hypersurface of degree d defined by polynomials $F = \sum c_I x^I$ with $I = (d_0, \dots, d_{n+1})$ and let H be a hyperplane defined by $\sum h_i x_i$ where $c_I, h_i \in \mathbb{K}$. We define their *associated sets of monomials* $(\mathcal{X}, \mathcal{H})$ as the pair of sets

$$\mathcal{X} = \{x^I \in \Xi_d \mid c_I \neq 0\}, \quad \mathcal{H} = \{x_i \in \Xi_1 \mid h_i \neq 0\}.$$

Let λ be a normalized one-parameter subgroup of G . By definition [11, 21, p. 81], the *Hilbert-Mumford function* is

$$\mu(X, \lambda) := \min\{\langle I, \lambda \rangle \mid c_I \neq 0\}.$$

Note that for fixed X , the function $\mu(X, -)$ is piecewise linear. Finally, there is a natural partial order on Ξ_k which we call *Mukai order* [10, Lemma 7.18]: given $v, m \in \Xi_k$,

$$v \leq m \iff \langle v, \lambda \rangle \leq \langle m, \lambda \rangle,$$

for all normalized one-parameter subgroups λ . Under this order there is a unique *maximal element* x_0^k and unique *minimal element* x_{n+1}^k in Ξ_k . In the special case when $k = 1$, the Mukai order is a total one.

Our results, together with a good knowledge of the singularities of $(X, D \cap H)$ for given d and n , are sufficient to describe all the GIT compactifications. A sketch of such an algorithm is discussed in section 6. We refer the reader to [7] for the details and to [6] for the case of cubic surfaces and their anticanonical divisors.

2. VGIT SETTING

Let $\mathcal{R} = \mathcal{R}_{n,d}$ be the parameter scheme of pairs (X, H) given by

$$\mathcal{R}_{n,d} = \mathbb{P}(H^0(\mathbb{P}^{n+1}, \mathcal{O}_{\mathbb{P}^{n+1}}(d))) \times \mathbb{P}(H^0(\mathbb{P}^{n+1}, \mathcal{O}_{\mathbb{P}^{n+1}}(1))) \cong \mathbb{P}^N \times \mathbb{P}^{n+1},$$

where $N = \binom{n+1+d}{d} - 1$.

Lemma 2.1. *The set of G -linearizable line bundles $\text{Pic}^G(\mathcal{R})$ is isomorphic to \mathbb{Z}^2 . Then a line bundle $\mathcal{L} \in \text{Pic}^G(\mathcal{R})$ is ample if and only if*

$$\mathcal{L} = \mathcal{O}(a, b) := \pi_1^*(\mathcal{O}_{\mathbb{P}^N}(a)) \otimes \pi_2^*(\mathcal{O}_{\mathbb{P}^{n+1}}(b)) \in \text{Pic}^G(\mathcal{R}),$$

where π_1 and π_2 are the natural projections on \mathbb{P}^N and \mathbb{P}^{n+1} , respectively, and $a, b > 0$.

Proof. Let $\pi_1: \mathcal{R} \rightarrow \mathbb{P}^N$, $\pi_2: \mathcal{R} \rightarrow \mathbb{P}^{n+1}$ be the natural projections. The action of G on Ξ_d and Ξ_1 induces a natural action on $\mathcal{R} \cong \mathbb{P}^N \times \mathbb{P}^{n+1}$, which preserves the fibers. Hence we have an action of G on both \mathbb{P}^N and \mathbb{P}^{n+1} and π_1, π_2 are morphisms of G -varieties. Recall there is an exact sequence (see [2, Theorem 7.2])

$$0 \longrightarrow \mathcal{X}(G) \longrightarrow \text{Pic}^G(\mathcal{R}) \longrightarrow \text{Pic}(\mathcal{R}) \longrightarrow \text{Pic}(G),$$

where $\mathcal{X}(G)$ is the kernel of the forgetful morphism $\text{Pic}^G(\mathcal{R}) \rightarrow \text{Pic}(\mathcal{R})$. Since $\mathcal{X}(G) = \{1\}$ and $\text{Pic}(G) = \{1\}$ by [2, Chapter 7.2] then $\text{Pic}^G(\mathcal{R}) \cong \text{Pic}(\mathcal{R})$. Moreover, given that $\text{Pic}^G(\mathcal{R}) \subseteq \text{Pic}(\mathcal{R})^G \subset \text{Pic}(\mathcal{R})$, where $\text{Pic}(\mathcal{R})^G$ is the group of G -invariant line bundles, the result follows from

$$\text{Pic}^G(\mathcal{R}) \cong \text{Pic}(\mathcal{R})^G \cong \text{Pic}(\mathcal{R}) \cong \pi_1^*(\text{Pic}(\mathbb{P}^N)) \times \pi_2^*(\text{Pic}(\mathbb{P}^{n+1})) \cong \mathbb{Z} \times \mathbb{Z}.$$

□

For $\mathcal{L} \cong \mathcal{O}(a, b)$, the GIT quotient is defined as

$$\overline{M}_{n,d,t}^{GIT} = \text{Proj} \bigoplus_{m \geq 0} H^0(\mathcal{R}, \mathcal{L}^{\otimes m})^G,$$

where $t = \frac{b}{a}$.

The main tool to understand variations of GIT from a computational viewpoint is the Hilbert-Mumford numerical criterion, which in our particular case has the following form.

