

## Hints for solving the exercises in Chapter 4

**Hints to Exercise 4.3** (a) For “ $\Leftarrow$ ” proceed as for the square root method to compute a Cholesky factorization of symmetric, positive definite matrices. For “ $\Rightarrow$ ” show that a  $LR$  factorization of  $A$  can be used to determine a  $LR$  factorization for each of the considered principal submatrices.

**Hints to Exercise 4.4** (a) Use the positive definiteness of the matrix  $A$  with a special well-known vector.

(b) For fixed indices  $i$  and  $j$ , apply the positive definiteness of the matrix  $A$  with the vector

$$x = (x_k) \in \mathbb{R}^N \quad \text{with } x_k = \begin{cases} 1, & k = i, \\ 0, & k \neq i, k \neq j, \\ \alpha, & k = j, \end{cases}$$

with  $\alpha \in \mathbb{R}$  arbitrary. From that conclude that no real solution  $\alpha$  to the corresponding quadratic equation exists. This finally yields the solution to the problem.

(c) A contradictory assumption leads to a contradiction to the statement of part (b) of the exercise.

**Hints to Exercise 4.5** Consider the decomposition (\*)  $A = LL^T$  with the lower triangular matrix  $L = (\ell_{ij}) \in \mathbb{R}^{N \times N}$ . For fixed index  $i \in \{m+2, m+3, \dots, N\}$ , prove by mathematical induction w.r.t.  $j \in \{1, 2, \dots, i-m-1\}$  that  $\ell_{ij} = 0$  holds. (Use (\*) to derive necessary conditions for the numbers  $\ell_{ij}$ ).

**Hints to Exercise 4.6** Consider the notations

$$U = \left[ \begin{array}{c|c|c} u_1 & \dots & u_N \end{array} \right], \quad V = \left[ \begin{array}{c|c|c} v_1 & \dots & v_N \end{array} \right], \quad \langle u, v \rangle_2 = u^T v$$

and show first that the representation

$$Ax \stackrel{(*)}{=} \sum_{k=1}^N \sigma_k \langle x, u_k \rangle_2 v_k \quad \text{for } x \in \mathbb{R}^N$$

holds. This representation (\*) has to be applied several times in the sequel.

(a) Derive a formula for  $\|A\|_2$  in terms of  $\sigma_1$ , and proceed similarly for  $\|A^{-1}\|_2$  and  $\sigma_N$ .

(b) Consider  $x = \sum_{k=1}^N \alpha_k u_k$  and find out under which conditions on the coefficients  $\alpha_1, \alpha_2, \dots, \alpha_N$  the identity  $\|b\|_2 = \|A\|_2 \|x\|_2$  is satisfied. Similarly consider  $\Delta x = \sum_{k=1}^N \beta_k u_k$  and find out under which conditions on the coefficients  $\beta_1, \beta_2, \dots, \beta_N$  the identity  $\|\Delta x\|_2 = \|A^{-1}\|_2 \|\Delta b\|_2$  is satisfied. As a consequence from these properties, the solution to the third subproblem in part (b) is obtained.

(c) First reduce the problem and determine vectors  $b \in \mathbb{R}^N$  so that  $\|x\|_2 = \|A^{-1}\|_2 \|b\|_2$  holds.

**Hints to Exercise 4.9** Consider the notations

$$A = \left[ \begin{array}{c|c|c} a_1 & \dots & a_N \end{array} \right], \quad Q = \left[ \begin{array}{c|c|c} q_1 & \dots & q_N \end{array} \right], \quad R = (r_{ij}).$$

and compute  $|\det A|$  by using the identity  $A = QR$ . On the other hand there holds  $a_j = \sum_{i=1}^j r_{ij} q_i$  with mutually orthonormal vectors  $q_1, q_2, \dots, q_i$ . This can be used to determine lower bounds for the number  $\|a_j\|_2$ .

**Hints to Exercise 4.10** In part (a) compute

$$(A + uv^T) \left( A^{-1} - \frac{A^{-1}uv^T A^{-1}}{1 + v^T A^{-1}u} \right).$$