Lemma 2.2. *Given an ample $\mathcal{L} \cong \mathcal{O}(a, b) \in \text{Pic}^G(\mathcal{R})$, let (X, H) be a pair parametrized by \mathcal{R} , and let λ be a normalized one-parameter subgroup of G . The Hilbert-Mumford function (see [11, Definition 2.2]) is $\mu^{\mathcal{L}}((X, H), \lambda) = a\mu_t(X, H, \lambda)$, where $t = \frac{b}{a} \in \mathbb{Q}_{>0}$ and*

$$\begin{aligned} \mu_t(X, H, \lambda) &:= \mu(X, \lambda) + t\mu(H, \lambda) \\ &= \min\{\langle I, \lambda \rangle \mid x^I \in \mathcal{X}\} + t \min\{r_i \mid x_i \in \mathcal{H}\}. \end{aligned}$$

Proof. By [11, p. 49], for fixed (X, H) and λ , $\mu^{\mathcal{L}}: \text{Pic}^G(\mathcal{R}) \rightarrow \mathbb{Z}$ is a group homomorphism. Moreover, given any G -equivariant morphism of G -varieties $\pi: \mathcal{R} \rightarrow Y$, we have that $\mu^{\pi^* \mathcal{L}}((X, H), \lambda) = \mu^{\mathcal{L}}(\pi(X, H), \lambda)$. Applying these two properties, the result follows from

$$\begin{aligned} \mu^{\mathcal{O}(a,b)}((X, H), \lambda) &= \mu^{\pi_1^* \mathcal{O}_{\mathbb{P}^N}(a) \otimes \pi_2^* \mathcal{O}_{\mathbb{P}^{n+1}}(b)}((X, H), \lambda) \\ &= \mu^{\pi_1^* \mathcal{O}_{\mathbb{P}^N}(a)}((X, H), \lambda) + \mu^{\pi_2^* \mathcal{O}_{\mathbb{P}^{n+1}}(b)}((X, H), \lambda) \\ &= a\mu^{\mathcal{O}_{\mathbb{P}^N}(1)}(X, \lambda) + b\mu^{\mathcal{O}_{\mathbb{P}^{n+1}}(1)}(H, \lambda) = a\mu_t(X, H, \lambda). \quad \square \end{aligned}$$

Remark 2.3. Let (X, H) and (X', H') be such that $(\mathcal{X}, \mathcal{H}') = (\mathcal{X}, \mathcal{H})$. Then, $\mu_t(X, H, \lambda) = \mu_t(X', H', \lambda)$.

Definition 2.4. Let $t \in \mathbb{Q}_{\geq 0}$. The pair (X, H) is *t-stable* (resp. *t-semistable*) if $\mu_t(X, H, \lambda) < 0$ (resp. $\mu_t(X, H, \lambda) \leq 0$) for all non-trivial one-parameter subgroups λ of G . A pair (X, H) is *t-unstable* if it is not *t-semistable*. A pair (X, H) is *strictly t-semistable* if it is *t-semistable* but not *t-stable*.

3. STRATIFICATION OF THE SPACE OF STABILITY CONDITIONS

In this section, we fix a maximal torus T of one-parameter subgroups of G and a coordinate system of \mathbb{P}^n such that T is diagonal in G .

Definition 3.1. The *fundamental set* $S_{n,d}$ of one-parameter subgroups $\lambda \in T$ consists of all non-trivial elements $\lambda = \text{Diag}(s^{r_0}, \dots, s^{r_{n+1}})$ where

$$(r_0, \dots, r_{n+1}) = c(\gamma_0, \dots, \gamma_{n+1}) \in \mathbb{Z}^{n+1},$$

satisfying the following:

- (1) $\gamma_i = \frac{a_i}{b_i} \in \mathbb{Q}$ such that $\text{gcd}(a_i, b_i) = 1$ for all $i = 0, \dots, n + 1$ and $c = \text{lcm}(b_0, \dots, b_{n+1})$.
- (2) $1 = \gamma_0 \geq \gamma_1 \geq \dots \geq \gamma_{n+1} = -1 - \sum_{i=1}^n \gamma_i$.
- (3) $(\gamma_0, \dots, \gamma_{n+1})$ is the unique solution of a consistent linear system given by n equations chosen from the union of the following sets:

$$(2) \quad \text{Eq}(n, d) := \{ \gamma_i - \gamma_{i+1} = 0 \mid i = 0, \dots, n \} \\ \cup \left\{ \sum_{i=0}^{n+1} (d_i - \bar{d}_i) \gamma_i = 0 \mid d_i, \bar{d}_i \in \mathbb{Z}_{\geq 0} \text{ for all } i \text{ and } \sum_{i=0}^{n+1} d_i = \sum_{i=0}^{n+1} \bar{d}_i = d \right\}.$$

The set $S_{n,d}$ is finite since there are a finite number of monomials in Ξ_d .

Lemma 3.2. A pair (X, H) is not *t-stable* (respectively not *t-semistable*) if and only if there is $g \in G$ satisfying

$$\mu_t(X, H) = \max_{\lambda \in S_{n,d}} \{ \mu_t(g \cdot X, g \cdot H, \lambda) \} \geq 0 \quad (\text{respectively } > 0),$$

where μ_t is the Hilbert-Mumford function defined in Lemma 2.2 and $S_{n,d}$ is the fundamental set of Definition 3.1.

Proof. Let $R_{T_i}^{ns}$ be the non-*t-stable* loci of \mathcal{R} with respect to a maximal torus T_i , and let \mathcal{R}^{ns} be the non-*t-stable* loci of \mathcal{R} . By [2, p. 137]), the following holds:

$$\mathcal{R}^{ns} = \bigcup_{T_i \subset G} R_{T_i}^{ns}.$$

Let (X', H') be a pair which is not t -stable. Then, $\mu_t(X', H', \rho) \geq 0$ for some $\rho \in T'$ in a maximal torus T' which may be *different* from T . All the maximal tori are conjugate to each other in G , and by [2, Exercise 9.2(i)] the following holds:

$$\mu_t((X', H'), \rho) = \mu_t(g \cdot (X', H'), g\rho g^{-1}).$$

Then, there is $g_0 \in G$ such that $\lambda := g_0\rho g_0^{-1}$ is normalized and $(X, H) := g_0 \cdot (X', H')$ has coordinates in our coordinate system such that $\mu_t(X, H, \lambda) \geq 0$. In this coordinate system one-parameter subgroups form a closed convex polyhedral subset Δ of dimension $n + 1$ in $M \otimes \mathbb{Q} \cong \mathbb{Q}^{n+2}$ (in fact Δ is a standard simplex). Indeed, this is the case since for any normalized one-parameter subgroup, $\lambda = \text{Diag}(s^{r_0}, \dots, s^{r_{n+1}})$, $\sum r_i = 0$, and $r_i - r_{i+1} \geq 0$.

By Lemma 2.2, for any fixed t , X , and H , the function $\mu_t(X, H, -) : M \otimes \mathbb{Q} \rightarrow \mathbb{Q}$ is piecewise linear. The critical points of μ_t (i.e., the points where μ_t fails to be linear) correspond to those points in $M \otimes \mathbb{Q}$ where $\langle I, \lambda \rangle = \langle \bar{I}, \lambda \rangle$ for $I = (d_0, \dots, d_{n+1})$, $\bar{I} = (\bar{d}_0, \dots, \bar{d}_{n+1})$ representing monomials of degree d of the form $f = \sum f_I x^I$ defining f . Since $\langle -, - \rangle$ is bilinear that is equivalent to saying that $\langle I - \bar{I}, \lambda \rangle = 0$. These points define a hyperplane in $M \otimes \mathbb{Q}$, and the intersection of this hyperplane with Δ is a simplex $\Delta_{I, \bar{I}}$ of dimension n .

The function $\mu_t(X, H, -)$ is linear on the complement of the hyperplanes defined by $\langle I - \bar{I}, \lambda \rangle = 0$. Hence its minimum is achieved on the boundary, i.e., either on $\partial\Delta$ or on $\Delta_{I, \bar{I}}$ which are all convex polytopes of dimension n . We can repeat this reasoning by finite inverse induction on the dimension until we conclude that the minimum of $\mu_t(X, H, -)$ is achieved at one of the vertices of Δ or $\Delta_{I, \bar{I}}$. But these correspond precisely, up to multiplication by a constant, to the finite set of one-parameter subgroups in $S_{n,d}$. \square

Corollary 3.3. *Let $(X, H) \in \mathcal{R}$ and*

$$a = \min\{t \in \mathbb{Q}_{\geq 0} \mid \mu_t(g \cdot (X, H), \lambda_i) \leq 0 \text{ for all } \lambda_i \in S_{n,d}, g \in G\},$$

$$b = \max\{t \in \mathbb{Q}_{\geq 0} \mid \mu_t(g \cdot (X, H), \lambda_i) \leq 0 \text{ for all } \lambda_i \in S_{n,d}, g \in G\}.$$

If (X, H) is t -semistable for some $t \in \mathbb{Q}_{\geq 0}$, then

- (i) (X, H) is t -semistable if and only if $t \in [a, b] \cap \mathbb{Q}_{\geq 0}$,
- (ii) if (X, H) is t -stable for some t , then (X, H) is t -stable for all $t \in (a, b) \cap \mathbb{Q}_{> 0}$.

We will call $[a, b]$ the interval of stability of the pair (X, H) . We say $[a, b] = \emptyset$ if (X, H) is t -unstable for all $t \in \mathbb{Q}_{\geq 0}$.

Proof. Recall that $S_{n,d}$ is a finite set, by Lemma 3.2. Moreover, the pair (X, H) is t -(semi)stable if and only if

$$\mu_t(X, H) = \max_{\substack{\lambda_i \in S_{n,d} \\ g \in G}} \{\mu_t(g \cdot (X, H), \lambda_i)\} < 0 \quad (\leq 0).$$

Notice that each of the functions $\mu_t(g \cdot (X, H), \lambda_i)$ is affine on t and that there are only a finite number of such functions to consider in the definition of $\mu_t(X, H)$. Indeed, the last statement follows from observing that μ_t depends only on λ_i (finite number of choices in $S_{n,d}$ to consider) and the monomials with non-zero coefficients in the polynomials defining $g \cdot (X, H)$. But there are only a finite number of such subsets of those monomials, since $\mathcal{P}(\Xi_d) \times \mathcal{P}(\Xi_1)$ is finite.

To see that $b < \infty$, observe that any hyperplane in \mathbb{P}^{n+1} is conjugate by an element of G to the hyperplane given by $\{x_0 = 0\}$. Let $r = (1, 0, \dots, 0, -1) \in \mathbb{Z}^{n+2}$ and $\lambda = \text{Diag}(s^r) \in S_{n,d}$. Then $\mu(\{x_0 = 0\}, \lambda) = 1 > 0$. Hence, for $t \gg 0$, we have that $\mu_t(X, D) > 0$ as each $\mu_t(g \cdot (X, D), \lambda)$ is piecewise affine. We conclude that if (X, D) is not t -semistable for some $t \in \mathbb{Q}_{\geq 0}$, then

$$[a, b] = \bigcap_{\substack{\lambda_i \in S_{n,d} \\ g \in G}} \{t \mid \mu_t(g \cdot (X, H), \lambda_i) \leq 0\}$$

is a bounded interval, as it is an intersection of a finite number of intervals. This proves (i).

For (ii), notice that (X, H) being t -stable for some t_0 is equivalent to the functions $\mu_{t_0}(g \cdot (X, H), \lambda_i)$ being always strictly negative. Then, the statement follows because $\mu_t(g \cdot (X, H), \lambda_i)$ are affine functions, and $[a, b]$ is a compact interval. \square

4. CENTROID CRITERION

Lemma 3.2 allows us to detect the lack of t -stability of a G -orbit by having to consider only a finite number of one-parameter subgroups, precisely those in $S_{n,d}$. However, sometimes it is convenient to decide on the t -stability of a given pair (X, H) without comparing to all the elements in $S_{n,d}$. For this purpose and to shorten the proof of Theorem 1.1, we developed the Centroid Criterion, for which we need to introduce extra notation. Fix $t \in \mathbb{Q}_{\geq 0}$. We have a map $\text{disc}_t: \Xi_d \times \Xi_1 \rightarrow M \otimes \mathbb{Q} \cong \mathbb{Q}^{n+2}$, defined as

$$\text{disc}_t(x_0^{d_0} \cdots x_{n+1}^{d_{n+1}}, x_j) = (d_0, \dots, d_{j-1}, d_j + t, d_{j+1}, \dots, d_{n+1}).$$

The image of disc_t is supported on the first quadrant of the hyperplane

$$H_{n,d,t} = \left\{ (y_0, \dots, y_{n+1}) \in \mathbb{Q}^{n+2} \mid \sum_{i=0}^{n+1} y_i = d + t \right\}.$$

We define the set $\text{Conv}_t(X, H)$ as the convex hull of

$$\{\text{disc}_t(v, b) \mid v \in \mathcal{X}, b = \min(\mathcal{H})\} \subset H_{n,d,t},$$

where the minimum is for the Mukai order in Ξ_1 , which is a total order (see Section 1.1). Observe that $\overline{\text{Conv}_t(X, H)}$ is a convex polytope.

Given $t \in \mathbb{Q}_{\geq 0}$, we define the t -centroid as

$$\mathcal{O}_t = \mathcal{O}_{n,d,t} = \left(\frac{d+t}{n+2}, \dots, \frac{d+t}{n+2} \right) \in H_{n,d,t} \subset \mathbb{Q}^{n+2}.$$

Proof of Lemma 1.5. First we note that (X, H) is t -semistable (t -stable, respectively) if and only if $(X, X \cap \{\min(\mathcal{H}) = 0\})$ is t -semistable (t -stable, respectively). Indeed, let $x_k = \min(\mathcal{H})$. Given any one-parameter subgroup $\lambda \in N$ we have

$$\begin{aligned} \mu_t((X, H), \lambda) &= \mu(\mathcal{X}, \lambda) + t \min_{b \in \mathcal{H}} \{ \langle b, \lambda \rangle \} \\ &= \mu(\mathcal{X}, \lambda) + t \langle x_k, \lambda \rangle = \mu_t((X, X \cap \{x_k = 0\}), \lambda). \end{aligned}$$

Hence, we may assume that $D = X \cap \{x_k = 0\}$. Suppose $\mathcal{O}_t \notin \overline{\text{Conv}_t(X, H)}$. Then there is an affine function $\phi: \mathbb{R}^{n+2} \rightarrow \mathbb{R}$ such that $\phi|_{\overline{\text{Conv}_t(X, H)}}$ is positive

and $\phi(\mathcal{O}_t) = 0$. In fact, since the vertices of $\text{Conv}_t(X, H)$ have rational coefficients, we can choose ϕ to have integral coefficients. Write

$$\phi(y_0, \dots, y_{n+1}) = \sum_{i=0}^{n+1} a_i y_i + l.$$

For $\text{disc}_t(x^{d_0} \dots x^{d_{n+1}}, x_k) = (d_0, \dots, d_k + t, \dots, d_{n+1}) \in \overline{\text{Conv}_t(X, H)}$ we have

$$\sum_{i=0}^{n+1} a_i d_i + t a_k + l > 0,$$

and since $\phi(\mathcal{O}_t) = 0$, we obtain $\frac{d+t}{n+2} \sum_{i=0}^{n+1} a_i + l = 0$. Let $p = -\frac{l}{d+t} \in \mathbb{Q}$ and choose $m \in \mathbb{Z}_{\geq 0}$ such that $mp \in \mathbb{Z}$. Let

$$\lambda(s) = \begin{pmatrix} s^{m(a_0-p)} & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & s^{m(a_{n+1}-p)} \end{pmatrix} \in N.$$

Hence

$$\begin{aligned} \mu_t((X, H), \lambda) &= \min_{\prod_i x_i^{d_i} \in \mathcal{X}} \left\{ \sum_{i=0}^{n+1} m(a_i - p)d_i \right\} + tm(a_k - p) \\ &= m \left(\min_{\prod_i x_i^{d_i} \in \mathcal{X}} \left\{ \left(\sum_{i=0}^{n+1} a_i d_i \right) + t a_k \right\} - p(d+t) \right) \\ &= \min_{v \in \overline{\text{Conv}_t(X, H)}} \phi(v) > 0. \end{aligned}$$

Hence (X, H) is not t -semistable. We have shown that if (X, H) is t -semistable, then $\mathcal{O}_t \in \overline{\text{Conv}_t(X, H)}$. The proof of the statement when (X, H) is t -stable is similar; in the above reasoning we only need to replace $\overline{\text{Conv}_t(X, H)}$ by $\text{Int}(\overline{\text{Conv}_t(X, H)})$ and the strict inequalities by ≥ 0 .

Conversely, suppose that (X, H) is not t -semistable. Then there is a normalized one-parameter subgroup $\lambda = \text{Diag}(s^{r_0}, \dots, s^{r_{n+1}}) \in N$ with $\sum r_i = 0$ and such that

$$\begin{aligned} 0 < \mu_t(X, H, \lambda) &= \min_{\prod_i x_i^{d_i} \in \mathcal{X}} \left\{ \sum_{i=0}^{n+1} d_i r_i \right\} + t r_k \\ &= \min_{\prod_i x_i^{d_i} \in \mathcal{X}} \{ r_0 d_0 + \dots + r_k (d_k + t) + \dots + r_{n+1} d_{n+1} \}. \end{aligned}$$

Let $\phi(y_0, \dots, y_{n+1}) = \sum r_i y_i$. By convexity, we have that $\phi|_{\overline{\text{Conv}_t(X, H)}} > 0$. On the other hand, $\phi(\mathcal{O}_t) = \sum r_i \frac{d+t}{n+2} = \frac{d+t}{n+2} \sum r_i = 0$. Hence $\mathcal{O}_t \notin \overline{\text{Conv}_t(X, H)}$. The proof for t -stability is similar. \square

Lemma 4.1. *Let $(X, H) \in \mathcal{R}$. Suppose that its interval of semi-stability $[a, b]$ is not empty. Then:*

- (i) $a = 0$ if and only if X is a GIT-semistable hypersurface of degree d .
- (ii) $b \leq t_{n,d} = \frac{d}{n+1}$.
- (iii) The pair (X, H) is $t_{n,d}$ -semistable if and only if $X \cap H$ is a semistable hypersurface of degree d in $H \cong \mathbb{P}^n$.

Proof. The first statement holds because the Hilbert-Mumford function at $t = 0$ coincides with the Hilbert-Mumford function for hypersurfaces, and the natural projection $\mathcal{R} \rightarrow \mathbb{P}^{n+1}$ is G -invariant.

For part (ii), suppose that $t > t_{n,d}$. Without loss of generality, we can suppose that the equations of any pair (X, H) are given by

$$X = (F(x_0, \dots, x_{n+1}) = 0), \quad H = (x_0 = 0).$$

Let $\lambda = (n + 1, -1, \dots, -1)$; then

$$\mu_{t_{n,d}}((X, H), \lambda) > -d + \frac{d}{n + 1}(n + 1) = 0$$

holds and (X, H) is t -unstable. Therefore $b \leq t_{n,d}$.

Next, we discuss (iii). Suppose that $Y_0 := X \cap H$ is unstable. We can select a coordinate system such that

$$Y_0 := (p_d(x_1, \dots, x_{n+1}) = 0), \quad H := \{x_0 = 0\},$$

and Y_0 is unstable in the coordinate system $\{x_1, \dots, x_{n+1}\}$. By using Mukai's order of monomials, we claim that among all possible pairs (X, H) such that $Y_0 = X \cap H$, the pair (\tilde{X}, H) given by

$$(3) \quad \tilde{X} := p_d(x_1, \dots, x_{n+1}) + x_{n+1}^{d-1}x_0, \quad H := (x_0 = 0)$$

will minimize the Hilbert-Mumford function for any normalized one-parameter subgroup, because

$$\mu(\tilde{X}, \lambda) = \min\{\mu(X, \lambda) \mid X \cap H = Y_0\}.$$

Indeed, any other X with $X \cap H = Y_0$ differs from \tilde{X} by a monomial involving the variable x_0 . Then, we observe that any other monomial divided by x_0 is greater than $x_0 x_{n+1}^{d-1}$ in Mukai's order. As a consequence if $\mu_{t_{n,d}}(\tilde{X}, H, \lambda) > 0$, then any pair (X, H) with $X \cap H = Y_0$ is $t_{n,d}$ -unstable. Next, we use the Centroid Criterion (Lemma 1.5). By hypothesis, Y_0 is not a semistable hypersurface in \mathbb{P}^n . Then the convex hull of its monomials does not contain the point $(\frac{d}{n+1}, \dots, \frac{d}{n+1}) \in \mathbb{R}^{n+1}$. If we consider the monomials of Y_0 as monomials in $\mathbb{K}[x_0, \dots, x_{n+1}]$, then the convex hull of the monomials of \tilde{X} does not contain the point $(0, \frac{d}{n+1}, \dots, \frac{d}{n+1}) \in \mathbb{R}^{n+2}$.

Notice that this implies that $\overline{\text{Conv}_{t_{n,d}}(\tilde{X}, (x_0 = 0))}$ does not contain the point

$$\mathcal{O}_{n,d,t_{n,d}} = \left(0, \frac{d}{n+1}, \dots, \frac{d}{n+1}\right) + \frac{d}{n+1}(1, 0, \dots, 0),$$

and by the Centroid Criterion (X, H) is $t_{n,d}$ -unstable. To see the last assertion, notice that $\overline{\text{Conv}_{t_{n,d}}(\tilde{X}, (x_0 = 0))}$ is the convex hull of

$$V = \{\text{disc}_{t_{n,d}}(m, x_0) \mid m \text{ is a monomial in } p_d\} \subset P := \{y_0 = t_{n,d}\} \subset \mathbb{R}^{n+2},$$

and the point $q := (1 + t_{n,d}, \dots, 0, d - 1) \notin P$. Therefore $\overline{\text{Conv}_{t_{n,d}}(\tilde{X}, (x_0 = 0))}$ is a pyramid with base V and vertex q . Since $\mathcal{O}_{t_{n,d}} \in P \setminus V$, the claim follows.

Next suppose that (X, H) is unstable. Then, by the Centroid Criterion there is a coordinate system such that $\overline{\text{Conv}_t(X, H)}$ does not contain the centroid $\mathcal{O}_{n,d,\frac{d}{n+1}}$. By using the Mukai order as in the previous case, we may assume $H = \{x_i = 0\}$. Let

$$v := \left(\frac{d}{n+1}, \dots, \frac{d}{n+1}, 0, \frac{d}{n+1}, \dots, \frac{d}{n+1}\right),$$

where the value 0 corresponds to the i -th entry. Observe that $v \notin \overline{\text{Conv}_0(X, H)}$, since otherwise

$$\mathcal{O}_{n,d,t_n,d} = \text{disc}_{\frac{d}{n+1}}(v, x_i) \in \overline{\text{Conv}_{t_n,d}(X, H)}.$$

The monomials in the polynomial defining $X \cap (x_i = 0)$ are precisely those monomials m_j in the polynomial defining X with exponents of the form

$$a_j = (d_0^j, \dots, d_{i-1}^j, 0, d_{i+1}^j, \dots, d_{n+1}^j).$$

Those monomials correspond to the points generating a face F of $\overline{\text{Conv}_{t_n,d}(X, H)}$, namely the convex hull of points $(d_0^j, \dots, d_{i-1}^j, t_{d,n}, d_{i+1}^j, \dots, d_{n+1}^j)$. The projection F_P of F onto the hyperplane $P = \{y_i = 0\} \subset \mathbb{R}^{n+2}$ gives us that $v \notin F_P$ since $F_P \subseteq \overline{\text{Conv}_0(X, H)}$. But F_P corresponds to $\overline{\text{Conv}_0(X \cap H)}$ and $v = \mathcal{O}_{n-1,d,0}$, so by the Centroid Criterion $X \cap H$ is unstable. \square

Proof of Theorem 1.1. By Remark 2.3 and the fact that $\mathcal{P}(\Xi_k) \times \mathcal{P}(\Xi_1)$ is a finite set, there is a finite number of possible intervals of stability, say $[a_j, b_j]$. Hence $t_i \in \bigcup_j \{a_j, b_j\}$, and Lemma 4.1 implies that all $b_i \leq t_{n,d}$. Notice that given any wall t_i there is at least a pair (X, H) such that

$$\mu_t(X, H) = \max_{\lambda \in S_{n,d}} \{\mu_t((X, H), \lambda)\}$$

satisfies $\mu_t(X, H) \leq 0$ for $t \leq t_i$ and $\mu_t(X, H) > 0$ for $t > t_i$. Hence $\mu_t(X, H) = 0$ for $t = t_i$ since μ_t is continuous. The result follows from Lemma 3.2 and Remark 2.3. \square

Proof of Corollary 1.2. From [13, Theorem 2.1], any hypersurface X of degree $d \geq 3$ has $\dim(\text{Aut}(X)) = 0$. Hence, for any log smooth pair $p = (X, D) \in \mathcal{R}$, its stabilizer G_p satisfies

$$0 \leq \dim(G_p) = \dim(G_X \cap G_D) \leq \dim(G_X) \leq \dim(\text{Aut}(X)) = 0,$$

where the last equality follows from [13, Theorem 2.1]. The result follows from the following identity (see [2, Corollary 6.2]):

$$\begin{aligned} \dim(\overline{M}_{n,d,t}^{GIT}) &= \dim(\mathcal{H}) - \dim(G) + \min_{p \in \mathcal{H}} \dim G_p \\ &= \left(\binom{n+1+d}{d} - 1 + (n+1) \right) - ((n+2)^2 - 1). \end{aligned}$$

We are left to prove the following claim: any pair (X, D) such that $D \not\subset X$ and $X \cap D$ is smooth is t -semistable for all $t \in [0, t_{n,d}]$. Since smooth hypersurfaces are GIT semistable, the claim follows from Lemma 4.1. \square

Proof of Theorem 1.3. Suppose $n+2 \geq d$ and (X, H) is a pair such that $\text{Supp}(H) \subset \text{Supp}(X)$. It suffices to show that (X, H) is t -unstable for all $t \geq 0$. We choose a coordinate system such that $H = (x_0 = 0)$ and X is given as the zero locus of $F = x_0 f_{d-1}(x_0, x_1, \dots, x_{n+1})$. The monomial $x_0 x_{n+1}^{d-1}$ is minimal for the Mukai order in the set $\mathcal{X} \cup \{x_{n+1}^{d-1} x_0\}$. Then for any normalized one-parameter subgroup $\lambda = (s^{r_0}, \dots, s^{r_{n+1}})$,

$$\mu_t(X, H, \lambda) \geq (r_0 + (d-1)r_{n+1}) + tr_0$$

holds. Since $d \leq n + 2$, the one-parameter subgroup $\lambda_0 = \text{Diag}(s^r)$ is normalized, where

$$r = (n(d - 1), -(d - 2), \dots, -(d - 2), -n).$$

Then $\mu_t(X, H, \lambda_0) \geq tn(d - 1) > 0$ and (X, H) is unstable for any $t > 0$. Now, if X is a reducible Fano hypersurface, then $d \leq n + 1$, and we may assume that $F = x_0 f_{d-1}(x_0, \dots, x_{n+1})$. Let $\lambda = \text{Diag}(n + 1, -1, \dots, -1)$. By the previous step $H \neq \{x_0 = 0\}$, so

$$\mu_t(X, D, \lambda) = n + 1 - (d - 1) - t,$$

and as $t \leq \frac{d}{n+1}$ and $d \leq n + 1$, the result follows. □

5. FAMILIES OF t -UNSTABLE PAIRS

In this section we determine, for a given t , the set of monomials that characterize non- t -stable and t -unstable pairs.

Definition 5.1. Fix $t \in [0, t_{n,d}]$, and let λ be a normalized one-parameter subgroup. A non-empty pair of sets $A \subset \Xi_d$ and $B \subset \Xi_1$ is a *maximal t -(semi)destabilized pair* (A, B) with respect to λ if the following conditions hold:

- (i) Each pair $(v, m) \in A \times B$ satisfies $\langle v, \lambda \rangle + t\langle m, \lambda \rangle > 0$ (≥ 0 , respectively).
- (ii) If there is another pair of sets $\tilde{A} \subset \Xi_d, \tilde{B} \subset \Xi_1$ such that $A \subseteq \tilde{A}, B \subseteq \tilde{B}$, and for all $(v, m) \in \tilde{A} \times \tilde{B}$ the inequality $\langle v, \lambda \rangle + t\langle m, \lambda \rangle > 0$ (≥ 0 , respectively) holds, then $\tilde{A} = A$ and $\tilde{B} = B$.

Lemma 5.2. *Given a one-parameter subgroup λ any maximal t -(semi)destabilized pair with respect to λ can be written as*

$$N_t^+(\lambda, x_i) := (V_t^+(\lambda, x_i), B^+(x_i)),$$

(respectively $N_t^\oplus(\lambda, x_i) := (V_t^\oplus(\lambda, x_i), B^\oplus(x_i))$),

where $x_i \in \Xi_1$ and

$$V_t^+(\lambda, x_i) := \{v \in \Xi_d \mid \langle v, \lambda \rangle + t\langle x_i, \lambda \rangle > 0\}, \quad B^+(x_i) := \{m \in \Xi_1 \mid m \geq x_i\},$$

$$V_t^\oplus(\lambda, x_i) := \{v \in \Xi_d \mid \langle v, \lambda \rangle + t\langle x_i, \lambda \rangle \geq 0\}, \quad B^\oplus(x_i) := \{m \in \Xi_1 \mid m \geq x_i\}.$$

Proof. Let (A, B) be a maximal t -semidestabilized pair with respect to λ . Let $x_i := \min(B)$. By Mukai’s order,

$$\langle v, \lambda \rangle + t\langle m, \lambda \rangle \geq \langle v, \lambda \rangle + t\langle x_i, \lambda \rangle \geq 0, \quad \text{for all } (v, m) \in (A, B).$$

Then $(A, B) \subseteq N_t^\oplus(\lambda, x_i)$, and the maximality condition implies that $(A, B) = N_t^\oplus(\lambda, x_i)$. In particular, this proves that $N_t^\oplus(\lambda, x_i)$ is a maximal t -semidestabilized pair with respect to λ . The proof for maximal t -destabilized pairs is similar, exchanging the inequalities for strict inequalities. □

Proof of Theorem 1.4. Suppose (X, H) is a t -unstable pair (a non- t -stable pair, respectively). By Lemma 3.2 there is $g \in G$ and $\lambda \in S_{n,d}$ such that

$$\mu_t((g \cdot X, g \cdot H), \lambda) > 0 \quad (\geq 0, \text{ respectively}).$$

Then, every $(v, m) \in (g \cdot \mathcal{X}, g \cdot \mathcal{H})$ satisfies $\langle v, \lambda \rangle + t\langle m, \lambda \rangle > 0$ (≥ 0 , respectively). By the definition of maximal t -(semi)stable pairs and Lemma 5.2, $g \cdot \mathcal{X} \subseteq V_t^+(\lambda, x_i)$ and $g \cdot \mathcal{H} \subseteq B^+(x_i)$ ($g \cdot \mathcal{X} \subseteq V_t^\oplus(\lambda, x_i)$ and $g \cdot \mathcal{H} \subseteq B^\oplus(x_i)$, respectively) hold for some $\lambda \in S_{n,d}$ and some $x_i \in \Xi_1$. Choosing the maximal pairs of sets $N_t^\oplus(\lambda, x_i)$

under the containment order where $\lambda \in S_{n,d}$ and $x_i \in \Xi_1$, we obtain families of pairs whose coefficients belong to maximal t -(semi)destabilized sets. \square

Proposition 5.3. *Let $t \in (0, t_{n,d})$. If the set*

$$\text{Ann}_t(\lambda, x_i) = \{(v, m) \in V_t^\oplus(\lambda, x_i) \times B^\oplus(x_i) \mid \langle v, \lambda \rangle + t\langle m, \lambda \rangle = 0\}$$

is not empty, then it is equal to the cartesian product $V_t^0(\lambda, x_i) \times B^0(\lambda, x_i)$ where

$$V_t^0(\lambda, x_i) = \{v \in V_t^\oplus(\lambda, x_i) \mid \exists m' \in B^\oplus(x_i) \text{ such that } \langle v, \lambda \rangle + t\langle m', \lambda \rangle = 0\},$$

$$B^0(\lambda, x_i) = \{m \in B^\oplus(x_i) \mid \langle \bar{m}, \lambda \rangle \geq \langle m, \lambda \rangle \text{ for all } \bar{m} \in B^\oplus(x_i)\}.$$

We call $\text{Ann}_t(\lambda, x_i)$ the Annihilator of λ and x_i at t .

Proof. Let $(v, m) \in \text{Ann}_t(\lambda, x_i)$. Then $v \in V_t^0(\lambda, x_i)$. Suppose there is $\bar{m} \in B^\oplus(x_i)$ such that $\langle m, \lambda \rangle > \langle \bar{m}, \lambda \rangle$. Then, since $t > 0$,

$$0 = \langle v, \lambda \rangle + t\langle m, \lambda \rangle > \langle v, \lambda \rangle + t\langle \bar{m}, \lambda \rangle,$$

which contradicts the fact that $(v, \bar{m}) \in N_t^\oplus(\lambda, x_i)$. Therefore $m \in B^0(\lambda, x_i)$.

Let $(v, m) \in V_t^0(\lambda, x_i) \times B^0(\lambda, x_i)$. Then there is $m' \in B^\oplus(x_i)$ such that $\langle v, \lambda \rangle + t\langle m', \lambda \rangle = 0$. Since $m \in B^0(\lambda, x_i)$, then $\langle m', \lambda \rangle \geq \langle m, \lambda \rangle$. Therefore, we have that

$$0 = \langle v, \lambda \rangle + t\langle m', \lambda \rangle \geq \langle v, \lambda \rangle + t\langle m, \lambda \rangle \geq 0,$$

because $(v, m) \in N_t^\oplus(\lambda, x_i)$. This implies that $(v, m) \in \text{Ann}_t(\lambda, x_i)$. \square

Proof of Theorem 1.6. Let $p = (X, H)$. By [2, Remark 8.1 (5)], since $p = (X, H)$ is strictly t -semistable and represents a closed orbit, then the stabilizer subgroup $G_p \subset G = \text{SL}(n+2, \mathbb{K})$ is infinite. This implies there is a one-parameter subgroup $\lambda \in G_p$. In particular $\lim_{s \rightarrow 0} \lambda(s) \cdot (X, H) = (X, H)$. This implies that $\mu_t(X, H, \lambda) = 0$. By choosing an appropriate coordinate system and applying Lemma 3.2 we may assume that $\lambda \in S_{n,d}$ and $(\mathcal{X}, \mathcal{D}) = (V_t^0(\lambda, x_i), B^0(\lambda, x_i))$. Indeed, the latter follows from Proposition 5.3. \square

6. A METHOD TO STUDY STABILITY

The following method can be extended to a full algorithm to describe $M_{n,d,t}^{GIT}$ [7]:

1. By Theorem 1.1, the interval of stability of any pair (X, H) for *any* polarization $t \in \mathbb{Q}_{\geq 0}$ is determined by a finite set of one-parameter subgroups $S_{n,d}$ which can be computed using Definition 3.1.
2. The walls $t_0, \dots, t_{n,d}$ are among those in (1).
3. For each wall $t = t_i$ or for any $t \in (t_i, t_{i+1})$ we may compute the sets of monomials $N_t^\oplus(\lambda, x_j)$ for each $\lambda \in S_{n,d}$ and $0 \leq j \leq n+1$ and choose the *maximal* among them. By Theorem 1.4, these correspond to families in $R_{n,d}$ of non- t -stable pairs. Each non- t -stable pair corresponds to one of these families. Then, the Centroid Criterion (Lemma 1.5) distinguishes for which of these families the general element is strictly t -semistable or t -unstable.
4. For each family which is strictly t -semistable, we consider the set

$$(V_t^0(\lambda, x_i), B^0(\lambda, x_i))$$

of each maximal $N_t^\oplus(\lambda, x_j)$. Any strictly t -semistable closed orbit must belong to families whose defining equations have monomials in this set

(Theorem 1.6). These are also called t -polystable orbits which are not t -stable.

5. To determine the t -stable orbits geometrically, we classify the families given by $N_t^\oplus(\lambda, x_j)$ according to their singularities. This requires an understanding of the singularities of (X, H) for given n and d as well as their deformations. See [6] for the case of cubic surfaces.

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Our results have been implemented in a Python software package available in [7]. Detailed algorithms implemented in the software package will appear in [5]. The source code, but not the text of this article, is released under a Creative Commons CC BY-SA 4.0 license. See [7] for details. Use of the source code in an academic or commercial context should be acknowledged by including a reference or citation to this article.

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